

# EWELLIX

A Schaeffler Company

## Actuator range catalogue





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# The heritage of innovation

Ewellix is a global innovator and manufacturer of linear motion and actuation solutions. Our state-of-the-art linear solutions are designed to increase machine performance, maximise uptime, reduce maintenance, improve safety and save energy. We engineer solutions for assembly automation, medical equipment, mobile machinery, distribution and a wide range of other industrial applications.

## Technology leadership

We earned our reputation through decades of engineering excellence. Our journey began over 50 years ago as part of the SKF Group, a leading global technology provider. Our history provided us with the expertise to continuously develop new technologies and use them to create cutting edge products that offer our customers a competitive advantage.

In 2019, we became independent and changed our name to Ewellix. We are proud of our heritage. This gives us a unique foundation on which to build an agile business with engineering excellence and innovation as our core strengths.

## Global presence and local support

With our global presence, we are uniquely positioned to deliver standard components and custom-engineered solutions, with full technical and applications support around the world. Our skilled engineers provide total life-cycle support, helping to optimise the design, operation and maintenance of equipment thus improving productivity and reliability while reducing costs. At Ewellix, we don't just provide products; we engineer integrated solutions that help customers realise their ambitions.



## Schaeffler Group – We pioneer motion

Ewellix is since 2023 owned by the Schaeffler Group.

As a leading global supplier to the automotive and industrial sectors, the Schaeffler Group has been driving forward groundbreaking inventions and developments in the fields of motion and mobility for over 75 years.

With innovative technologies, products, and services for electric mobility, CO<sub>2</sub>-efficient drives, Industry 4.0, digitalization, and renewable energies, the company is a reliable partner for making motion and mobility more efficient, intelligent, and sustainable.

Schaeffler manufactures high-precision components and systems for powertrain and chassis applications as well as rolling and plain bearing solutions for a large number of industrial applications.





# Trusted engineering expertise

Our industry is in motion; pushing towards solutions that reduce environmental impact and leverage new technology. We provide technical and manufacturing expertise to overcome our customers' challenges.

## Engineering for the future

We work in a **wide range of industries**, where our solutions provide key functionality for business critical applications.

For the **medical industry**, we provide precision components for use in core medical equipment.

Our unparalleled understanding of **assembly automation** systems is based on decades of research into advanced automation components and techniques.

Our deep knowledge of **mobile machinery** provides powerful and reliable electromechanical solutions for the harshest conditions. In an **industrial distribution** setting, we supply linear expertise to our partners, empowering them to serve customers with greater efficiency.

## We offer excellence

We have a **unique understanding of linear equipment** and how it's integrated in customers' applications to provide the best performance and machine efficiency.

**We assist our customers** by creating equipment that runs faster, longer and that is safe and sustainable.

We provide a wide variety of **linear motion components** and **electromechanical actuators** for equipping any automation application, thus helping our customers **increase productivity, reduce their footprint, energy use and maintenance**.

### Actuation systems



### Ball and roller screws



### Linear guides and systems



The background is a solid yellow color with a light gray grid pattern. There are four thick, dark gray diagonal bars: one in the top-left, one in the top-right, one in the bottom-left, and one in the bottom-right, all pointing towards the center.

# 1

## Introduction

- Cost effectiveness
- Controllability
- Stability

# Core technologies

## Actuation technology

Our extensive experience and knowledge of actuation systems allows us to satisfy the most demanding requirements using linear actuators, lifting columns and control units.

### Linear actuators

We offer a wide range of low- to medium-duty actuator designs and configurations for simple industrial or specific health care applications. Our versatile range provides everything from low- to high-load capacities and medium operating speeds to quiet and aesthetically designed systems (→ **fig. 1**).

### High-performance actuators

Our range of high-duty actuators meets the needs of demanding industrial applications with high loads and speeds in continuous operation. These actuators provide the best controllability and reliability for programmable motion cycles (→ **fig. 2**).

### Lifting columns

We offer a wide range of options for several applications. In addition, our lifting columns are quiet, robust, powerful, resistant to high offset loads and feature attractive designs (→ **fig. 3**).

### Control units

Ideal for applications focused on system control, Ewellix control units provide connections for foot and hand or desk switches (→ **fig. 4**).

### Operating switches

Ewellix offers different operating switches to control the position of your equipment. The range includes:

- Hand switches
- Foot switches
- Desk switches

These switches can be used with control units to drive linear actuators and lifting columns or directly with the devices in AC powered versions.



Fig. 1



Fig. 2



Fig. 3



Fig. 4

## Ball and roller screw technology

For applications that require driving by transforming rotary action into linear motion, we provide a comprehensive range of solutions including rolled ball screws, roller screws and ground ball screws.

### Miniature ball screws

Ewellix miniature ball screws are very compact and provide silent operations (↳ **fig. 5**).

### Rolled ball screws

We offer several, highly precise recirculating systems to cover most application requirements which can reduce or eliminate backlash (↳ **fig. 6**).

### Ground ball screws

Ewellix ground ball screws offer increased rigidity and precision.

### Roller screws

Ewellix roller screws go far beyond the limits of ball screws providing the ultimate precision, rigidity, high speed and acceleration. In addition, backlash can be reduced or eliminated. Long leads are available for very fast movements (↳ **fig. 7**).



Fig. 5



Fig. 6



Fig. 7

## Linear guide technology

To provide optimal solutions for all your guiding needs, our product range features shaft guidings, profile rail guides and precision rail guides.



Fig. 8



Fig. 9

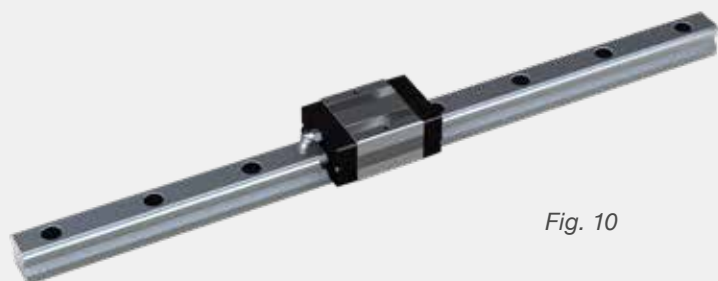


Fig. 10

### Linear ball bearings

Cost-effective, simple and self-aligning, Ewellix shaft guidings feature unlimited stroke, adjustable preload and excellent sealing performance. They are also available in corrosion-resistant versions and pre-mounted on an aluminium housing as a unit (→ fig. 8).

### Precision rail guides

With a range of modular options, Ewellix precision rail guides feature different rolling elements and cages. These guides feature high precision, high load carrying capacity and stiffness, and also come with an anti-creeping system. They are also available as a ready-to-mount kit (→ fig. 9).

### Profile rail guides

Featuring unlimited stroke through joint rails and excellent rigidity, capable of withstanding moment loads in all directions, Ewellix profile rail guides are ready to mount and provide easy maintenance along with high reliability. They are available in ball or roller versions as well as standard and miniature sizes (→ fig. 10).

The terms used in the catalog are listed in a **Glossary** on **page 303** and the **Symbols** are described from the **page 307**.

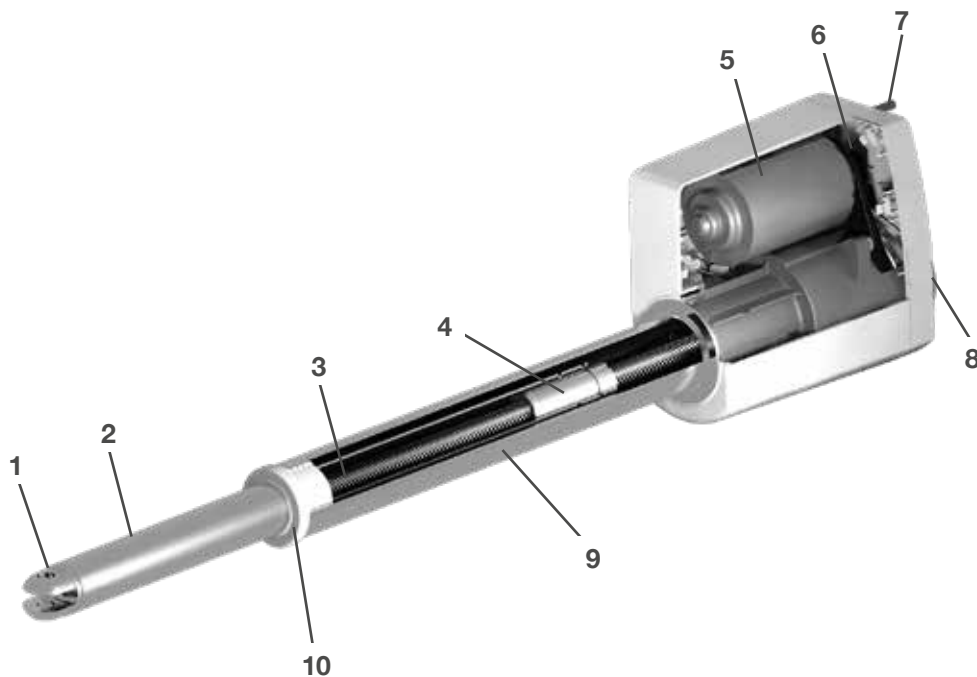
# Product overview

## Linear actuators

Electromechanical linear actuators enable precise, controlled, and repeatable push/pull movements in linear drive applications. Linear actuators serve as efficient, virtually maintenance-free, and environmentally friendly alternatives to hydraulic or pneumatic types.

Actuators with a modular design and open architecture offer opportunities to choose and integrate components to achieve customized solutions within existing envelopes. Application potential expands with the introduction of technologies for specific purposes, such as hall sensors, limit

switches, potentiometers, friction clutches, or back-up nuts. Equipped with brushed DC motor or AC motor, the duty cycle is rated up to 20% or up to 40% if equipped with a AC motor.



1. Front attachment
2. Inner tube or Push tube
3. Screw
4. Nut
5. Electrical motor
6. Gearbox
7. Electrical cable
8. Rear attachment
9. Outer tube or protection tube
10. Sealing system

## Lifting column

Lifting columns enable precise, controlled, and repeatable lifting movements of in linear drive applications including with those with torsion and off set loads.

Lifting columns with a modular design and open architecture offer opportunities to choose and integrate components like linear actuators or drive to achieve customized solutions within existing aluminum profiles. Application potential expands with the introduction of technologies for specific pur-

poses, such as hall sensors, limit switches but also Integrated Circuits for switch mode power supply and motor control. Equipped with brushes DC motor or AC motor, the duty cycle is rated up to 10%, which means when the load is the maximum.



1. Inner tube
2. Outer tube
3. Screw and nut
4. Cables through
5. Power supply
6. Electrical Motor
7. Gearbox
8. Control board
9. Cable connector



*Lead screw*



*Precision rolled ball screws*

## Screws

Ball and roller screws are key components to build electric cylinders. They transfer rotary movements of the motor into linear movements. Their efficiency and their load and speed capabilities have a very big influence on the performance of electric cylinders.

Thanks to decades of experience with manufacturing ball and roller screws and continuous product and process development, Ewellix builds electric cylinders with precision screw solutions that fulfill the most demanding applications in terms of efficiency, precision, durability and value. All screws are made of high-strength materials with specific heat-treatment.

### Lead screw

These screws transmit torque into linear motion through direct sliding friction. A typical assembly consists of a steel screw and plastic nut. Some of the electric cylinders are equipped with lead screws with a relatively high friction coefficient that makes them well suited for self-locking application. Lead screw actuators accommodate high static force, withstand excessive vibration, operate quietly, and represent cost-effective solutions.

## Precision rolled ball screws

Ewellix ball screw assemblies provide high performance solutions suitable for a wide range of applications where high loads, precision driving, durability and value are prerequisites.

High technology machinery associated with precise control of the cold forming and metallurgical processes enable the production of screws that offer virtually the same accuracy and performance of ground ball screws, but at a lower cost. Standard lead precision is G9, according to ISO 286-2:1988. Ewellix production meets G7 lead precision for screw shaft nominal diameter starting from 20 mm. On request, Ewellix can deliver ball screws with G5 lead precision, according to ISO 3408-3:2006, defined for positioning screws, and matching the lead precision of G5 ground ball screws.



# Ewellix engineering tools

1

## Web-based solutions

To simplify the product selection process, Ewellix offers a set of free Web tools that allow a quick and easy navigation into the complete linear motion offering.

## Actuator Select

Users can choose the desired product family among Columns, Linear Actuators, Rotary Actuators and Controls. Then, by entering few simple parameters, they will be guided in the product selection.

Key features include:

- Four complete product lines
- Dynamic filtering of the results
- Result ranking by application
- Product comparison (up to 3 at time)
- Indication of compatible control unit for selected Column or Actuator
- Cost saving calculator
- Direct link to product drawing, technical datasheet and catalogues

A web-based version of the tool is available at [ewellix.com/actuator-select](https://ewellix.com/actuator-select)

The screenshot shows the Ewellix Actuator Select web tool interface. At the top, there is a navigation bar with the Ewellix logo and links for PRODUCTS, INDUSTRIES, CUSTOMIZATION CAPABILITY, SOLUTIONS, and PRODUCT SELECTIONS. Below the navigation bar is a header image with the text "Actuator select". The main content area includes a description of the tool and a "Cost saving calculator" button. Below this, there is a diagram of a mechanical system. The "Application information" section contains several input fields for user data:

Application information			
Application name:	Electricity cost (kWh):	Operational weeks per year:	Hours per week full load:
Application:	0.12	Week	
Currency:	Operational time per week (hours):	Hours operating at full load (%):	Hours per week idling:
EUR	Hour	Percentage	

# Actuation System set-up

## Linear actuator definition and type

Electro-mechanical linear actuators enable precise, controlled, and repeatable push/pull movement in linear drive applications.

Linear actuators serve as efficient, virtually maintenance-free, and environmentally friendly alternatives to hydraulic or pneumatic types.

Standard versions can handle loads as great as 50 kN, deliver speeds over 150 mm/s, and travel as far as 700 mm. They can be self-contained in aluminum, zinc, or polymer housings and ready-to-mount for easy plug-in operation.

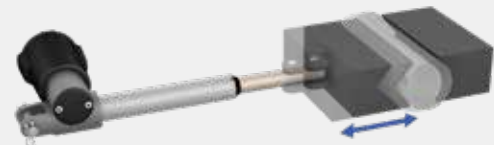
Actuators with modular design and open architecture offer opportunities to choose and integrate components to achieve customized solutions within existing envelopes. Application potential expands with the introduction of technologies for specific purposes, such as hall sensors, limit switches, potentiometers, friction clutches, ball detent clutches, or back-up nuts.

Screw-type linear actuators powered by an electric AC or DC motor basically consist of a lead screw (threaded shaft/spindle) with drive nut and push tube with a gearbox between the motor and the screw also present.

When power is supplied, the motor rotates the lead screw, which causes the drive nut to travel and extend the push tube. Reversing the motor rotation retracts the push tube.



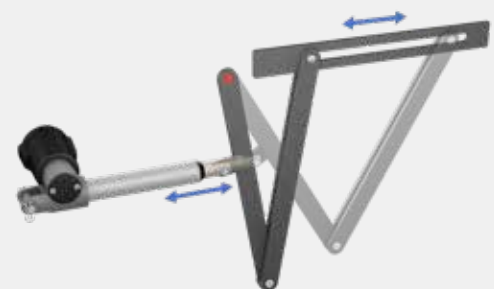
*Pushing/pulling*



*Clamping/gripping*



*Raising/lowering*



*Opening/closing*

## Ball screw vs. acme screw

Traditional types of lead screws include ball screws and acme screws, whose specification will be influenced by an actuator's configuration and load requirements.



Fig. 1  
Ball screw

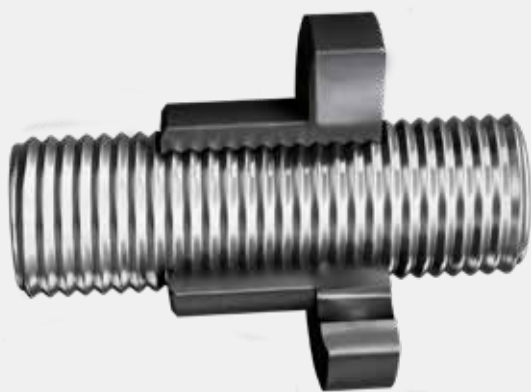


Fig.2  
Acme screw

### Ball screws

All-steel ball screws consist of a screw shaft, ball nut with a ball recirculation system to convert rotary motion into smooth, accurate, and reversible linear motion (or torque to thrust) (→ **fig. 1**). The row of circular rolling elements is self-contained in a closed system between the nut and screw for a design exhibiting extremely low friction coefficients. The low frictional resistance minimizes wear, improves efficiency, and reduces operating temperature for longer service life.

Ball screws can handle high loads, with a very good efficiency, achieve high duty cycles, operate over a wide temperature range, and deliver the precision necessary to enable actuators performing over long periods at high speeds and requiring high dynamic capability.

Brakes usually are adopted in ball screw actuators or non-self locking gear boxes to prevent back-drive and provide an high static load performance.

### Acme screws

These screws transmit torque into linear motion through direct sliding friction. A typical assembly consists of a steel screw and plastic nut (→ **fig. 2**).

Some of the products are equipped with acme screws with a relatively high friction coefficient that makes them well suited for self-locking applications. Acme screw actuators accommodate high static load, withstand excessive vibration, operate quietly, and represent cost-effective solutions. Brakes could be adopted to increase the static load performance.

## Performance considerations

Beyond the basic fundamentals of actuator operation, applications may require feedback on position and/or direction, limits on motion or travel in a particular direction, or protection against dynamic overload. Enabling technologies have been developed for these purposes.

### Limit switches

Its purpose is to limit actuator motion or travel in both direction. It is used on DC and AC versions (→ **fig. 3**). When activated, the switch typically opens an electrical contact integrated on the electrical circuit of the motor. By reversing the voltage, the limit switch circuit is over pass, the motor runs in the opposite direction and the switch is released. The second limit switch will proceed in the same way but for the opposite direction. These devices prevent actuators from running into the mechanical ends.

### End-stop output

Its purpose is to provide output information on when the actuator reaches a position in a particular direction (→ **fig. 4**). When activated, the switch opens or closes an electrical contact. When the contact is closed, current will flow through the switch; when the contact is open, no current will flow through the switch. These devices could be used on the application to prevent actuators from running into the mechanical ends and may allow for the adjustment of stroke length. End-stop output could be used by a control board to limit the stroke of the actuator, for instance.

### Hall sensors

These rotary or linear sensing devices are incremental no contact sensors that are used to define the relative position of an actuator. Two sensors detect the changing magnetic field created by a rotating magnet and then relay corresponding output pulses to a control unit to provide the travel feedback. Two sensors could detect also the direction of the movement (→ **fig. 5**). After a homing procedure, the travel distance can be defined with counting the pulse.

### Potentiometer

A potentiometer is an analog feedback device. The potentiometer is considered an absolute sensor with unique value in each position. Sometimes it is called a variable resistance that can be read and fed into a controller for positioning control of the application (→ **fig. 6**).

Fig. 3

Limit switches

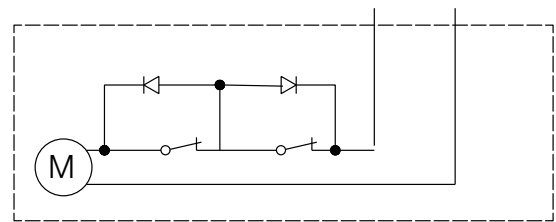


Fig. 4

End-stop outputs

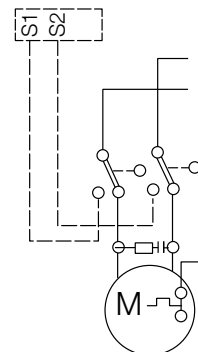


Fig. 5

Hall sensor

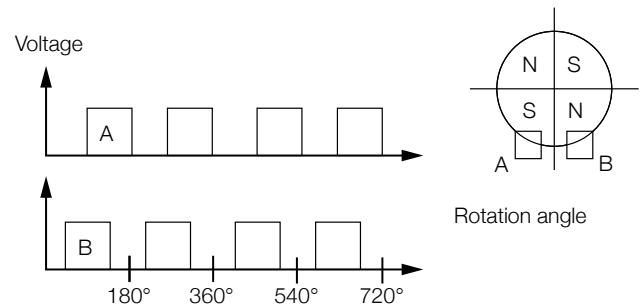
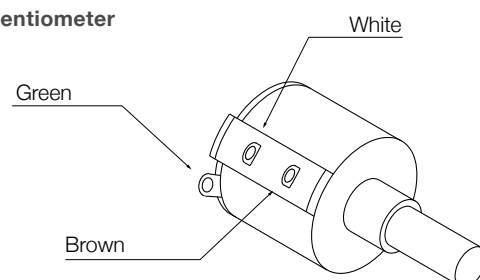


Fig. 6

Potentiometer



## Absolute analogue position output

An absolute analog position output uses a non-contact sensor, so no wear and the absolute positioning provide an unique value in each position by voltage from 0.5 to 4.5. The input voltage is 5V or 10 to 55 V depending the series. The output signal can be read and fed into a controller for positioning control of the application. It is the best of the two solutions, hall sensor or potentiometer without compromise (→ fig. 7).

## Friction clutch

This function will protect the actuator from mechanical damage when it reaches either of its mechanical end positions or when the maximum dynamic load is momentarily exceeded. A friction clutch consists of a series of steel plates engaging a hub and a series of friction rings engaging a housing (→ fig. 8).

Pressure is exerted on the plates and rings by an adjuster acting through a spring and pressure plate. The friction clutch is not intended for use as a load limiter, but only for protection of the actuator and end- use equipment in the event of dynamic overload.

## Ball detent clutch

A ball detent type clutch transmits force through hardened balls which rest in detents on the shaft and are held in place with springs. An overtorque/load condition pushes the balls out of their detents, thereby decoupling the lead-screw from the motor.

## Back-up nut

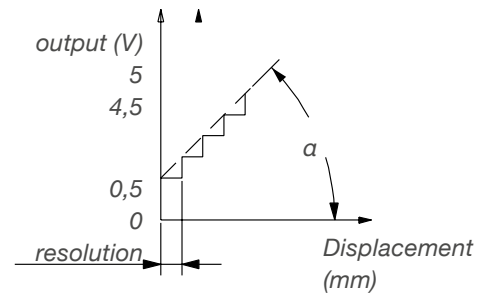
This prevents an actuator from collapsing if a drive nut fails. The back- up nut is usually in metal, exhibits greater anti-shear strength than the drive nut, and only makes contact with the threads of the spindle when the threads of the drive nut fail (→ fig. 9). The back-up nut carries the load and may be able to lower the load (signaling need for repair).

## Slip stick effect

The cycle of alternating slipping and sticking as two surfaces rub against each other results in vibration and noise. Resonances within other materials can occur. This effect can sometimes be heard, felt or seen. With linear actuators and columns, slip stick has been witnessed between the Delrin and aluminum or steel, such as between drive nut and spindle, and glide pad and extrusion.

Fig. 7

### Absolute analogue position sensor



$$\tan(\alpha) = \text{output relation to displacement (V/mm)}$$

Fig. 8

### Friction clutch

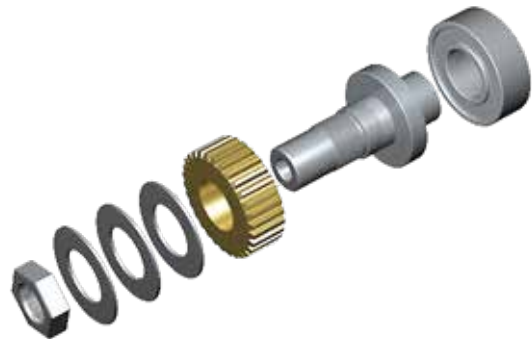


Fig. 9

### Back-up nut








# Product range comparison

## Linear actuators

Ewellix offers a wide range of linear actuators in terms of push or pull load, speed, stroke length and input voltage. Most of them are approved as a component of a medical device that complies with IEC 60601-1 and UL mark RU.



Family	Load kN	Speed mm/s	Stroke mm	Voltage V		See page –
<b>MATRIX</b>	8	13	700	12, 24		57
<b>RUNNER</b>	12	8	700	24		70
<b>CAJA 35C</b>	3,5	7,5	250	24		76
<b>Ecomag</b>	6	9	300	24		80
<b>CAHB</b>	10	60	700	12, 24, 48		84
<b>CAT and CAR</b>	4	193	700	12, 24, 120, 230, 3x400		137
<b>CAHM</b>	50	74	700	24, 230, 3x400		187



Harsh environment



Medical



Some products are designed for a specific application but are suitable for others applications that request the similar performance.

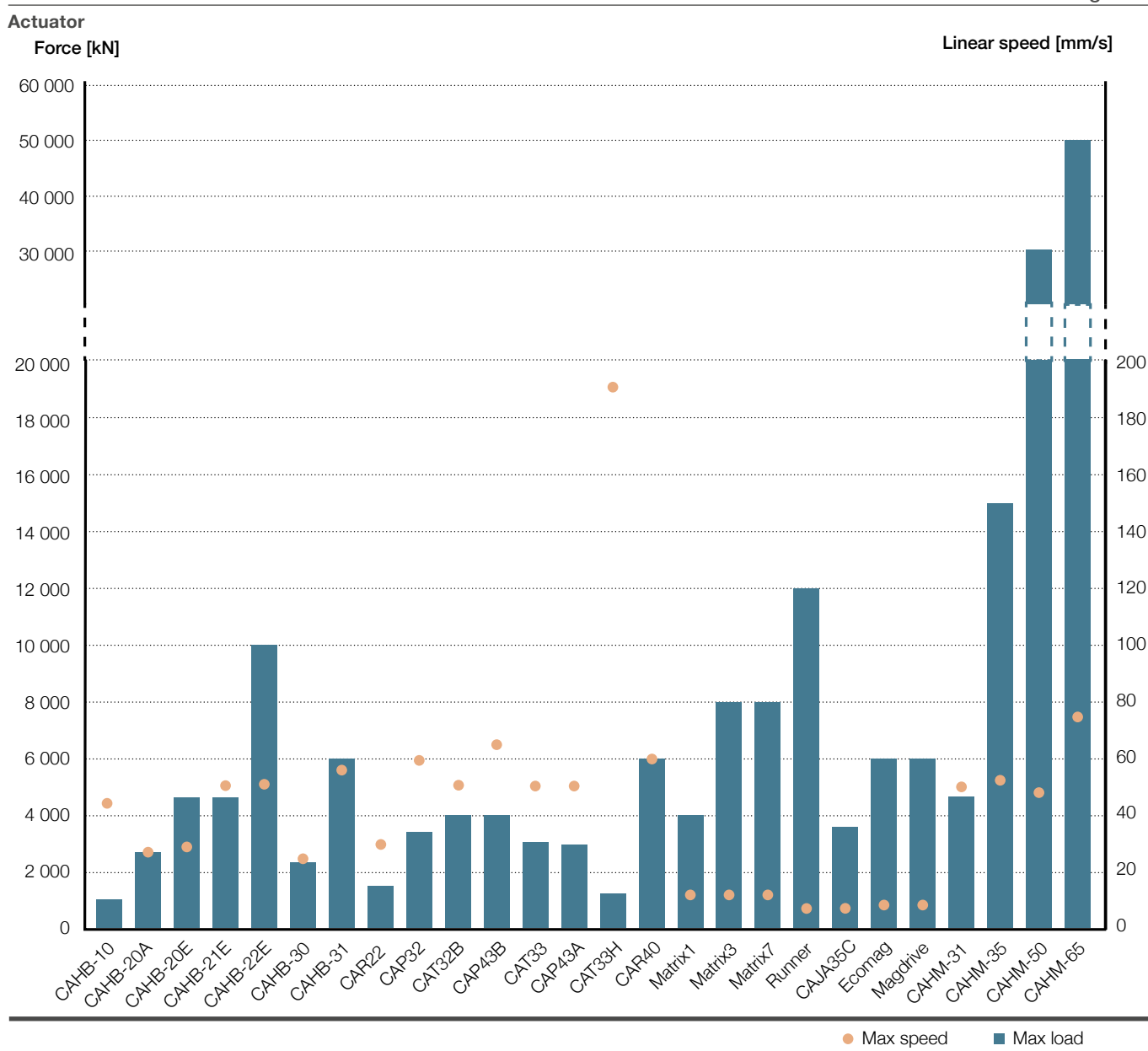
If you request a higher force than 12 kN, we invite you to review the **High performance actuator catalogue (PUB NUM IL-05001)**.

## Force and speed capabilities

Diagram 1 provides a quick overview of the rated load and the speed of the actuators. Use this graph to quickly evaluate which actuator could fit best in your application.

The rated load describes the weight that the actuator can push or pull at the rated duty cycle without overheating. The speed is the maximum linear speed the actuator can reach without load when powered at the rated voltage.

Diagram 1



## Columns

Ewellix offers a wide range of lifting columns in term of push and pull load, offset load in movement, stroke length and input voltage. Most of them are approved as a component of a medical device that complies with IEC 60601-1 and UL mark RU.



Product	Load kN	Bending moment Nm	Speed mm/s	Stroke mm	Voltage V		See page
CPMA-B	2	250	15	400	24, 100 to 240		194-202
CPMT	6	1 400	34	600	24		210
TFG	2,5	500	15	700	120, 230		216
THG	2	1 000	15	700	24		220
TLC	4	2 100	11	700	120, 230		224
TLG	4	2 800	10	700	24		228
TLT	4	1 000	25	700	24		232
TXG	1,5	210	17	600	24, 120, 230		236
FRE	–	–	–	700	–		240



Medical

## Force and speed capabilities

Diagram 2 provides a quick overview of the rated load and the speed of the actuators. Use this graph to quickly evaluate which actuator could fit best in your application.

The rated load describes the weight that the actuator can push or pull at the rated duty cycle without overheating. The speed is the maximum linear speed the actuator can reach without load when powered at the rated voltage.

Some products are designed for a specific application but are suitable for others applications that request the similar performance

Diagram 2

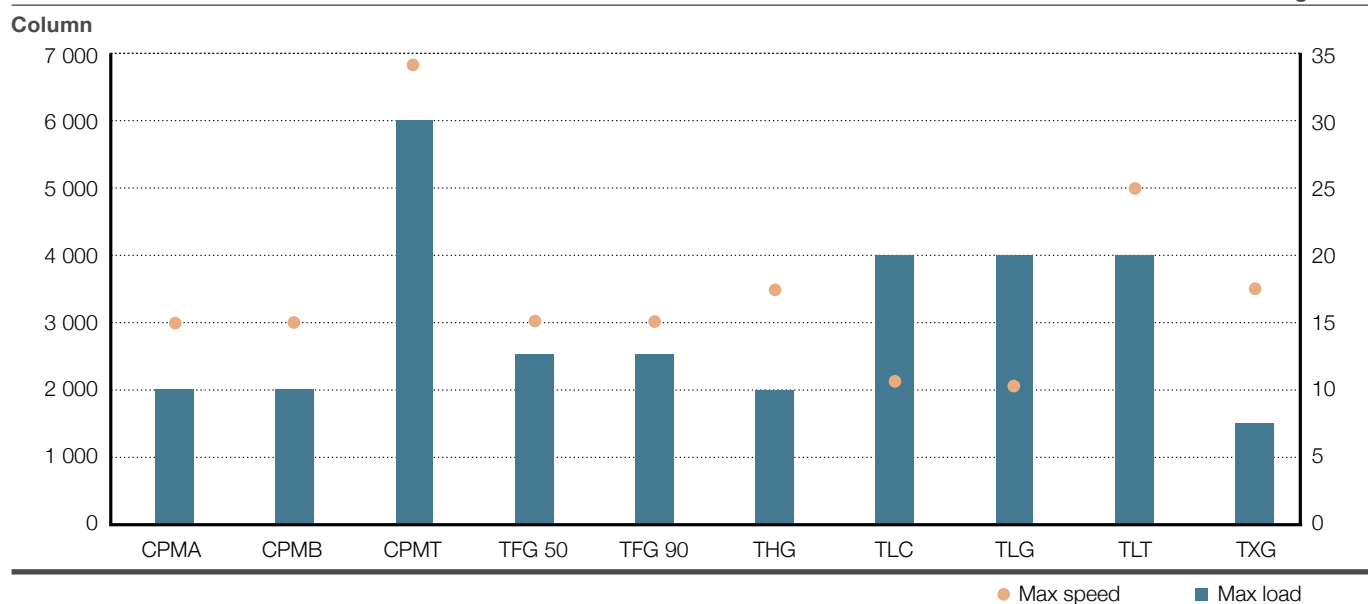
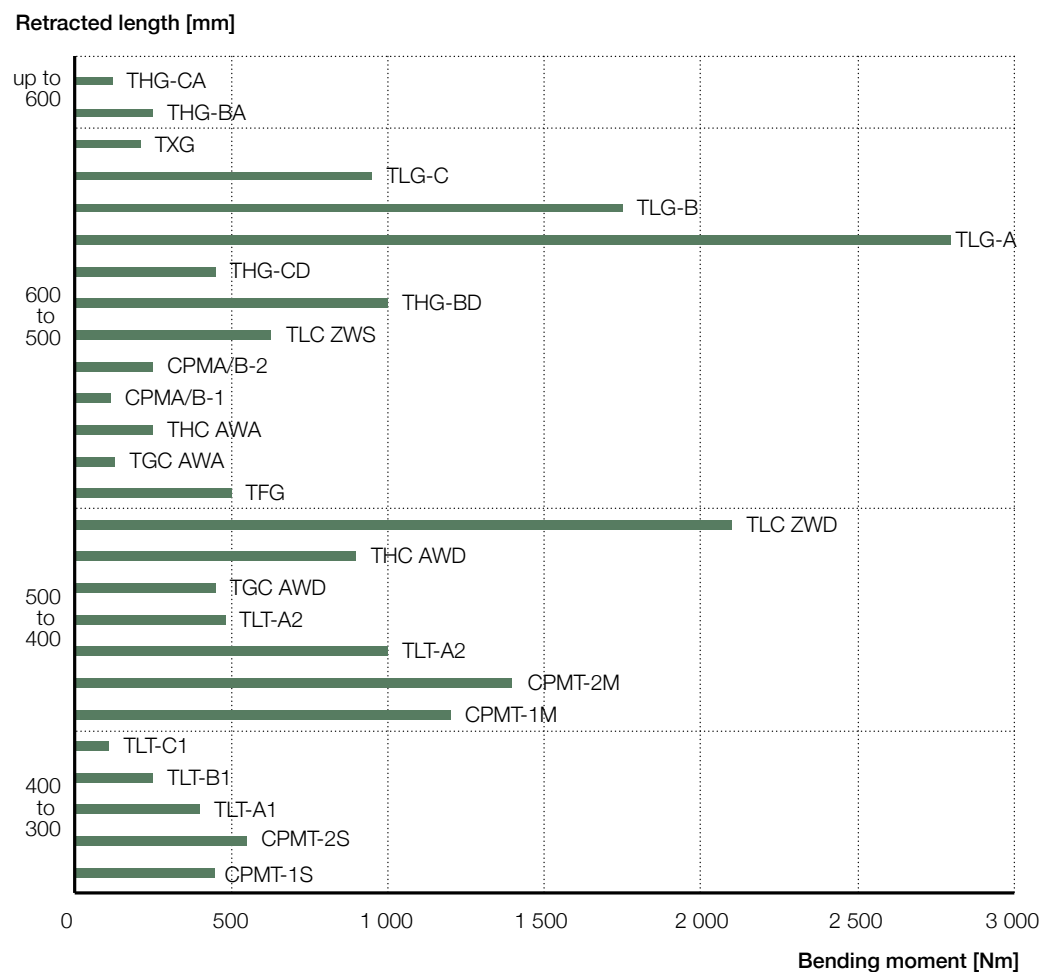




Diagram 3

## Bending moment vs retracted length for stroke length of 400 mm



## Control units

Ewellix offers a wide range of control units in terms of number of connections, functions and input voltage. They are compatible with Ewellix actuators and columns. Most of them are approved as components for medical devices that comply with IEC 60601-1 and UL mark RU.

In order to select the proper accessories for linear actuators and lifting columns, please use the table below.

Start selecting your actuator or column and find horizontally the compatible control units identified by a black dot, then vertically select the appropriate operating switches.

Some products do not need control units, so please continue horizontally to find the appropriate operating switches.



### Combination matrix Actuator

	Control units						Operating switches		
	BCU	VCU	SCU	MCU	SEM	COMPACT	Hand switches	Table switches	Foot switches
<b>Linear actuators</b>									
CAHB-10	•	•	–	–	–	–	–	–	–
CAJA	•	•	•	–	–	–	–	–	–
ECOMAG	•	•	•	•	•	–	–	–	–
MAGDRIVE	•	•	•	•	–	–	–	–	–
MAX1/3	•	•	•	•	–	–	–	–	–
MAX70	–	–	–	–	–	–	PHC	PAM	PFP
MAX72	–	–	–	–	–	–	EHA1	STA	STF
RUNNER	•	•	•	•	–	–	–	–	–
<b>Columns</b>									
CPMA/CPMB	–	–	–	–	–	–	EHA4	STK	STL
CPMT	•	•	•	–	–	–	–	–	–
TFG1	•	•	•	–	–	•	–	–	–
TFG5/9	–	–	–	–	–	–	EHA3	STE	STJ
THG	•	•	•	•	–	–	–	–	–
TLC electric <sup>1)</sup>	–	–	–	–	–	–	–	–	–
TLC low voltage	–	–	–	–	–	–	EHA1	–	–
TLC pneumatic	–	–	–	–	–	–	PHC	PAM	PFP
TLG	•	•	•	•	–	–	–	–	–
TLT	•	•	•	•	–	–	–	–	–
TXG1	–	–	–	–	–	•	–	–	–
TXG4/5/8/9	–	–	–	–	–	–	EHE	STA	STF
<b>Operating switches</b>									
<b>Hand switches</b>									
EHA1	–	–	–	•	–	–			
EHA3	•	•	•	–	–	–			
EHE	–	–	–	–	•				
<b>Table switches</b>									
STA	–	–	–	•	–	–			
STE	•	•	•	–	–	–			
HSM	–	–	–	–	–	•			
HSF	–	–	–	–	–	•			
<b>Foot switches</b>									
STF	–	–	–	•	–	–			
STJ	•	•	•	–	–	–			

<sup>1)</sup> No need of CU, but there is non OS provided by Ewellix

# Operating switches

Ewellix offers a wide range of different operating switches to control the position of your equipment. The range includes: Hand switches, Foot switches, Desk switches.



Combination Matrix Control units			
	Operating switches		
	Hand switches	Table switches	Foot switches
BCU	EHA3	STE	STJ
VCU	EHA3	STE	STJ
SCU	EHA3	STE	STJ
MCU	EHA1	STA	STF
COMPACT	–	HSM, HSF	–
SEM	EHE	–	–



Linear actuators



Lifting column



Control unit

Hand switches



Foot switches



Desk switches



## Input voltage

AC or DC, this is the voltage that is used to power the system or the stand alone linear actuator or lifting column.

For instance, a AC system is one powered by a cable connected to the mains power that provides alternating voltage, typically 230 V AC in Europe and 120 V AC in USA. AC system or linear actuator or lifting column doesn't say that the motor is an AC motor.

For a linear actuator or a lifting column, the motor voltage could be different than mains power. The control unit that

drives the DC lifting column or linear actuator is equipped with a power supply to convert the voltage. The linear actuator and the lifting column could be also equipped with a built-in power supply. In this case, the equipment is powered by the mains power but the motor and other equipment are powered by a DC cable. This is the most convenient system; easy to power and to control.



Case of stand alone lifting column with AC motor: TLC



Case of stand-alone linear actuator with DC motor and built in power supply: MAX7



Case of stand alone lifting column with DC motor and built in power supply: CPMA



Case of AC System with DC linear actuator and lifting column: SCU+TLG + Matrix

## How to read a performance diagram

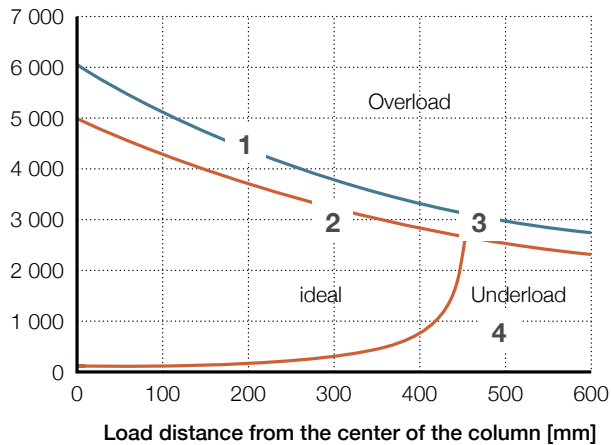
In the product range chapter, a technical description is available for each actuator family. This includes performance overview, a detailed product description, motors and adapter information. In addition to that, each actuator type and size has a dedicated table with the main technical data.

In particular, for the lifting column, we describe the offset load performance.

Here below is a general description on how to read the axial force /linear speed diagram.

### CPMT1-1M, -2M

Load [N]



— CPMT1-2M

— CPMT1-1M

Offset load at full extension

## For a CPMT1-2M

1. (4 500 N at 200 mm): The column can lift and lower a load of 450 kg with a center of gravity located at 200 mm from the center of the column.
2. (3 000 N at 300 mm): The column can lift and lower a load of 300 kg with a center of gravity located at 300 mm from the center of the column.
3. (3 000 N at 450 mm): The column can lift and lower a load of 300 kg with a center of gravity located at 450 mm from the center of the column.
4. (1 000 N at 450 mm): The column can lift a load of 100 kg with a center of gravity located at 450 mm from the

center of the column but during the lowering, the retraction will be not optimal. We recommend to increase the weight or change the load distance. To Increase the load distance, you can change the center of gravity of the lifted part.

# Product benefits

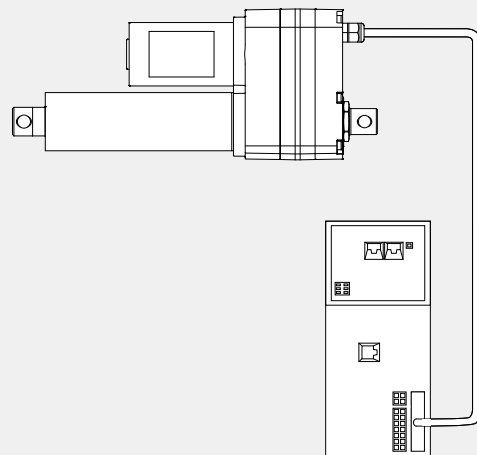
## Pneumatic and hydraulic replacement

Linear movements in modern applications place high demand on travel profiles. Pneumatic and hydraulic cylinders quickly reach their system performance limits. Ewellix electric cylinders offer improved performance and simpler setup in applications that were traditionally served by pneumatic and hydraulic cylinders.

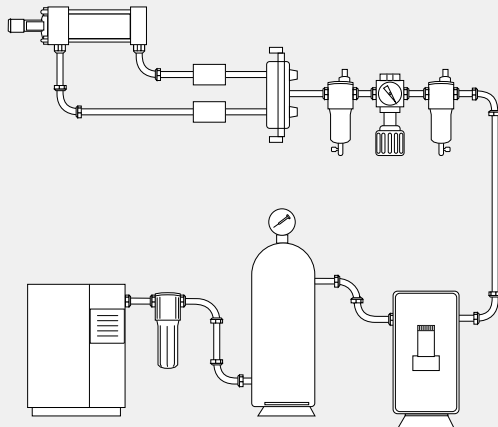
Along with the elimination of air or oil in applications, Ewellix electric linear actuators offer many advantages. Key benefits include a high degree of flexibility, positioning accuracy even to any intermediate target, improved productivity through low maintenance, new options in programming, and seamless integration into machine control systems. These benefits enable new and reliable concepts that can be integrated into a variety of production processes, ultimately allowing new application possibilities.

Electric linear actuators with ball screws provide an energy-saving alternative to pneumatic.

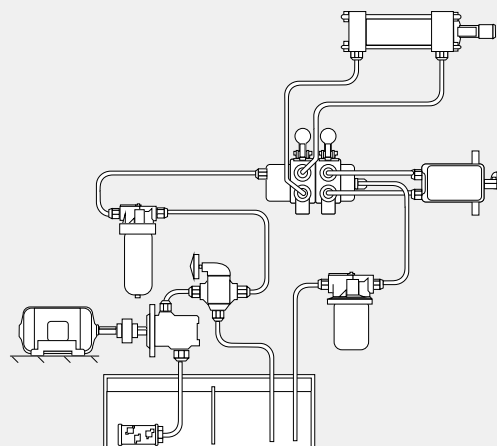
*Electromechanical layout*



*Pneumatic layout*



*Hydraulic layout*



## Replacement of pneumatic cylinders

Pneumatic cylinders are based on a technology which was invented in the year 1728. The commercial use of this technology started at the beginning of the 20th century. The principle of pneumatic technology seems to be simple. Air is pressed via valves either on one side or the other side of a pneumatic cylinder to cause a movement of the push tube.

There is a lot of equipment needed to make the pneumatic system run. The more cylinders in a system, the smaller its section of the cost cake for each cylinder. For a low number of cylinders in a system, the common equipment cost is quite high.

Ewellix electric linear actuators operated by motors with position feedback are fully controllable.

## Replacement of hydraulic cylinders

Hydraulic cylinders are traditionally used in high load applications. The force range of Ewellix electric linear actuators has been extended. Indeed, Ewellix electric linear actuators can provide a force up to 12 kN for DC motor version, up to 50 kN for AC motor version, opening up more applications to switch from hydraulic to electric solutions. Ewellix electric linear actuators are more reliable, easier to control and cleaner to operate than hydraulic cylinders. They eliminate typical operational problems such as contamination, oil leaks, fluid maintenance checks and disposal procedures and require no ancillary equipment.

The technology of hydraulic cylinders is based on Blaise Pascal's hydrostatic law and offers virtually unlimited force. It's the most powerful technology for many applications. The cost for a hydraulic cylinder is moderate, but there is a lot of installation equipment needed to make it work. The operating and maintenance cost is high while the waste disposal is problematic.

Hydraulic cylinders get their power from pressurized hydraulic fluid (typically oil). The installation requires expensive plumbing, filtering, pumps and electronic/ fluid interfaces (valves). The control is quite complicated when considering hysteresis, supply pressure and temperature changes. Hydraulic systems are reliable, as long as the hydraulic fluid is well maintained. With low maintenance, the seals are prone to leak which results in contamination.

Ewellix electric linear actuators solve many of the problems of hydraulic cylinders. The motor is directly linked with the linear movement of the push tube which allows excellent position feedback and full controllability. The power transmission is typically made with a rotating screw and a nut with or without rolling element to carry loads of up to 50 kN with AC motor version. The installation is simple, the maintenance low and there is less noise and no contamination. Due to the efficiency of up to 50%, the operating cost is very low.



## Controllability

Electric drive systems use a screw that offers an easy controllability by counting the number of turns of the screw or other elements mechanically connected. You can control the position, the displacement as well as the speed.

## Precision

The precision depends on the resolution of the position feedback system and how the output is used by the control board. The backlash of the driving mechanism will influence if the direction of the load and movement is changing. The accuracy also depends on the set up and homing procedure of the system.

## Holding force

Electric drive systems offer a high stability and self-locking that prevent unplanned movement in case of static overload or shock applied even if not powered. In addition of built-in brake and the short circuit of the brushed DC motor used in the most of the case, all mechanical driving part participates of the stability.

## Degrees of protection provided by enclosures

The IP Code, International Protection Marking, IEC standard 60529, sometimes interpreted as Ingress Protection Marking, classifies and rates the degree of protection provided against intrusion (body parts such as hands and fingers), dust, accidental contact, and water by mechanical casings and electrical enclosures (→ fig. 1).

It is published by the International Electrotechnical Commission (IEC). The equivalent European standard is EN 60529.

## Safety and environment friendly

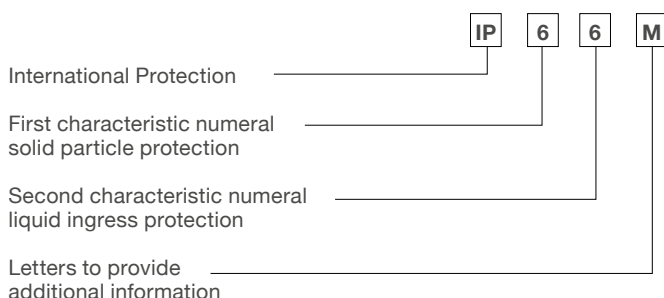
The safety typically starts by the high holding force as compared to the load applied during the normal use of the application that should be lower than the rated load of the electric drive system. The risk of abnormal use of the application should also be considered.

For some application or function in the Medical industry, the manufacturer of the medical device should manage the risk assessment and comply with some regulation as IEC 60601-1, general requirements for basic safety and essential performance. As a component of the medical device, some Ewellix electric drive systems were tested under the same condition to demonstrate compliance to IEC 60601-1 and are registered by UL to be marked RU. Saying that the Safety factor of the complete system is 2 or 2.5 or 4 is not enough. This standard requests that each individual component of the drive system used on a suspended mass be checked and could request a tensile safety factor up to 12, depending on the material, the possible alteration, the backup system and the calculation method.

Nor do electric cylinders have problems with fluid leaks or contaminated air. Moreover, the absence of fluid constantly operating under high-pressure eliminates potential risks to operators in case of cylinder failure.

Without fluid to drive or keep in position and with a good ingress protection up to IP66M, means during movement and IP69K when static, the risk of leakage and contamination is almost negligible. With a static ingress protection, the actuator can be cleaned easily. Actuators rated IP69K accept a high pressure and hot temperature cleaning procedure, that contribute to the later elimination of the risk of pollution.

Fig. 1





## RoHS

Our standard products fall under category 11 in Annex I to Directive 2011/65/EU and therefore do not need to comply with the provisions in the directive before July 22, 2019.

Nevertheless, most of our standard products are already mentioned on a list where we declare that the products do not contain any of the restricted substances over the threshold values stated in the Annex II to Directive 2011/65/EU in any homogenous part of the product.

## REACH

Ewellix has a policy, process and dedicated resources in order to comply with REACH, the Regulation concerning Registration, Evaluation, Authorization and Restriction of Chemicals.

## CE mark

Most of our product have CE mark with a Certificate of Compliance signed by the factory.

## Installation

The installation is simplified. In most cases, the electric drive systems request just the mechanical connection of the 2 attachment points and the electrical connector plug in. Then, it is ready to work.

## Virtually maintenance-free

Ewellix expertise in manufacturing the main components of linear actuator – screws, bearings, guides, seals and lubrication – allows us to maximize service life. With the special hardening treatment of the screws and balls, the linear actuators keep high performance and efficiency during the service life. Compared to their fluid power alternatives, the electromechanical linear actuator systems require no maintenance.

With electromechanical system technology, filter changes and air bleeding are a thing of the past. Simply mount the actuator, plug in the cable to the control unit or a Programmable Logic Controller and you are up and running in record time.

## Tests

Environmental, electrical and mechanical tests are performed in the Ewellix facilities or by external laboratories and recorded internally or by external bodies like UL.



# Customization capabilities

## Ewellix electric cylinder customization

On the standard electric cylinder product range, Ewellix offers an extensive customization program that is able to meet virtually any application need. There are 3 levels of customization that depend on specific requirements and the complexity of implementation.

### Basic customization

These basic design options can be implemented quickly and easily:

- Stroke length
- Retracted length
- Attachment and Mounting holes
- Colors
- Cables and connectors
- De-rated load

### Advanced customization

These design options are more complex and require a dedicated project with the customer:

- Materials
- Housing
- Guiding system (for column)
- Gearbox (e.g., with hand crank)
- Screw (e.g., lead, treatments)
- Screw Nut (e.g., additional backup nut)
- Painting and surface treatments
- Output signal

### Complete customization

In case the standard actuator offering cannot fully satisfy the technical requirements, Ewellix can offer completely customized solutions that are tailor made for each customer.



## Examples of basic and advanced customizations

### CPMA coloured tubes

Lifting columns with cable through the tubes can allow the designer of the equipment to remove shroud or cover even if wires are requested at each side of the tube set. To enhance its integration in the application, Ewellix proposes a customized color for the inner and outer tubes. This is typically proposed with the CPMA and CPMB lifting column but can be also requested for other lifting columns or actuators (→ fig. 1).

### CAHB 10 with connector

Cable length and connector can be customized according to a request have perfect integration with a quick assembly on the application and a drop-in solution (→ fig. 2).

### CAHB 2xE with trunnion mount

To optimize the design of the application or to create a drop-in solution, Ewellix can customize the retracted and extended lengths and the attachments as well (→ fig. 3).

### Column low boy

Precise movement, stiffness and reliability are some of the key factors when it comes to patient tables. Ewellix Low-boy columns provide the precision for easy and safe patient entry with maximum lift functionality. The simple and open motor interface gives the option to mount every motor on customer's side and makes the system very flexible and accessible (→ fig. 4).



Fig. 1



Fig. 2



Fig. 3



Fig. 4

### Clam shell grill

Clam shell grills with electrical lifting are automatized with a linear actuator. The cooking of the steak is exactly as requested by the customer and the operator is more efficient (→ fig. 5).

A customization of the motor could be proposed if a long life time is requested.

To ensure perfect French fries, the lifting of basket is automatized with a linear actuator.

The operator appreciates also the simplicity and the comfort and can focus on other preparation.

### Special motor and external switches

For specific applications such as commercial kitchen equipment where a higher duty cycle and long life time are requested, Ewellix can propose specific motors like brushless DC version. Ewellix could also propose the integration of external switches to have multiple adjustable position feedback or other full system integration (→ fig. 6).

### Very long stroke and graduated tube

On Applications like Medical fluid carts where the liquid pressure is provided by the height of the liquid bag, Ewellix can provide an automatized solution based on a linear actuator with a long and stable inner tube of 1 meter to hang the liquid bag (→ fig. 7).

The laser etched graduated tube provides quick visual information about the height.

### Marked on the tube

On Applications like Medical fluid carts where the liquid pressure is provided by the height of the liquid bag, Ewellix can provide an automatized solution based on a linear actuator with a long and stable inner tube of 1 meter to hang the liquid bag (→ fig. 8).

The laser etched graduated tube provides quick visual information about the height.

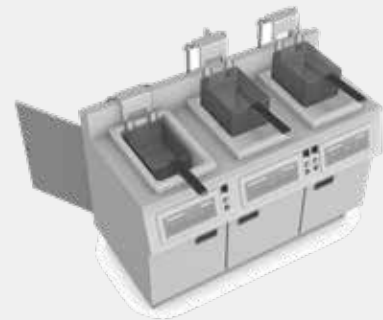


Fig. 5



Fig. 6

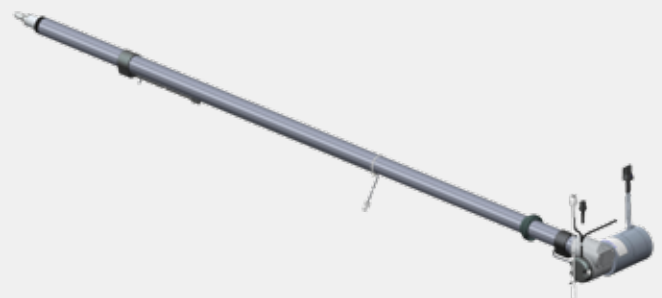


Fig. 7

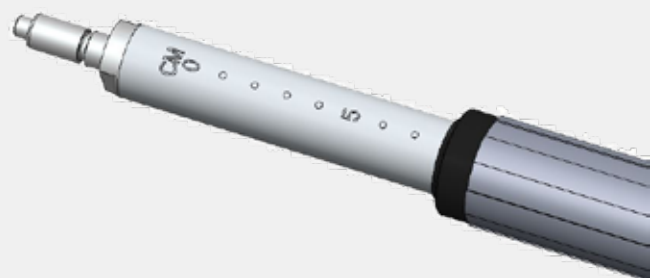


Fig. 8

## Customization request form

### Customization request for linear actuator or column

Company: .....

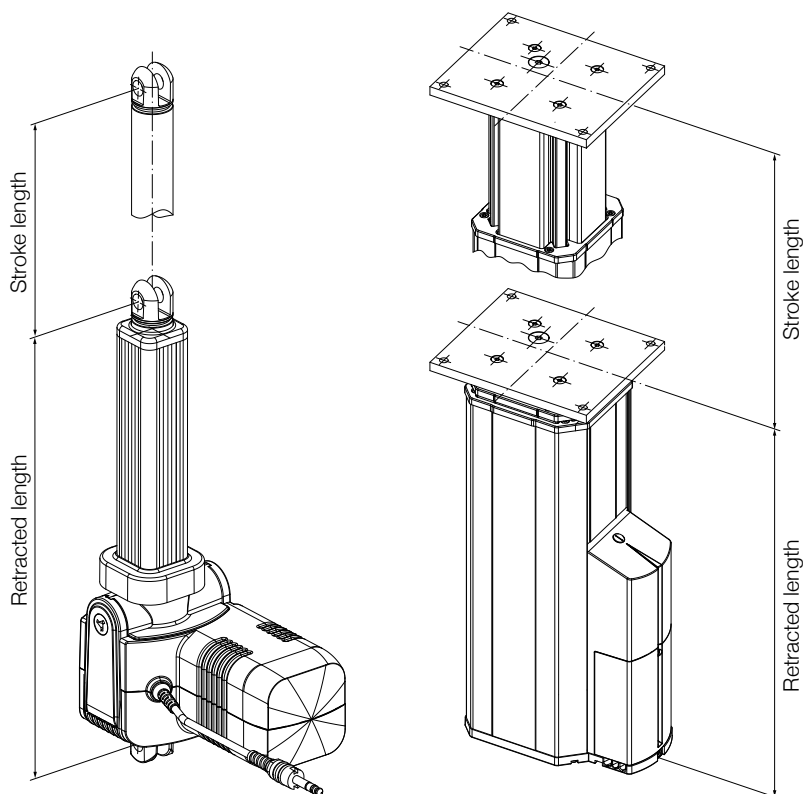
Country: .....

Contact person: .....

Preferred way to be contacted:.....

☐ Phone, Phone number: .....

☐ e-mail: .....



Preferred series (if known) .....

1. Stroke length .....mm

2. Retracted length: .....mm

3. Cable length: .....mm

Connector: ..... Pinning: .....

4. Rear attachment:    rod with hole ☐    fork head with hole ☐    threaded ☐    Inner diameter and width .....

5. Front attachment:    rod with hole ☐    fork head with hole ☐    threaded ☐    Inner diameter and width .....

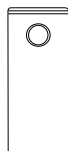
6. Push / Pull max force: .....

7. Color: .....

8. If you need more, describe here:

.....

.....



Rod with hole



Fork head with hole



Threaded

# Application examples

## Medical mobile C-arm

In mobile C-arms, the safe and smooth positioning of the x-ray system is essential.

Ewellix columns deliver high offset load capability, stability and safety to achieve the best possible performance in this application.

The columns can be individually configured to best match each customer's requirements. Additional customizations, such as cable channelling or special hardware interfaces, are possible and simplify the final installation.

Also the monitor can be adjusted the position (up and down); thanks to the Ewellix actuators is possible to set the right position according to the C-arm.

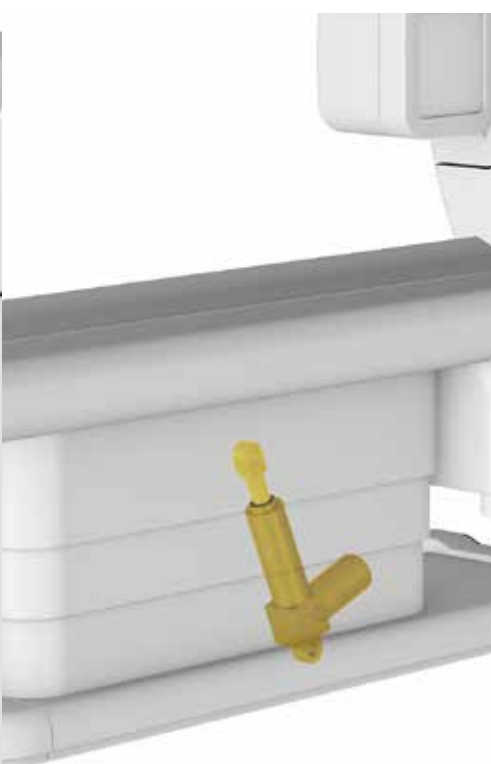
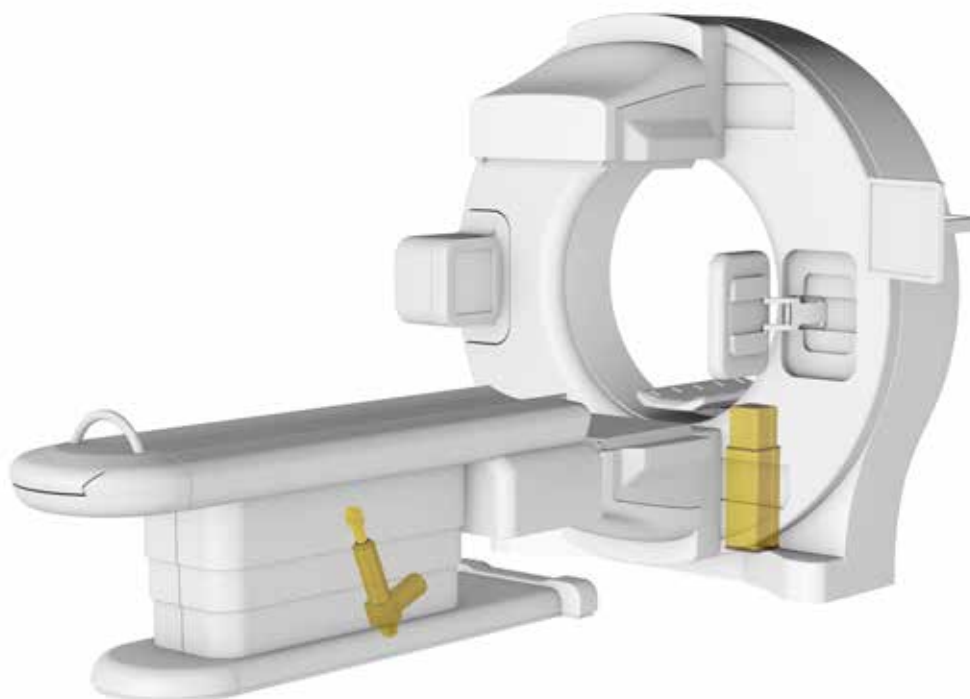


## Medical imaging tables

Imaging tables are used for safely positioning patients during imaging procedures, such as general x-ray, CT or MRI.

Ewellix provides different solutions to design the lifting function. For scissor tables, Ewellix medical actuators with high safety levels can be used.

Alternatively, two synchronized columns deliver an easy to install and very stable complete solution for a table base. Such a column solution can greatly reduce development costs for our customers.



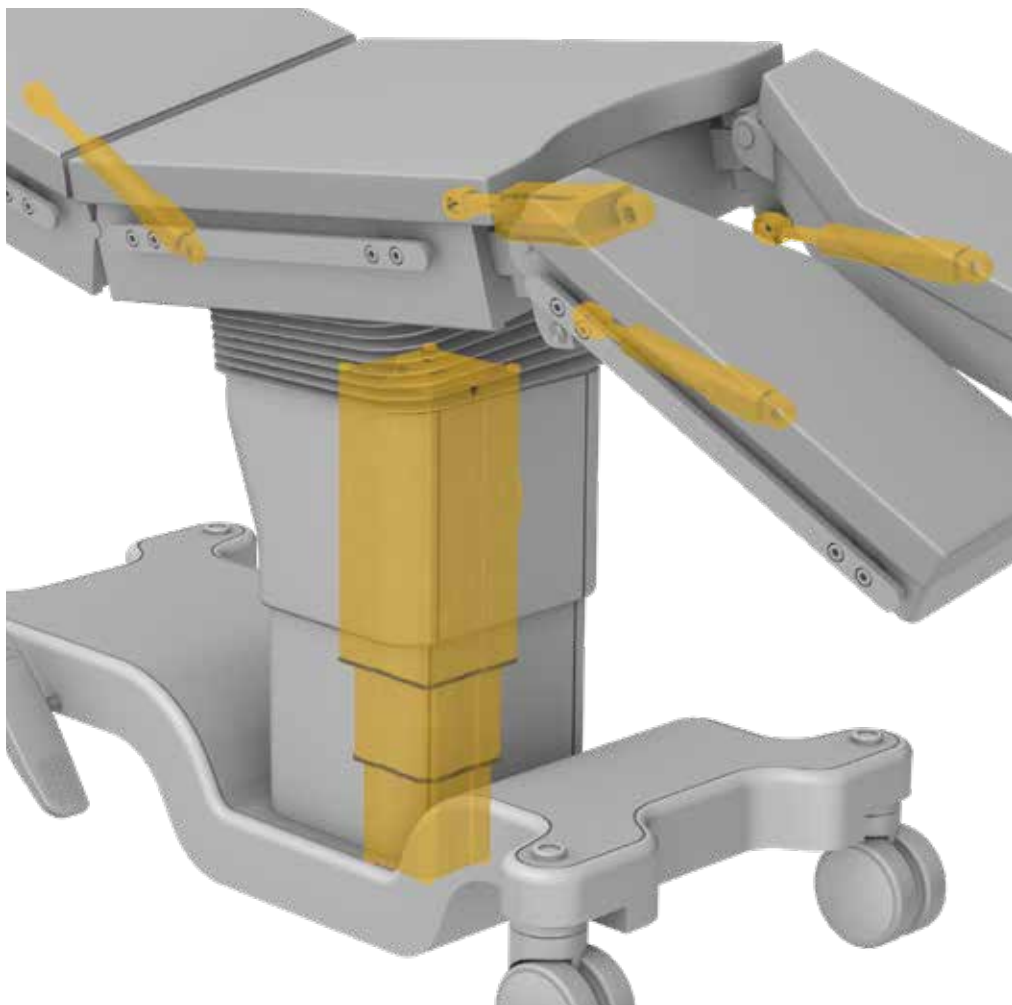
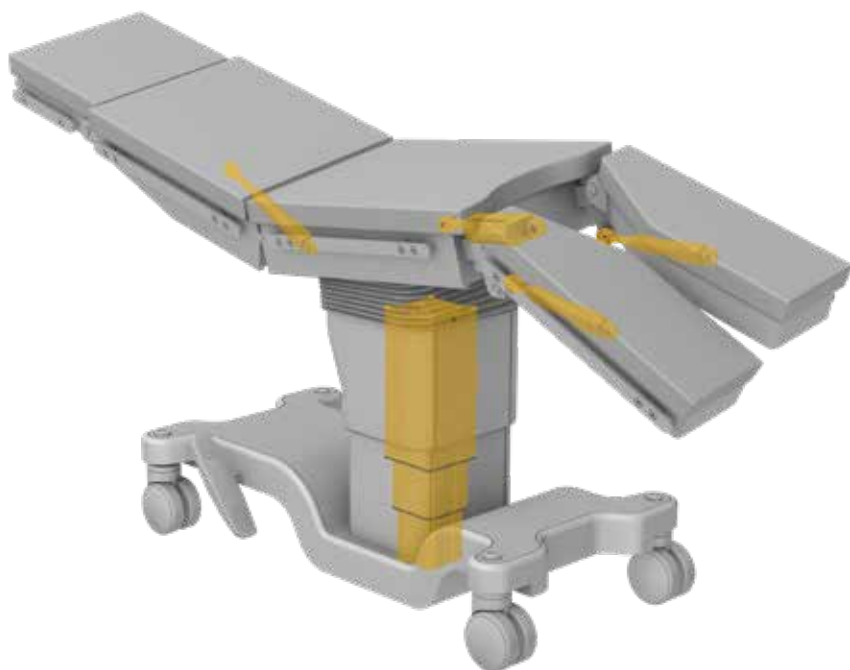


## Medical surgical chair/table

Surgical tables or procedure chairs are used in a wide range of medical applications, either in the operating room or in smaller clinics. To optimally position a patient for different procedures, multiple actuators are installed.

Ewellix is able to provide a complete UL certified mechatronic system including actuators, columns and control units, to meet customer requirements for functionality and safety. Ewellix columns offer a strong single pedestal solution with low retracted height and high stroke options to meet market demands. Configurable medical controllers can be customized for each customer to exactly meet functional demands.

With an Ewellix system, the market challenges of increasing patient weight, lower entry height and faster patient throughput can be met.





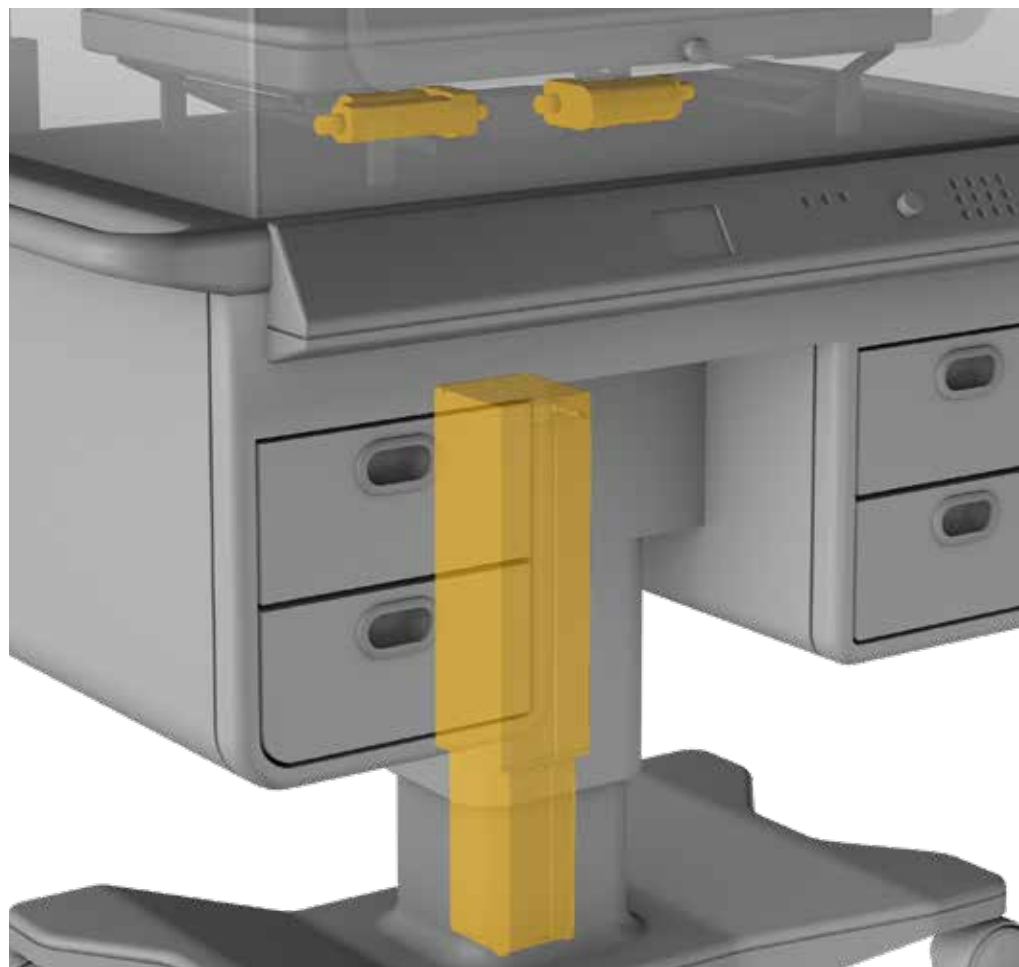
## Medical dental X-ray

Dental panoramic x-ray equipment is able to generate a detailed 2D/3D image of all teeth. Ewellix actuators and drive trains help our customers implement the height adjustment in this equipment. High speed, high stroke and a high level of safety are critical features of these actuators and a core strength of Ewellix. A modular set of screw and motors enable an optimal configuration to meet every customer's requirements.



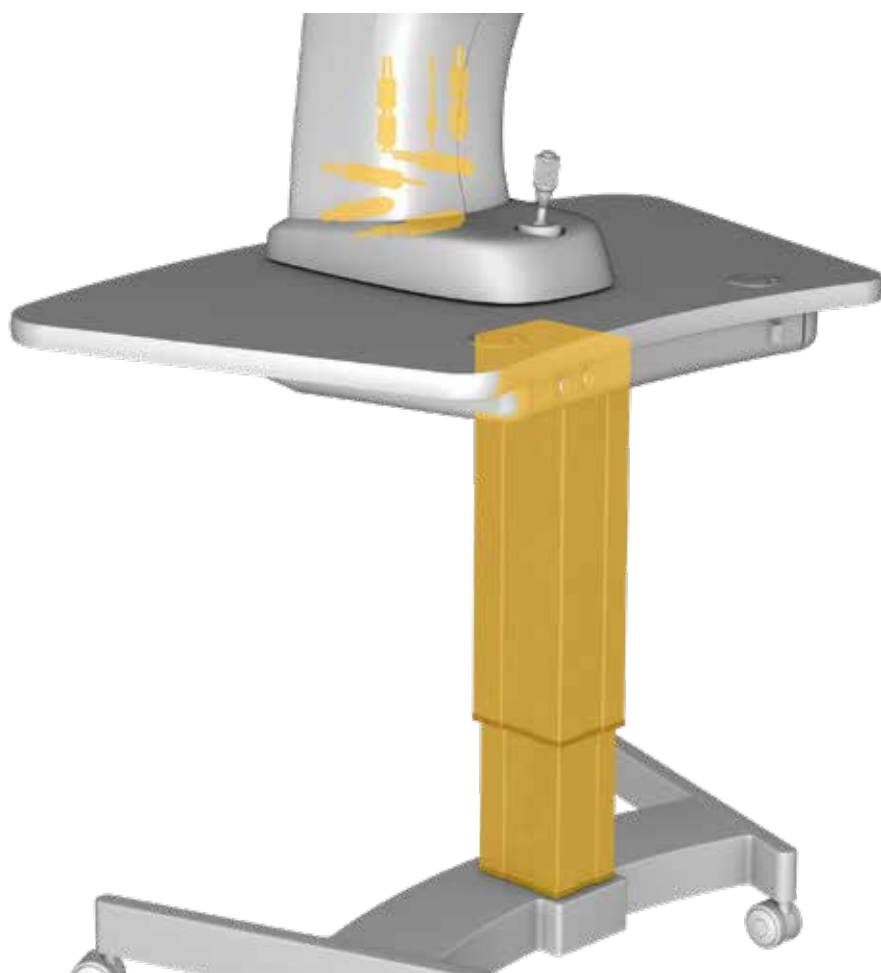
## Medical incubator

Modern designs of incubators reduce the stress for babies and minimize the numbers of transfers from incubators to beds. Incubators require columns with very smooth movement to help keep babies safe and comfortable. Thanks to its long experience with medical equipment, Ewellix has identified such needs and developed columns to fulfil the exact needs and requirements of baby care, such as soft start/stop, extremely quiet operation and virtually vibration free movement.



## Medical ophthalmic

Ophthalmic instrument tables are used to lift the eye care instruments and measurement devices. All of these instruments and devices are placed on a small table plate and need to be adjusted in height to find the position when the doctor or nurse is doing the measurement on the patient sitting in front of the table. Ewellix columns offer all the needs of adjustable height functions like iteration or small movements to fine tune the position to help for better accessibility and comfort of the operators and patients.



## Adjustable industrial workstation

Incorporating Ewellix columns into your workstation will help create ergonomically appropriate work patterns and ultimately result in satisfied users and increased productivity. Our lifting columns offer the flexibility and reliability required to create a completely ergonomic workplace in a variety of industrial environments.



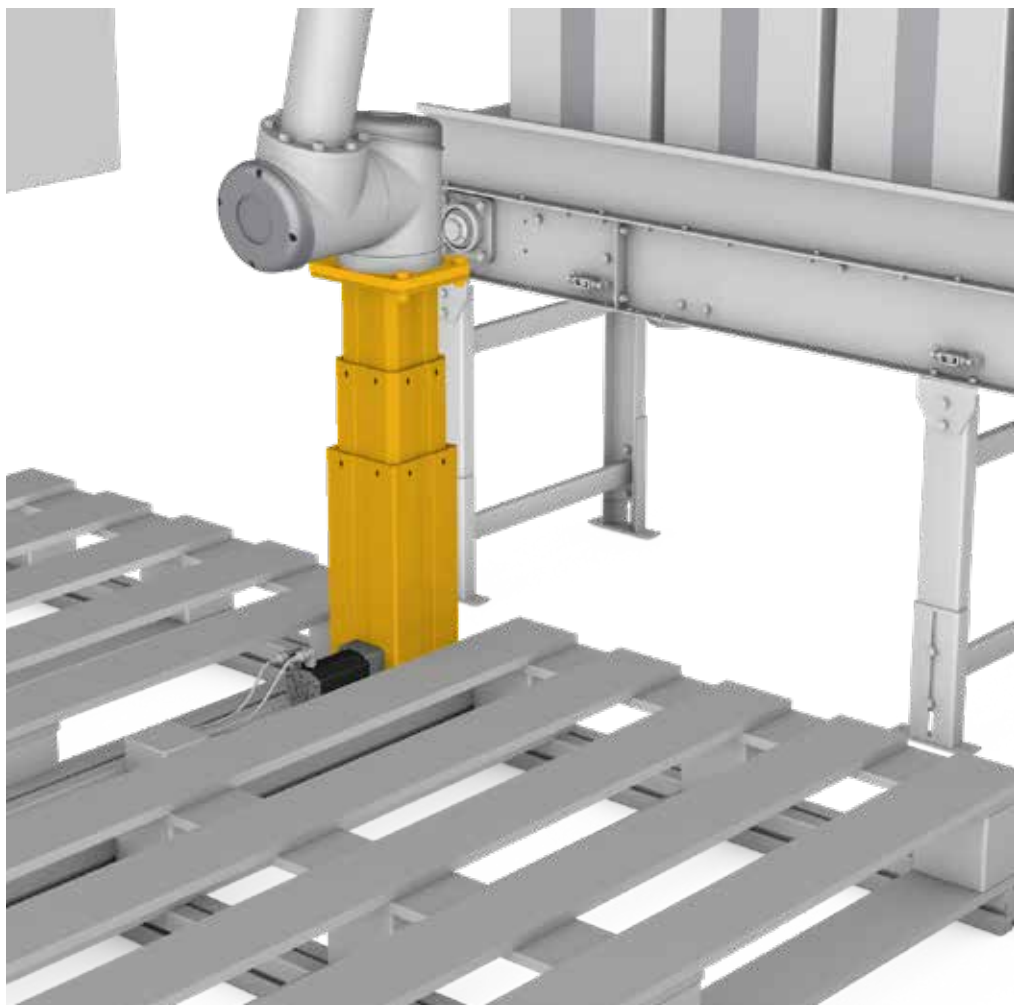
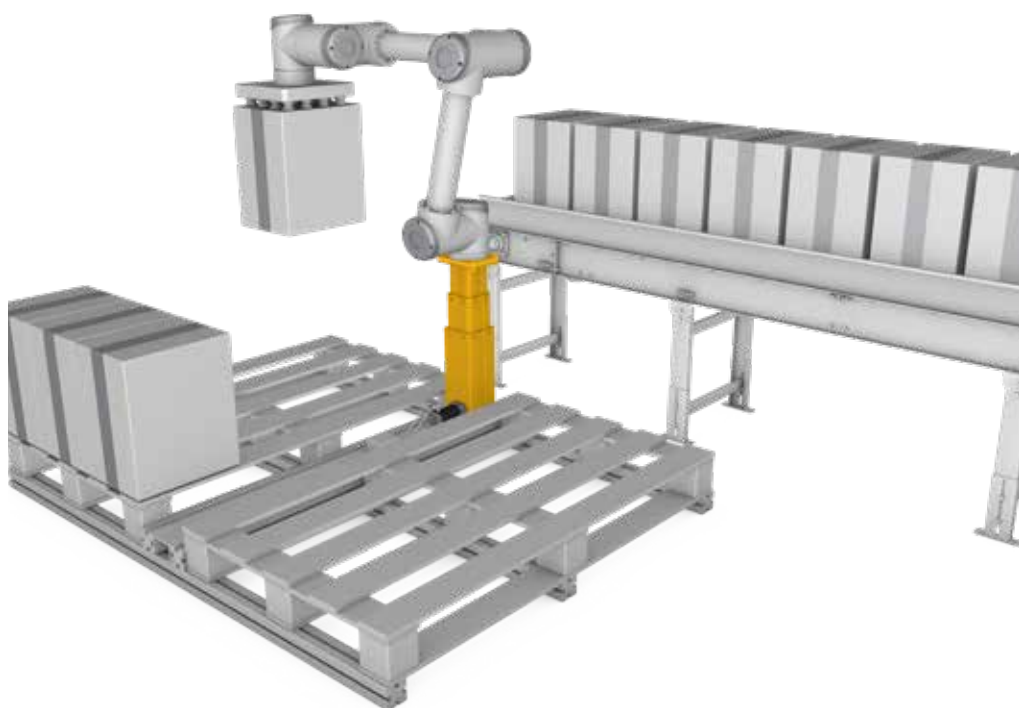
## Industrial automation production machines

Electromechanical linear actuator can replace pneumatic or hydraulic cylinder to provide control positioning of the door or hood used time to time thanks to the positioning feed-back that secure the movement. It is also easy to operate by PLC or switches.



## Factory automation

Competitiveness in factory automation entails a permanent productivity improvement process. In the search for more efficient and ergonomic solutions, many manufacturers have successfully used actuators in many working machinery. The automated movement for hoods and covers helps to reduce production downtime and lessen the workload for operators. In addition, quick lifting of heavy machine parts is helping to increase the speed of the machine maintenance. A lifting system will provide an easy access to component of the machine during maintenance operation like cleaning or repair.

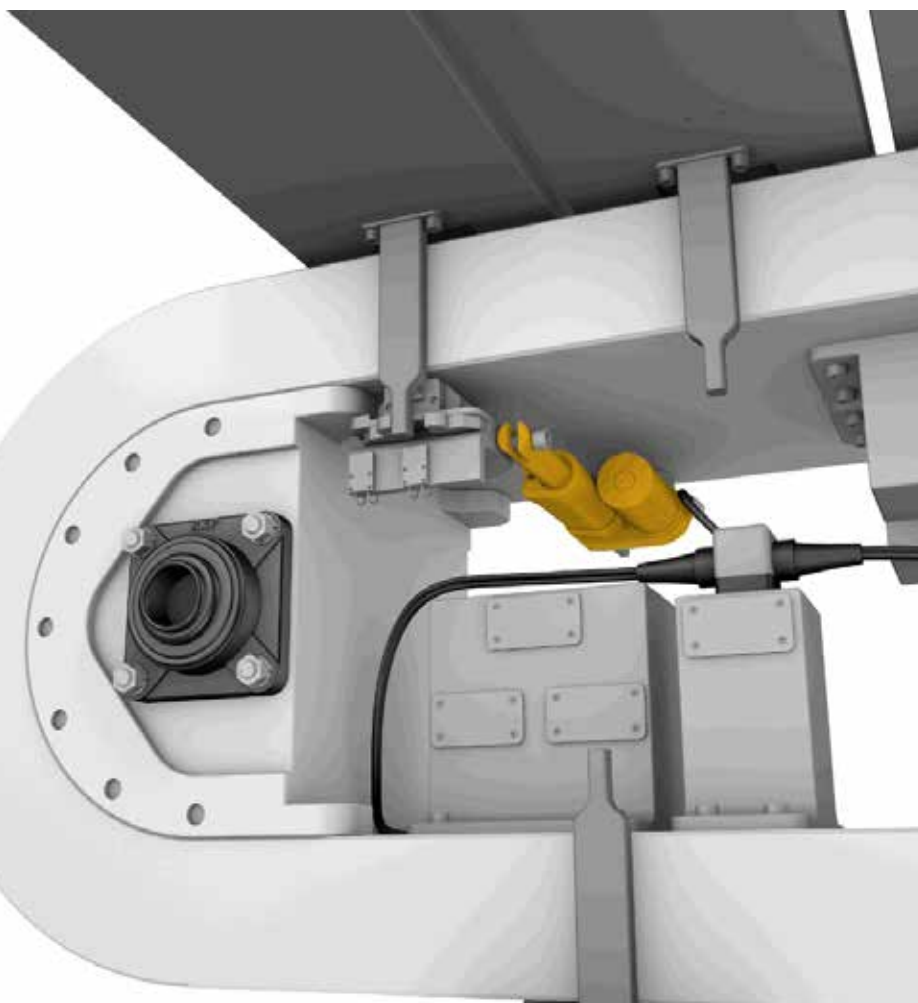


## Automation conveyor system

Conveyor lines are heavily used across different industries and applications. The different automatized movements are usually achieved by pneumatic cylinders. The need of increasing energy efficiency and simplifying the system has lead to a usage of electro-mechanical actuators over the conveyor line.

For a stop-pallet function, CAHB-10 actuators have been successfully used to replace standard pneumatic cylinder, thanks to their compact dimension and easy controllability.

By using electro-mechanical actuators, it has been possible to have a fully electric line, getting rid of the whole pneumatic system (cylinders, hoses, valves...).

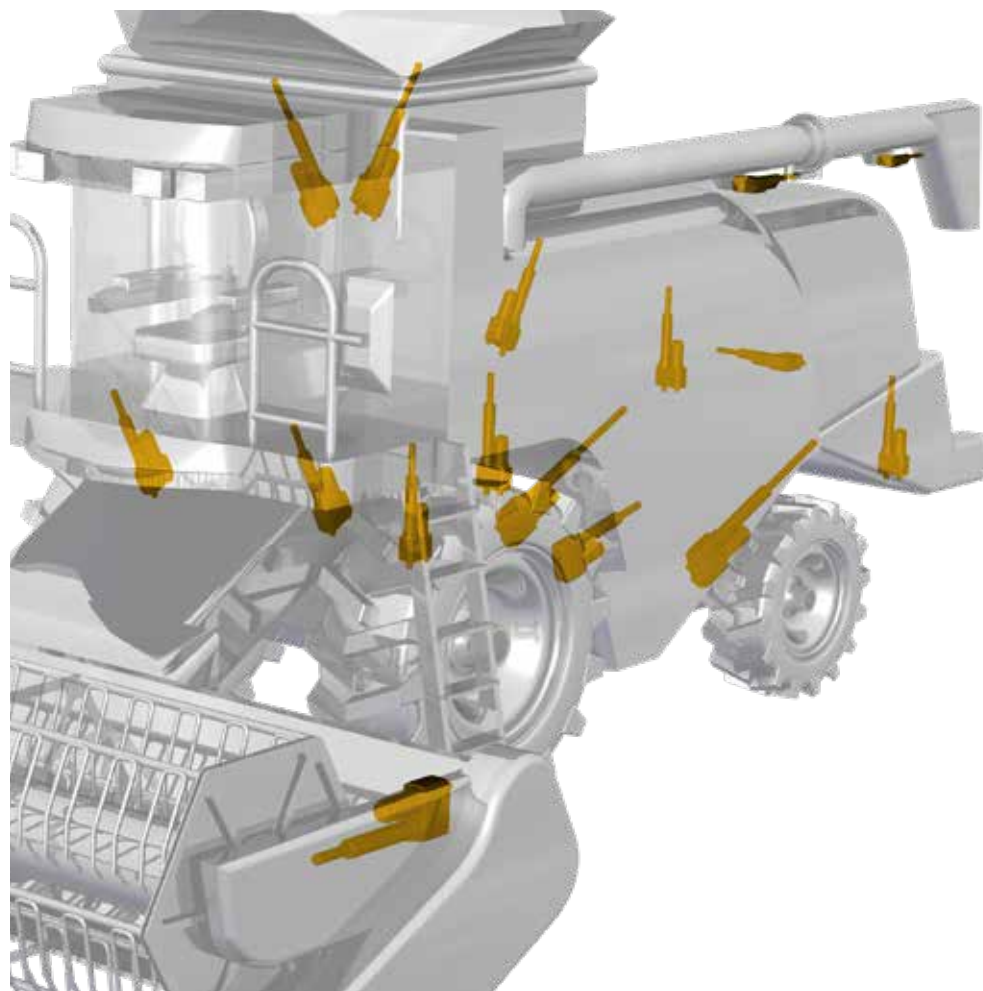
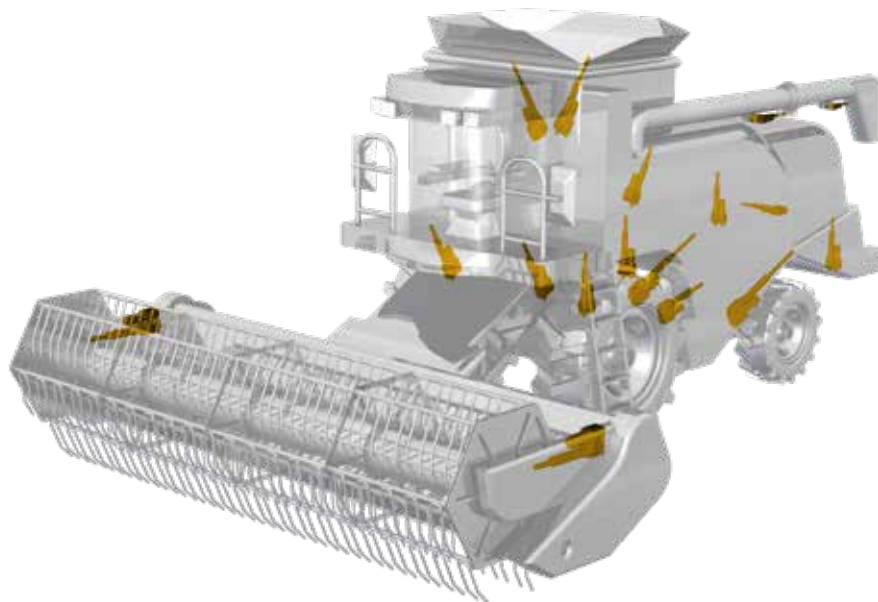




## Agriculture equipment

### Harvester combine

Today's farmers are challenged by the demands on cutting costs while increasing the crop yield. Modern harvester combines use many linear actuators to adjust on demand different equipment like sieve or concave clearance that help to minimize lost crops, thus resulting in the best crop yield. The position signal from the actuator ensures that the position is reached. At the appropriate adjustment, any shock or vibration should move the position of the actuator thanks to the high push and pull force and the high holding force of the linear actuator. To avoid pollution by oil leakage or missin a cleaning process, request the best class of Ingress protection IP69K/66M with a vent.

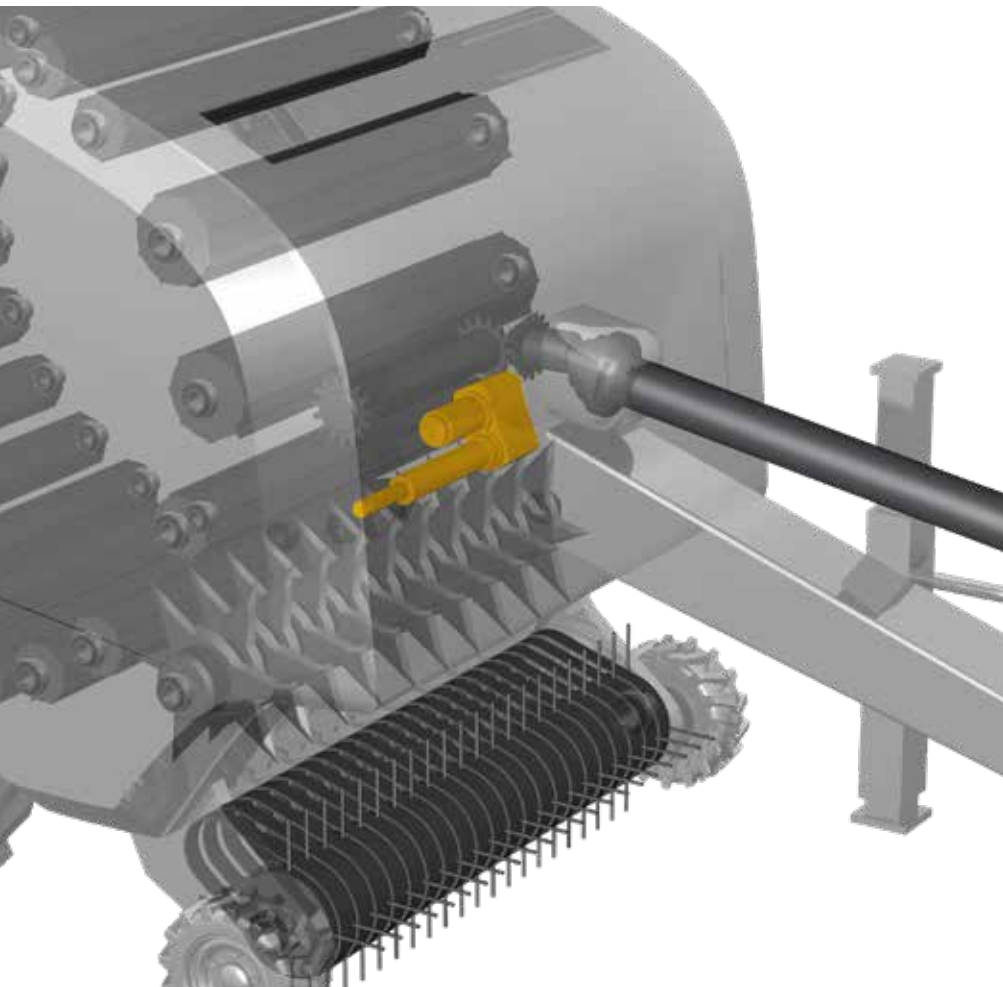
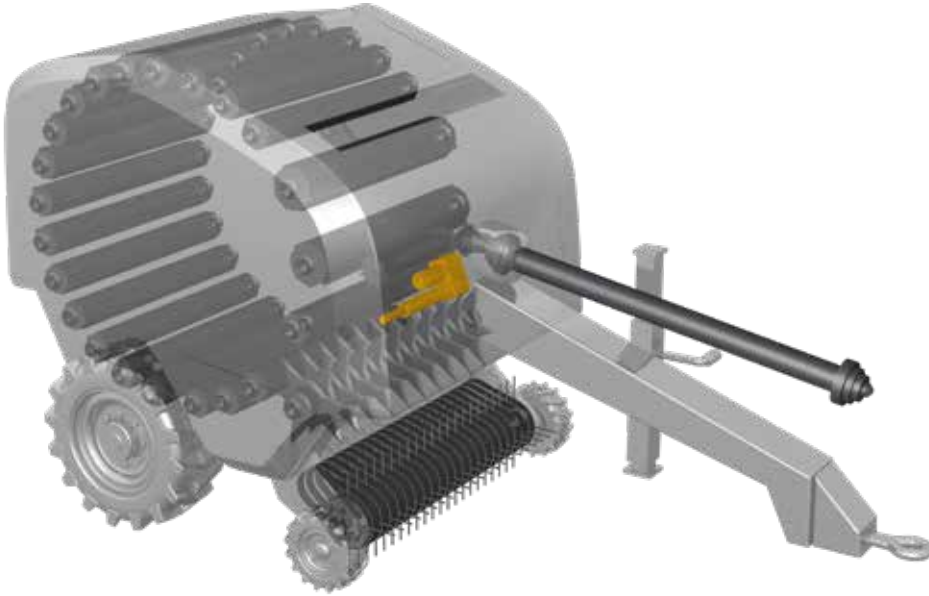




## Round baler

Today's farmers are challenged by the demands to cut costs while increasing productivity. The wrapping process of rounded bales needs an accurate movement to position and cut the net or the twine.

1



## Trucks

Today's freight companies are challenged by the demands on cutting fuel consumption and better productivity. The truck manufacturers develop innovative devices to optimize air circulation while driving, with or without a trailer. The linear actuator, with or without a motor, provides a quick, safe and precise adjustment of the roof air deflector.



## Special vehicles Sweeper

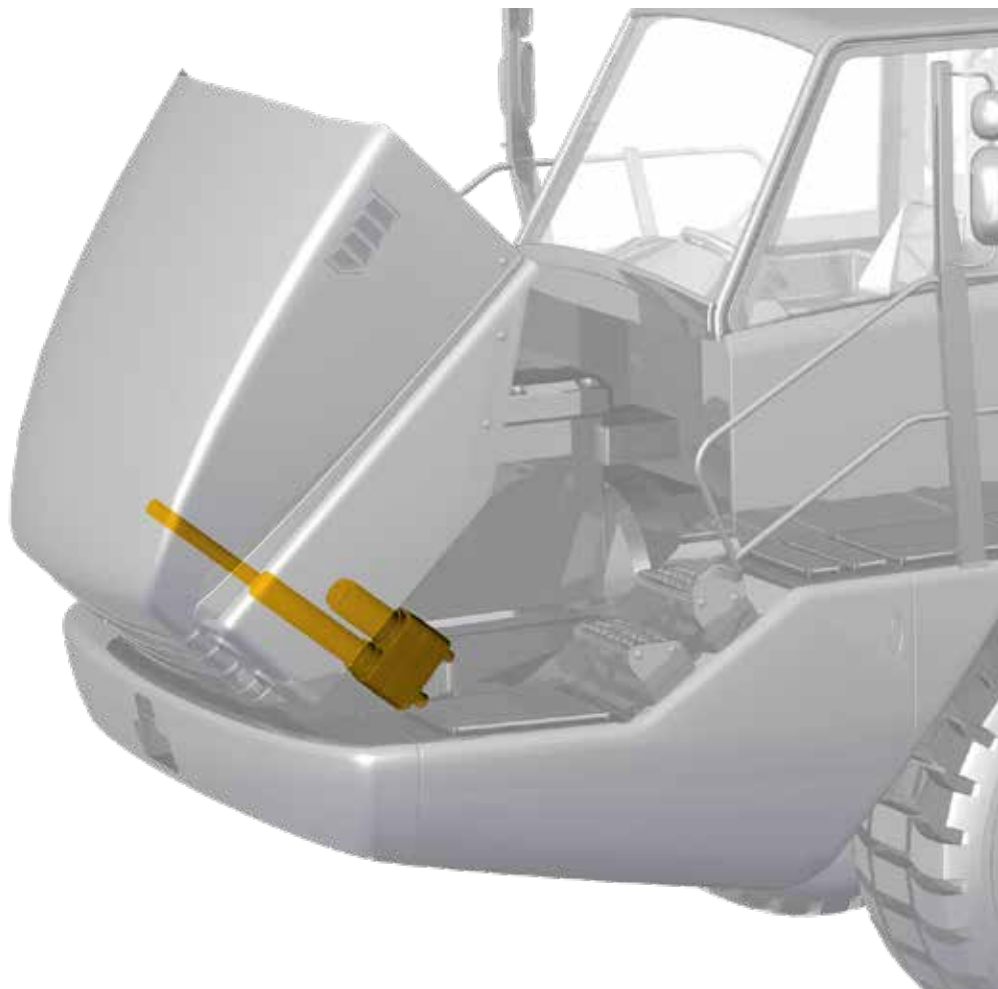
1

To improve the productivity and increase the comfort and safety of the worker, the electro mechanical linear electrical systems are used on many applications such as warning sign lifter on a vehicle or brush adjustment in the sweeper. Quick and easy to control, the linear actuators are also reliability with an ingress protection IP69K/66M and a vent.



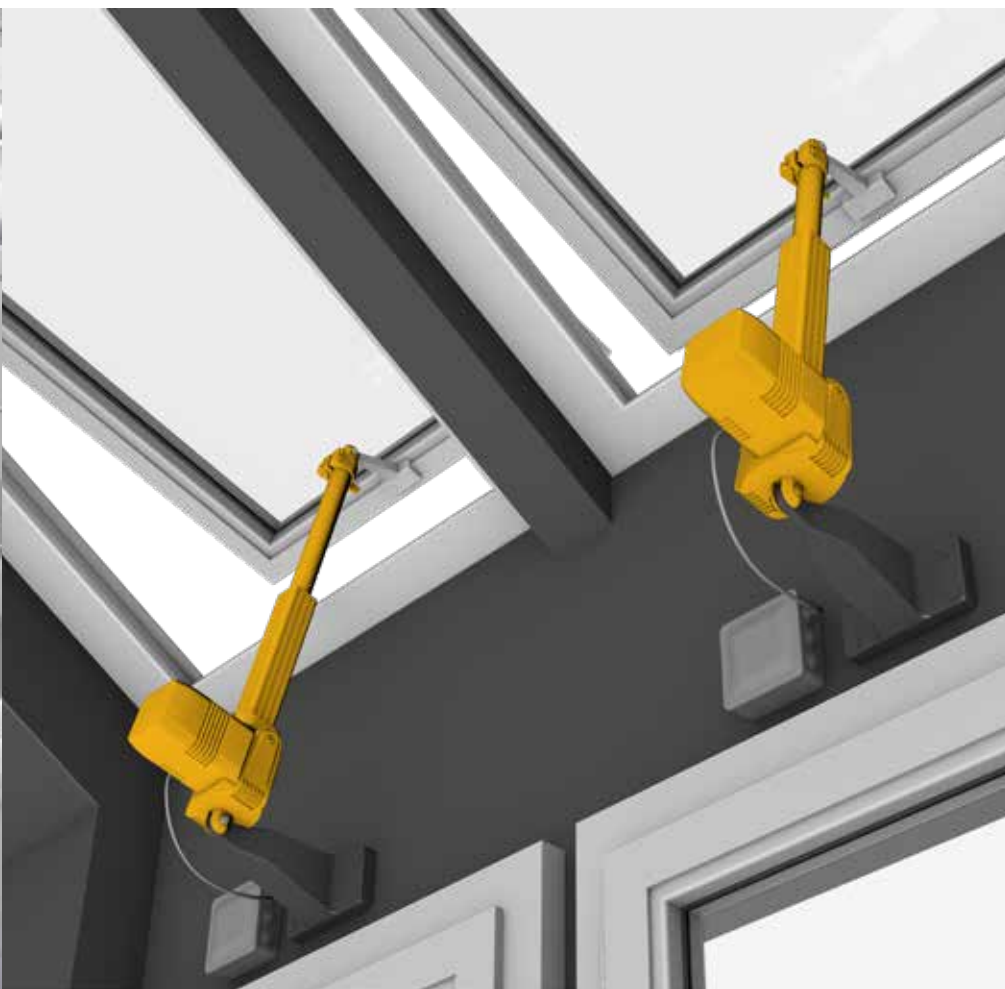
## Construction equipment

Today's construction companies are challenged by the demands on cutting fuel consumption and providing better productivity. Products such as Articulated Dump Trucks, wheel loaders or rollers, the engines are more sophisticated to comply with the CO<sub>2</sub> emission regulations and the engine hood are bigger and heavier due to the cooling system. The maintenance operation requires the engine hood be lifted. The operator needs a fast and safe operation. The linear actuator can quickly lift the engine hood but also keep it open thanks to the high push force and the high holding force that keep the hood at a stable position even if there is shock or wind.



## Building automation

Modern commercial, administrative and industrial buildings, as well as schools and care centers are often fitted with a variety of small electronic appliances which can perform important functions remotely and simply. Actuators for light domes, doors, windows and smoke and heat outlet systems are installed in many modern buildings. These actuators open and close traditional and tilting windows, light domes, facade elements, sun blinds and smoke and heat outlet shutters, at the touch of a button or automatically, using climatic (wind/rain) sensors and temperature and smoke sensors.

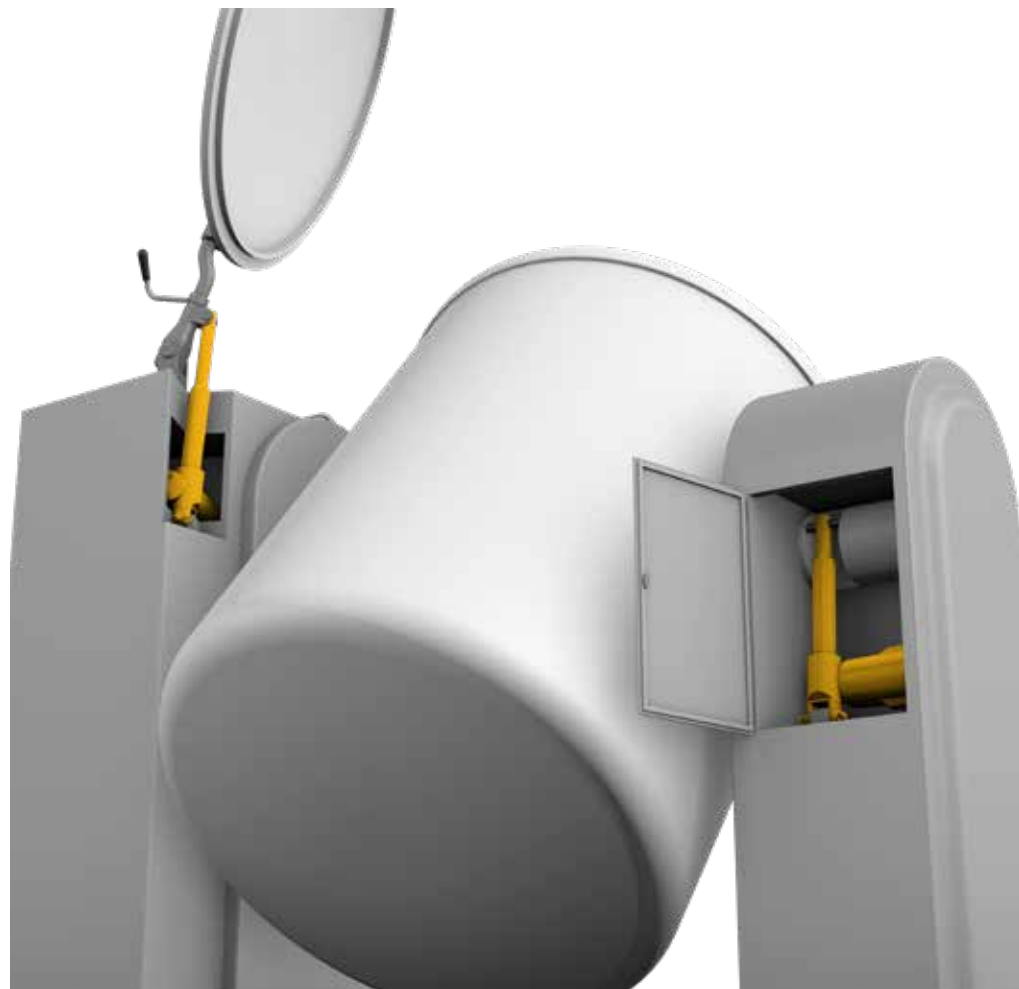




## Food and beverage Commercial kitchen equipment

### Kettles

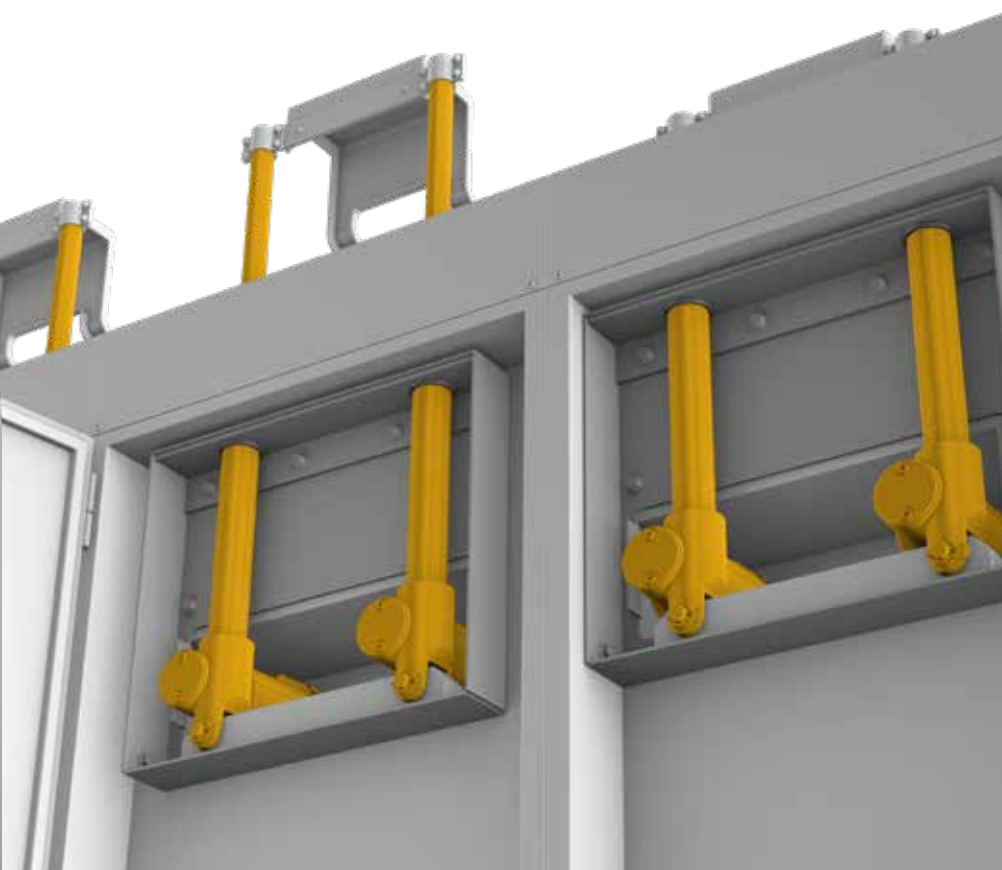
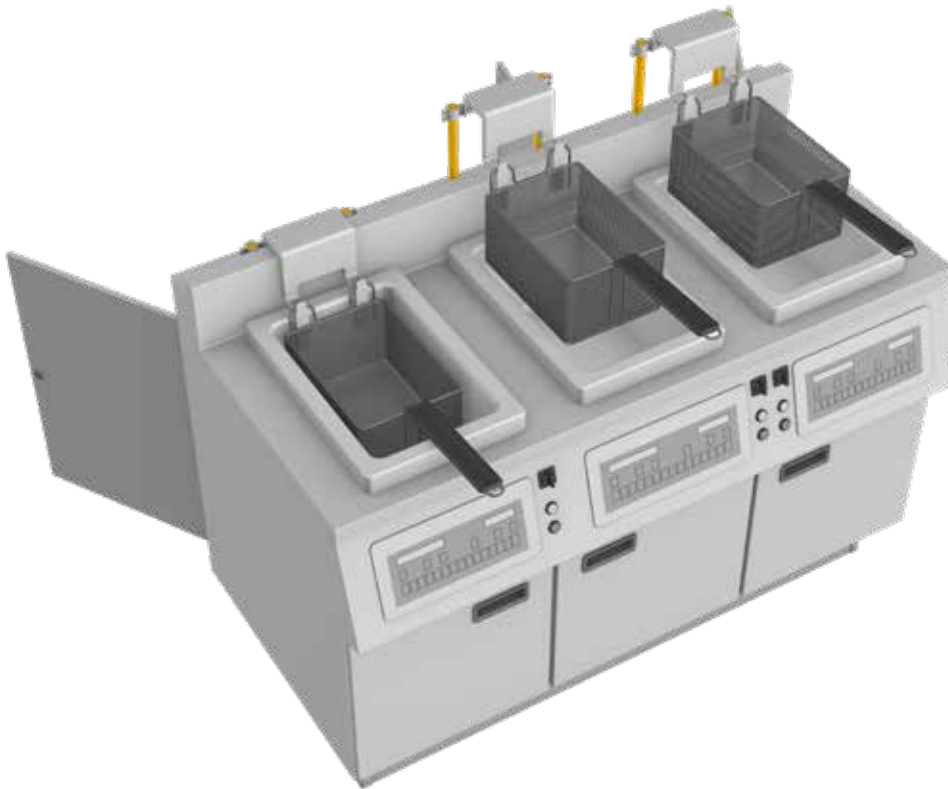
Machine flexibility, process control and cost efficiency are important in modern industrial kitchens. High end food processing equipment requires automated, repetitive and sometimes difficult operations. Whether it is raising or lowering an exhaust hood or a complete stove, actuators can enable people to work more comfortably and efficiently by adjusting the environment to their own personal needs.



## Fryer basket

Clam shell grill with electrical lifting are automatized with a linear actuator. The cooking of the steak is exactly as requested by the customer and the operator is more efficient. A customization of the motor could be proposed if a long life time is requested.

To ensure perfect French fries, the lifting of basket is automatized with a linear actuator. The operator appreciates also the simplicity and comfort and can focus on other preparation.



# 2

## Selection process

- Medical
- Harsh environment
- Automation



# Simplified selection process

By following the described flow (↳ **diagram 1**), the user can select the right solution based on linear actuator, lifting column and electronics that fulfill the application needs. If further assistance is needed, please contact Ewellix to get complete technical support (↳ **page 3**).

2

## AC version

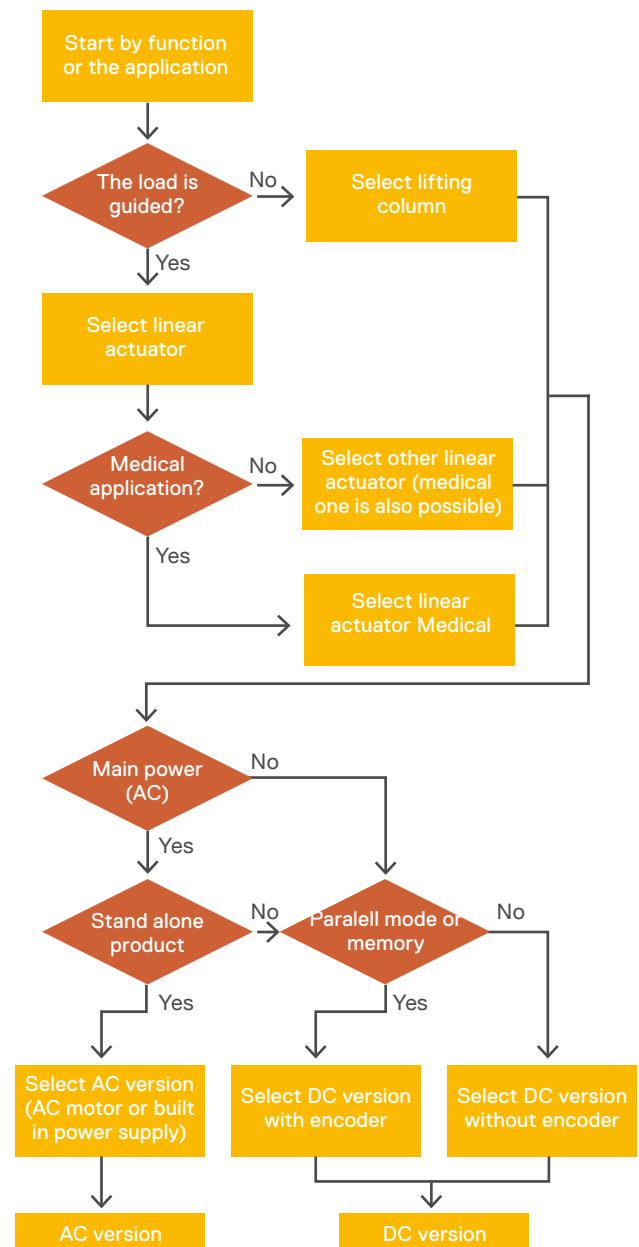
- Selection by load and direction, offset load if column, stroke, speed, IP, Self-locking/holding/static force dimension.
- Verify the environment and standard: IP, duty cycle, temperature, standard
- Select accessories if requested. Power cable or Power cord, connection plates, wires, inlet / outlet boxes
- Select the compatible operating device / switches per number of functions to control.

## DC version

- Selection by load and direction, offset load if column, stroke, speed, IP, Self-locking/holding/static force dimension.
- Verify the environment and standard: IP, duty cycle, temperature, standard
- Select the control unit: Channel per motor, output per channel, Sum output power (see compatibility Matrix), accessories
- Select the compatible operating device / switches per number of functions to control.

See **pages 52 and 53** for more information.

Diagram 1



## Selection by load and direction, off set load if column, stroke, speed, Self-locking/holding/static force, dimensions

- Rated load should match with the maximum force applied to the actuator by the application during the movement. Consider the “worst case scenario” and also the direction; push is the extension and pull is the retraction direction.
- For Column, it is the load and offset load / distance that should be considered.
- The static load should match with the force applied on the actuator by the application when the actuator is static. Consider the dynamic effect of vibration or chock on the application.
- The stroke length of the actuator including the tolerance should match with the travel distance of the application. In case of limit switches option, the extra stroke length to reach the mechanical end stop of the actuator could be considered for added safety.
- The speed should match with the expected running time. Consider that the speed will change depending on the load but also depending on the voltage fluctuation in case of a DC motor, except for a Switch Mode Power Supply.
- For some products, you could select the attachment dimension and retracted length. Consider the tolerance.

## Verify the environment and standard: IP, duty cycle, temperature, standard

- Each product should have an Environmental and standard specification that should match the environment of the application.
- Ingress Protection.
- Ambient Temperature during working condition, storage condition.
- Duty cycle % or “**Time ON / Time OFF**” are specified.
- The longest running time should not exceed the **Time ON** specified.
- The shortest rest time should be longer than the running time multiplied by the “**Time ON / Time OFF**” specified, or running time multiplied by (1- Duty cycle specified) and divided by duty cycle.

Formula:

$$\text{Rest time} > \frac{\text{Running time} \times \text{Time ON}}{\text{Time OFF}}$$

or

$$\text{Rest time} > \frac{\text{Running time} \times (1 - \text{Duty Cycle}\%)}{\text{Duty Cycle}\%}$$

Example:

Time ON / Time OFF = 85 s / 340 s or Duty Cycle 20%;  
the Running time must be less than 85 seconds.  
If the running time is 30 seconds, the Rest Time should be more than

$$\frac{30 \times 340}{85} = 120 \text{ seconds}$$

or

$$\text{Rest time} > \frac{30 \times (1 - 20\%)}{20\%}$$

so

$$\text{Rest time} > \frac{30 \times (1 - 0,2)}{0,2}$$

so at least 120 seconds

Some products are designed for a specific application but are suitable for others applications that request the similar performance.

### Select the Control Unit: Channel per motor, output per channel, Sum Output power (see compatibility Matrix)

- Select the control unit that is compatible with the actuator or column selected. Consider the sum of the number of channels requested by each product; some columns could request 2.
- Accessories can be selected: power cable or power cord, extra wires, Inlet and Outlet boxes, Connection plates.

### Select the compatible operating device / buttons per number of functions to control

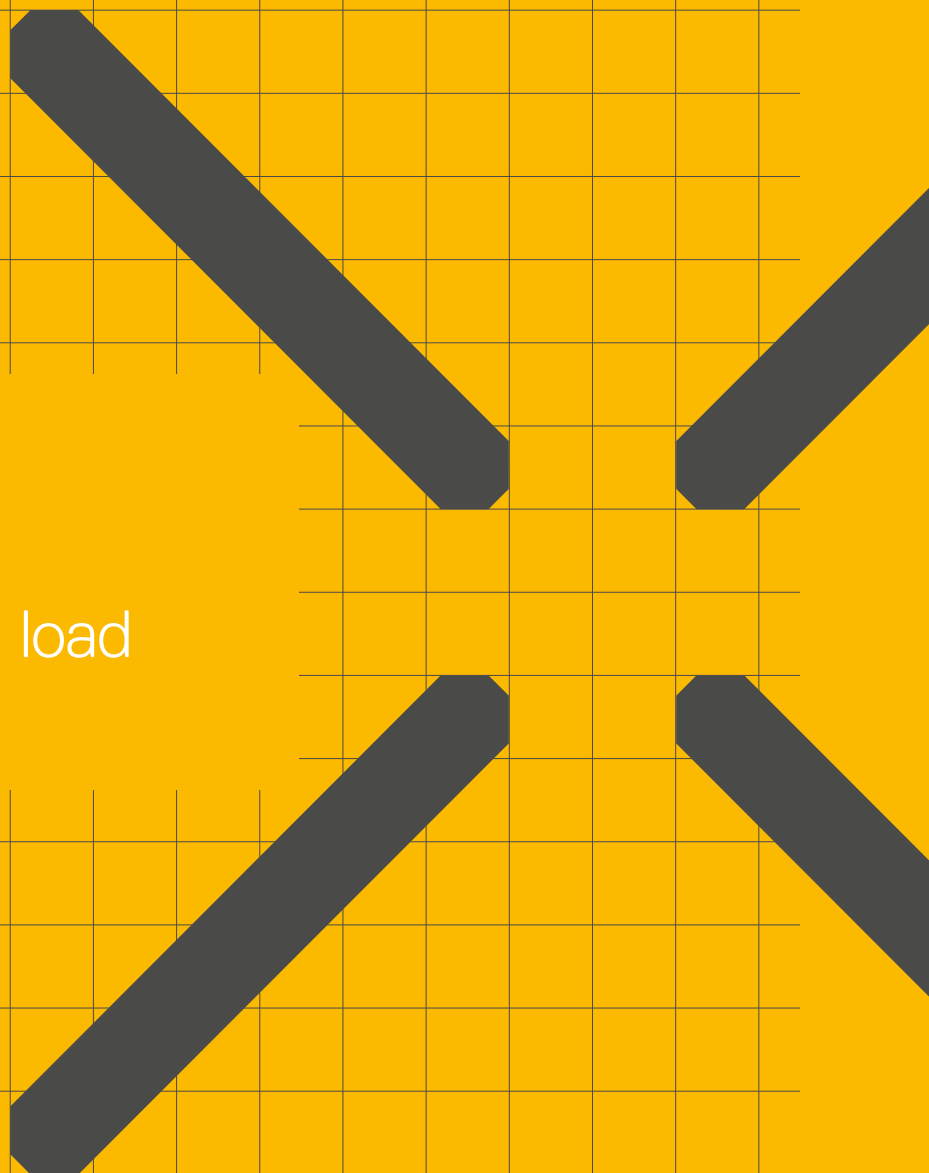
- Select the operating device that is compatible with the control unit.
- The type of switch must be selected: the switch can have different number of buttons according to the numbers of functions to drive (i.e. for only up and down function is necessary two buttons); number of buttons increase according to the number of actuators or columns to drive or if memory position or other functions are needed.



3

## Actuators

Up to 50 kN rated load



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# Matrix series

The Matrix series is designed for medical devices and includes powerful AC and DC linear actuators using DC motor.

They run very quietly, take up little space and can be installed at virtually every angle in vertical or horizontal position. The series is medical approved by third parties and available with options like anti-pitching, incremental position feedback and emergency lowering. The Matrix series can be supplied as a full system with controls, operating units and accessories.



## Features

- Designed for medical devices
- Full system with controls, operating units and accessories
- Back up nut as standard
- Safety factor up to 4

## Benefits

- Synchronization possible
- Silent operation
- Compact and aesthetic
- Back-up nut as standard

# Matrix1

## Linear actuator

### Benefits

- Silent operation
- Full system with control unit, switch and accessories
- Synchronization possible
- Compact and aesthetic
- Back-up nut as standard



### Technical data

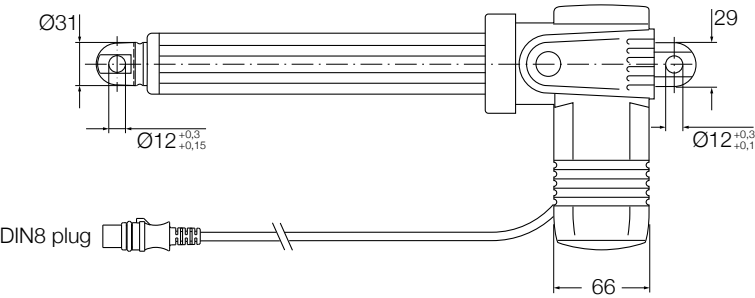
	Unit	MAX1..A..	MAX1..B..	MAX1..C..
Rated push load	N	4 000	2 000	1 500
Rated pull load	N	4 000	2 000	1 500
Speed (full load to no load)	mm/s	5 to 7	6 to 9	13 to 18
Stroke	mm	50 to 700	50 to 700	50 to 700
Retracted length	mm	S + 195/260 <sup>1)</sup>	S + 195/260 <sup>1)</sup>	S + 195/260 <sup>1)</sup>
Voltage	V DC	24	24	24
Power consumption	W	120	120	120
Current consumption	A	5	5	5
Duty cycle	%	10 (1/9)	10 (1/9)	10 (1/9)
Ambient temperature	°C	0 to +40	0 to +40	0 to +40
Degree of protection	IP	66S	66S	66S
Weight (at 200 mm stroke)	kg	4	3,7	3,6
Color	–	Grey	Grey	Grey

<sup>1)</sup> S < 350 mm, L = 195 + S  
S > 350 mm, L = 260 + S

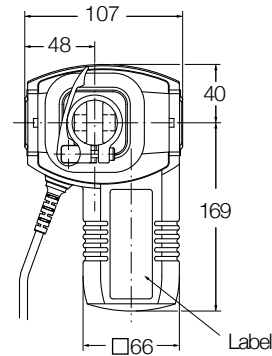


Dimensional drawing

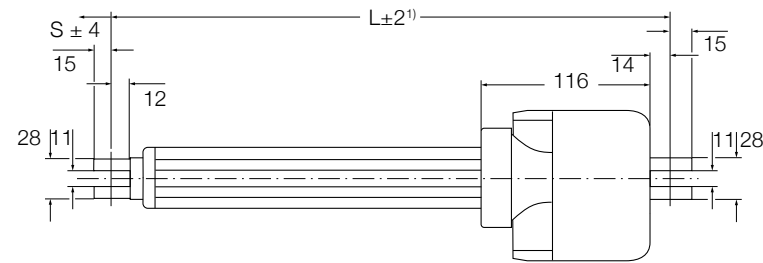
Side view



Front view

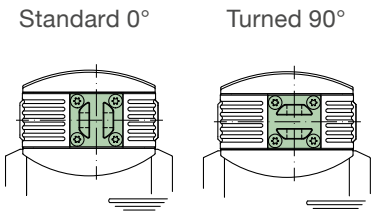


Top view

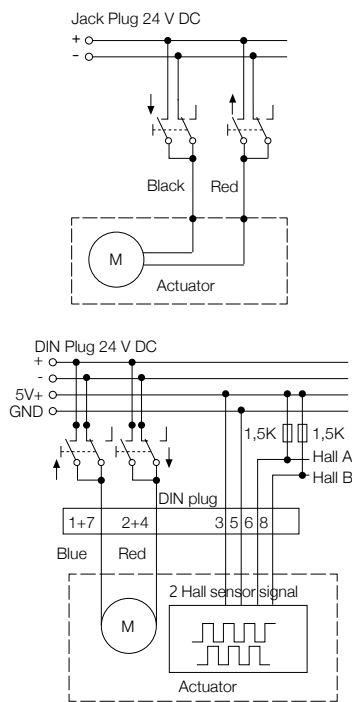


¹) S < 350 mm; L = 195 + S  
S > 350 mm; L = 260 + S

Rear view



Connecting diagrams



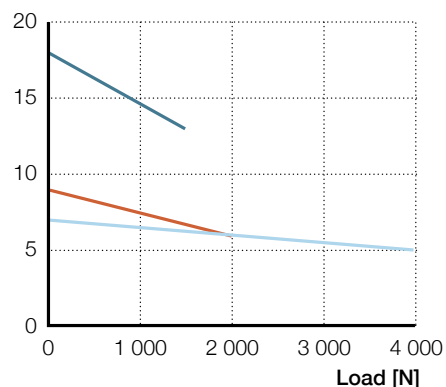
Suitable control units and accessories

	Control units			
	SCU	VCU	BCU	MCU
MAX 1	•	•	•	•
Operating switches				
EHA 1	Hand switch			•
EHA 3	Hand switch			
STJ	Foot switch	•	•	
STF	Foot switch	•	•	
STE	Desk switch	•	•	
STA				•
Hand switch      Foot switch      Desk switch				

## Performance diagrams

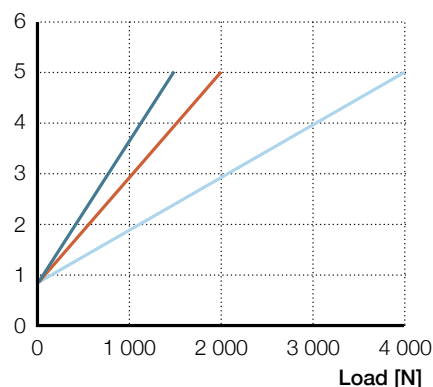
Speed-load diagram

Speed [mm/s]



Current-load diagram

Current consumption [A]



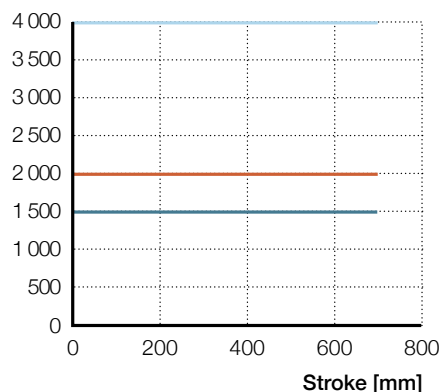
— Rated push force 1 500

— Rated push force 2 000

— Rated push force 4 000

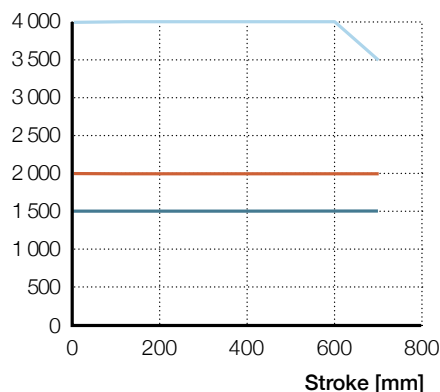
## Safety factor load conditions

Load [N]



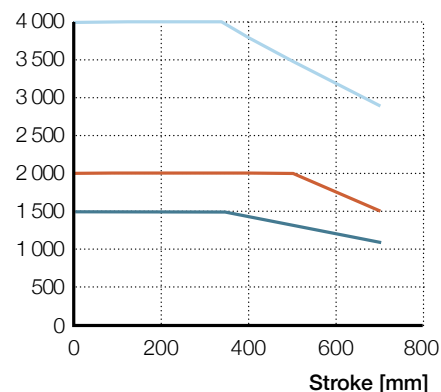
Push load reduction static  
Safety factor S=1

Load [N]



Push load reduction static  
Safety factor S=2

Load [N]



Push load reduction static  
Safety factor S=4 (EN60601)

— Rated push force 1 500

— Rated push force 2 000

— Rated push force 4 000

## Ordering key

		M	A	X	1		-							A						0	0	0
Type																						
Voltage																						
0	24 V DC																					
1	24 V DC with integrated current cut-off																					
Load																						
A	4 000 N																					
B	2 000 N																					
C	1 500 N																					
Stroke (S)																						
050 245	50 mm																					
100 295	100 mm																					
150 345	150 mm																					
200 395	200 mm																					
250 445	250 mm																					
300 495	300 mm																					
350 545	350 mm																					
400 660	400 mm																					
450 710	450 mm																					
500 760	500 mm																					
550 810	550 mm																					
600 860	600 mm																					
650 910	650 mm																					
700 960	700 mm																					
----- Other stroke lengths; 50<S<700 mm																						
Cable / Connecting plug																						
0 B	Coiled, 0,75 m (not stretched) / DIN8 plug																					
C 5	Straight, 2,5 m / DIN8 plug																					
0 A	Coiled, 0,75 m (not stretched) / Jack plug																					
2 5	Straight, 2,5 m / Jack plug																					
- -	Special cable length on request																					
Orientation of rear attachment																						
0	No fork head (customized option)																					
1	Standard (as drawing)																					
2	Turned 90°																					
Option 1																						
0	No option, only valid for actuator "A" (push and pull)																					
E	Quick-release +EKZm, push, fork head bore parallel to button (for actuator design "C" is L= +115 mm) <sup>1)</sup>																					
F	Quick-release +EKZm, push, fork head bore 90° to button (for actuator design "C" is L= +115 mm) <sup>1)</sup>																					
M	Push load, for actuator version "B" and "C"																					
N	Pull load, for actuator version "B" and "C"																					
Option 2																						
0	No option																					
F	2-Hall encoder, DIN8 plug																					
M	Lifetime monitoring																					
P	Lifetime monitoring, 2-Hall encoder, DIN8 plug																					
Option 3																						
0	No option																					
V	Emergency lowering, fork head bore parallel to clamping lever (for actuator design "A", L+30 mm)																					
W	Emergency lowering, fork head bore 90° to clamping lever (for actuator design "A", L+30 mm)																					
Customized																						

<sup>1)</sup> EKZm: mechanical anti-pinching min. stroke 150 mm up to 300 mm

■ Options shown in red are only available on request. Contact Ewellix for more information on minimum quantities and additional costs.

# Matrix3

## Linear actuator



### Benefits

- Silent operation
- Full system with control unit, switch and accessories
- Synchronization possible
- Compact and aesthetic
- Back-up nut as standard

### Technical data

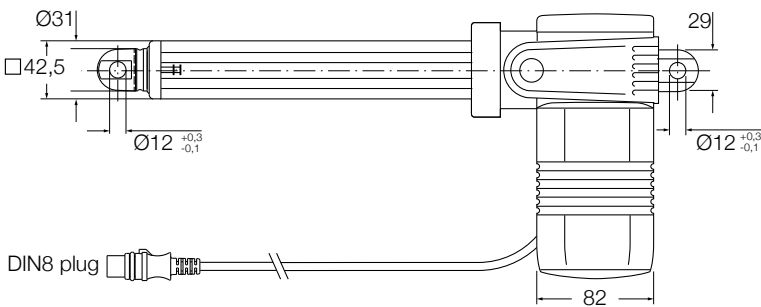
	Unit	MAX3..A..	MAX3..B..	MAX3..C..
Rated push load	N	8 000	4 000	3 000
Rated pull load	N	6 000 <sup>1)</sup>	4 000	3 000
Speed (full load to no load)	mm/s	5 to 7	6 to 9	13 to 18
Stroke	mm	50 to 700	50 to 700	50 to 700
Retracted length	mm	S + 215/280 <sup>2)</sup>	S + 215/280 <sup>2)</sup>	S + 215/280 <sup>2)</sup>
Voltage	V DC	12 or 24	12 or 24	12 or 24
Power consumption	W	120	120	120
Current consumption	A	5	5,2	5,2
Duty cycle	%	10 (1/9)	10 (1/9)	10 (1/9)
Ambient temperature	°C	0 to +40	0 to +40	0 to +40
Degree of protection	IP	66S	66S	66S
Weight (at 200 mm stroke)	kg	4,5	4,2	4
Color	–	Grey	Grey	Grey

<sup>1)</sup> Max load for medical application is 5 000 N

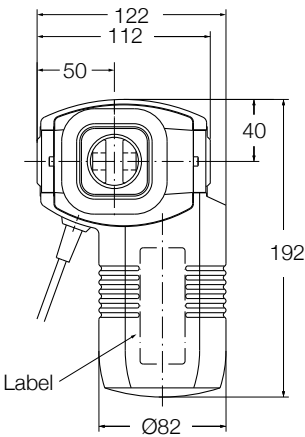
<sup>2)</sup> S ≤ 350 mm; L = S + 215  
S > 350 mm; L = S + 280

Dimensional drawing

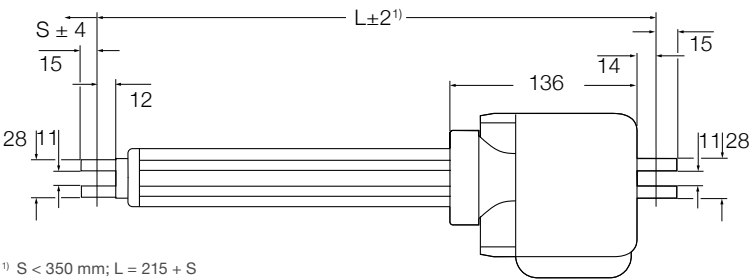
Side view



Front view

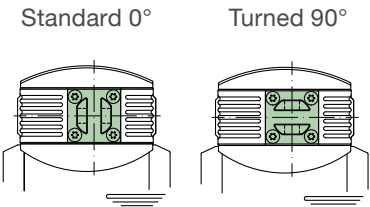


Top view

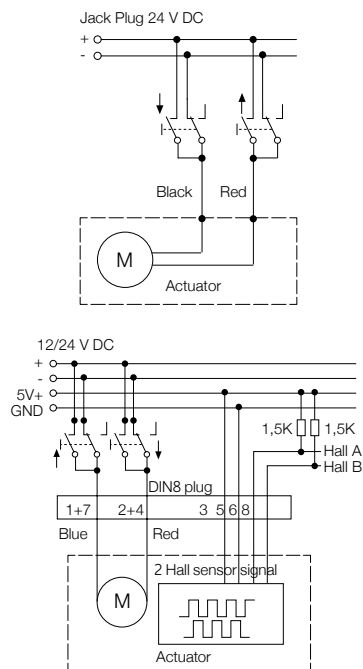


¹) S < 350 mm; L = 215 + S  
S > 350 mm; L = 280 + S

Rear view



Connecting diagrams



Suitable control units and accessories

	Control units			
	SCU	VCU	BCU	MCU
MAX 3	•	•	•	•
Operating switches				
EHA 1	•	•	•	•
EHA 3	•	•	•	•
STJ	•	•	•	•
STF	•	•	•	•
STE	•	•	•	•
STA	•	•	•	•

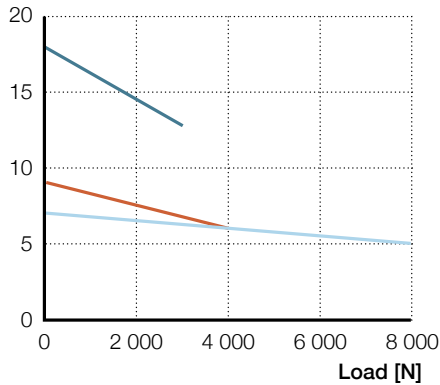
• Hand switch • Foot switch • Desk switch

¹) Only valid for MAX 31. MAX 30 must be operated by a BCU, MCU, SCU or VCU control unit.

## Performance diagrams

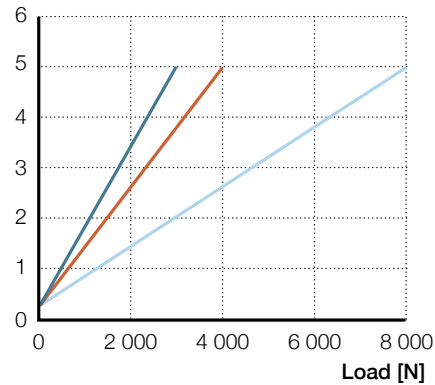
Speed-load diagram

Speed [mm/s]



Current-load diagram

Current consumption [A]



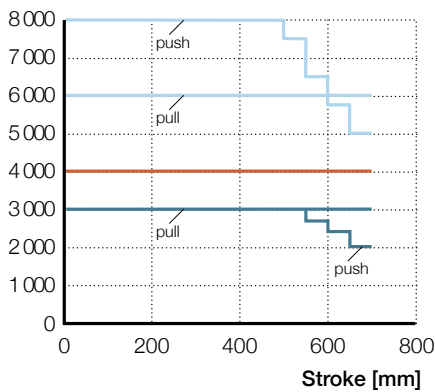
— Rated push force 3 000

— Rated push force 4 000

— Rated push force 8 000

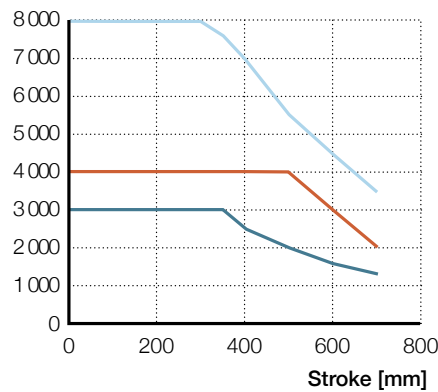
## Safety factor load conditions

Load [N]



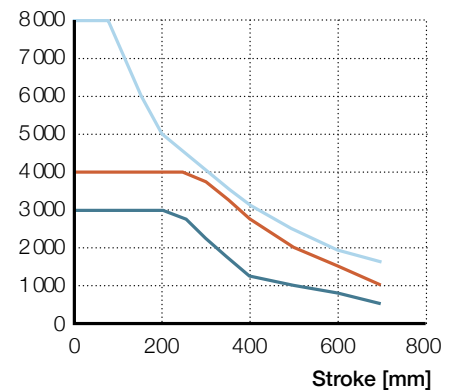
Push load reduction static  
Safety factor S=1

Load [N]



Push load reduction static  
Safety factor S=2

Load [N]



Push load reduction static  
Safety factor S=4 (EN60601)

— Rated push force 3 000

— Rated push force 4 000

— Rated push force 8 000

## Ordering key

Type		Voltage		Load		Stroke (S)		Cable / Connecting plug		Orientation of rear attachment		Option 1		Option 2		Option 3		Customized	
M A X 3		0 1 2		A B C		050 265 100 315 150 365 200 415 250 465 300 515 350 565 400 680 450 730 500 780 550 830 600 880 650 930 700 980		0 B C 0 A 2 5 - -		0 1 2		0 E F K L M N		0 F M P		0 V W			
		24 V DC 24 V DC with integrated current cut-off 12 V DC		8 000 N 4 000 N 3 000 N		50 mm 100 mm 150 mm 200 mm 250 mm 300 mm 350 mm 400 mm 450 mm 500 mm 550 mm 600 mm 650 mm 700 mm		Coiled, 0,75 m (not stretched) / DIN8 plug Straight, 2,5 m / DIN8 plug Coiled, 0,75 m (not stretched) / Jack plug Straight, 2,5 m / Jack plug Special cable length on request		No fork head (customized option) Standard (as drawing) Turned 90°		No option, only valid for actuator "A" (push and pull) Quick-release +EKZm, push, fork head bore parallel to button (for actuator design "C" is L= +115 mm) <sup>1)</sup> Quick-release +EKZm, push, fork head bore 90° to button (for actuator design "C" is L= +115 mm) <sup>1)</sup> Electrical anti-pinching protection, motor direction pull Electrical anti-pinching protection, motor direction push Push load, for actuator version "B" and "C" Pull load, for actuator version "B" and "C"		No option 2-Hall encoder, DIN8 plug Lifetime monitoring Lifetime monitoring, 2-Hall encoder, DIN8 plug		No option Emergency lowering, fork head bore parallel to clamping lever (for actuator design "A", L+30 mm) Emergency lowering, fork head bore 90° to clamping lever (for actuator design "A", L+30 mm)			

<sup>1)</sup> EKZm: mechanical anti-pinching min. stroke 150 mm up to 300 mm

Options shown in red are only available on request. Contact Ewellix for more information on minimum quantities and additional costs.

# Matrix7

## Linear actuator



### Benefits

- Universal power supply
- Power indicator
- Plug and play with integrated control unit
- Designed for medical devices, compliant to IEC 60601-1

### Technical data

	Unit	MAX7..A..	MAX7..B..	MAX7..C..
Rated push load	N	8 000	4 000	3 000
Rated pull load	N	6 000 <sup>1)</sup>	4 000	3 000
Speed (full load to no load)	mm/s	6 to 7,5	8 to 10	13 to 18
Stroke	mm	50 to 700	50 to 700	50 to 700
Retracted length	mm	S + 215/280 <sup>2)</sup>	S + 215/280 <sup>2)</sup>	S + 215/280 <sup>2)</sup>
Voltage	V	100-240 AC 50/60 Hz	100-240 AC 50/60 Hz	100-240 AC 50/60 Hz
Power consumption	W	180	180	180
Current consumption	100 V AC	3,2	3,2	3,2
	240 V AC	1,6	1,6	1,6
Duty cycle	%	10 (1/9)	10 (1/9)	10 (1/9)
Ambient temperature	°C	0 to +40	0 to +40	0 to +40
Degree of protection	IP	66S	66S	66S
Weight (at 200 mm stroke)	kg	4,8	4,5	4,2
Color	–	Grey	Grey	Grey

<sup>1)</sup> Max load for medical application is 5 000 N

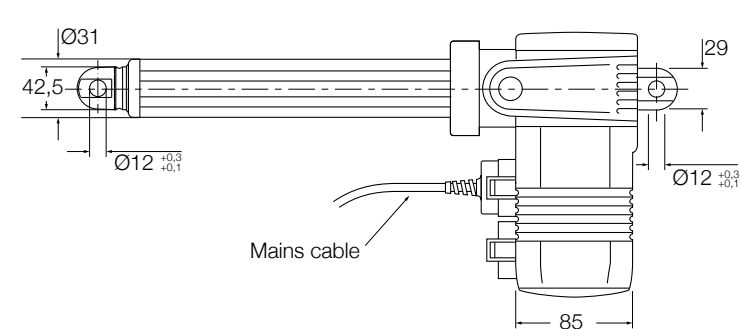
<sup>2)</sup> S < 350 mm; L = S + 215

S > 350 mm; L = S + 280

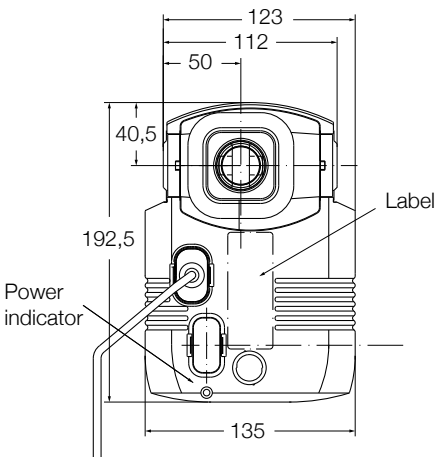


Dimensional drawing

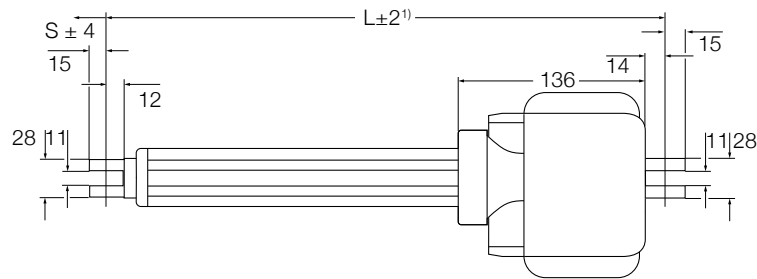
Side view



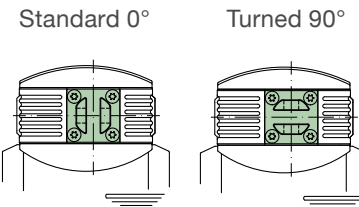
Front view



Top view

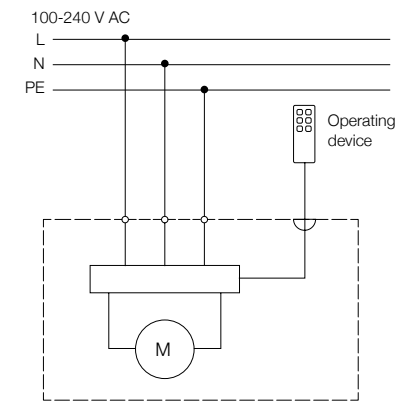


Rear view












¹) S < 350 mm; L = 215 + S  
S > 350 mm; L = 280 + S

Connecting diagrams



Suitable operating switches

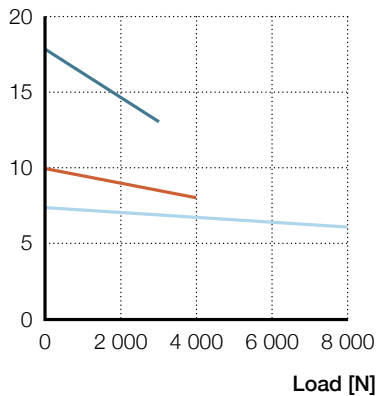
Operating switches						
	 EHA1	 PHC	 STF	 PFP	 STA	 PAM
MAX70						
MAX72/74						

 Hand switch     Foot switch     Desk switch

## Performance diagrams

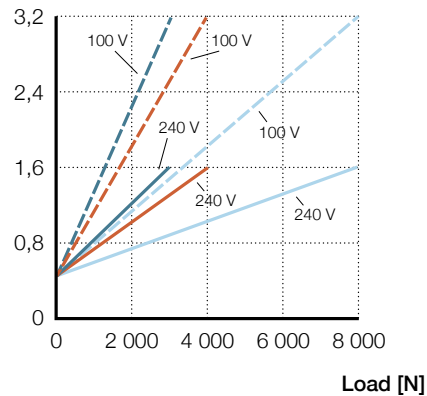
Speed-load diagram

Speed [mm/s]



Current-load diagram

Current consumption [A]



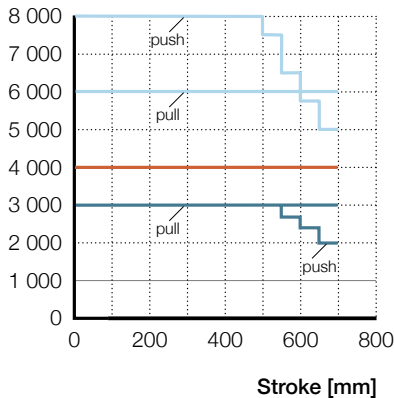
— Rated push force 3 000

— Rated push force 4 000

— Rated push force 8 000

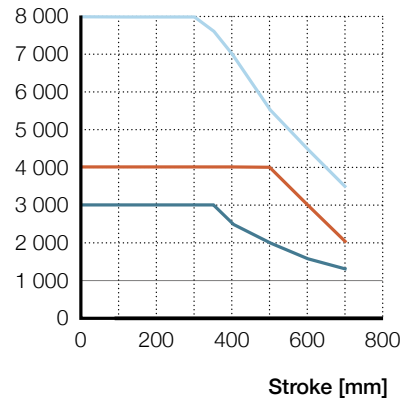
## Safety factor load conditions

Load [N]



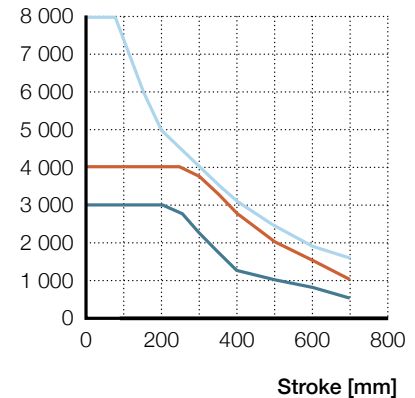
Push load reduction static  
Safety factor S=1

Load [N]



Push load reduction static  
Safety factor S=2

Load [N]



Push load reduction static  
Safety factor S=4 (EN60601)

— Rated push force 3 000

— Rated push force 4 000

— Rated push force 8 000

## Accessories

	Plug	Country	Designation	Order number
Straight cable 3,5 m	Schuko	DE	ZKA-140306-3500	0121723
Straight cable 3,5 m	SEV	CH	ZKA-140316-3500	0121737
Straight cable 3,5 m	UL	USA	ZKA-140355-3500	0121724
Straight cable 3,5 m	Hospital grade	USA	ZKA-140360-3500	0121732
Straight cable 3,5 m	British standard	UK	ZKA-140350-3500	0121743
Coiled cable 1,2 m / 2,2 m	Schuko	DE	ZKA-140342-1500	0121728
Coiled cable 1,2 m / 2,2 m	SEV	CH	ZKA-140378-1200	0121738
Straight polyurethane cable 3,5 m	Schuko	DE	ZKA-140422-3500	0121739
Straight polyurethane cable 3,5 m	SEV	CH	ZKA-140426-3500	0121740
Strain relief for mains cable			ZUB-952253	0102848
Tool for plugs (Jack/D-Sub/Mains)			ZWS-140375	0125322

## Ordering key

		M	A	X	7	-							A						0	0	0
Type																					
Voltage																					
0	100-240 V AC/50-60 Hz, integrated pneumatic control																				
2	100-240 V AC/50-60 Hz, integrated low voltage control with additional 24 V output																				
4	100-240 V AC/50-60 Hz, integrated low voltage control																				
Load																					
A	8 000 N																				
B	4 000 N																				
C	3 000 N																				
Stroke (S)																					
050 265	50 mm																				
100 315	100 mm																				
150 365	150 mm																				
200 415	200 mm																				
250 465	250 mm																				
300 515	300 mm																				
350 565	350 mm																				
400 680	400 mm																				
450 730	450 mm																				
500 780	500 mm																				
550 830	550 mm																				
600 880	600 mm																				
650 930	650 mm																				
700 980	700 mm																				
--- Other stroke lengths; 50<S<700 mm																					
Cable / Connecting plug																					
0	No cable																				
Orientation of rear attachment																					
0	No fork head (customized option)																				
1	Standard (as drawing)																				
2	Turned 90°																				
Option 1																					
0	No option, only valid for actuator "A" (push and pull)																				
E	Quick-release +EKZm, push, fork head bore parallel to button (for actuator design "C" is L= +115 mm) <sup>1)</sup>																				
F	Quick-release +EKZm, push, fork head bore 90° to button (for actuator design "C" is L= +115 mm) <sup>1)</sup>																				
K	Electrical anti-pinching protection, motor direction pull																				
L	Electrical anti-pinching protection, motor direction push																				
M	Push load, for actuator version "B" and "C"																				
N	Pull load, for actuator version "B" and "C"																				
Option 2																					
0	No option																				
Option 3																					
-	No option																				
V	Emergency lowering, fork head bore parallel to clamping lever (for actuator design "A", L+30 mm)																				
W	Emergency lowering, fork head bore 90° to clamping lever (for actuator design "A", L+30 mm)																				
Customized																					

<sup>1)</sup> EKZm: mechanical anti-pinching min. stroke 150 mm up to 300 mm

Options shown in red are only available on request. Contact Ewellix for more information on minimum quantities and additional costs.

# Runner

## Linear actuator



### Benefits

- High push/pull load
- Compact
- Back-up nut as standard
- High safety factor
- Silent operation

### Technical data

	Unit	RU20	RU21	RU22	RU23	RU24	RU25
Rated push load	N	8 000	10 000	12 000 <sup>1)</sup>	8 000	10 000	12 000 <sup>1)</sup>
Rated pull load	N	8 000	8 000	8 000	8 000	8 000	8 000
Speed (full load to no load)	mm/s	7 to 10	5 to 8	4 to 7	8 to 15	6 to 12	5 to 9
Stroke	mm	50 to 700	50 to 700	50 to 700	50 to 700	50 to 700	50 to 700
Retracted length	mm	S+215/315 <sup>2)</sup>	S+215/315 <sup>2)</sup>	S+215/315 <sup>2)</sup>	S+215/315 <sup>2)</sup>	S+215/315 <sup>2)</sup>	S+215/315 <sup>2)</sup>
Voltage	V DC	24	24	24	24	24	24
Power consumption	W	N/A	N/A	N/A	N/A	N/A	N/A
Current consumption	A	7	7	7	10	10	10
Duty cycle	%	10 (1/9)	10 (1/9)	10 (1/9)	10 (1/9)	10 (1/9)	10 (1/9)
Ambient temperature	°C	+10 to +40	+10 to +40	+10 to +40	+10 to +40	+10 to +40	+10 to +40
Degree of protection	IP	×4/×6S	×4/×6S	×4/×6S	×4/×6S	×4/×6S	×4/×6S
Weight	kg	4,7	4,7	4,7	4,7	4,7	4,7
Color	–	Grey	Grey	Grey	Grey	Grey	Grey

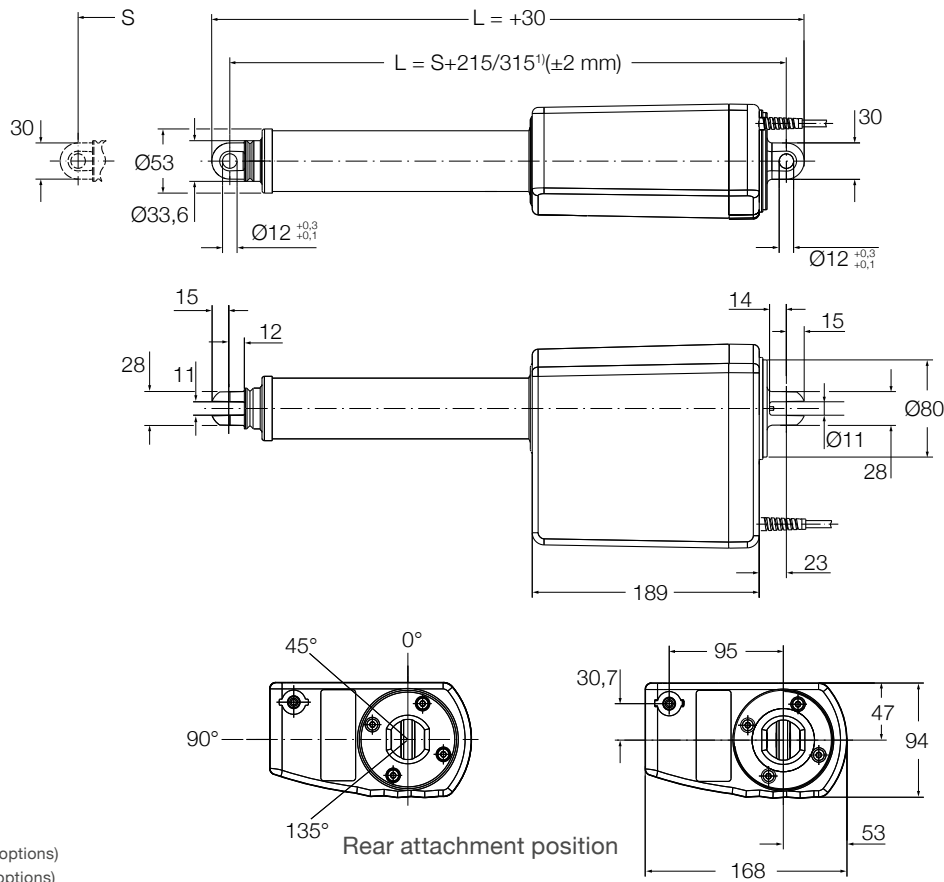
	Unit	RU30	RU31	RU32	RU33	RU34	RU35
Rated push load	N	8 000	10 000	12 000 <sup>1)</sup>	8 000	10 000	12 000 <sup>1)</sup>
Rated pull load	N	8 000	8 000	8 000	8 000	8 000	8 000
Speed (full load to no load)	mm/s	14 to 15	11 to 13	9 to 10	17 to 24	14 to 20	11 to 15
Stroke	mm	50 to 700	50 to 700	50 to 700	50 to 700	50 to 700	50 to 700
Retracted length	mm	S+215/315 <sup>2)</sup>	S+215/315 <sup>2)</sup>	S+215/315 <sup>2)</sup>	S+215/315 <sup>2)</sup>	S+215/315 <sup>2)</sup>	S+215/315 <sup>2)</sup>
Voltage	V DC	36	36	36	36	36	36
Power consumption	W	N/A	N/A	N/A	N/A	N/A	N/A
Current consumption	A	7	7	7	10	10	10
Duty cycle	%	10 (1/9)	10 (1/9)	10 (1/9)	10 (1/9)	10 (1/9)	10 (1/9)
Ambient temperature	°C	+10 to +40	+10 to +40	+10 to +40	+10 to +40	+10 to +40	+10 to +40
Degree of protection	IP	×4/×6S	×4/×6S	×4/×6S	×4/×6S	×4/×6S	×4/×6S
Weight	kg	4,7	4,7	4,7	4,7	4,7	4,7
Color	–	Grey	Grey	Grey	Grey	Grey	Grey

<sup>1)</sup> Safety working load for medical application is 10 000 N (EN 60601)

<sup>2)</sup> S ≤ 500 mm; L = S + 215

S &gt; 500 mm; L = S + 315

Dimensional drawing



Legend:

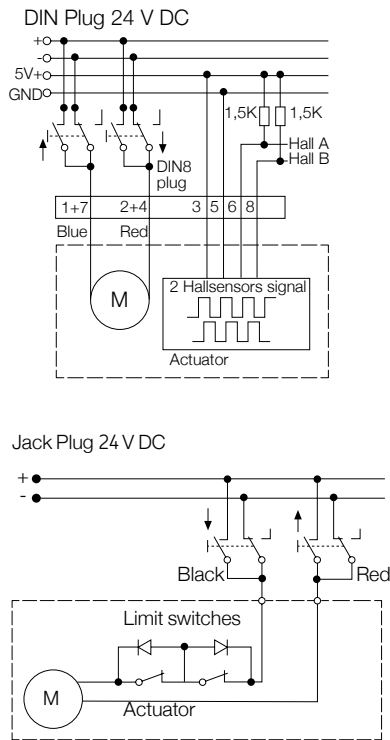
S = stroke

L = retracted length

<sup>1)</sup> Retracted length:  
up to 500 mm stroke: stroke +215 mm (plus options)  
from 500 mm stroke: stroke +315 mm (plus options)

Suitable control units and accessories

Connecting diagrams



	Control units			
	SCU	VCU	BCU	MCU
RU20, RU21, RU22	•	•	•	•
RU23, RU24, RU25	•	•	•	•
Operating switches				
EHA 1	Hand switch			•
EHA 3	Hand switch	•	•	
STJ	Foot switch	•	•	
STF	Foot switch			•
STE	Desk switch	•	•	
STA				•

Hand switch

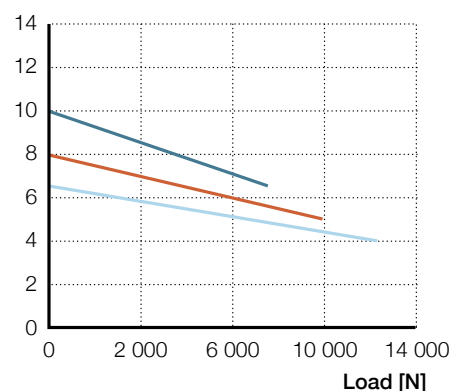
Foot switch

Desk switch

## Performance diagrams

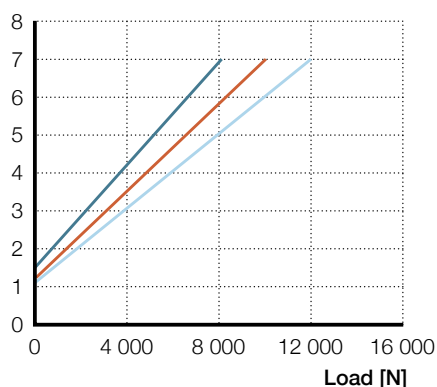
### Speed-load diagrams

Speed [mm/s]



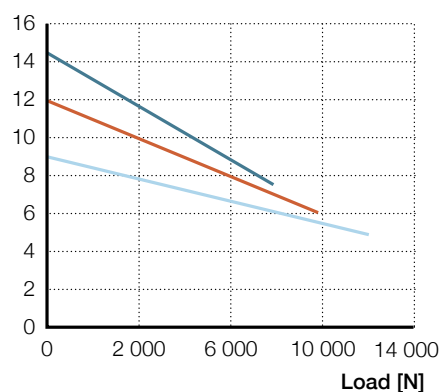
### Current-load diagrams

Current consumption [A]

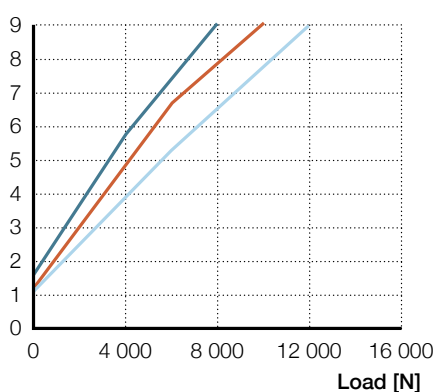


— Rated push load 8 000 RU20  
— Rated push load 10 000 RU21  
— Rated push load 12 000 RU22

Speed [mm/s]

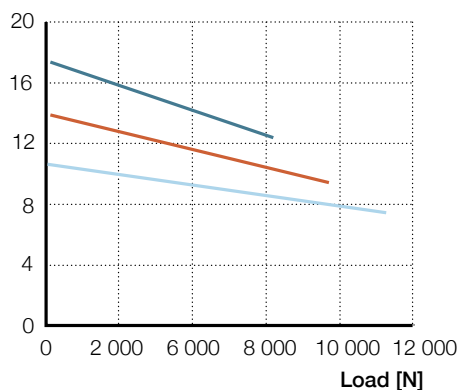


Current consumption [A]

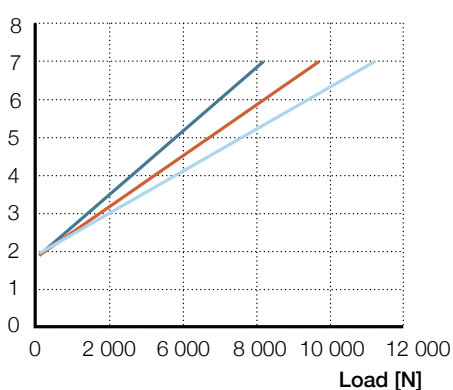


— Rated push load 8 000 RU23  
— Rated push load 10 000 RU24  
— Rated push load 12 000 RU25

Speed [mm/s]

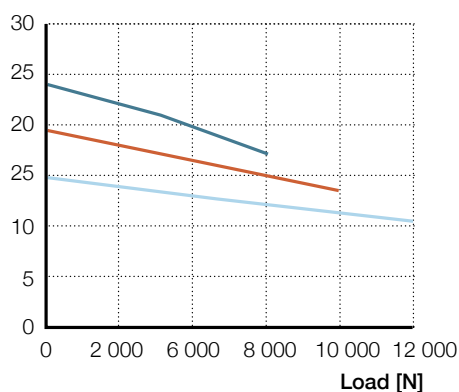


Current consumption [A]

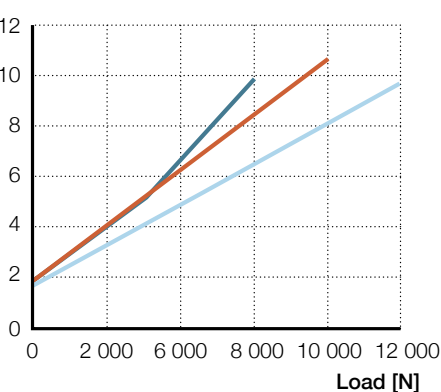


— Rated push load 8 000 RU30  
— Rated push load 10 000 RU31  
— Rated push load 12 000 RU32

Speed [mm/s]

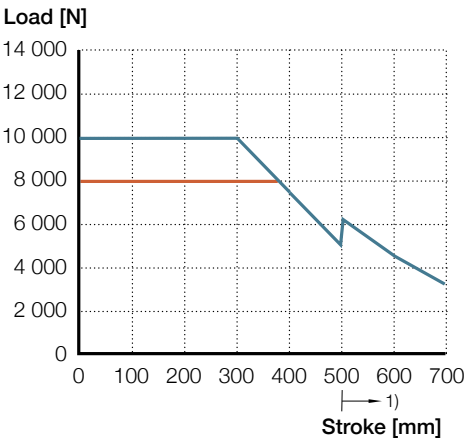


Current consumption [A]



— Rated push load 8 000 RU33  
— Rated push load 10 000 RU34  
— Rated push load 12 000 RU35

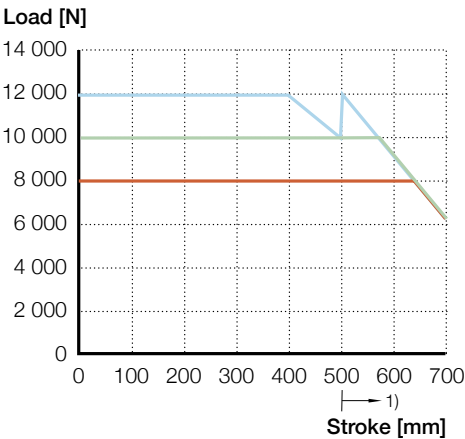
Safety factor load conditions



Push load limit, safety factor <sup>2)</sup> S=4 (EN 60601)

<sup>1)</sup> retracted length extension at stroke >500 mm  
<sup>2)</sup> with option "Emergency lowering", safety factor S=2.5

— RU21 RU22 RU24 RU25	— RU20 RU23
RU31 RU32 RU34 RU35	RU30 RU33



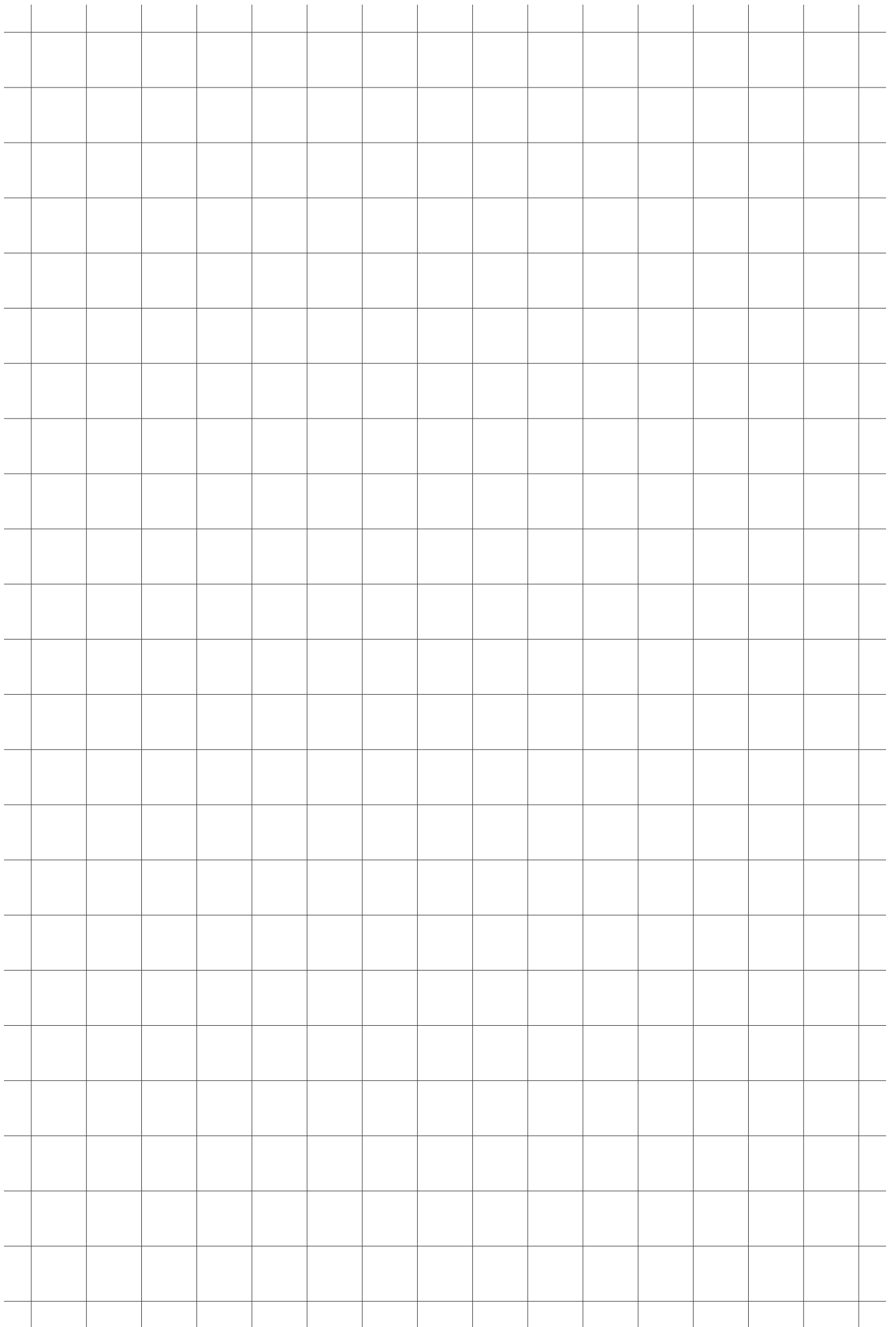
Push load limit, safety factor S=2

<sup>1)</sup> retracted length extension at stroke >500 mm

— RU22 RU25	— RU21 RU24
RU32 RU35	RU31 RU34







# CAJA35C

## Linear actuator

### Benefits

- Quick-release solution for fast CPR intervention
- Detachable cable for quick assembly and service
- Integrated brake to maintain self-locking and stability under maximum static load in compression



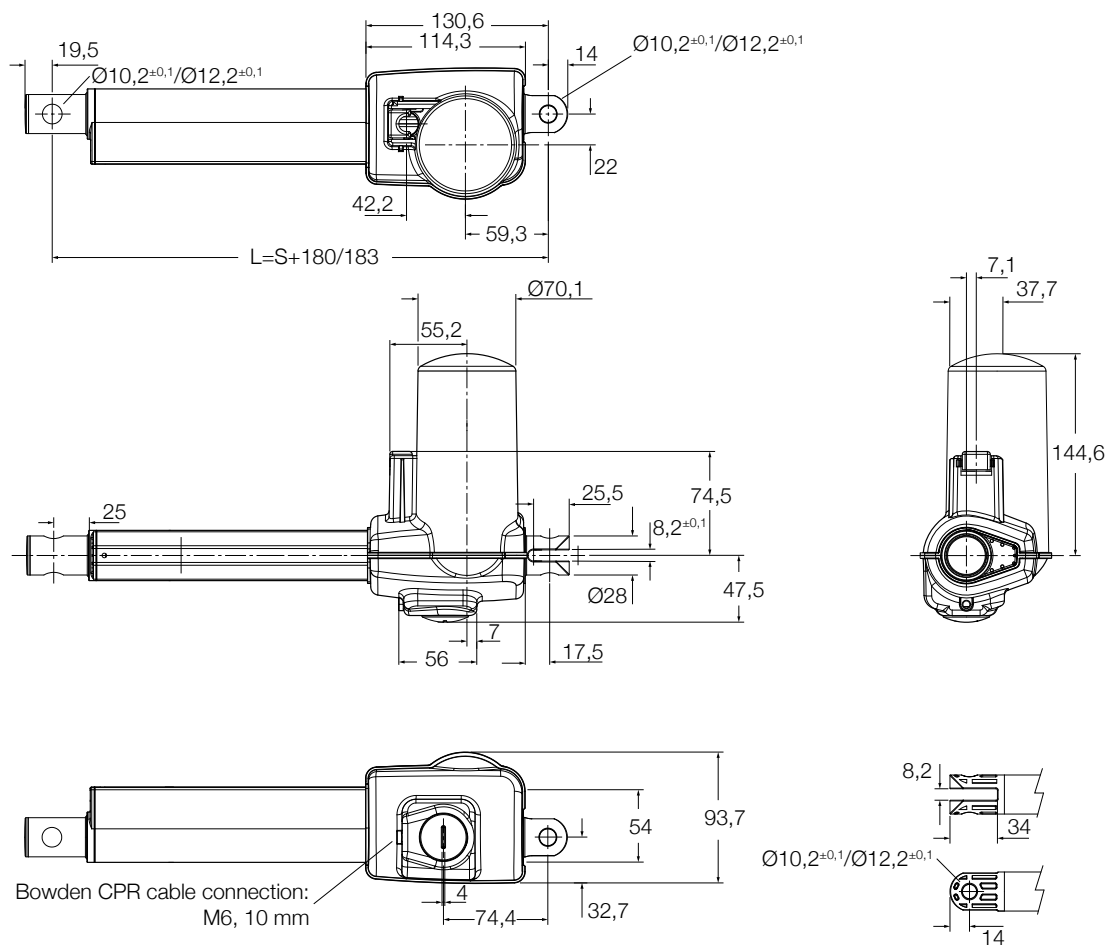
### Technical data

	Unit	CAJA35C
Push load	N	3 500
Speed (full load to no load)	mm/s	5,5 to 8,5
Stroke	mm	30 to 250
Retracted length <sup>1)</sup>	mm	S+180 <sup>2)</sup>
Voltage	V DC	24
Current consumption	A	4
Duty cycle	%	10
Ambient temperature	°C	+10 to +40
Degree of protection	IP	56
Weight	kg	2,5
Color	–	Grey

<sup>1)</sup> Tolerance ±3 mm

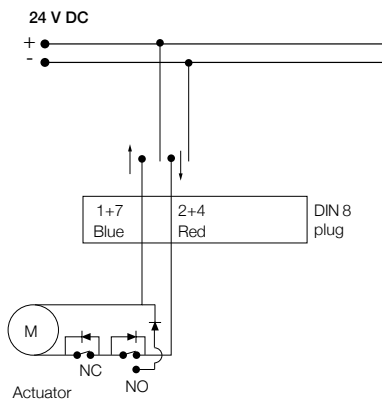
<sup>2)</sup> Retracted length +3 mm if U fork used as front attachment (L = S + 183)

Dimensional drawing









**Legend:**  
S = stroke  
L = retracted length

Connecting diagrams  
DC version



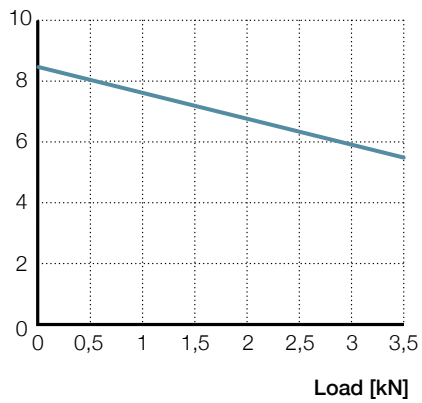
Suitable control units and accessories

	Control units		
	SCU	VCU	BCU
CAJA 35C	•	•	•
Operating switches			
EHA 3 	•	•	•
STJ 	•	•	•
STE 	•	•	•
 Hand switch	 Foot switch	 Desk switch	

## Performance diagrams

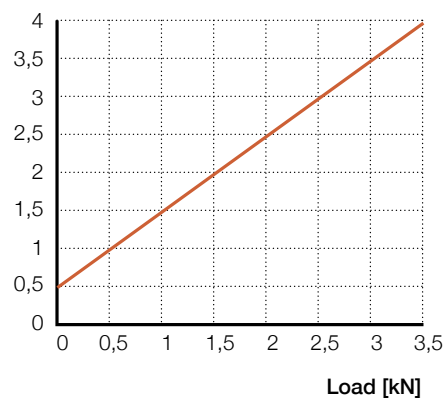
Speed-load diagram

Speed [mm/s]

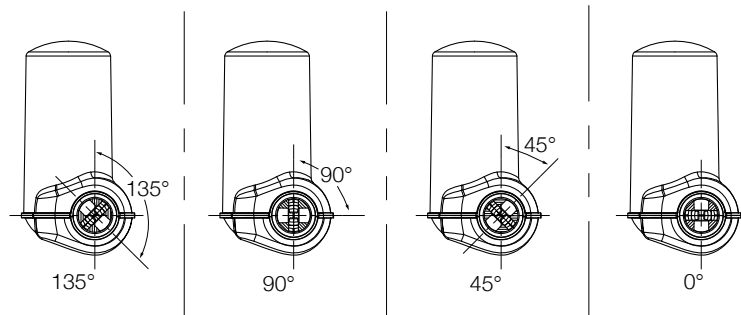


Current-load diagram

Current consumption [A]



## Orientation



Accessories

Straight motor cable	Length [mm]
G517C0-094001-0460	460
G517C0-094001-1350	1 350
G517C0-094001-2650	2 650

Ordering key

C

A

J

A

3

5

C

U

6

Type

Stroke

100100 mm

200200 mm

250250 mm

XXXAll other customized strokes between 30-250 mm

Rear attachment

AU-fork, metal, Ø10,2 mm

BU-fork, metal, Ø12,2 mm

Front attachment

ATube with hole and metal bushings, Ø10,2 mm

BTube with hole and metal bushings, Ø12,2 mm

CU-fork end, metal, Ø10,2 mm (increase "L" by 3 mm)

DU-fork end, metal, Ø12,2 mm (increase "L" by 3 mm)

Attachment orientation (clockwise)

00°

145°

990°

2135°

Housing material

ABS UL94 V0

Protection class (with power cables M6, 10 mm connected)

IP56

Option 1

0No option

1Antipinching solution ("push only" actuator)

Option 2

0No option

1With back-up nut (for "push" load)

Option 3

0No option

1Motor with thermoswitch

Customization

000Standard series

# Ecomag

## Linear actuator

### Benefits

- Compact
- Cost effective
- Silent operation
- Control unit can be mounted to the actuator

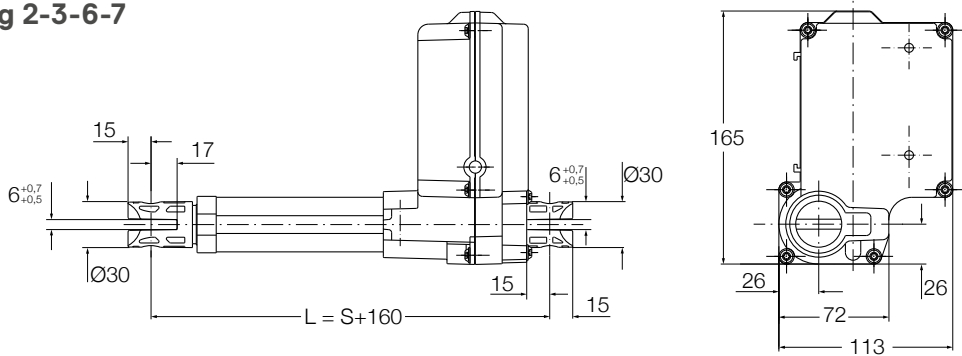


### Technical data

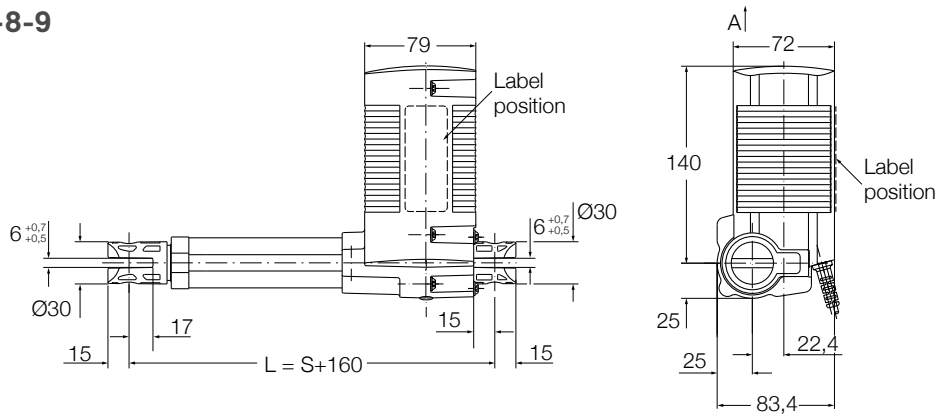
	Unit	ECO 20/40	ECO 60/80	ECO 30/50	ECO 70/90
Rated push load	N	2 000	6 000	2 000	6 000
Rated pull load	N	0	0	2 000	4 000
Speed (full load to no load)	mm/s	9 to 13	4 to 7	9 to 13	4 to 7
Stroke	mm	50 to 300	50 to 300	50 to 300	50 to 300
Retracted length	mm	S+160	S+160	S+160	S+160
Voltage	V DC	24	24	24	24
Power consumption	W	70	120	70	120
Current consumption	A	4	6	4	6
Duty cycle	%	10 (1/9)	10 (1/9)	10 (1/9)	10 (1/9)
Ambient temperature	°C	+10 to +40	+10 to +40	+10 to +40	+10 to +40
Degree of protection	IP	×4S	×4S	×4S	×4S
Weight	kg	2,1	2,1	2,5	2,5
Color	–	Black or grey	Black or grey	Black or grey	Black or grey

Dimensional drawing

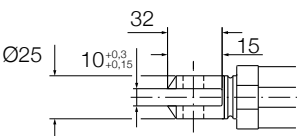
Ecomag 2-3-6-7



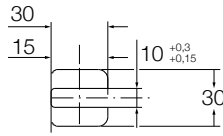
Ecomag 4 -5-8-9



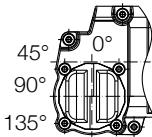
Front attachment  
push and pull version



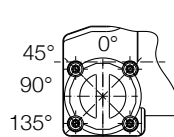
Rear attachment  
push and pull version



Rear attachment  
position



Push version only



Push and pull version

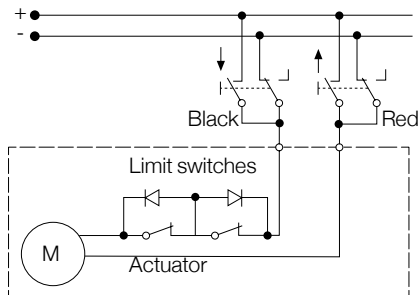
Legend:

S = stroke

L = retracted length

Connecting diagrams

Jack Plug 24 V DC



Suitable control units and accessories

	Control units				
	SCU	VCU	BCU	MCU	SEM
ECOMAG	•	•	•	•	•
Operating switches					
EHA 1	Hand switch				
EHA 3	Hand switch				
EHE	Hand switch				
STJ	Foot switch				
STF	Foot switch				
STA	Desk switch				
STE	Desk switch				

Hand switch

Foot switch

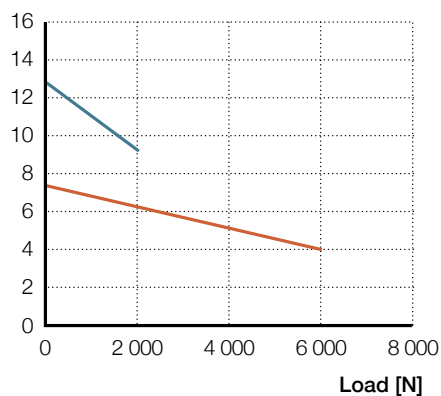
Desk switch



## Performance diagrams

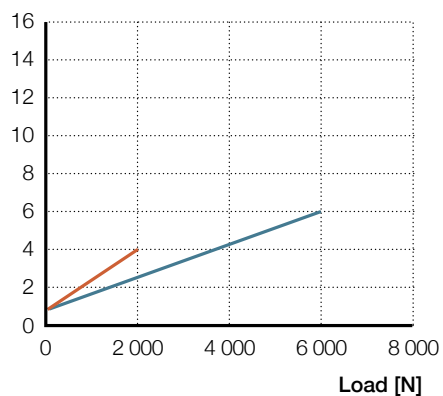
Speed-load diagram

Speed [mm/s]



Current-load diagram

Current consumption [A]

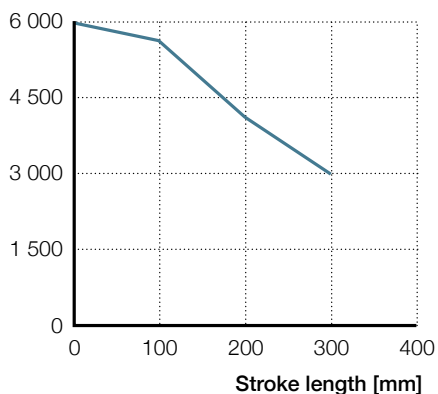


— ECO 20 / 30 / 40 / 50 — ECO 60 / 70 / 80 / 90

## Safety factor load conditions

Push load reduction safety factor = 4

Push load [N]



## Ordering key

Type	Load /Housing	Encoder	Current cut-off	Stroke (S)	Front attachment (groove depth 17 mm)	Rear attachment (groove depth 15 mm)	Orientation of rear attachment	Color	Option	Customization																																			
	<table border="1"> <thead> <tr> <th>Push</th> <th>Pull</th> <th>Housing</th> </tr> </thead> <tbody> <tr><td>2</td><td>2 000 N</td><td>0 N</td><td>Large</td></tr> <tr><td>3</td><td>2 000 N</td><td>2 000 N</td><td>Large</td></tr> <tr><td>4</td><td>2 000 N</td><td>0 N</td><td>Small</td></tr> <tr><td>5</td><td>2 000 N</td><td>2 000 N</td><td>Small</td></tr> <tr><td>6</td><td>6 000 N</td><td>0 N</td><td>Large</td></tr> <tr><td>7</td><td>6 000 N</td><td>4 000 N</td><td>Large</td></tr> <tr><td>8</td><td>6 000 N</td><td>0 N</td><td>Small</td></tr> <tr><td>9</td><td>6 000 N</td><td>4 000 N</td><td>Small</td></tr> </tbody> </table>	Push	Pull	Housing	2	2 000 N	0 N	Large	3	2 000 N	2 000 N	Large	4	2 000 N	0 N	Small	5	2 000 N	2 000 N	Small	6	6 000 N	0 N	Large	7	6 000 N	4 000 N	Large	8	6 000 N	0 N	Small	9	6 000 N	4 000 N	Small	0 No encoder, coiled cable, 2-pin Minifit plug or customization 9 No encoder, coiled cable, DIN8 plug or customization F 2-Hall encoder, 8 pulses, straight cable, DIN8 plug (small housing only)	0 No 1 Yes (not available for ECO4.-/ECO5.-/ECO8.-/ECO9.-)	05 50 mm 10 100 mm 15 150 mm 20 200 mm 25 250 mm 30 300 mm 00 Other stroke lengths; 50<S<300 mm	M Hole, Ø12 mm, groove width 10 mm X Customized	M Hole, w12 mm, groove width 10 mm X Customized	1 0° 3 45° 5 90° 7 135°	A Black (available only for small housing) B Grey	0 No option A Back-up nut (available only for drives with 6 kN, mandatory for IEC 60601-1) – only for ECO 7/9, L = +23 mm	
Push	Pull	Housing																																											
2	2 000 N	0 N	Large																																										
3	2 000 N	2 000 N	Large																																										
4	2 000 N	0 N	Small																																										
5	2 000 N	2 000 N	Small																																										
6	6 000 N	0 N	Large																																										
7	6 000 N	4 000 N	Large																																										
8	6 000 N	0 N	Small																																										
9	6 000 N	4 000 N	Small																																										

# CAHB series

Linear actuator

CAHB series with 7 families of linear actuator, virtually maintenance-free, self-locking up to 2 times the rated load and up to IP69K/66M, covers low, medium and high loads for mobile applications,

Additional design options are available like limit switches, positioning feedback and manual override.

The smart CAHB-20S, CAHB-21S and CAHB-22S offer unique features at a competitive cost with integrated controller and advanced functions.



## Features

### New smart version CAHB-20S, -21S and -22S

- Integrated controller with I/O and CAN bus SAE J1939
- Motion with soft start / -stop and parallel movement of 2 actuators
- Key actuator functions monitoring with diagnostic

### For all versions

- Electronic or mechanical overload protection and thermal protection
- Long stroke and high speed
- High holding force up to 20 000 N
- Low backlash
- Absolute or incremental Position feedback and limit switches option
- Manual override option
- Ingress protection IP69K/66M with vent
- Anti-rotation with free spinning (option for E design)
- Stainless steel push tube with anti rotation, free spinning attachment and corrosion protected metal parts
- Wide temperature range (-40 to 85 °C)
- High efficiency
- Virtually maintenance-free
- Mechanical, electrical and climatic tests

See **pages 130 to 135** for test results.

## Benefits

- Higher productivity with fast and smooth movement
- Easy and quick integration into customer equipment
- Higher reliability and protection
- Cost effective and virtually maintenance-free
- Monitoring and onboard diagnostic

## Performance overview of the CAHB series

Family	Version	Rated force	Speed (up to)	Max stroke	Voltage	Smart	Page
		N	mm/s	mm	V	Integrated controller	
<b>CAHB-10 xx A</b>	CAHB-10-x1A	120	56	300	12 or 24 VDC	No	6
	CAHB-10-x2A	240	30	300	12 or 24 VDC	No	
	CAHB-10-x3A	500	16	300	12 or 24 VDC	No	
	CAHB-10-x4A	750	10	300	12 or 24 VDC	No	
	CAHB-10-x5A	1 000	8	300	12 or 24 VDC	No	
	CAHB-10-x6A	1 500	8	300	12 or 24 VDC	No	
<b>CAHB-20 xx A</b>	CAHB-20-x1A	1 500	33	610	12 or 24 VDC	No	12
	CAHB-20-x2A	2 500	17	610	12 or 24 VDC	No	
<b>CAHB-20 xx E/S</b>	CAHB-20-x1E or S	1 500	31	700	12 or 24 or 48 or 24-48 VDC	Yes	16
	CAHB-20-x2E or S	2 500	23	700	12 or 24 or 48 or 24-48 VDC	Yes	
	CAHB-20-x3E or S	4 500	13	700	12 or 24 or 48 or 24-48 VDC	Yes	
<b>CAHB-21 xx E/S</b>	CAHB-21-x1E or S	1 500	51	700	12 or 24 or 48 or 24-48 VDC	Yes	20
	CAHB-21-x2E or S	2 500	41	700	12 or 24 or 48 or 24-48 VDC	Yes	
	CAHB-21-x3E or S	4 500	23	700	12 or 24 or 48 or 24-48 VDC	Yes	
<b>CAHB-22 xx E/S</b>	CAHB-22-x1E or S	2 300	57	700	12 or 24 or 48 or 24-48 VDC	Yes	24
	CAHB-22-x2E or S	3 500	45	700	12 or 24 or 48 or 24-48 VDC	Yes	
	CAHB-22-x3E or S	6 800	22	610	12 or 24 or 48 or 24-48 VDC	Yes	
	CAHB-22-x4E or S	10 000	13	450	12 or 24 or 48 or 24-48 VDC	Yes	
<b>CAHB-30 xx A</b>	CAHB-30-x1A	1 500	26	610	115 VAC / 60 Hz or 230 VAC / 50Hz	No	42
	CAHB-30-x2A	2 300	13	610	115 VAC / 60 Hz or 230 VAC / 50Hz	No	
<b>CAHB-31 xx N</b>	CAHB-31-x1N	2 300	57	610	115 VAC / 60 Hz or 230 VAC / 50Hz	No	46
	CAHB-31-x2N	4 500	28	610	115 VAC / 60 Hz or 230 VAC / 50Hz	No	
	CAHB-31-x3N	6 000	15	610	115 VAC / 60 Hz or 230 VAC / 50Hz	No	



# CAHB-10

## Linear actuator

### Benefits

- Designed and tested under demanding conditions
- Reliable and cost-effective
- Reduced overall set time
- Virtually maintenance-free

### Features

- Compact and robust design, IP66S/69K, wide temperature range and corrosion resistant
- Integrated limit switches, optional absolute or incremental positioning feedback
- Integrated thermal protection



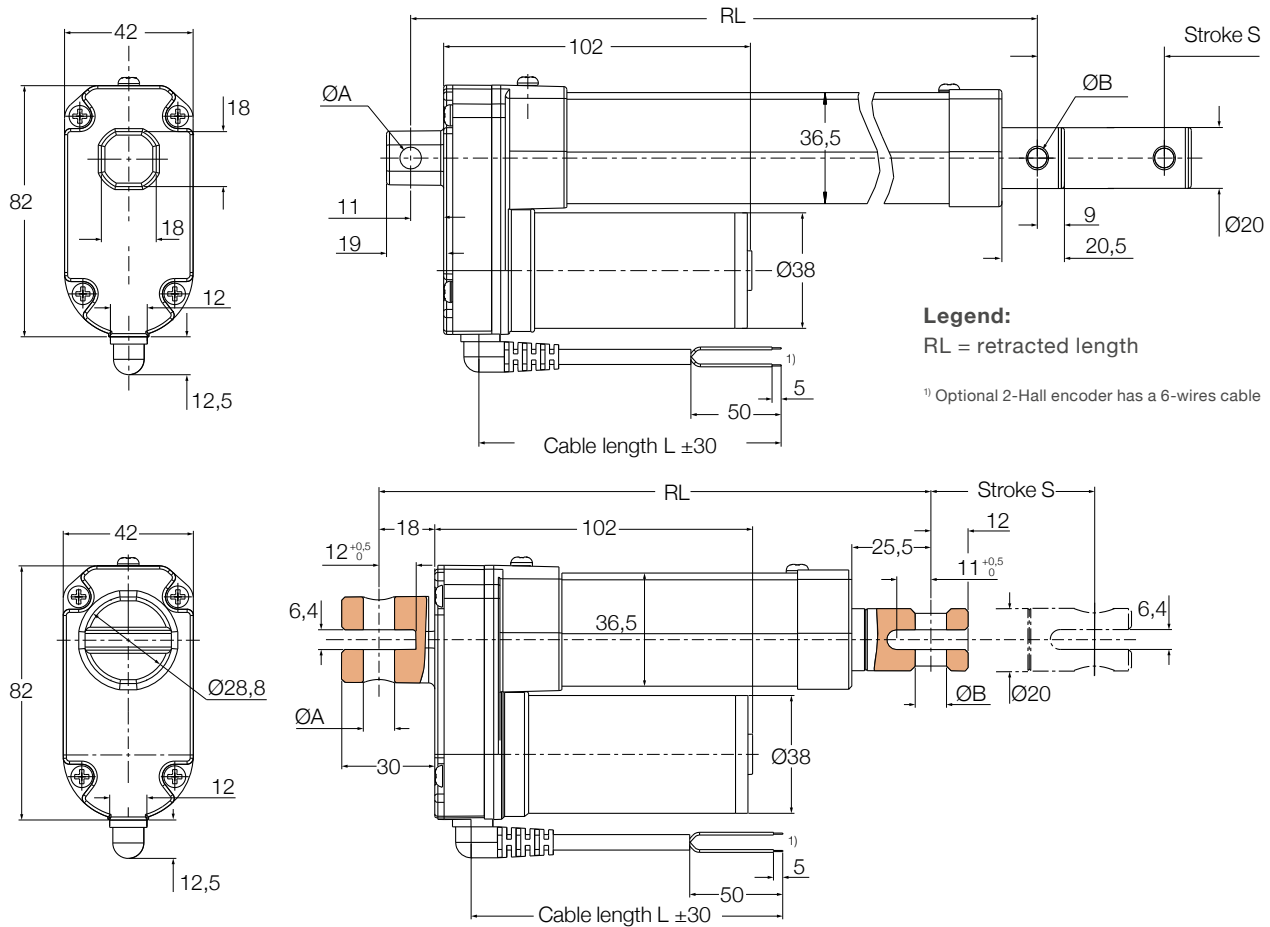
## Technical data

Designation	Unit	CAHB-10... 1	CAHB-10... 2	CAHB-10... 3	CAHB-10... 4	CAHB-10... 5	CAHB-10... 6
Rated push force	N	120	240	500	750	1 000	1 500
Rated pull force	N	120	240	500	750	1 000	1 500
Holding force <sup>1)</sup>	N	2 500	2 500	2 500	2 500	2 500	2 500
Speed (full load to no load)	mm/s	45 to 56	24 to 30	13 to 16	8 to 10	6 to 8	5 to 8
Stroke	mm	50 to 300	50 to 300	50 to 300	50 to 300	50 to 300	50 to 300
Voltage	V DC	12 or 24	12 or 24	12 or 24	12 or 24	12 or 24	12 or 24
Nominal current 12 V DC	A	4	3,5	3,2	3	2,8	4,4
24V DC	A	2,2	2	1,8	1,8	1,6	2,8
Duty cycle	%	25	25	25	25	25	20
Ambient temperature	°C	–40 to +85	–40 to +85	–40 to +85	–40 to +85	–40 to +85	–40 to +85
Type of protection	IP	66s/69k	66s/69k	66s/69k	66s/69k	66s/69k	66s/69k
Weight (at 300 mm stroke)	kg	1,5	1,5	1,5	1,5	1,5	1,5
Color	–	Silver	Silver	Silver	Silver	Silver	Silver
Limit switches	–	Yes	Yes	Yes	Yes	Yes	Yes
Thermal protection	–	Yes	Yes	Yes	Yes	Yes	Yes

<sup>1)</sup> The holding force is the highest load a powered-down actuator can statically hold without slipping backwards..

## Dimensional drawing

### Basic configuration and optional 2-Hall encoder



Front / Rear attachment	Ø A	Ø B
Rod end with hole (A)	6,4 (0, +0,1)	6,4 (0, +0,1)
Rod end with hole (B)	8,0 (0, +0,1)	8,0 (0, +0,1)
Fork head with hole, (C)	10,1 (0, +0,1)	10,1 (0, +0,1)

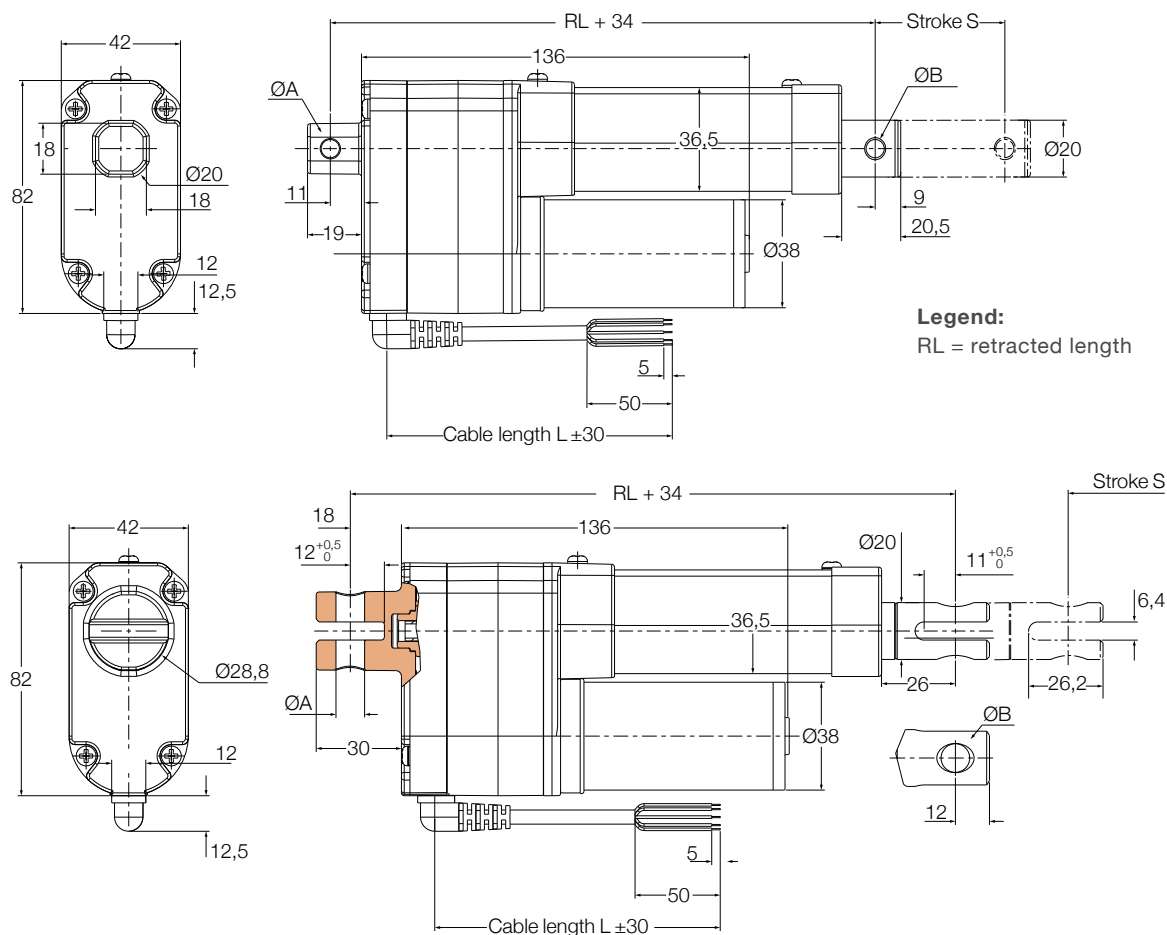
	RL tolerance	S tolerance
CAHB10...1 and 2	(-5, +1)	(-1, +5)
CAHB10...3 and 4	(-3, +3)	(-3, +3)
CAHB10...5 and 6	(-2, +4)	(-4, +2)

### Retracted length calculation (RL)

Stroke [mm]	50	100	150	200	250	300
Retracted length (RL) with Rod end (Front) + Rod end (Rear)	158	209	260	311	362	413
Retracted length (RL) with Rod end (Front) + Fork head (Rear)	165	216	267	318	369	420
Retracted length (RL) with Fork head (Front) + Rod end (Rear)	172	223	274	325	376	427
Retracted length (RL) with Fork head (Front) + Fork head (Rear)	179	230	281	332	383	434

## Dimensional drawing

### Optional potentiometer and absolut analogue



Front / Rear attachment	Ø A	Ø B
Rod end with hole (A)	6,4 (0, +0,1)	6,4 (0, +0,1)
Rod end with hole (B)	8,0 (0, +0,1)	8,0 (0, +0,1)
Fork head with hole, (C)	10,1 (0, +0,1)	10,1 (0, +0,1)

	RL tolerance	S tolerance
CAHB10...1 and 2	(-5, +1)	(-1, +5)
CAHB10...3 and 4	(-3, +3)	(-3, +3)
CAHB10...5 and 6	(-2, +4)	(-4, +2)

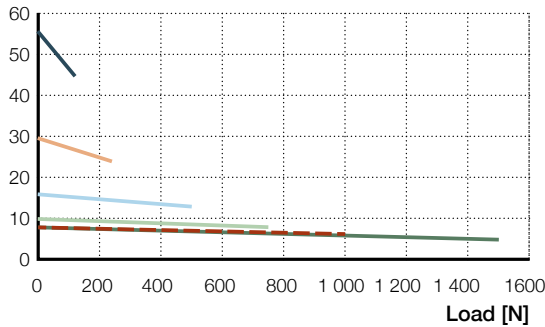
### Retracted length calculation (RL)

Stroke [mm]	50	100	150	200	250	300
Retracted length (RL) with Rod end (Front) + Rod end (Rear)	192	243	294	345	396	447
Retracted length (RL) with Rod end (Front) + Fork head (Rear)	199	250	301	352	403	454
Retracted length (RL) with Fork head (Front) + Rod end (Rear)	206	257	308	359	410	461
Retracted length (RL) with Fork head (Front) + Fork head (Rear)	213	264	315	366	417	468

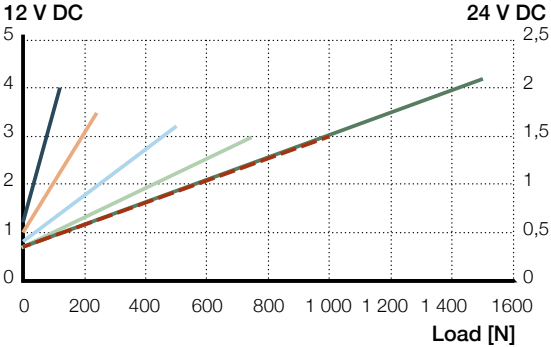


Performance diagrams

Speed-load diagram  
Speed [mm/s]



Current-load diagram  
Nominal current [A]



CAHB-10...1	CAHB-10...3	CAHB-10...5
CAHB-10...2	CAHB-10...4	CAHB-10...6

Encoder resolution

Type	CAHB-10...1	CAHB-10...2	CAHB-10...3	CAHB-10...4	CAHB-10...5/6
mm/pulse	0,3	0,15	0,075	0,05	0,0375

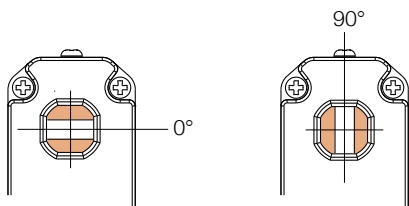
Potentiometer resolution

Stroke [mm]	50~80	80~160	160~300
Minimum resistance value of potentiometer	700~1 300 Ω	700~1 300 Ω	700~1 300 Ω
Potentiometer resolution	100 Ω/mm	50 Ω/mm	16,6 Ω/mm

Absolute analog output

Stroke [mm]	50~80	80~160	160~300
Initial value VS RL position (V)	0,5	0,5	0,5
Resolution (mm)	0,024	0,049	0,146
Position feedback change (V/mm)	0,05	0,025	0,0083

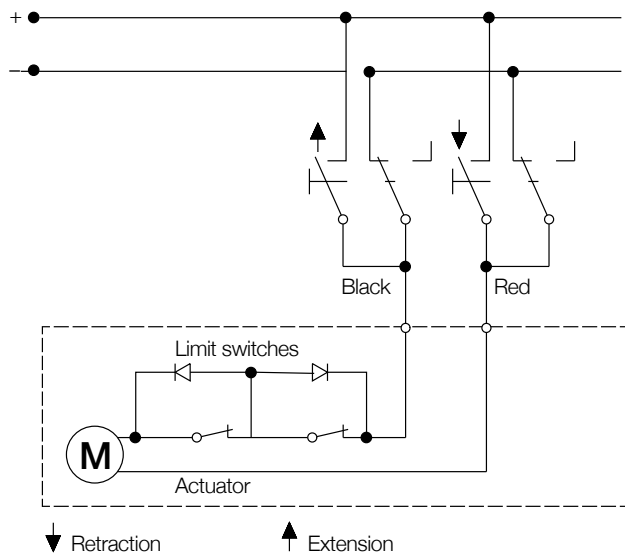
Attachment orientation (refer to ordering key Attachment orientation)



## Connecting diagram

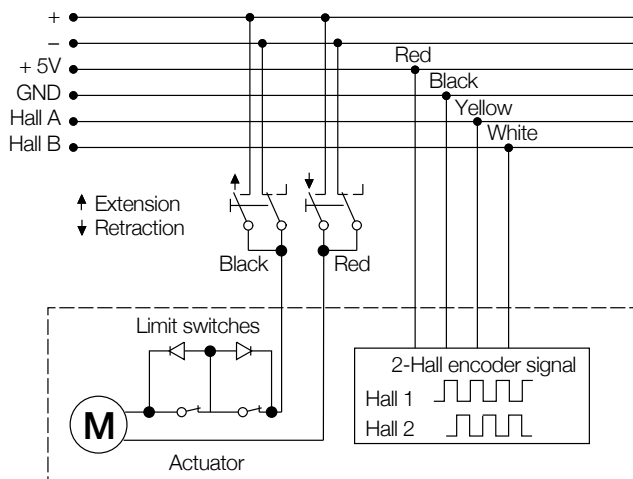
### Basic configuration

12/24 V DC



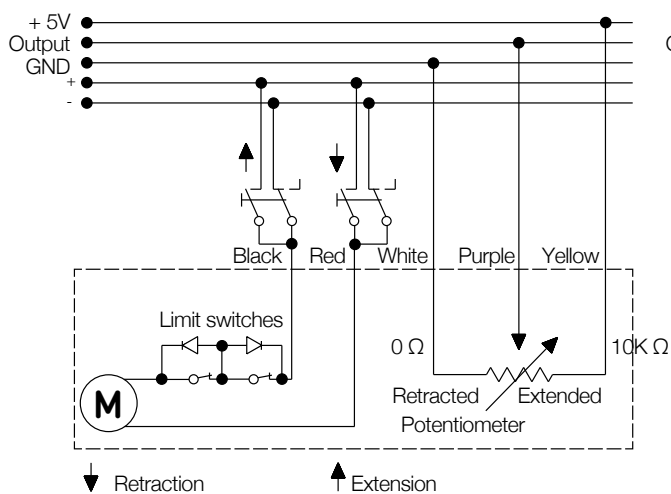
### 2-Hall encoder

12/24 V DC



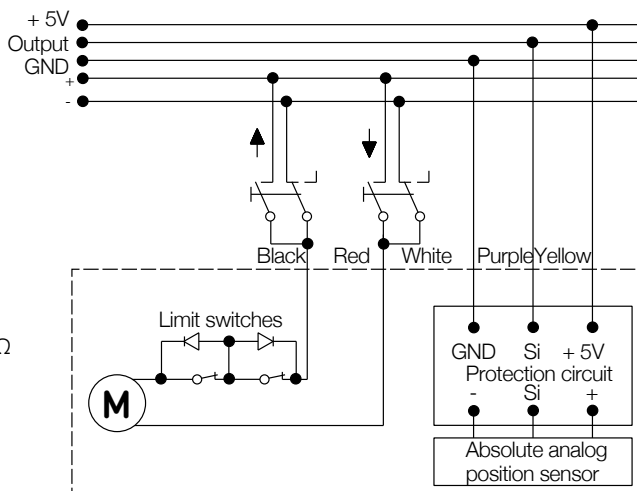
### Potentiometer

12/24 V DC



### Absolute analog output

12/24 V DC



## Ordering key

Type		Voltage		Load		Design		3 digital Stroke and 3 digital Retracted length (mm)		Ingress protection		Front attachment		Rear attachment		Hole direction of the attachments		Option 1: Position output		Cable length		Customized	
C A H B - 1 0 -		A 12 V DC B 24 V DC		1 120 N 2 240 N 3 500 N 4 750 N 5 1 000 N 6 1 500 N		A TR12 screw X Customized		Stroke    Retracted length Base <sup>1)</sup> with Front fork head    with Rear fork head    with Potentiometer or Absolute analog output A, P 050    158    +14    +7    +34 100    209    +14    +7    +34 150    260    +14    +7    +34 200    311    +14    +7    +34 250    362    +14    +7    +34 300    413    +14    +7    +34		A Standard (IP 66s/69k)		A Rod with hole Ø6,4 (0, +0,1) mm B Rod with hole Ø8 (0, +0,1) mm C Fork head with hole Ø10,1 (0, +0,1) mm X Customized		A Rod with hole Ø6,4 (0, +0,1) mm B Rod with hole Ø8 (0, +0,1) mm C Fork head with hole Ø10,1 (0, +0,1) mm X Customized		A 0° B 90°		0 None A Absolute analog output P Potentiometer H 2-Hall encoder		A 600 mm without connector B 1 000 mm without connector C 1 500 mm without connector D 2 000 mm without connector E 2 500 mm without connector F 3 000 mm without connector		X	

1) Base: the Retracted length with front and rear attachment "Rod with hole", without "Potentiometer" and without "Absolute analog output"

# CAHB-20A

## Linear actuator

### Benefits

- Compact design which has been tested for vigorous use
- Robust and reliable
- Thermal protection and virtually maintenance-free

### Features:

- Integrated overload and thermal protection
- Robust design
- IP66
- Optional potentiometer and limit switches



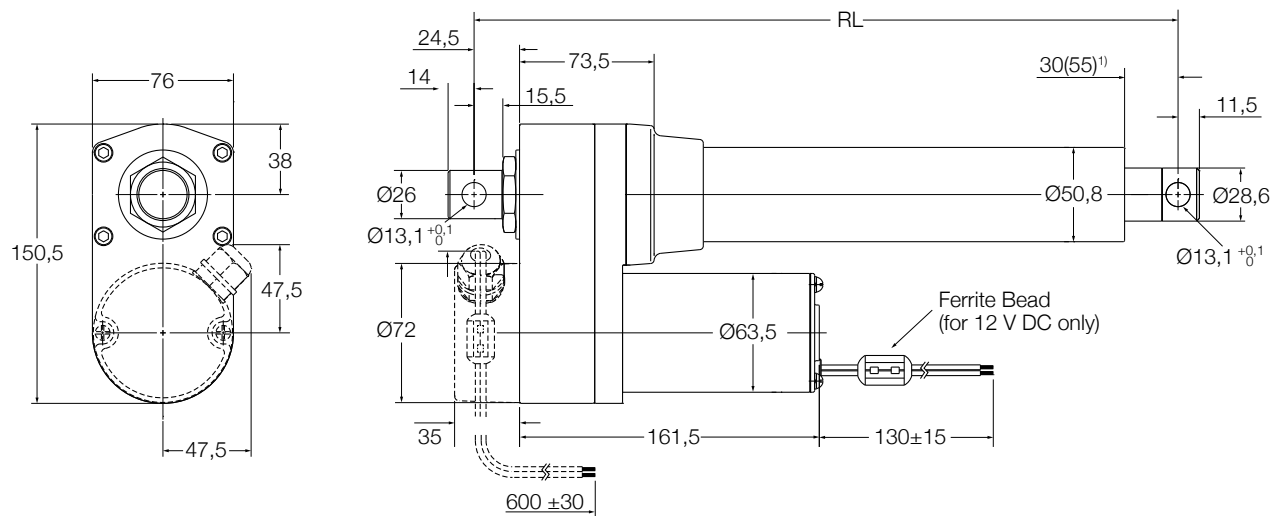
### Technical data

Designation	Unit	CAHB-20-x1A	CAHB-20-x2A
<b>Performance data</b>			
Rated push force	N	1 500	2 500
Rated pull force	N	1 500	2 500
Holding force <sup>1)</sup>	N	10 000	10 000
Speed (full load to no load)	mm/s	27 to 33	13 to 17
Stroke	mm	102 to 610	102 to 610
Voltage	V DC	12 or 24	12 or 24
Nominal current 12 V DC	A	16	14
24 V DC	A	8	7
Duty cycle	%	25	25
Ambient temperature	°C	–40 to +85	–40 to +85
Type of protection	IP	66	66
Weight (at 305 mm stroke)	kg	5,5	5,5
Color	–	Black	Black

<sup>1)</sup> The holding force is the highest load a powered-down actuator can statically hold without slipping backwards.

## Dimensional drawing

Basic configuration (dashed line for optional limit switch)



Attachment orientation (see page 94)

<sup>1)</sup> 55 = dimension with limit switch

**Without limit switch:**

RED (+) & BLACK (-) = retraction  
RED (-) & BLACK (+) = extension

**With limit switch:**

RED (+) & BLACK (-) = extension  
RED (-) & BLACK (+) = retraction

**Legend:**

RL = retracted length

## Retracted length calculation (RL)

Stroke [mm]	With limit switch <sup>1)</sup>						Without limit switch <sup>2)</sup>					
	102	153	204	305	457	610	102	153	204	305	457	610
Retracted length (RL)	338	389	440	592	744	897	262	313	364	465	668	821

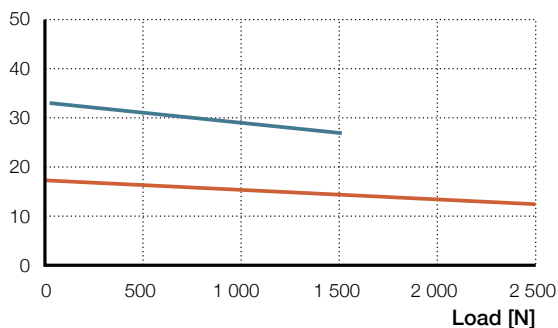
<sup>1)</sup> Tolerance: S and RL =  $\pm 5,0$  mm (If S  $\geq 305$  mm, S =  $\pm 7,5$  mm)

<sup>2)</sup> Tolerance: S =  $\pm 2,5$  mm and L =  $\pm 3,8$  mm

## Performance diagrams

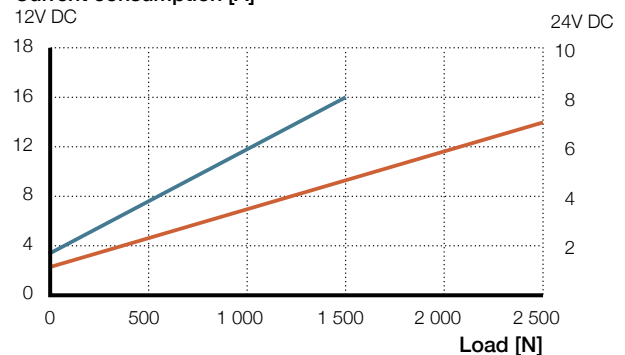
**Speed-load diagram**

Speed [mm/s]



**Current-load diagram**

Current consumption [A]

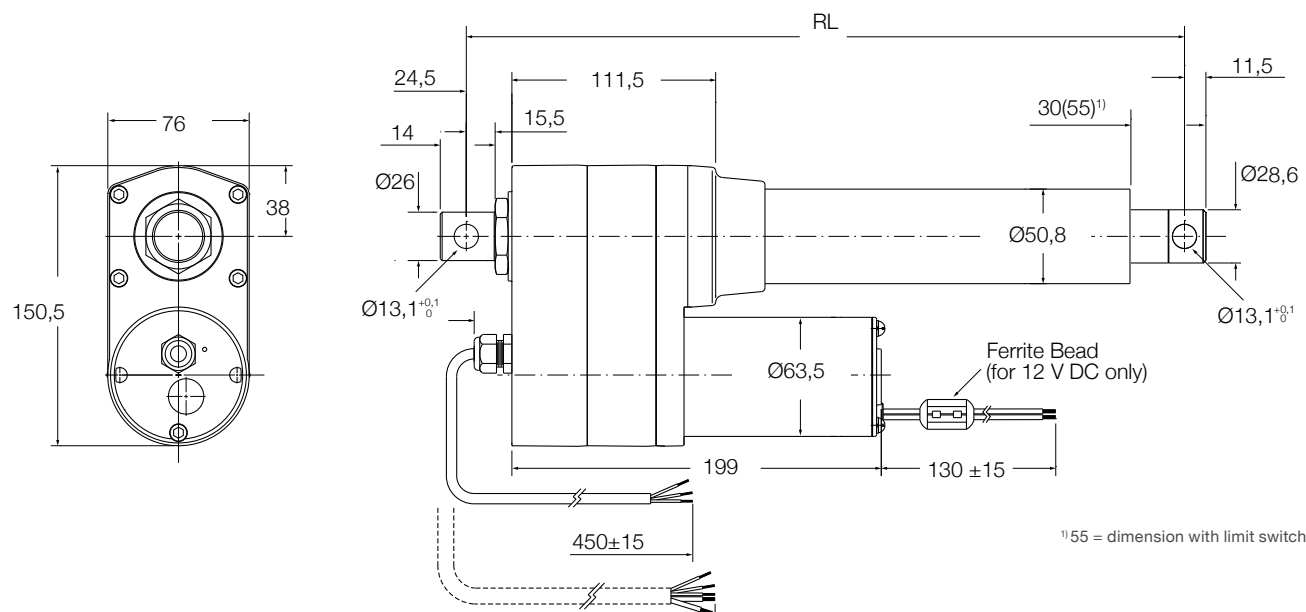


— CAHB-20...1

— CAHB-20...2

## Dimensional drawing

Optional potentiometer (dashed line for optional limit switch)



**Without limit switch:**

RED (+) & BLACK (-) = retraction  
RED (-) & BLACK (+) = extension

**With limit switch:**

RED (+) & BLACK (-) = extension  
RED (-) & BLACK (+) = retraction

**Legend:**

RL = retracted length

## Retracted length calculation (RL)

	With limit switch <sup>1)</sup>						Without limit switch <sup>2)</sup>					
Stroke [mm]	102	153	204	305	457	610	102	153	204	305	457	610
Retracted length (RL)	376	427	478	630	782	935	300	351	402	503	706	859

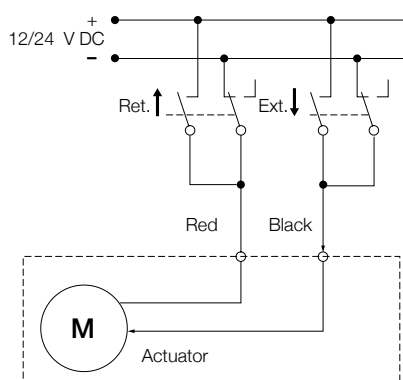
<sup>1)</sup> Tolerance: S and RL = ± 5,0 mm (If S ≥ 305 mm, S = ± 7,5 mm)

<sup>2)</sup> Tolerance: S = ± 2,5 mm and RL = ± 3,8 mm

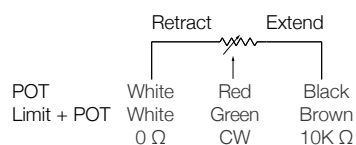
## Potentiometer resolution

Stroke [mm]	102	153	204	305	457	610
Ω/mm	59,0	59,0	29,5	29,5	9,84	9,84

## Connecting diagram

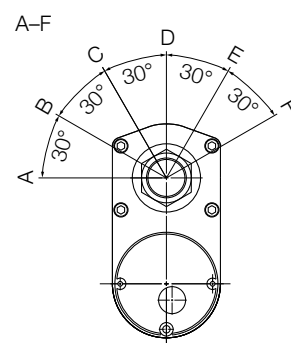


## Electrical diagrams



## Attachment orientation

(refer to ordering key Attachment orientation)



Ordering key

C

A

H

B

-

2

0

-

A

-

-

A

-

0

0

0

Type

Voltage

A12 V DC

B24 V DC

Load

11 500 N

22 500 N

Design

A

3 digital Stroke and 3 digital Retracted length (mm)

Stroke	Retracted length		
	Base <sup>1)</sup>	with Limit switch	with Potentiometer
		L	P
102	262	+76	+38
153	313	+76	+38
204	364	+76	+38
305	465	+127	+38
457	668	+76	+38
610	821	+76	+38

<sup>1)</sup> Base: the Retracted length without "Limit switch", without "Potentiometer"

Ingress protection

AStandard: IP66

Attachment diameter (Front and rear)

AStandard (hole: Ø13,1 mm)

XCustomized

Attachment orientation (Front and rear)

AStandard (0°)

B30°

C60°

D90°

E120°

F150°

XCustomized

Option 1

0None

LLimit switch (only for load version 2 500 N)

Option 2

0None

PPotentiometer

Option 3

0None

TThermal protection

Customization

The actuators have protection Clutch and EMC filter.



# CAHB-20E and -20S

## Linear actuator

### Benefits

- High productivity
- Reliability and safety
- Save development time
- Cost effectiveness
- Quick time to market (for Smart version)

### Features:

- Holding force
- Overload protection
- Corrosion protection and stainless steel tube
- Manual override option
- Enhanced ingress protection and virtually maintenance free



### Smart version S features

- Integrated controller with complete motion control
- True absolute position contactless sensor
- Monitoring and onboard diagnostic (force, voltage, temperature)
- I/O and CAN bus SAE J1939 communication

### Technical data

Designation	Unit	CAHB-20E / 12 V			CAHB-20E / 24 V		
Performance data							
Rated Push Force	N	1 500	2 500	4 500	1 500	2 500	4 500
Rated Pull Force	N	1 500	2 500	4 500	1 500	2 500	4 500
Max pull / push Force <sup>1)</sup>	N	2 600	3 800	6 300	2 600	3 800	6 300
Holding force <sup>2)</sup>	N						
Speed without load <sup>3)</sup>	mm/s	27,0	23,5	13,5	29,0	22,0	13,0
Speed with the rated force <sup>3)</sup>	mm/s	24,5	17,5	10,5	25,5	19,0	11,0
Electric data							
Nominal voltage	V DC	12	12	12	24	24	24
Nominal current @ rated load <sup>3)</sup>	A	12,5	15	17	5	6,5	8
Rated current (clutch activation)	A	18,4	21	22,4	6,8	8,8	10,4
Duty cycle	%	10	10	10	20	20	20
ON time / OFF time	s	85/765	85/765	85/765	85/340	85/340	85/340
Mechanical data							
Stroke	mm	50 ... 700	50 ... 700	50 ... 700	50 ... 700	50 ... 700	50 ... 700
Backlash	mm	0,6	0,6	0,6	0,6	0,6	0,6
Weight for 200 mm stroke	kg	4,5	4,5	4,5	4,5	4,5	4,5
Colour	–	Black	Black	Black	Black	Black	Black
Environment and standards							
Ambient temperature <sup>4)</sup>	°C	–40 ... 85	–40 ... 85	–40 ... 85	–40 ... 85	–40 ... 85	–40 ... 85
Degree of protection	–	IP 69K/66M					
Standards / EMC	–	EN61000-6-2:2005, EN61000-6-4:2007/A1:2011					
Salt spray test	–	ISO 9227:2012, 250 hours					

<sup>1)</sup> Upper limit of the pull/push force limited by the clutch. The lower limit is just above the rated force. The limitation of the force will happen between these 2 limits

<sup>2)</sup> The holding force is the highest load a powered-down actuator can statically hold without slipping backwards. Ultimate Static Load, refer to the "Static load" diagrams

<sup>3)</sup> The data of speed and current on this list is defined at +20 °C

<sup>4)</sup> Full performance from 0 °C to +40 °C

Designation	Unit	CAHB-20E / 48 V		
Performance data				
Rated Push Force	N	1 500	2 500	4 500
Rated Pull Force	N	1 500	2 500	4 500
Max pull / push Force <sup>1)</sup>	N	2 600	3 800	6 300
Holding force <sup>2)</sup>	N			
Speed without load <sup>3)</sup>	mm/s	31,0	23,0	13,0
Speed with the rated force <sup>3)</sup>	mm/s	27,5	20,0	11,0
Electric data				
Nominal voltage	V DC	48	48	48
Nominal current @ rated load <sup>3)</sup>	A	2,6	3,8	4,2
Rated current (clutch activation)	A	4,3	5,6	5,8
Duty cycle	%	20	20	20
ON time / OFF time	s	85/340	85/340	85/340
Mechanical data				
Stroke	mm	50 ... 700	50 ... 700	50 ... 700
Backlash	mm	0,6	0,6	0,6
Weight for 200 mm stroke	kg	4,5	4,5	4,5
Colour	–	Black	Black	Black
Environment and standards				
Ambient temperature <sup>4)</sup>	°C	–40 ... 85	–40 ... 85	–40 ... 85
Degree of protection	–	IP 69K/66M		
Standards / EMC	–	EN61000-6-2:2005, EN61000-6-4:2007/A1:2001		
Salt spray test	–	ISO 9227:2012, 250 hours		

<sup>1)</sup> Upper limit of the pull/push force limited by the clutch. The lower limit is just above the rated force. The limitation of the force will happen between these 2 limits

<sup>2)</sup> The holding force is the highest load a powered-down actuator can statically hold without slipping backwards. Ultimate Static Load, refer to the "Static load" diagrams

<sup>3)</sup> The data of speed and current on this list is defined at +20 °C

<sup>4)</sup> Full performance from 0 °C to +40 °C

Designation	Unit	CAHB-20S / 12 V			CAHB-20S / 24 – 48 V		
Performance data							
Rated Push Force	N	1 500	2 500	4 500	1 500	2 500	4 500
Rated Pull Force	N	1 500	2 500	4 500	1 500	2 500	4 500
Max pull / push Force <sup>1)</sup>	N	2 600	3 800	6 300	2 600	3 800	6 300
Holding force <sup>2)</sup>	N						
Speed without load <sup>3)</sup>	mm/s	27,0	23,5	13,5	29,0	22,0	13,0
Speed with the rated force <sup>3)</sup>	mm/s	24,5	17,5	10,5	25,5	19,0	11,0
Electric data							
Nominal voltage <sup>4)</sup>	V DC	12	12	12	24 – 48	24 – 48	24 – 48
Nominal current <sup>3)</sup>	A	12,5	15,0	17,0	5,0 – 2,5	6,5 – 3,3	8,0 – 4,0
Max. current, rated current <sup>5)</sup>	A	31,3	31,3	31,3	20,7 – 10,4	20,7 – 10,4	20,7 – 10,4
Duty cycle <sup>6)</sup>	%	10	10	10	20	20	20
ON time / OFF time	s	85/765	85/765	85/765	85/340	85/340	85/340
Mechanical data							
Stroke	mm	50 ... 700	50 ... 700	50 ... 700	50 ... 700	50 ... 700	50 ... 700
Backlash	mm	0,6	0,6	0,6	0,6	0,6	0,6
Max. manual override torque	Nm	1,5	1,2	1,0	1,5	1,2	1,0
Max. manual override speed	rpm	1 600	1 600	1 600	1 600	1 600	1 600
Weight for 200 mm stroke	kg	4,8	4,8	4,8	4,8	4,8	4,8
Colour	–	Black	Black	Black	Black	Black	Black
Environment and standards							
Ambient temperature <sup>7)</sup>	°C	–40 ... 85	–40 ... 85	–40 ... 85	–40 ... 85	–40 ... 85	–40 ... 85
Degree of protection	–	IP69K/66M					
Standards / EMC	–	refer to environmental performances - electrical tests, page 55					
Salt spray test	–	ISO 9227:2012 500 hours					

<sup>1)</sup> Upper limit of the pull/push force, limited by the E-clutch.

<sup>2)</sup> The holding force is the highest load a powered-down actuator can statically hold without slipping backwards. Ultimate static load, refer to the "Static load" diagrams.

<sup>3)</sup> The data of speed and current on this list is defined temperature at +20°C, PWM 100%

<sup>4)</sup> 12 V version use 12 V DC motor, 24 – 48 V version use 24 V DC motor.

<sup>5)</sup> Max. current is the upper limit of the input current to the actuator. In any circumstances, the current will not exceed to max. current.

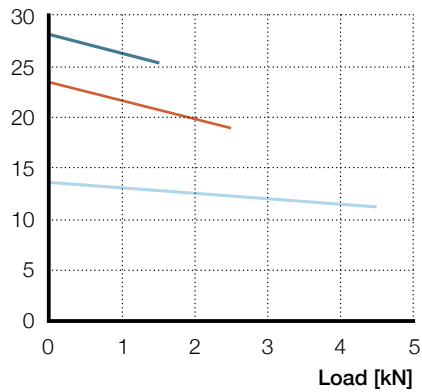
<sup>6)</sup> Duty cycle is defined temperature at +20°C.

<sup>7)</sup> Full performance from 0°C to +40°C

## Performance diagrams

Speed-Load diagram

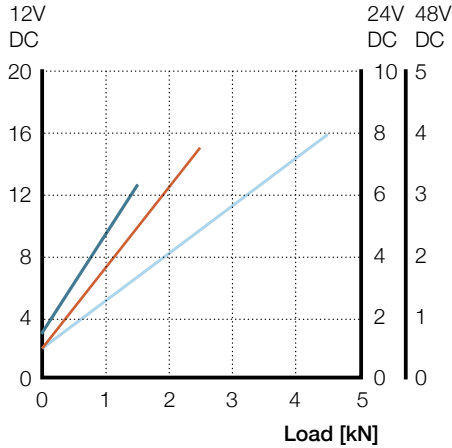
Speed [mm/s]



— CAHB-20-x1E  
— CAHB-20-x2E  
— CAHB-20-x3E

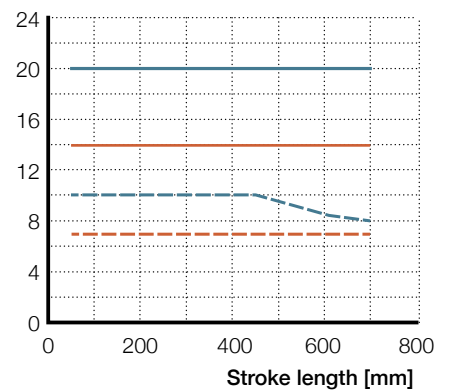
Current-Load diagram

Current consumption [A]



Static load-Stroke length

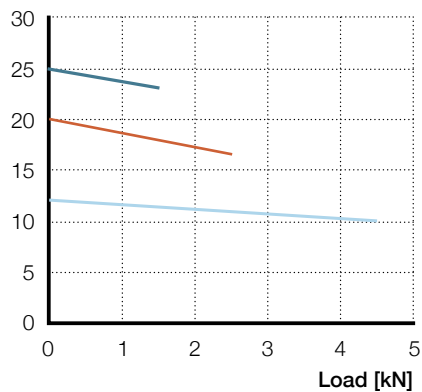
Load [kN]



— Ultimate CAHB-20-xxE (pull)  
- - Ultimate CAHB-20-xxE (push)  
— Recommended CAHB 20-xxE (pull)  
- - Recommended CAHB 20-xxE (push)

Speed-Load diagram

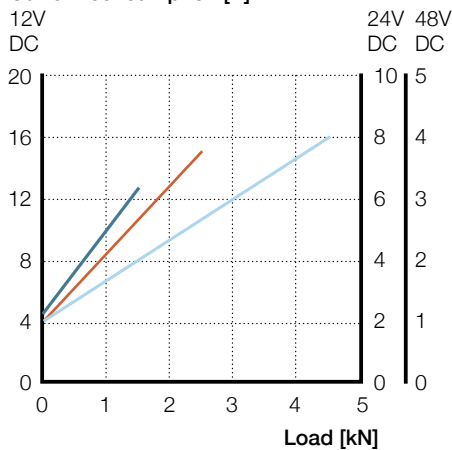
Speed [mm/s]



— CAHB-20-x1S  
— CAHB-20-x2S  
— CAHB-20-x3S

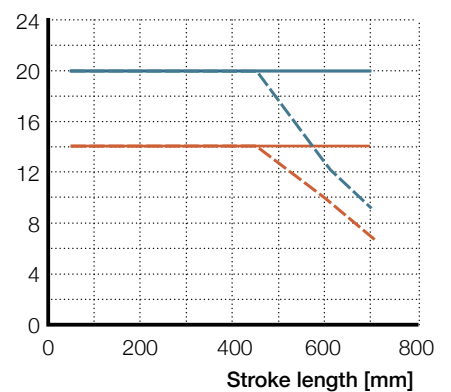
Current-Load diagram

Current consumption [A]



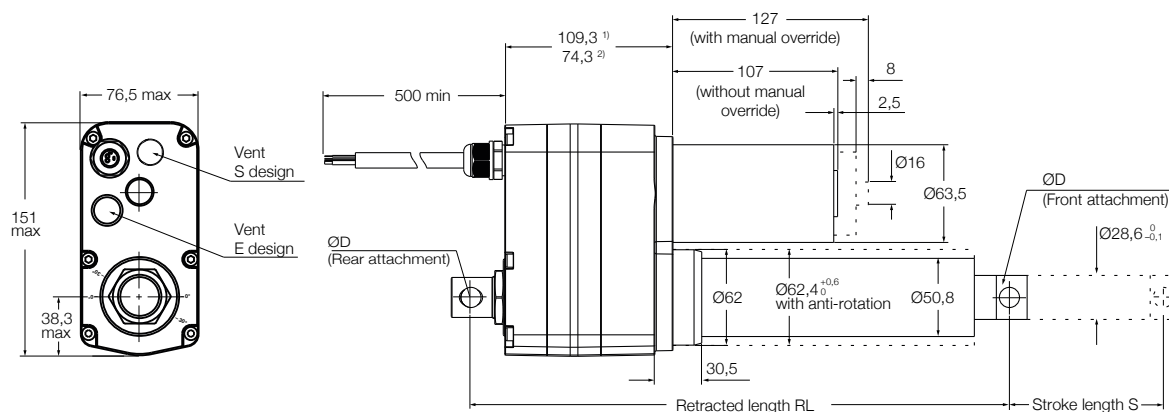
Static load-Stroke length

Load [kN]



— Ultimate CAHB-20-xxS (pull)  
- - Ultimate CAHB-20-xxS (push)  
— Recommended CAHB-20-xxS (pull)  
- - Recommended CAHB-20-xxS (push)

## Dimensional drawing CAHB-20E and -20S



<sup>1)</sup> 109,3 for E design with position output

<sup>2)</sup> 74,3 for E design without position output and S design

	Stroke tolerance	Retracted length tolerance
E design	±2	±2
S design	±1	±1

## Retracted length calculation (RL)

	Baseline: Rod with hole attachment		Fork head attachment	Anti-rotation tube with free spinning front attachment		Rod end Spherical plain bearing with anti rotation tube	
Stroke [mm]	50-305	306-700	50-700	50-305	306-700	50-305	306-700
CAHB-20E							
Retracted length (RL) no position output <sup>1)</sup>	160 + S	211 + S	+12	+5	-11	+47	+19
Retracted length (RL) with position output <sup>2)</sup>	195 + S	246 + S	+12	+5	-11	+47	+19
CAHB-20S							
Retracted length (RL)	167+S	202+S	+12	+0	+0	+43	+33

Example for Ordering key, in **red** baseline configuration:

<sup>1)</sup> **160 + 50** (stroke) **+12** (Fork head attachment) **+5** (Anti-rotation tube with free spinning front attachment) = **227**

<sup>2)</sup> **246 + 400** (stroke) **+19** (Rod end Spherical plain bearing with anti rotation tube) = **665**

# CAHB-21E and -21S

## Linear actuator

### Benefits

- High productivity
- Reliability and safety
- Save development time
- Cost effectiveness
- Quick time to market (for Smart version)

### Features:

- High holding force
- High speed
- Mechanical overload protection
- Corrosion protection and stainless steel tube
- Manual override option
- Enhanced ingress protection, virtually maintenance free



### Smart version S features

- Integrated controller with complete motion control
- True absolute position contactless sensor
- Monitoring and on board diagnostic (force, voltage, temperature)
- I/O and CAN bus SAE J1939 communication

### Technical data

Designation	Unit	CAHB-21E / 12 V			CAHB-21E / 24 V		
Performance data							
Rated Push Force	N	1 500	2 500	4 500	1 500	2 500	4 500
Rated Pull Force	N	1 500	2 500	4 500	1 500	2 500	4 500
Max pull / push Force <sup>1)</sup>	N	2 500	3 600	6 300	2 500	3 600	6 300
Holding force <sup>2)</sup>	N						
Speed without load <sup>3)</sup>	mm/s	49,5	37	24,0	52,5	38	22,5
Speed with the rated force <sup>3)</sup>	mm/s	43	31,5	19,0	50	31,5	21,0
Electric data							
Nominal voltage	V DC	12	12	12	24	24	24
Nominal current @ rated load <sup>3)</sup>	A	14,5	16	19	7	7,5	10,5
Rated current (clutch activation)	A	19,2	20,2	24,8	9,1	9,3	13,7
Duty cycle <sup>4)</sup>	%	10	10	10	20	20	20
ON time / OFF time	s	85/765	85/765	85/765	85/340	85/340	85/340
Mechanical data							
Stroke	mm	50 ... 700	50 ... 700	50 ... 700	50 ... 700	50 ... 700	50 ... 700
Backlash	mm	0,6	0,6	0,6	0,6	0,6	0,6
Weight for 200 mm stroke	kg	4,8	4,8	4,8	4,8	4,8	4,8
Colour	–	Black	Black	Black	Black	Black	Black
Environment and standards							
Ambient temperature <sup>5)</sup>	°C	–25...85	–25...85	–25...85	–25...85	–25...85	–25...85
Degree of protection	–	IP 69K/66M					
Standards / EMC	–	EN61000-6-2:2005, EN61000-6-4:2007/A1:2011					
Salt spray test	–	ISO 9227:2012, 250 hours					

<sup>1)</sup> Upper limit of the pull/push force limited by the clutch. The lower limit is just above the rated force. The limitation of the force will happen between these 2 limits

<sup>2)</sup> The holding force is the highest load a powered-down actuator can statically hold without slipping backwards. Ultimate Static Load, refer to the "Static load" diagrams

<sup>3)</sup> The data of speed and current on this list is defined at +20 °C

<sup>4)</sup> Duty cycle: actuator output force and actuator movement are in the same way direct, otherwise, duty cycle is 10% (25 s ON / 225 s OFF)

<sup>5)</sup> Full performance from 0 °C to +40 °C contact Ewellix for application operating at low temperature (-40 to -25°C)

Designation	Unit	CAHB-21E / 48 V		
Performance data				
Rated Push Force	N	1 500	2 500	4 500
Rated Pull Force	N	1 500	2 500	4 500
Max pull / push Force <sup>1)</sup>	N	2 500	3 600	6 300
Holding force <sup>2)</sup>	N			
Speed without load <sup>3)</sup>	mm/s	51,5	41,0	23,5
Speed with the rated force <sup>3)</sup>	mm/s	46,0	33,5	19,0
Electric data				
Nominal voltage	V DC	48	48	48
Nominal current @ rated load <sup>3)</sup>	A	4,0	4,5	5,0
Rated current (clutch activation)	A	5,6	6,1	6,4
Duty cycle <sup>4)</sup>	%	20	20	20
ON time / OFF time	s	85/340	85/340	85/340
Mechanical data				
Stroke	mm	50 ... 700	50 ... 700	50 ... 700
Backlash	mm	0,6	0,6	0,6
Weight for 200 mm stroke	kg	4,8	4,8	4,8
Colour	–	Black	Black	Black
Environment and standards				
Ambient temperature <sup>5)</sup>	°C	–25...85	–25...85	–25...85
Degree of protection	–	IP 69K/66M		
Standards / EMC	–	EN61000-6-2:2005, EN61000-6-4:2007/A1:2011		
Salt spray test	–	ISO 9227:2012, 250 hours		

<sup>1)</sup> Upper limit of the pull/push force limited by the clutch. The lower limit is just above the rated force. The limitation of the force will happen between these 2 limits

<sup>2)</sup> The holding force is the highest load a powered-down actuator can statically hold without slipping backwards. Ultimate Static Load, refer to the "Static load" diagrams

<sup>3)</sup> The data of speed and current on this list is defined at +20 °C

<sup>4)</sup> Duty cycle: actuator output force direction is same with the actuator movement direction. otherwise, duty cycle is 10%(25 s ON / 225 s OFF)

<sup>5)</sup> Full performance from 0 °C to +40 °C, contact Ewellix for application operating at low temperature (-40 to -25°C)

Designation	Unit	CAHB-21S / 12 V			CAHB-21S / 24 – 48 V		
Performance data							
Rated Push Force	N	1 500	2 500	4 500	1 500	2 500	4 500
Rated Pull Force	N	1 500	2 500	4 500	1 500	2 500	4 500
Max pull / push Force <sup>1)</sup>	N	2 500	3 600	6 300	2 500	3 600	6 300
Holding force <sup>2)</sup>	N						
Speed without load <sup>3)</sup>	mm/s	49,5	37,0	24,0	52,5	38,0	22,5
Speed with the rated force <sup>3)</sup>	mm/s	43,0	31,5	19,0	50,0	31,5	21,0
Electric data							
Nominal voltage <sup>4)</sup>	V DC	12	12	12	24 – 48	24 – 48	24 – 48
Nominal current <sup>3)</sup>	A	14,5	16,0	19,0	7,0 – 3,5	7,5 – 3,8	10,5 – 5,3
Max. current, rated current <sup>5)</sup>	A	31,3	31,3	31,3	20,7 – 10,4	20,7 – 10,4	20,7 – 10,4
Duty cycle <sup>6)</sup>	%	10	10	10	20	20	20
ON time / OFF time	s	85/765	85/765	85/765	85/340	85/340	85/340
Mechanical data							
Stroke	mm	50 ... 700	50 ... 700	50 ... 700	50 ... 700	50 ... 700	50 ... 700
Backlash	mm	0,6	0,6	0,6	0,6	0,6	0,6
Max. manual override torque	Nm	1,0	1,0	1,0	1,0	1,0	1,0
Max. manual override speed	rpm	1 600	1 600	1 600	1 600	1 600	1 600
Weight for 200 mm stroke	kg	4,8	4,8	4,8	4,8	4,8	4,8
Colour	–	Black	Black	Black	Black	Black	Black
Environment and standards							
Ambient temperature <sup>7)</sup>	°C	–25...85	–25...85	–25...85	–25...85	–25...85	–25...85
Degree of protection	–	IP69K/66M					
Standards / EMC	–	Refer to environmental performances - electrical tests, page 55					
Salt spray test	–	ISO 9227:2012 500 hours					

<sup>1)</sup> Upper limit of the pull/push force, limited by the E-clutch.

<sup>2)</sup> The holding force is the highest load a powered-down actuator can statically hold without slipping backwards. Ultimate static load, refer to the "Static load" diagrams.

<sup>3)</sup> The data of speed and current on this list is defined temperature at +20°C, PWM 100%

<sup>4)</sup> 12 V version use 12 V DC motor, 24 – 48 V version use 24 V DC motor

<sup>5)</sup> Max. current is the upper limit of the input current to the actuator. In any circumstances, the current will not exceed to max. current.

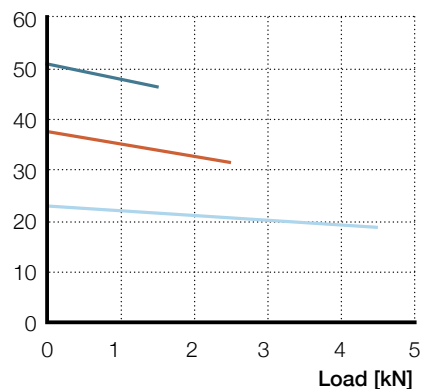
<sup>6)</sup> Duty cycle is defined temperature at +20° C, and actuator output force direction is same with the actuator movement direction. otherwise, duty cycle is 10%(25 s ON / 225 s OFF)

<sup>7)</sup> Full performance from 0°C to +40°C, contact Ewellix for application operating at low temperature (-40 to -25°C)

## Performance diagrams

Speed-Load diagram

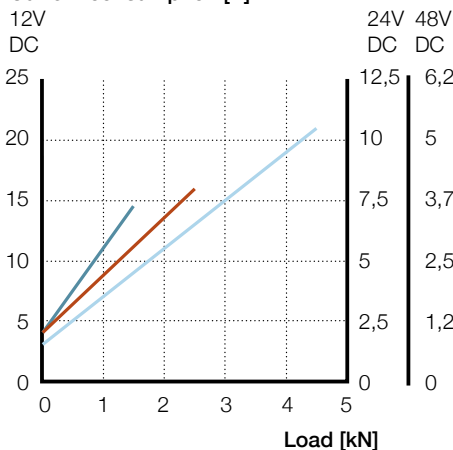
Speed [mm/s]



— CAHB-21-x1E  
— CAHB-21-x2E  
— CAHB-21-x3E

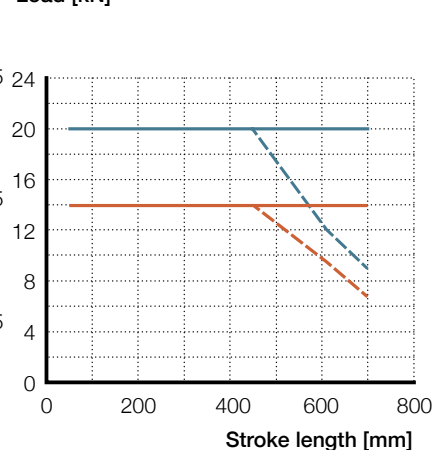
Current-Load diagram

Current consumption [A]



Static load-Stroke length

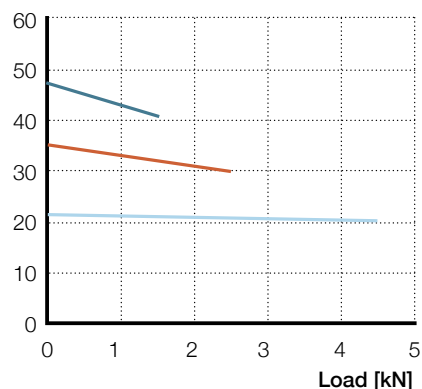
Load [kN]



— Ultimate CAHB-21-xxE (pull)  
- - Ultimate CAHB-21-xxE (push)  
— Recommended CAHB 21-xxE (pull)  
- - Recommended CAHB 21-xxE (push)

Speed-Load diagram

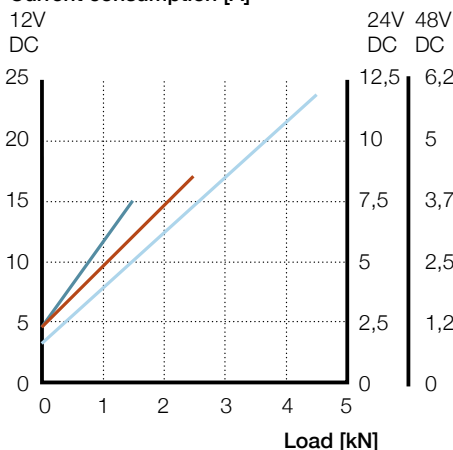
Speed [mm/s]



— CAHB-21-x1S  
— CAHB-21-x2S  
— CAHB-21-x3S

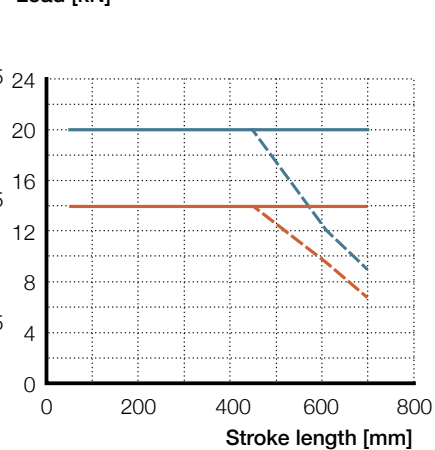
Current-Load diagram

Current consumption [A]



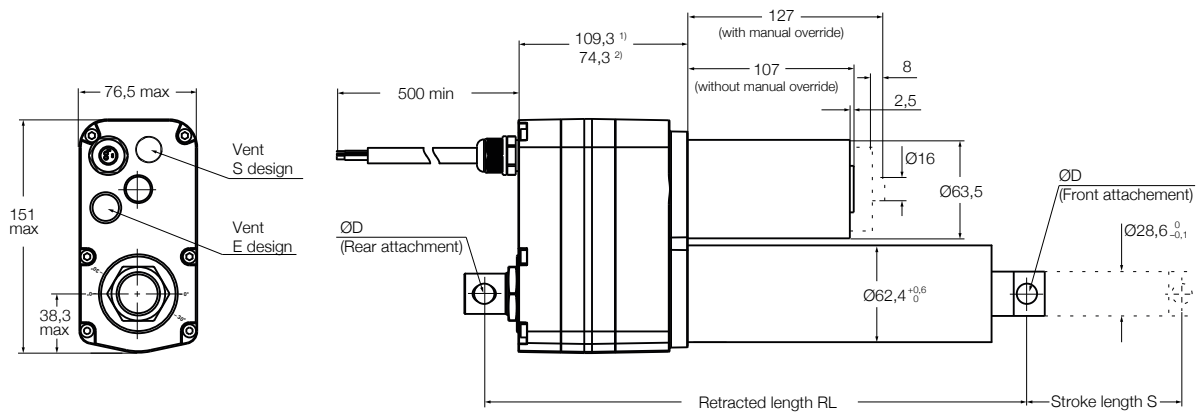
Static load-Stroke length

Load [kN]



— Ultimate CAHB-21-xxS (pull)  
- - Ultimate CAHB-21-xxS (push)  
— Recommended CAHB-21-xxS (pull)  
- - Recommended CAHB-21-xxS (push)

## Dimensional drawing CAHB-21E and -21S



<sup>1)</sup> 109,3 for E design with position output

<sup>2)</sup> 74,3 for E design without position output and S design

	Stroke tolerance	Retracted length tolerance
E design with LS (S≤305)	±2	±2
E design without LS (S≤305)	(-2, -0.5)	±2
E design with LS (S>305)	±3	±2
E design without LS (S>305)	(-3, -1)	±2
S design	±1	±1

## Retracted length calculation (RL)

	Baseline: Rod with hole attachment		Fork head attachment	Anti-rotation tube with free spinning front attachment	Rod end Spherical plain bearing with anti rotation tube	
S Stroke [mm]	50-305	306-700	50-700	50-700	50-305	306-700
CAHB-21E						
Retracted length (RL) no option <sup>1)</sup>	182+S	217+S	+12	+1	+43	+31
Retracted length (RL) with LS	191+S	226+S	+12	+1	+43	+31
Retracted length (RL) with position output	217+S	252+S	+12	+1	+43	+31
Retracted length (RL) with LS and position output <sup>2)</sup>	226+S	261+S	+12	+1	+43	+31
CAHB-21S						
Retracted length (RL)	182+S	217+S	+12	+0	+43	+33

Example for Ordering key, in **red** baseline configuration:

<sup>1)</sup> **182 + 50** (stroke) + **12** (Fork head attachment) + **1** (Anti-rotation tube with free spinning front attachment) = **245**

<sup>2)</sup> **261 + 400** (stroke) + **31** (Rod end Spherical plain bearing with anti rotation tube) = **692**



# CAHB-22E and -22S

## Linear actuator

### Benefits

- High productivity
- Reliability and safety
- Save development time
- Cost effectiveness
- Quick time to market (for Smart version)

### Features

- High force
- High speed
- High holding force
- Mechanical overload protection
- Corrosion protection and stainless steel tube
- Manual override option
- Enhanced ingress protection, virtually maintenance free



### Smart version S features

- Integrated controller with complete motion control
- True absolute position contactless sensor
- Monitoring and onboard diagnostic (force, voltage, temperature)
- I/O and CAN bus SAE J1939 communication

### Technical data

Designation	Unit	CAHB-22E / 12 V				CAHB-22E / 24 V			
Performance data									
Rated Push Force	N	2 300	3 500	6 800	10 000	2 300	3 500	6 800	10 000
Rated Pull Force	N	2 300	3 500	6 800	10 000	2 300	3 500	6 800	10 000
Max pull / push Force <sup>1)</sup>	N	3 500	4 900	9 500	14 000	3 500	4 900	9 500	14 000
Holding force <sup>2)</sup>	N								
Speed without load <sup>3)</sup>	mm/s	55,0	45,0	22,0	13,0	53,0	45,0	22,0	13,0
Speed with the rated force <sup>3)</sup>	mm/s	42,0	36,0	15,5	10,2	42,0	37,0	17,0	10,2
Electric data									
Nominal voltage	V DC	12	12	12	12	24	24	24	24
Nominal current @ rated load <sup>3)</sup>	A	18	19,5	19,5	19	8	9,5	9,5	8,5
Rated current (clutch activation)	A	24,3	25,5	25,5	25	10,6	12,3	12,3	10,9
Duty cycle <sup>4)</sup>	%	10	10	10	10	20	20	20	20
ON time / OFF time	s	85/765	85/765	85/765	85/765	85/340	85/340	85/340	85/340
Mechanical data									
Stroke	mm	50 ... 700	50 ... 700	50 ... 610	50 ... 450	50 ... 700	50 ... 700	50 ... 610	50 ... 450
Backlash	mm	1,0	1,0	0,6	0,6	1,0	1,0	0,6	0,6
Weight for 200 mm stroke	kg	4,8	4,8	4,8	4,8	4,8	4,8	4,8	4,8
Colour	–	Black	Black	Black	Black	Black	Black	Black	Black
Environment and standards									
Ambient temperature	°C	–25...85	–25...85	–25...85	–25...85	–25...85	–25...85	–25...85	–25...85
Degree of protection	–	IP 69K/66M							
Standards / EMC	–	EN61000-6-2:2005, EN61000-6-4:2007/A1:2011							
Salt spray test	–	ISO 9227:2012, 250 hours							

<sup>1)</sup> Upper limit of the pull/push force limited by the clutch. The lower limit is just above the rated force. The limitation of the force will happen between these 2 limits

<sup>2)</sup> The holding force is the highest load a powered-down actuator can statically hold without slipping backwards. Ultimate Static Load, refer to the "Static load" diagrams

<sup>3)</sup> The data of speed and current on this list is defined at +20 °C

<sup>4)</sup> Duty cycle: actuator output force direction is same with the actuator movement direction. otherwise, duty cycle is 10%(25 s ON / 225 s OFF)

<sup>5)</sup> Full performance from 0 °C to +40 °C, contact Ewellix for application operating at low temperature (-40 to -25°C)

Designation	Unit	CAHB-22E / 48 V			
Performance data					
Rated Push Force	N	2 300	3 500	6 800	10 000
Rated Pull Force	N	2 300	3 500	6 800	10 000
Max pull / push Force <sup>1)</sup>	N	3 500	4 900	9 500	14 000
Holding force <sup>2)</sup>	N				
Speed without load <sup>3)</sup>	mm/s	57,0	45,0	22,0	13,0
Speed with the rated force <sup>3)</sup>	mm/s	50,0	37,0	18,5	10,2
Electric data					
Nominal voltage	V DC	48	48	48	48
Nominal current @ rated load <sup>3)</sup>	A	4,5	5	5	4,3
Rated current (clutch activation)	A	6,5	7	7	5,5
Duty cycle <sup>4)</sup>	%	20	20	20	20
ON time / OFF time	s	85/340	85/340	85/340	85/340
Mechanical data					
Stroke	mm	50 ... 700	50 ... 700	50 ... 610	50 ... 450
Backlash	mm	1,0	1,0	0,6	0,6
Weight for 200 mm stroke	kg	4,8	4,8	4,8	4,8
Colour	–	Black	Black	Black	Black
Environment and standards					
Ambient temperature <sup>5)</sup>	°C	–25...85	–25...85	–25...85	–25...85
Degree of protection	–	IP 69K/66M			
Standards / EMC	–	EN61000-6-2:2005, EN61000-6-4:2007/A1:2011			
Salt spray test	–	ISO 9227:2012, 250 hours			

<sup>1)</sup> Upper limit of the pull/push force limited by the clutch. The lower limit is just above the rated force. The limitation of the force will happen between these 2 limits

<sup>2)</sup> The holding force is the highest load a powered-down actuator can statically hold without slipping backwards. Ultimate Static Load, refer to the "Static load" diagrams

<sup>3)</sup> The data of speed and current on this list is defined at +20 °C

<sup>4)</sup> Duty cycle: actuator output force direction is same with the actuator movement direction. otherwise, duty cycle is 10%(25 s ON / 225 s OFF)

<sup>5)</sup> Full performance from 0 °C to +40 °C, contact Ewellix for application operating at low temperature (-40 to -25°C)

Designation	Unit	CAHB-22S / 12 V				CAHB-22S / 24 – 48 V			
Performance data									
Rated Push Force	N	2 300	3 500	6 800	10 000	2 300	3 500	6 800	10 000
Rated Pull Force	N	2 300	3 500	6 800	10 000	2 300	3 500	6 800	10 000
Max pull / push Force <sup>1)</sup>	N	3 500	4 900	9 500	14 000	3 500	4 900	9 500	14 000
Holding force <sup>2)</sup>	N								
Speed without load <sup>3)</sup>	mm/s	55,0	45,0	22,0	13,0	53,0	45,0	22,0	13,0
Speed with the rated force <sup>3)</sup>	mm/s	42,0	36,0	15,5	10,2	42,0	37,0	17,0	10,2
Electric data									
Nominal voltage <sup>4)</sup>	V DC	12	12	12	12	24 – 48	24 – 48	24 – 48	24 – 48
Nominal current <sup>3)</sup>	A	18,0	19,5	19,5	19,0	8,0 – 4,0	9,5 – 4,8	9,5 – 4,8	8,5 – 4,3
Max. current, rated current <sup>5)</sup>	A	31,3	31,3	31,3	31,3	20,7 – 10,4	20,7 – 10,4	20,7 - 10,4	20,7 - 10,4
Duty cycle <sup>6)</sup>	%	10	10	10	10	20	20	20	20
ON time / OFF time	s	85/765	85/765	85/765	85/765	85/340	85/340	85/340	85/340
Mechanical data									
Stroke	mm	50 ... 700	50 ... 700	50 ... 610	50 ... 450	50 ... 700	50 ... 700	50 ... 610	50 ... 450
Backlash	mm	1,0	1,0	0,6	0,6	1,0	1,0	0,6	0,6
Max. manual override torque	Nm	1,0	1,0	1,0	1,0	1,0	1,0	1,0	1,0
Max. manual override speed	rpm	1 600	1 600	1 600	1 600	1 600	1 600	1 600	1 600
Weight for 200 mm stroke	kg	4,8	4,8	4,8	4,8	4,8	4,8	4,8	4,8
Colour	–	Black	Black	Black	Black	Black	Black	Black	Black
Environment and standards									
Ambient temperature <sup>7)</sup>	°C	–25...85	–25...85	–25...85	–25...85	–25...85	–25...85	–25...85	–25...85
Degree of protection	–	IP69K/66M							
Standards / EMC	–	refer to environmental performances - electrical tests, page 55							
Salt spray test	–	ISO 9227:2012 500 hours							

<sup>1)</sup> Upper limit of the pull/push force, limited by the E-clutch.

<sup>2)</sup> The holding force is the highest load a powered-down actuator can statically hold without slipping backwards. Ultimate static load, refer to the "Static load" diagrams.

<sup>3)</sup> The data of speed and current on this list is defined temperature at +20°C, PWM 100%

<sup>4)</sup> 12 V version use 12 V DC motor, 24 – 48 V version use 24 V DC motor.

<sup>5)</sup> Max. current is the upper limit of the input current to the actuator. In any circumstances, the current will not exceed to max. current.

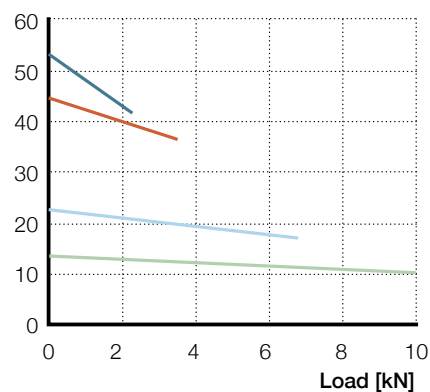
<sup>6)</sup> Duty cycle is defined temperature at +20°C, and actuator output force direction is same with the actuator movement direction. otherwise, duty cycle is 10%(25 s ON / 225 s OFF)

<sup>7)</sup> Full performance from 0°C to +40°C, contact Ewellix for application operating at low temperature (-40 to -25°C)

## Performance diagrams

Speed-Load diagram

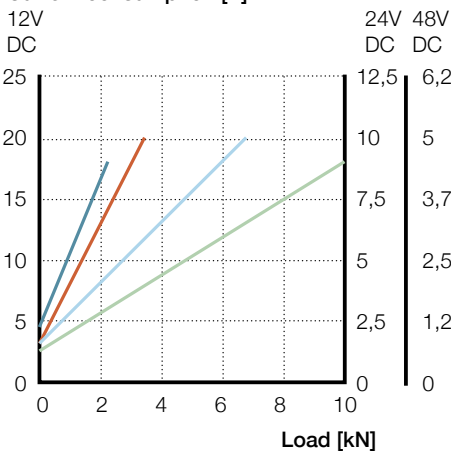
Speed [mm/s]



- CAHB-22-x1E
- CAHB-22-x2E
- CAHB-22-x3E
- CAHB-22-x4E

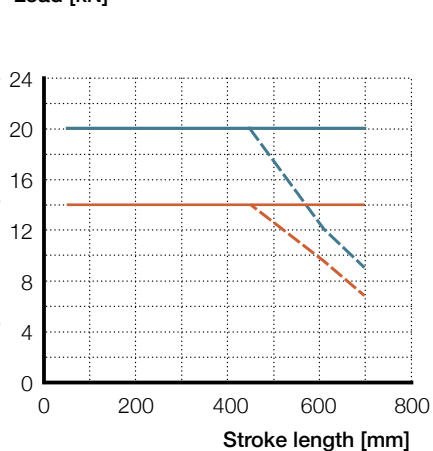
Current-Load diagram

Current consumption [A]



Static load-Stroke length

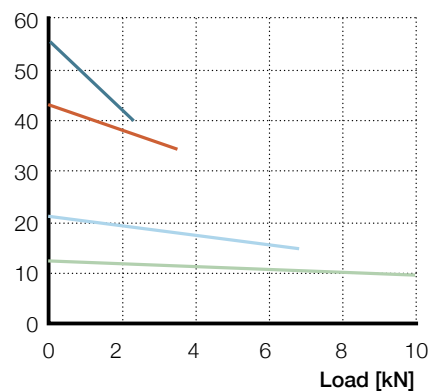
Load [kN]



- Ultimate CAHB-22-xxE (pull)
- - Ultimate CAHB-22-xxE (push)
- Recommended CAHB 22-xxE (pull)
- - Recommended CAHB 22-xxE (push)

Speed-Load diagram

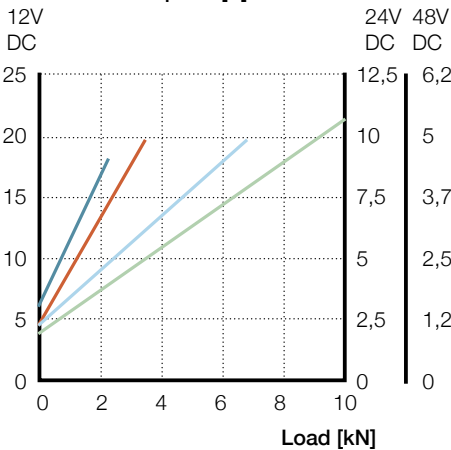
Speed [mm/s]



- CAHB-22-x1S
- CAHB-22-x2S
- CAHB-22-x3S
- CAHB-22-x4S

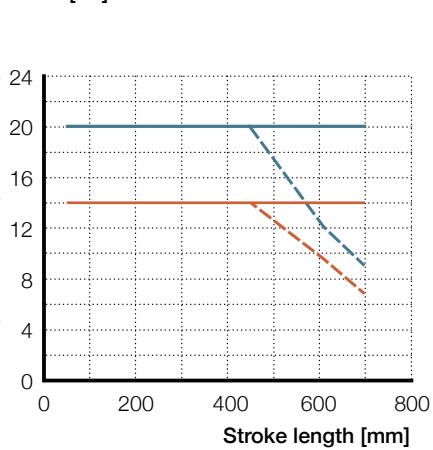
Current-Load diagram

Current consumption [A]



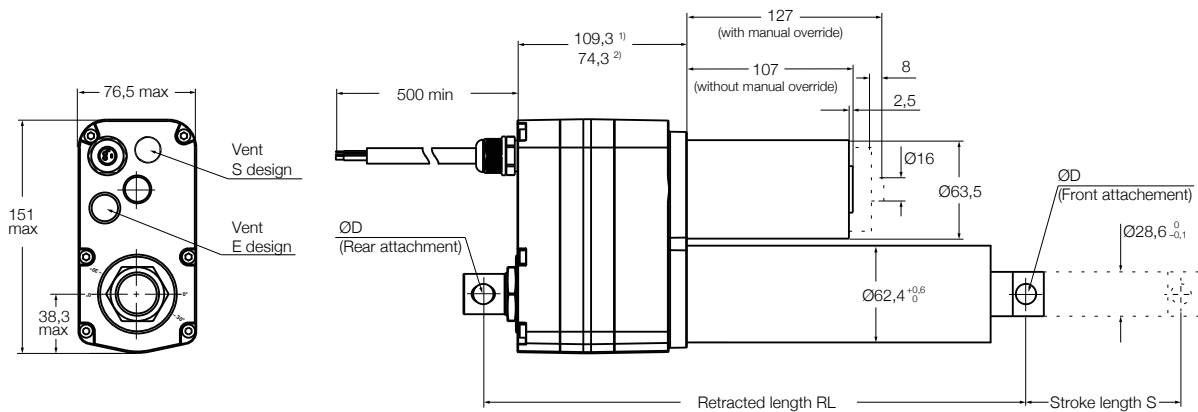
Static load-Stroke length

Load [kN]



- Ultimate CAHB-22-xxS (pull)
- - Ultimate CAHB-22-xxS (push)
- Recommended CAHB-22-xxS (pull)
- - Recommended CAHB-22-xxS (push)

## Dimensional drawing CAHB-22E and -22S



<sup>1)</sup> 109,3 for E design with position output

<sup>2)</sup> 74,3 for E design without position output and S design

	Stroke tolerance	Retracted length tolerance
E design with LS (S≤305)	±2	(0, +4)
E design without LS, 1E/2E (S≤305)	(-3, -1.5)	(0, +4)
E design without LS, 3E/4E (S≤305)	(-2, -0.5)	(0, +4)
E design with LS (S>305)	±3	(0, +4)
E design without LS, 1E/2E (S>305)	(-4, -2)	(0, +4)
E design without LS, 3E/4E (S>305)	(-3, -1)	(0, +4)
S design	±1	±1

## Retracted length calculation

Stroke [mm]	Baseline: Rod with hole attachment		Fork head attachment	Anti-rotation tube with free spinning front attachment	Rod end Spherical plain bearing with anti rotation tube	
	50-305	306-700	50-700	50-700	50-305	306-700
<b>CAHB-22E</b>						
Retracted length (RL) no option <sup>1)</sup>	194+S	229+S	+12	+7	+49	+37
Retracted length (RL) with LS	200+S	235+S	+12	+7	+49	+37
Retracted length (RL) with position output	229+S	264+S	+12	+7	+49	+37
Retracted length (RL) with LS and position output <sup>2)</sup>	235+S	270+S	+12	+7	+49	+37
<b>CAHB-22S</b>						
Retracted length (RL)	200+S	235+S	+12	+0	+43	+33

Example for Ordering key, in **red** baseline configuration:

<sup>1)</sup> **194 + 50** (stroke) + **12** (Fork head attachment) + **7** (Anti-rotation tube with free spinning front attachment) = **263**

<sup>2)</sup> **270 + 400** (stroke) + **37** (Rod end Spherical plain bearing with anti rotation tube) = **707**

# Electrical specifications (valid for CAHB-20E, -21E, -22E)

## Power input voltage tolerance

Power input	Tolerance
12 V DC version	10-16 V DC
24 V DC version	21-26 V DC
48 V DC version	40-55 V DC

## Wire connection without position output

Wire no.	AWG	Colour	Application
1	14	Red	Motor power(+) □ Extension, (-) □ Retraction
2	14	Black	Motor power(-) □ Extension, (+) □ Retraction

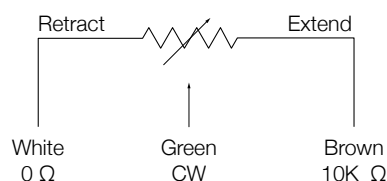
Cable reference standard: UL758, UL1581 & CSA C22.2 No. 210

## Wire connection with position output

Wire connection with potentiometer			
Wire no.	AWG	Colour	Application
1	22	Green	See picture description
2	22	White	See picture description
3	22	Brown	See picture description
4	14	Red	Motor power(+) □ Extension, (-) □ Retraction
5	14	Black	Motor power(-) □ Extension, (+) □ Retraction

Cable reference standard: UL758, UL1581 & CSA C22.2 No. 210

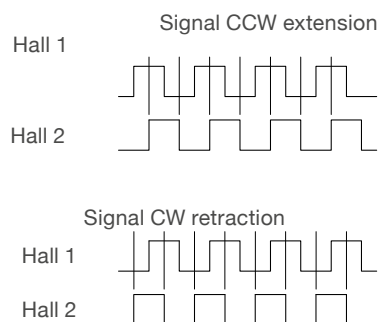
### Potentiometer



Wire connection with encoder			
Wire no.	AWG	Colour	Application
1	26	Green	Sensor signal 1 Encoder
2	26	Yellow	Sensor signal 2 Encoder
3	26	Black	Sensor power GND Encoder
4	26	Red	Sensor power 5 V Encoder
5	14	Red	Motor power(+) □ Extension, (-) □ Retraction
6	14	Black	Motor power(-) □ Extension, (+) □ Retraction

Cable reference standard: UL758, UL1581 & CSA C22.2 No. 210

### Encoder



Wire connection with absolute analog output			
Wire no.	AWG	Colour	Application
1	22	Green	Output signal
2	22	White	Sensor power GND
3	22	Brown	Sensor power +10~55 VDC
4	14	Red	Motor power(+) □ Extension, (-) □ Retraction
5	14	Black	Motor power(-) □ Extension, (+) □ Retraction

Cable reference standard: UL758, UL1581 & CSA C22.2 No. 210

### Absolut analog position output

Input voltage: 10~55 V DC

Current consumption: 15 mA max.

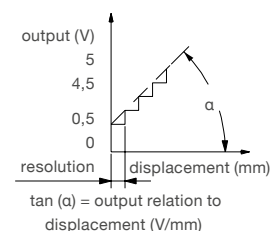
Output analog signal (voltage): 0~5 V DC

Max current output: 5 mA

Absolute analog output set up:

retracted  $0,5 \pm 0,15$  V

extended 4,5 V to the maximum



Output relation to displacement and resolution				
Actuator type	Hall sensor [pulses/mm]	Potentiometer [Ω/mm]	Absolute analogue position output [V/mm]	Resolution of the absolute analog position output [mm]
CAHB-20...E	2,76	59,06 if S=050-125	0,0295 if S=050-125	0,0413 if S=050-125
		29,53 if S=126-250	0,0148 if S=126-250	0,0827 if S=126-250
		9,84 if S=251-700	0,0049 if S=251-700	0,2480 if S=251-700
CAHB-21...E	1,56	33,33 if S=050-222	0,0167 if S=050-222	0,0732 if S=050-222
		16,67 if S=223-444	0,0083 if S=223-444	0,1465 if S=223-444
		5,56 if S=445-700	0,0028 if S=445-700	0,4395 if S=445-700
CAHB-22...1E	1,4	30 if S=050-254	0,0150 if S=050-254	0,0814 if S=050-254
CAHB-22...2E	1,4	15 if S=255-508	0,0075 if S=255-508	0,1628 if S=255-508
		5 if S=509-700	0,0025 if S=509-700	0,4883 if S=509-700
CAHB-22...3E	2,8	60 if S=050-127	0,030 if S=050-127	0,0407 if S=050-127
CAHB-22...4E	2,8	30 if S=128-254	0,015 if S=128-254	0,0814 if S=128-254
		10 if S=255-700	0,005 if S=255-700	0,2441 if S=255-700

# Electrical specifications (valid for CAHB-20S, -21S, -22S)

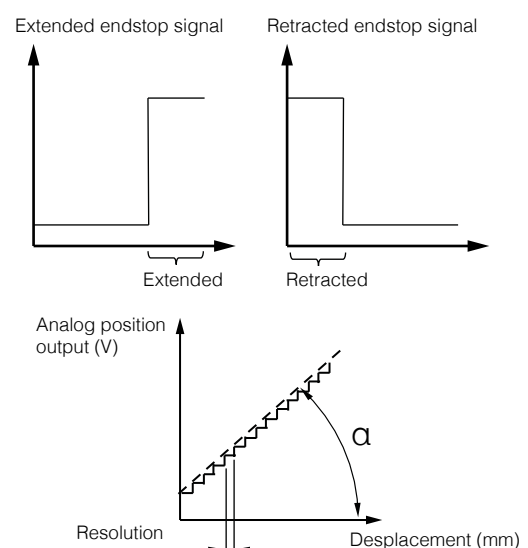
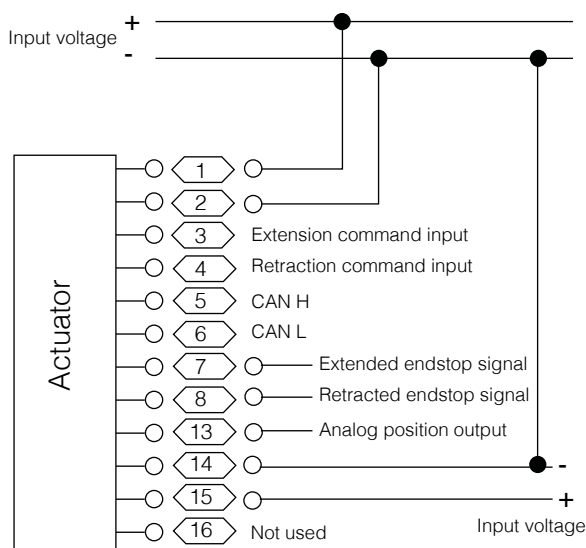
## CAN bus + I/O

Ordering key pages 37, 39, 41 (Cable and I/O Option 1: code A and code C)

Wire no.	AWG	Colour	Application
1	14	Red	Power (+) VCC Connect to positive 9 to 16 V DC (12 V version) 18 to 55 V DC (24 – 48 V version)
2	14	Black	Power (-) GND Connect to negative
3	26	Red	Extension command input High: 5 to 55 VDC Low: 0 to 1.19 VDC Max. current consumption: 1mA Delay before movement and stop: 50 ms
4	26	Black	Retraction command input High: 5 to 55 VDC Low: 0 to 1.19 VDC Max. current consumption: 1mA Delay before movement and stop: 50 ms
5	26	Yellow	CAN H (CAN bus J1939)
6	26	Blue	CAN L (CAN bus J1939)
7	26	Grey	End stop signal (Digital output, open collector) Normal (L): High-Z Extended (H): V power - 1.8 V Max. current consumption: 10 mA
8	26	Orange	End stop signal (Digital output, open collector) Normal (L): High-Z Retracted (H): V power - 1.8 V Max. current consumption: 10 mA
13	26	Green	Analog position signal output Retracted position: 0,5±0,02 V Extended position: 5 V or 10 V (default) Max. current output: 15 mA Ripple max: 200 mV Transaction delay: 20 ms Linear feedback 0,5% $\tan(\alpha)=4,5 / \text{stroke (V/mm)}$ , code A or 9,5 / stroke (V/mm), code C Resolution: 10 V / 4 000 / $\tan(\alpha)$
14	26	White	Analog position sensor power (-) GND Common ground with wire No. 2
15	26	Brown	Analog position sensor power (+) For 0~5 V position sensor output <sup>1)</sup> : 8 to 27 V DC For 0~10 V position sensor output <sup>1)</sup> : 13 to 27 V DC Max. current consumption: 15 mA
16	26	Purple	Reserved, not to be connected

<sup>1)</sup> Position sensor output to select by the ordering key

Cable reference standard: UL758, UL1581 & CSA C22.2 No. 210

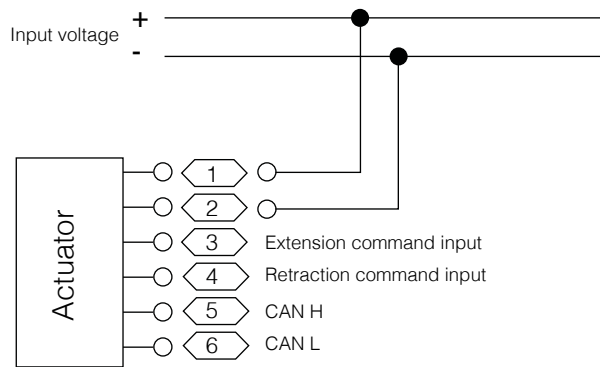


CAN bus + Input

Ordering key pages 37, 39, 41 (Cable and I/O Option 1: code B)

Wire no.	AWG	Colour	Application
1	14	Red	Power (+) VCC Connect to positive 9 to 16 V DC (12 V version) 18 to 55 V DC (24 – 48 V version)
2	14	Black	Power (-) GND Connect to negative
3	26	Red	Extension command input High: 5 to 55 VDC Low: 0 to 1.19 VDC Max. current consumption: 1mA Delay before movement and stop: 50 ms
4	26	Black	Retraction command input High: 5 to 55 VDC Low: 0 to 1.19 VDC Max. current consumption: 1mA Delay before movement and stop: 50 ms
5	26	Yellow	CAN H (CAN bus J1939)
6	26	Blue	CAN L (CAN bus J1939)

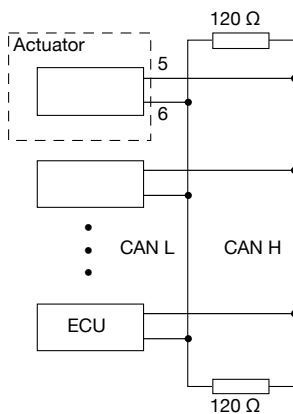
Cable reference standard: UL758, UL1581 & CSA C22.2 No. 210



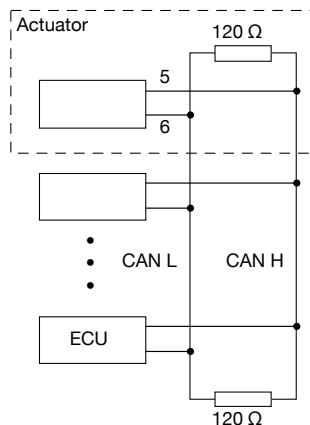
Termination resistance option

Ordering key pages 37, 39, 41 (Bus type Option 2)

Without termination resistor (code C)



With termination resistor (code T)



NOTE.

The CAN bus system of the vehicle request termination resistor.  
The CAHB 2xS could be equipped one.

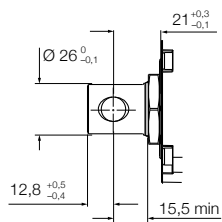


# Attachment option (valid for CAHB-20, -21, -22 E and S)

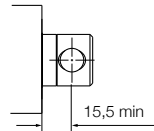
## Attachment type

### Rod end with hole (refer to ordering key Attachment diameter A - E)

#### Rear attachment

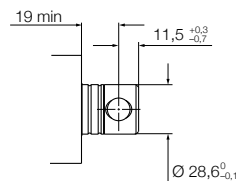


#### Front attachment without anti rotation tube

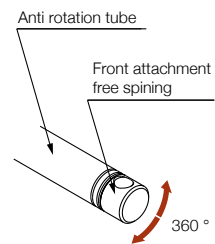


Attachment orientation: "A" to "F"

#### Front attachment with anti rotation tube



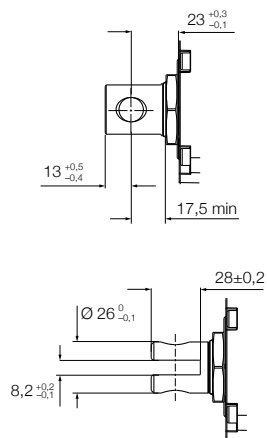
Attachment orientation: "G" to "L"



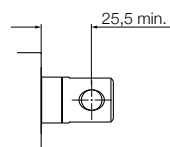
Hole version	A	B	C	D	E
Hole diameter Ø [mm]	13,1	12,8	12,5	14	12,2
Tolerance	H11	H11	H11	H11	H11

### Fork head with hole (refer to ordering key Attachment diameter F - G)

#### Rear attachment

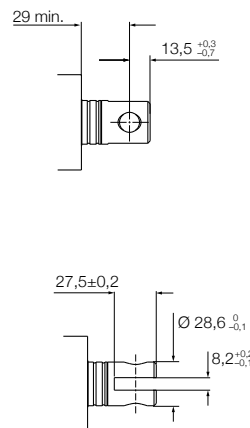


#### Front attachment without anti rotation tube

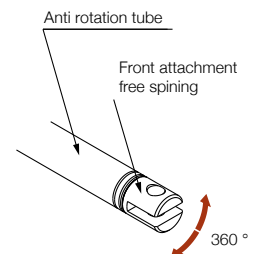


Attachment orientation: "A" to "F"

#### Front attachment with anti rotation tube



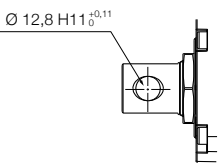
Attachment orientation: "G" to "L"



Hole version	F	G
Hole diameter Ø [mm]	12,2	12,8
Tolerance	H11	H11

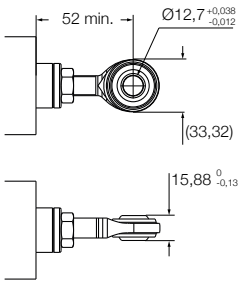
Rod end Spherical plain bearing (refer to ordering key Attachment diameter I)

Rear attachment



"I" and "B" have the same rear attachment

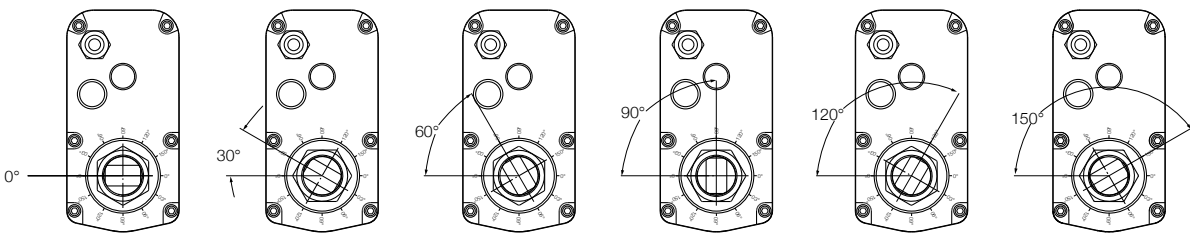
Front attachment with anti rotation tube



Attachment orientation: "G" to "L"

Hole version	I (Rear Attachment)	I (front Attachment)
Hole diameter Ø [mm]	12,8	12,7

Attachment orientation (refer to ordering key Attachment orientation)

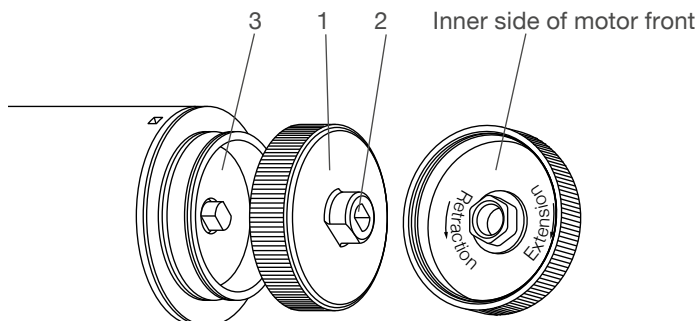


Orientation A / G      Orientation B / H      Orientation C / I      Orientation D / J      Orientation E / K      Orientation F / L

Attachment orientation	Description
A	0° without anti rotation tube
B	30° without anti rotation tube
C	60° without anti rotation tube
D	90° without anti rotation tube
E	120° without anti rotation tube
F	150° without anti rotation tube
G	0°: with anti rotation tube and free spinning front attachment
H	30° with anti rotation tube and free spinning front attachment
I	60° with anti rotation tube and free spinning front attachment
J	90° with anti rotation tube and free spinning front attachment
K	120° with anti rotation tube and free spinning front attachment
L	150° with anti rotation tube and free spinning front attachment

## Manual override

Release the motor cover (1). Use the slot (2) to rotate the motor shaft (3) in the proper direction



## List of function CAHB-20S, -21S, -22S

		CAHB-2xS only	CAN bus + I/O Ordering key Option 1 code A or C	CAN bus + Input Ordering key Option 1 code B
Interface	Voltage version	12 VDC	●	●
		24-48 VDC	●	●
	Cable	Power wires	2	2
		Low current wires	10	4
	BUS	CAN bus SAE J1939, 250 or 500 kbps <sup>1)</sup>	●	●
Functions	Motion	soft start / soft stop	●	●
	E clutch	Force limitation (calibration, temperature compensation)	●	●
	Adjustable end stops	Adjustable retracted and extended length by I/O and CAN bus	–	–
	Parallel motion	Drive actuator with the same length up to	2 pcs	2 pcs
Command	Command I/O	Motion Extend / Retract	●	●
	Command CAN bus J1939	Motion Extend / Retract	●	●
		Run to an actuator length in 1/10 mm	●	●
		Speed, command set in %	●	●
		Set max force in N	●	●
Real-time feedback	I/O End stop signal	End stop extended	●	–
		end stop retracted	●	–
	position feedback by I/O	0-10V or 0-5V absolute analog	●	–
	CAN bus J1939 feedback	Actuator length in 1/10 mm	●	●
		Force in N	●	●
		Speed in %	●	●
		Flag of Endstop retracted	●	●
		Flag of endstop extended	●	●
		Flag of run in retraction	●	●
		Flag of run in extension	●	●
Diagnostic by CAN bus (Onboard)	Application monitoring	Voltage upper limit reached	●	●
		Temperature upper limit reached	●	●
		Force upper limit reached	●	●
		Actuator blocking	●	●
	Integrity monitoring	Error code	●	●
Regulation and test	Compliance	CE marking, Declaration of incorporation for partly completed machine: RoHS, EMC + Reach	●	●
	Environmental test ( see pages 130-135)	Mechanic	Extended, see page 132	Extended, see page 132
		Climatic	Extended, see page 131	Extended, see page 131
		Electric	Extended, see page 134	Extended, see page 134
		Load Dump protection, chassis connected to negative terminal	●	●
		Load Dump protection, chassis not connected	●	●
		Reinforced load dump protection <sup>2)</sup> , chassis connected to negative terminal	Option for 12 VDC	Option for 12 VDC
		Reinforced load dump protection <sup>2)</sup> , chassis not connected	Option for 12 VDC	Option for 12 VDC

● Available

<sup>1)</sup> By default, the baud rate is 250 kbps. To change the CAN baud rate by CAN message, the ECU used for the setting must support both 500Kbps and 250Kbps.

<sup>2)</sup> For vehicle without centralized load dump protection

C

A

H

B

-

2

0

-

E

-

-

B

0

T

-

0

0

0

Type

Voltage

A

12 V DC

B

24 V DC

D

48 V DC

E

12 V DC with manual override

F

24 V DC with manual override

H

48 V DC with manual override

Load

1

1 500 N

2

2 500 N

3

4 500 N

Design

E

3 digital Stroke and 4 digital Retracted length (mm)

Stroke	Retracted length				
	Base <sup>1)</sup>	with Fork head F, G	with Spherical plain bearing <sup>2)</sup> I	with Anti rotation G to L	with Position output A, P, E
050	0210	+12	+42	+5	+35
100	0260	+12	+42	+5	+35
150	0310	+12	+42	+5	+35
200	0360	+12	+42	+5	+35
250	0410	+12	+42	+5	+35
300	0460	+12	+42	+5	+35
350	0561	+12	+30	-11	+35
400	0611	+12	+30	-11	+35
450	0661	+12	+30	-11	+35
500	0711	+12	+30	-11	+35
600	0811	+12	+30	-11	+35
700	0911	+12	+30	-11	+35

<sup>1)</sup> Base: the Retracted length with attachment "Rod end with hole", "without Anti rotation tube", without "Position output"  
<sup>2)</sup> With attachment "Spherical plain bearing", option "Anti rotation tube" is mandatory, the length "with Anti rotation" must be added to calculate the Retracted length

Ingress protection

B

Standard: IP69K/IP66M

Attachment diameter (Front and rear)

A

Rod end with hole Ø 13,1 mm

B

Rod end with hole Ø 12,8 mm

C

Rod end with hole Ø 12,5 mm

D

Rod end with hole Ø 14 mm

E

Rod end with hole Ø 12,2 mm

F

Fork head with hole Ø 12,2 mm and slot 8,2 mm

G

Fork head with hole Ø 12,8 mm and slot 8,2 mm

I

Rod end Spherical plain bearing Ø 12,7 mm, rear end with hole Ø 12,8 mm (request anti rotation tube option)

X

Customized

Attachment orientation (Front and rear)

A

0° without anti rotation tube

B

30° without anti rotation tube

C

60° without anti rotation tube

D

90° without anti rotation tube

E

120° without anti rotation tube

F

150° without anti rotation tube

G

0°: with anti rotation tube and free spinning front attachment

H

30° with anti rotation tube and free spinning front attachment

I

60° with anti rotation tube and free spinning front attachment

J

90° with anti rotation tube and free spinning front attachment

K

120° with anti rotation tube and free spinning front attachment

L

150° with anti rotation tube and free spinning front attachment

X

Customized

Option 1: Limit switch

0

Not available

Option 2: Position output

0

None

A

Absolute analog output

P

Potentiometer

E

Encoder

Thermal protection

T

Standard: Built-in thermal switch

Customization

Stroke length, retracted length, cable, connector, front attachment, rear attachment, color, de-rated load

Type	C A H B - 2 0 -										S -										0 0 0									
<b>Voltage</b>																														
A	12 V DC																													
B	24 – 48 V DC																													
E	12 V DC with manual override																													
F	24 – 48 V DC with manual override																													
<b>Load</b>																														
1	1 500 N																													
2	2 500 N																													
3	4 500 N																													
<b>Design</b>																														
S																														
<b>Stroke</b>																														
Stroke	Retracted length																													
	Base <sup>1)</sup>										with Fork head										with Spherical plain bearing									
											F, G										I									
050	0217										+12										+43									
100	0267										+12										+43									
150	0317										+12										+43									
200	0367										+12										+43									
250	0417										+12										+43									
300	0467										+12										+43									
350	0552										+12										+33									
400	0602										+12										+33									
450	0652										+12										+33									
500	0702										+12										+33									
600	0802										+12										+33									
700	0902										+12										+33									
<sup>1)</sup> Base: the Retracted length with attachment "Rod end with hole"																														
<b>Parallel operation self-controlled</b>																														
1	1 actuator run independently																													
2	2 actuators run simultaneously in parallel mode																													
<b>Attachment diameter (Front and rear)</b>																														
A	Rod end with hole Ø 13,1 mm																													
B	Rod end with hole Ø 12,8 mm																													
C	Rod end with hole Ø 12,5 mm																													
D	Rod end with hole Ø 14 mm																													
E	Rod end with hole Ø 12,2 mm																													
F	Fork head with hole Ø 12,2 mm and slot 8,2 mm																													
G	Fork head with hole Ø 12,8 mm and slot 8,2 mm																													
I	Rod end Spherical plain bearing Ø 12,7 mm, rear end with hole Ø 12,8 mm																													
X	Customized																													
<b>Attachment orientation (Front and rear)</b>																														
G	0° with anti rotation tube and free spinning front attachment																													
H	30° with anti rotation tube and free spinning front attachment																													
I	60° with anti rotation tube and free spinning front attachment																													
J	90° with anti rotation tube and free spinning front attachment																													
K	120° with anti rotation tube and free spinning front attachment																													
L	150° with anti rotation tube and free spinning front attachment																													
X	Customized																													
<b>Option 1: Cabling and I/O variant</b>																														
A	Analog I/O (Bus, 2 command input, 2 endstop output, absolute analog position output 0 – 10 V)																													
C	Analog I/O (Bus, 2 command input, 2 endstop output, absolute analog position output 0 – 5 V)																													
B	Bus (Bus, 2 command input)																													
<b>Option 2: BUS Type</b>																														
C	Standard: CAN without termination resistor																													
T	CAN with termination resistor																													
<b>Protection</b>																														
T	Standard: Chassis connected to negative terminal, built-in thermal protection																													
U	Chassis connected to negative terminal, reinforced load dump protection <sup>2)</sup> , built-in thermal protection																													
V	Chassis not connected, built-in thermal protection																													
W	Chassis not connected, reinforced load dump protection <sup>2)</sup> , built-in thermal protection																													
<b>Customization</b>																														
	Stroke length, retracted length, cable, connector, front attachment, rear attachment, color, de-rated load																													

<sup>2)</sup> For vehicle without centralized load dump protection option valid only for 12V.

**C A H B - 2 1 -** **E -** **B** **T - 0 0 0**

**Type** \_\_\_\_\_

**Voltage** \_\_\_\_\_

A 12 V DC  
 B 24 V DC  
 D 48 V DC  
 E 12 V DC with manual override  
 F 24 V DC with manual override  
 H 48 V DC with manual override

**Load** \_\_\_\_\_

1 1 500 N  
 2 2 500 N  
 3 4 500 N

**Design** \_\_\_\_\_

E

**3 digital Stroke and 4 digital Retracted length (mm)** \_\_\_\_\_

Stroke	Retracted length	Base <sup>1)</sup>	with Fork head	with Spherical plain bearing <sup>2)</sup>	with Anti rotation	with Limit switch	with Position output
			F, G	I	G to L	L	A, P, E
050	0232	+12	+42	+1	+9	+35	
100	0282	+12	+42	+1	+9	+35	
150	0332	+12	+42	+1	+9	+35	
200	0382	+12	+42	+1	+9	+35	
250	0432	+12	+42	+1	+9	+35	
300	0482	+12	+42	+1	+9	+35	
350	0567	+12	+30	+1	+9	+35	
400	0617	+12	+30	+1	+9	+35	
450	0667	+12	+30	+1	+9	+35	
500	0717	+12	+30	+1	+9	+35	
600	0817	+12	+30	+1	+9	+35	
700	0917	+12	+30	+1	+9	+35	

<sup>1)</sup> Base: the Retracted length with attachment "Rod end with hole", "without Anti rotation tube", without "Position output"  
<sup>2)</sup> With attachment "Spherical plain bearing", option "Anti rotation tube" is mandatory, the length "with Anti rotation" must be added to calculate the Retracted length

**Ingress protection** \_\_\_\_\_

B Standard: IP69K/IP66M

**Attachment diameter (Front and rear)** \_\_\_\_\_

A Rod end with hole Ø 13,1 mm  
 B Rod end with hole Ø 12,8 mm  
 C Rod end with hole Ø 12,5 mm  
 D Rod end with hole Ø 14 mm  
 E Rod end with hole Ø 12,2 mm  
 F Fork head with hole Ø 12,2 mm and slot 8,2 mm  
 G Fork head with hole Ø 12,8 mm and slot 8,2 mm  
 I Rod end Spherical plain bearing Ø 12,7 mm, rear end with hole Ø 12,8 mm (request anti rotation tube option)  
 X Customized

**Attachment orientation (Front and rear)** \_\_\_\_\_

A 0° without anti rotation tube  
 B 30° without anti rotation tube  
 C 60° without anti rotation tube  
 D 90° without anti rotation tube  
 E 120° without anti rotation tube  
 F 150° without anti rotation tube  
 G 0°: with anti rotation tube and free spinning front attachment  
 H 30° with anti rotation tube and free spinning front attachment  
 I 60° with anti rotation tube and free spinning front attachment  
 J 90° with anti rotation tube and free spinning front attachment  
 K 120° with anti rotation tube and free spinning front attachment  
 L 150° with anti rotation tube and free spinning front attachment  
 X Customized

**Option 1: Limit switch** \_\_\_\_\_

0 None (mandatory for 1 500 N, 2 500 N version and the 48 VDC version)  
 L Limit switch (valid only for load version 4 500 in 12 or 24 V DC)

**Option 2: Position output** \_\_\_\_\_

0 None  
 A Absolute analog output  
 P Potentiometer  
 E Encoder

**Thermal protection** \_\_\_\_\_

T Standard: Built-in thermal switch

**Customization** \_\_\_\_\_

Stroke length, retracted length, cable, connector, front attachment, rear attachment, color, de-rated load

Standard actuators are IP69K / IP66M and equipped with a vent, built-in thermal protection, protection Clutch and EMC filter.

Type	Voltage	Load	Design	3 digital Stroke and 4 digital Retracted length (mm)	Parallel operation self-controlled	Attachment diameter (Front and rear)	Attachment orientation (Front and rear)	Option 1: Cabling and I/O variant	Option 2: BUS Type	Protection	Customization
A	12 V DC	1 500 N	S	050	1	A	G	A	C	T	Stroke length, retracted length, cable, connector, front attachment, rear attachment, color, de-rated load
B	24 – 48 V DC	2 500 N		100	2	B	H	C	C	U	
E	12 V DC with manual override	4 500 N		150		C	I	B	T	V	
F	24 – 48 V DC with manual override			200		D	J			W	
				250		E	K				
				300		F	L				
				350		G	X				
				400							
				450							
				500							
				600							
				700							

**3 digital Stroke and 4 digital Retracted length (mm)**

Stroke	Retracted length Base <sup>1)</sup>	with Fork head F, G	with Spherical plain bearing I
050	0232	+12	+43
100	0282	+12	+43
150	0332	+12	+43
200	0382	+12	+43
250	0432	+12	+43
300	0482	+12	+43
350	0567	+12	+33
400	0617	+12	+33
450	0667	+12	+33
500	0717	+12	+33
600	0817	+12	+33
700	0917	+12	+33

<sup>1)</sup> Base: the Retracted length with attachment "Rod end with hole"

**Parallel operation self-controlled**

1 1 actuator run independently  
2 2 actuators run simultaneously in parallel mode

**Attachment diameter (Front and rear)**

A Rod end with hole Ø 13,1 mm  
B Rod end with hole Ø 12,8 mm  
C Rod end with hole Ø 12,5 mm  
D Rod end with hole Ø 14 mm  
E Rod end with hole Ø 12,2 mm  
F Fork head with hole Ø 12,2 mm and slot 8,2 mm  
G Fork head with hole Ø 12,8 mm and slot 8,2 mm  
I Rod end Spherical plain bearing Ø 12,7 mm, rear end with hole Ø 12,8 mm  
X Customized

**Attachment orientation (Front and rear)**

G 0° with anti rotation tube and free spinning front attachment  
H 30° with anti rotation tube and free spinning front attachment  
I 60° with anti rotation tube and free spinning front attachment  
J 90° with anti rotation tube and free spinning front attachment  
K 120° with anti rotation tube and free spinning front attachment  
L 150° with anti rotation tube and free spinning front attachment  
X Customized

**Option 1: Cabling and I/O variant**

A Analog I/O (Bus, 2 command input, 2 endstop output, absolute analog position output 0 – 10 V)  
C Analog I/O (Bus, 2 command input, 2 endstop output, absolute analog position output 0 – 5 V)  
B Bus (Bus, 2 command input)

**Option 2: BUS Type**

C Standard: CAN without termination resistor  
T CAN with termination resistor

**Protection**

T Standard: Chassis connected to negative terminal, built-in thermal protection  
U Chassis connected to negative terminal, reinforced load dump protection<sup>2)</sup>, Built-in thermal protection  
V Chassis not connected, Built-in thermal protection  
W Chassis not connected, reinforced load dump protection<sup>2)</sup>, Built-in thermal protection

**Customization**

Stroke length, retracted length, cable, connector, front attachment, rear attachment, color, de-rated load

<sup>2)</sup> For vehicle without centralized load dump protection, option valid only for 12V.



C

A

H

B

-

2

2

-

-

E

-

-

B

-

T

-

0

0

0

Type

Voltage

A

B

D

E

F

H

Load

1

2

3

4

Design

E

3 digital Stroke and 4 digital Retracted length (mm)

Stroke Retracted length

	Base <sup>1)</sup>	with Fork head F, G	with Spherical plain bearing <sup>2)</sup> I	with Anti rotation G to L	with Limit switch L	with Position output A, P, E
050	0244	+12	+42	+7	+6	+35
100	0294	+12	+42	+7	+6	+35
150	0344	+12	+42	+7	+6	+35
200	0394	+12	+42	+7	+6	+35
250	0444	+12	+42	+7	+6	+35
300	0494	+12	+42	+7	+6	+35
350	0579	+12	+30	+7	+6	+35
400	0629	+12	+30	+7	+6	+35
450	0679	+12	+30	+7	+6	+35
500	0729	+12	+30	+7	+6	+35
600	0829	+12	+30	+7	+6	+35
700	0929	+12	+30	+7	+6	+35

<sup>1)</sup> Base: the Retracted length with attachment "Rod end with hole", "without Anti rotation tube", without "Position output"

<sup>2)</sup> With attachment "Spherical plain bearing", option "Anti rotation tube" is mandatory, the length "with Anti rotation" must be added to calculate the Retracted length

Ingress protection

B

Standard: IP69K/IP66M

Attachment diameter (Front and rear)

A

B

C

D

E

F

G

I

X

Rod end with hole Ø 13,1 mm

Rod end with hole Ø 12,8 mm

Rod end with hole Ø 12,5 mm

Rod end with hole Ø 14 mm

Rod end with hole Ø 12,2 mm

Fork head with hole Ø 12,2 mm and slot 8,2 mm

Fork head with hole Ø 12,8 mm and slot 8,2 mm

Rod end Spherical plain bearing Ø 12,7 mm, rear end with hole Ø 12,8 mm (request anti rotation tube option)

Customized

Attachment orientation (Front and rear)

A

B

C

D

E

F

G

H

I

J

K

L

X

0° without anti rotation tube

30° without anti rotation tube

60° without anti rotation tube

90° without anti rotation tube

120° without anti rotation tube

150° without anti rotation tube

0°: with anti rotation tube and free spinning front attachment

30° with anti rotation tube and free spinning front attachment

60° with anti rotation tube and free spinning front attachment

90° with anti rotation tube and free spinning front attachment

120° with anti rotation tube and free spinning front attachment

150° with anti rotation tube and free spinning front attachment

Customized

Option 1: Limit switch

0

L

None (mandatory for 2 300 N, 3 500 N version and the 48 VDC version)

Limit switch (valid for load version 6 800 N and 10 000 N)

Option 2: Position output

0

A

P

E

None

Absolute analog output

Potentiometer

Encoder

Thermal protection

T

Standard: Built-in thermal switch

Customization

Stroke length, retracted length, cable, connector, front attachment, rear attachment, color, de-rated load

Standard actuators are IP69K / IP66M and equipped a vent, built-in thermal protection, protection Clutch and EMC filter.

Type	Voltage	Load	Design	3 digital Stroke and 4 digital Retracted length (mm)	Attachment diameter (Front and rear)	Attachment orientation (Front and rear)	Option 1: Cabling and I/O variant	Option 2: BUS Type	Protection	Customization
C A H B - 2 2 - S - - - - - - - - - - - - - - - - 0 0 0	A 12 V DC B 24 – 48 V DC E 12 V DC with manual override F 24 – 48 V DC with manual override	1 2 300 N 2 3 500 N 3 6 800 N 4 10 000 N	S	Stroke Retracted length Base <sup>1)</sup> with Fork head with Spherical plain bearing F, G I +12 +43	A Rod end with hole Ø 13,1 mm B Rod end with hole Ø 12,8 mm C Rod end with hole Ø 12,5 mm D Rod end with hole Ø 14 mm E Rod end with hole Ø 12,2 mm F Fork head with hole Ø 12,2 mm and slot 8,2 mm G Fork head with hole Ø 12,8 mm and slot 8,2 mm I Rod end Spherical plain bearing Ø 12,7 mm, rear end with hole Ø 12,8 mm X Customized	G 0° (Standard) with Free spinning H 30° with Free spinning I 60° with Free spinning J 90° with Free spinning K 120° with Free spinning L 150° with Free spinning	A Analog I/O (Bus, 2 command input, 2 endstop output, absolute analog position output 0 – 10 V) C Analog I/O (Bus, 2 command input, 2 endstop output, absolute analog position output 0 – 5 V) B Bus (Bus, 2 command input)	C Standard: CAN without termination resistor T CAN with termination resistor	T Standard: Chassis connected to negative terminal, built-in thermal protection U Chassis connected to negative terminal, reinforced load dump protection <sup>2)</sup> , Built-in thermal protection V Chassis not connected, Built-in thermal protection W Chassis not connected, reinforced load dump protection <sup>2)</sup> , Built-in thermal protection	Stroke length, retracted length, cable, connector, front attachment, rear attachment, color, de-rated load

<sup>1)</sup> Base: the Retracted length with attachment "Rod end with hole"

#### Parallel operation self-controlled

- 1 actuator run independently
- 2 actuators run simultaneously in parallel mode

#### Attachment diameter (Front and rear)

- A Rod end with hole Ø 13,1 mm
- B Rod end with hole Ø 12,8 mm
- C Rod end with hole Ø 12,5 mm
- D Rod end with hole Ø 14 mm
- E Rod end with hole Ø 12,2 mm
- F Fork head with hole Ø 12,2 mm and slot 8,2 mm
- G Fork head with hole Ø 12,8 mm and slot 8,2 mm
- I Rod end Spherical plain bearing Ø 12,7 mm, rear end with hole Ø 12,8 mm
- X Customized

#### Attachment orientation (Front and rear)

- G 0° (Standard) with Free spinning
- H 30° with Free spinning
- I 60° with Free spinning
- J 90° with Free spinning
- K 120° with Free spinning
- L 150° with Free spinning

#### Option 1: Cabling and I/O variant

- A Analog I/O (Bus, 2 command input, 2 endstop output, absolute analog position output 0 – 10 V)
- C Analog I/O (Bus, 2 command input, 2 endstop output, absolute analog position output 0 – 5 V)
- B Bus (Bus, 2 command input)

#### Option 2: BUS Type

- C Standard: CAN without termination resistor
- T CAN with termination resistor

#### Protection

- T Standard: Chassis connected to negative terminal, built-in thermal protection
- U Chassis connected to negative terminal, reinforced load dump protection<sup>2)</sup>, Built-in thermal protection
- V Chassis not connected, Built-in thermal protection
- W Chassis not connected, reinforced load dump protection<sup>2)</sup>, Built-in thermal protection

#### Customization

Stroke length, retracted length, cable, connector, front attachment, rear attachment, color, de-rated load

<sup>2)</sup> For vehicle without centralized load dump protection, option valid only for 12V.

# CAHB-30A

## Linear actuator

### Benefits

- Powered by AC voltage
- Designed and tested for harsh environments
- Reliable and cost-effective
- Reduced development and start-up times
- Virtually maintenance-free

### Features

- Optional potentiometer and limit switches
- Self-locking
- Integrated thermal and overload protection
- Robust design, IP65, wide temperature range, corrosion resistant



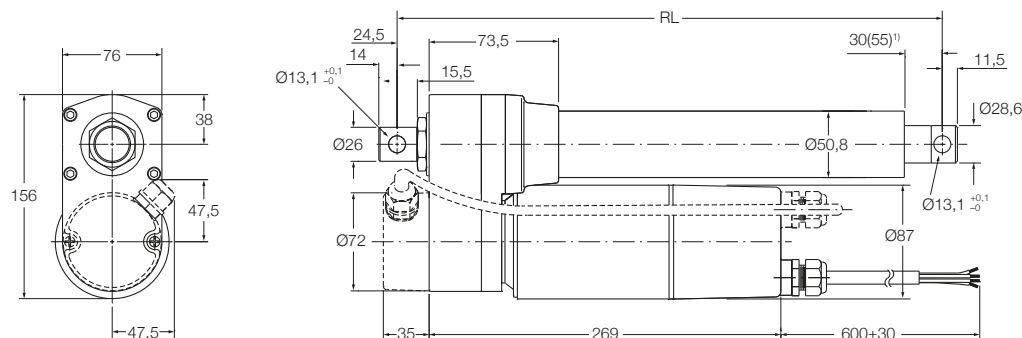
### Technical data

		Unit	CAHB-30A... 1	CAHB-30A... 2
Rated push load		N	1 500	2 300
Rated pull load		N	1 500	2 300
Holding force <sup>1)</sup>		N	10 000	10 000
Speed (full load to no load)	115 V AC/60 Hz	mm/s	25 to 26	12 to 13
	230 V AC/50 Hz	mm/s	21 to 22	11 to 12
Stroke		mm	102 to 610	102 to 610
Voltage		V AC	115 or 230	115 or 230
Nominal current	115 V AC/60 Hz	A	2,3	1,8
	230 V AC/50 Hz	A	1,35	1,4
Duty cycle		%	25	25
ON time / OFF time		s	94/376	94/376
Ambient temperature		°C	-26 to +65	-26 to +65
Type of protection		IP	65S	65S
Weight		kg	9	9
Color		–	Black	Black

<sup>1)</sup> The holding force is the highest load a powered-down actuator can statically hold without slipping backwards.

## Dimensional drawing

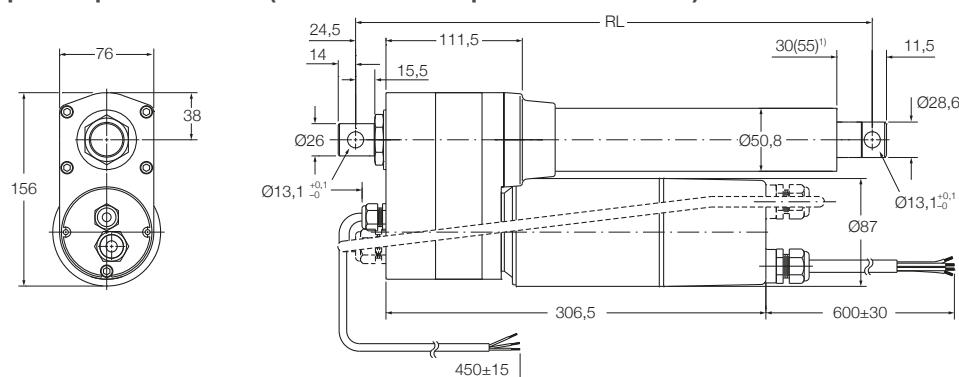
### Basic configuration (dashed line for optional limit switch)



**Legend:**  
RL = retracted length

<sup>1)</sup> 55 = dimension with limit switch

### Optional potentiometer (dashed line for optional limit switch)



**Legend:**  
RL = retracted length

<sup>1)</sup> 55 = dimension with limit switch

## Retracted length calculation (RL)

### Basic configuration

Stroke [mm]	With limit switch <sup>1)</sup>						Without limit switch <sup>2)</sup>					
	102	153	204	305	457	610	102	153	204	305	457	610
Retracted length (RL)	440	440	440	592	744	897	380	415	415	465	668	821

<sup>1)</sup> Tolerance: S and RL =  $\pm 5,0$  mm (If  $S \geq 305$  mm,  $S = \pm 7,5$  mm)

<sup>2)</sup> Tolerance: S =  $\pm 2,5$  mm and RL =  $\pm 3,8$  mm

### Optional potentiometer

Stroke [mm]	With limit switch <sup>1)</sup>						Without limit switch <sup>2)</sup>					
	102	153	204	305	457	610	102	153	204	305	457	610
Retracted length (RL)	478	478	478	630	782	935	418	453	453	503	706	859

<sup>1)</sup> Tolerance: S and RL =  $\pm 5,0$  mm (If  $S \geq 305$  mm,  $S = \pm 7,5$  mm)

<sup>2)</sup> Tolerance: S =  $\pm 2,5$  mm and RL =  $\pm 3,8$  mm



Ordering key

C

A

H

B

-

3

0

-

A

-

-

A

-

0

-

0

0

0

Type

Voltage

N

115 V AC

P

230 V AC

Load

1

1 500 N

2

2 300 N

Screw

A

Acme screw

3 digital Stroke and 3 digital Retracted length (mm)

Stroke

Retracted length

Base<sup>1)</sup>

with Limit switch

with Potentiometer

102

380

+60

+38

153

415

+25

+38

204

415

+25

+38

305

465

+127

+38

457

668

+76

+38

610

821

+76

+38

<sup>1)</sup> Base: the Retracted length without "Limit switch", without "Potentiometer"

Ingress protection

A

Standard (IP 65)

Attachment diameter (Front and rear)

A

Standard (hole: Ø13,1 mm)

X

Customized <sup>2)</sup>

Attachment orientation (Front and rear)

A

Standard (0°)

B

30°

C

60°

D

90°

E

120°

F

150°

X

Customized <sup>2)</sup>

Option 1

0

None

L

Limit switch (only for load version 2 300 N)

Option 2

0

None

P

Potentiometer

Customization

<sup>2)</sup> Only available on request. Contact Ewellix for more information on minimum quantities and additional costs.

# CAHB-31N

## Linear actuator

### Benefits

- Powered by AC voltage
- High efficiency
- Designed and tested for harsh environments
- Reliable and cost-effective
- Reduced development and start-up times
- Virtually maintenance-free

### Features

- Optional potentiometer and limit switches
- Ball screw with a brake
- Self-locking
- Integrated thermal and overload protection
- Robust design, IP65, wide temperature range, corrosion resistant



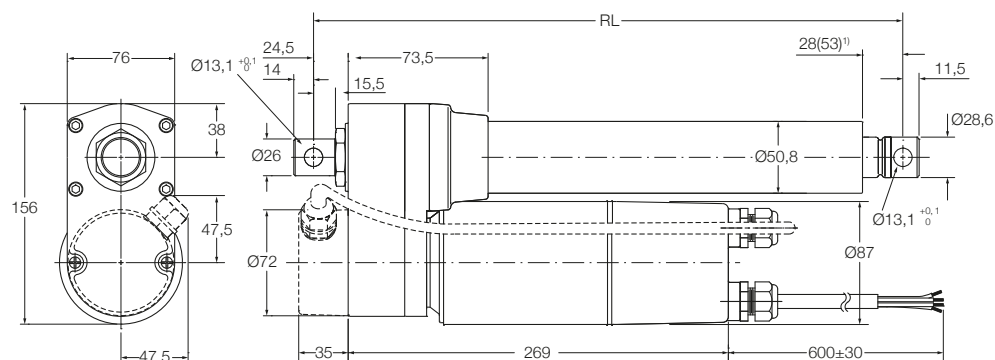
### Technical data

		Unit	CAHB-31N... 1	CAHB-31N... 2	CAHB-31N... 3
Rated push load		N	2 300	4 500	6 000
Rated pull load		N	2 300	4 500	6 000
Holding force <sup>1)</sup>		N	13 600	13 600	13 600
Speed (full load to no load)	115 V AC/60 Hz	mm/s	48 to 57	22 to 28	13 to 15
	230 V AC/50 Hz	mm/s	40 to 50	20 to 24	11 to 13
Stroke		mm	102 to 610	102 to 610	102 to 610
Voltage		V AC	115 or 230	115 or 230	115 or 230
Nominal current	115 V AC/60 Hz	A	3	2,6	2,2
	230 V AC/50 Hz	A	1,5	1,4	1,4
Duty cycle		%	25	25	25
ON time / OFF time		s	94/376	94/376	94/376
Ambient temperature		°C	-26 to +65	-26 to +65	-26 to +65
Type of protection		IP	65S	65S	65S
Weight		kg	9,5	9,5	9,5
Color		–	Black	Black	Black

<sup>1)</sup> The holding force is the highest load a powered-down actuator can statically hold without slipping backwards.

## Dimensional drawing

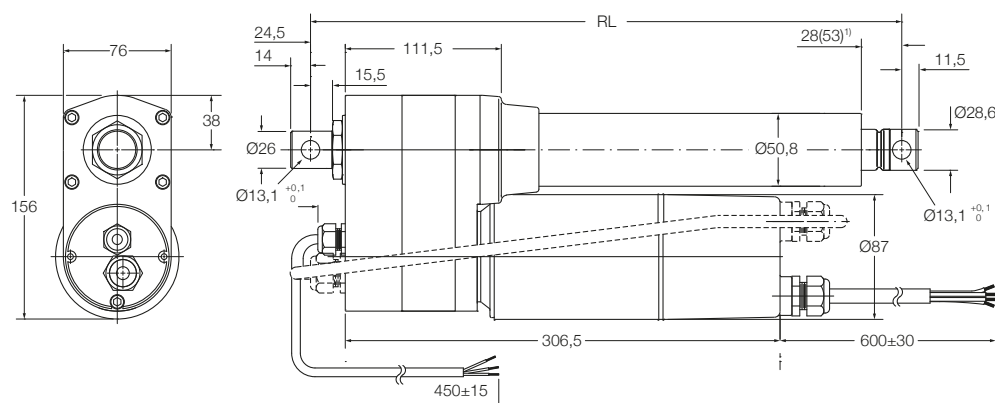
### Basic configuration (dashed line for optional limit switch)


**Legend:**

RL = retracted length

¹) 53 = dimension with limit switch

### Optional potentiometer (dashed line for optional limit switch)


**Legend:**

RL = retracted length

¹) 53 = dimension with limit switch

## Retracted length calculation (RL)

### Basic configuration

Stroke [mm]	With limit switch ¹)						Without limit switch ²)					
	102	153	204	305	457	610	102	153	204	305	457	610
Retracted length (RL)	444	444	495	659	811	964	380	419	419	521	735	888

¹) Tolerance: S and RL = ± 5,0 mm (If S ≥ 305 mm, S = ± 7,5 mm)

²) Tolerance: S = ± 2,5 mm and RL = ± 3,8 mm

### Optional potentiometer

Stroke [mm]	With limit switch ¹)						Without limit switch ²)					
	102	153	204	305	457	610	102	153	204	305	457	610
Retracted length (RL)	482	482	533	697	849	1002 (code A02)	418	457	457	559	773	926

¹) Tolerance: S and RL = ± 5,0 mm (If S ≥ 305 mm, S = ± 7,5 mm)

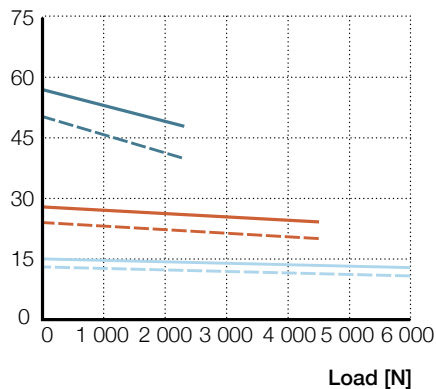
²) Tolerance: S = ± 2,5 mm and RL = ± 3,8 mm



## Performance diagrams

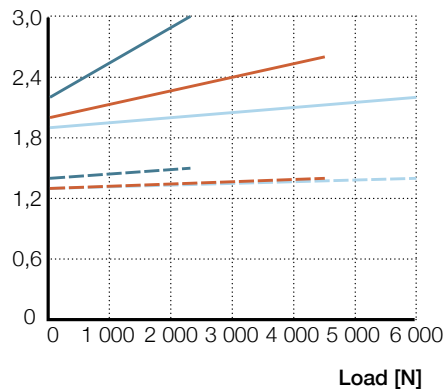
Speed-load diagram

Speed [mm/s]



Current-load diagram

Nominal current [A]



— 1 (115 VAC)      — 2 (115 VAC)      — 3 (115 VAC)  
 - - 1 (230 VAC)      - - 2 (230 VAC)      - - 3 (230 VAC)

## Electrical specifications

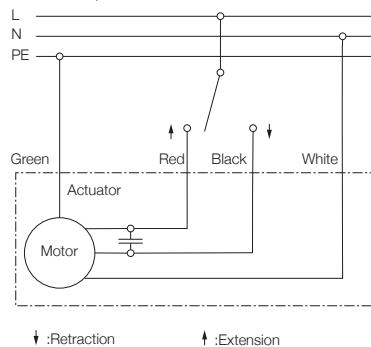
Potentiometer resolution

Stroke [mm]	102	153	204	305	457	610
$\Omega$ /mm	59,0	59,0	29,5	29,5	9,84	9,84

CAHB-3x

Connecting Diagram

115/230 VAC, 50/60 Hz

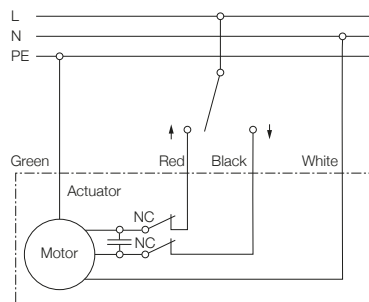


↓ :Retraction      ↑ :Extension

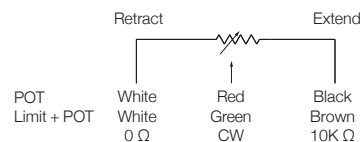
CAHB-3x with limit switch

Connecting Diagram

115/230 VAC, 50/60 Hz

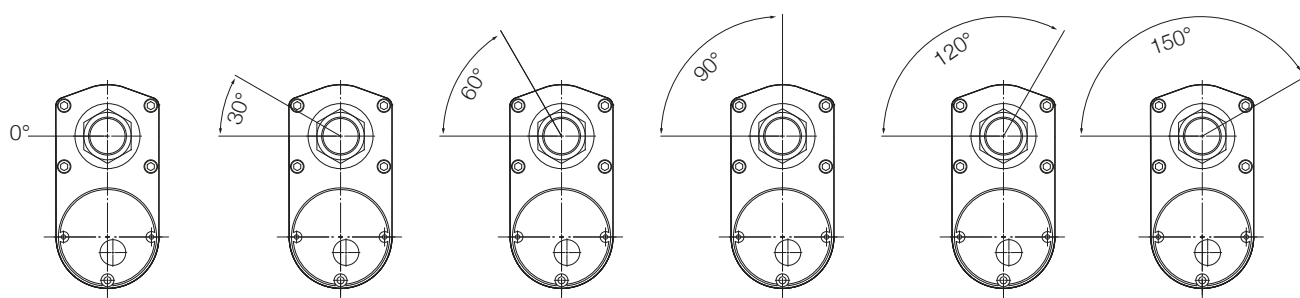


↓ :Retraction      ↑ :Extension



## Attachment orientation

(refer to ordering key Attachment orientation)



Orientation A

Orientation B

Orientation C

Orientation D

Orientation E

Orientation F

Ordering key

C

A

H

B

-

3

1

-

-

N

-

-

A

0

-

0

0

0

Type

Voltage

N115 V AC

P230 V AC

Load

12 300 N

24 500 N

36 000 N

Screw

NBall screw

3 digital Stroke and 3 digital 1) Retracted length (mm)

Stroke	Retracted length		
	Base <sup>2)</sup>	with Limit switch	with Potentiometer
		L	P
102	380	+64	+38
153	419	+25	+38
204	419	+76	+38
305	521	+138	+38
457	735	+76	+38
610	888	+76	+38

1) Use the letter "A" to represent "10" if the Retracted length exceeds 999 mm, for example: 1002 mm is A02

2) Base: the Retracted length without "Limit switch", without "Potentiometer"

Ingress protection

AStandard (IP 65)

Attachment diameter (Front and rear)

AStandard (hole: Ø13,1 mm)

XCustomized <sup>3)</sup>

Attachment orientation (Front and rear)

AStandard (0°)

B30°

C60°

D90°

E120°

F150°

XCustomized <sup>3)</sup>

Option 1

0None

LLimit switch (only for load version 6 000 N)

Option 2

0None

PPotentiometer

Customization

<sup>1)</sup> Only available on request. Contact Ewellix for more information on minimum quantities and additional costs.

# CAHB series - Environmental tests

Climatic tests						
Test and Standard	CAHB-20xE, CAHB-21xE, CAHB-22xE		CAHB-10		CAHB-30, CAHB-31	
	Performance	Report No.	Performance	Report No.	Performance	Report No.
<b>Cold test</b> <b>EN60068-2-1 (Ab)</b>	Storage at low temperature Temperature: -40 °C Duration: 6 hours Not connected Tested at room temperature.	PH_TR0295	Storage at low temperature Temperature: -40 °C Duration: 96 hours Not connected Tested at room temperature.	"Low temperature for CAHB-10"	Storage at low temperature: Temperature: -40 °C Duration: 8 hours Not connected Tested at room temperature.	PH_TR0265
<b>Cold test</b> <b>EN60068-2-1 (Ad)</b>	Storage at low temperature Temperature: -30 °C Duration: 6 hours Actuator is not activated/ connected Tested at low temperature.	PH_TR0295	Storage at low temperature Temperature: -20 °C Duration: 96 hours Actuator is not activated/ connected Tested at low temperature.	"Low temperature for CAHB-10"	Storage at low temperature: Temperature: -26 °C Duration: 8 hours Not connected Tested at room temperature.	PH_TR0265
<b>Dry Heat</b> <b>EN60068-2-2 (Bb)</b>	Storage at high temperature Temperature: +90 °C Duration: 72 hours Actuator is not activated/ connected. Tested at room temperature	PH_TR0278	Storage at high temperature Temperature: +85 °C Duration: 96 hours Actuator is not activated/ connected. Tested at room temperature	"High temperature for CAHB-10"	–	–
<b>Change of temperature</b> <b>EN60068-2-14 (Na)</b>	Rapid change of temperature High temperature: +100 °C in 60 min. Low temperature: -30 °C in 60 min. Transition time: < 10 seconds Duration: 100 cycles Actuator is not activated/ connected. Tested at room temperature.	PH_TR0278	–	–	–	–
<b>Salt mist</b> <b>EN60068-2-52 (Kb)</b>	Salt spray test Salt solution: 5 % sodium chloride (NaCl) 4 spraying periods, each of 2 hours. Humidity storage 7 days after each. Actuator not activated/ connected. Exposure time: 250 hours	PH_TR0268	Salt spray test Salt solution: 5 % sodium chloride (NaCl) 4 spraying periods, each of 2 hours. Humidity storage 7 days after each. Actuator not activated/ connected. Exposure time: 96 hours	"Salt spray test for CAHB-10"	–	–
<b>Degrees of protection</b> <b>IEC 60529</b>	1. Test Item: IP6XM Test Condition: Movement Test Dust: Talcum powder Dust Concentration: 2 kg/m <sup>3</sup> chamber volume and be kept in suspension during the test Test Duration: 8 hours	SHIN1607036235PS	1. Test Item: IP6XS Test Condition: Static Type of dust: Talcum powder  Test Duration: 8 hours	COM12-GPE080184AN, COM12-GPE080183AN	–	–
<b>Degrees of protection</b> <b>IEC 60529</b>	2. Test Item: IPX6M Test Condition: Movement Flux: 100 L/min Nozzle diameter: Ø12,5 mm Distance: 2,5 ~ 3,0 m Test duration: 3 min	SHIN1607036235PS	2. Test Item: IPX6S Test Condition: Static Flux: 100 (1 ±5 %) L/min Nozzle diameter: Ø12,5 mm Distance: 2,5 ~ 3,0 m Test duration: 3 min	COM12-GPE080184AN, COM12-GPE080183AN	2. Test Item: IPX5S Test Condition: Static Flux: 12,5 L/min Nozzle diameter: Ø6,3 mm Distance: 2,5 ~ 3,0 m Test duration: 3 min	SHIN1608042057MR
<b>Degrees of protection</b> <b>ISO 20653:2013</b>	3. Test Item: IPX9K Test Condition: Static Water flow: 14~16 L/min Water pressure: 8 000~10 000 kPa Water temperature: 80 to -5 °C Test angle: 0°, 30°, 60°, 90° Test distance from jet to sample: 100~150 mm Test duration: 30 s/position	SHIN1607036235PS	3. Test Item: IPX9K Test Condition: Static Water flow: 14~16 L/min Water pressure: 8 000~10 000 kPa Water temperature: 80 to -5 °C Test angle: 0°, 30°, 60°, 90° Test distance from jet to sample: 100~150 mm Test duration: 30 s/position	SHIN1510048959MR-01	–	–

Climatic tests						
Test and Standard	CAHB-20xE, CAHB-21xE, CAHB-22xE		CAHB-10		CAHB-30, CAHB-31	
	Performance	Report No.	Performance	Report No.	Performance	Report No.
Resistance to chemical product	–	–	Reagent on the surface 3 days 100 hours 0# Diesel Mobile H46 antiwear hydraulic Hydraulic DOT brake oil 50% Ethyleneglycol solution Urea saturated solution DEF NPK (15-15-15)	SHIN2104020949MR-01	–	–

Climatic tests		
Test and Standard	CAHB-20xS, CAHB-21xS, CAHB-22xS	
	Performance	Report No.
Temperature shock test	-55°C to +95°C, ≤15S 100 cycles	SHIN2007039234MR
Temperature cycle test	-40°C to +85°C 18h/cycle 10 cycles	SHIN2106042981PS
High temperature soak test (Operational)	+85°C, 96 hours	SHIN2012077900MR-01
Low temperature soak test (Operational)	-40°C, 96 hours	SUIN2101000352MR
Storage temperature	-55°C to +110°C, 24 hours	SUIN2012009686MR
Humidity and temperature cycles ISO16750-4:2010 Section 5.6	+25°C, 95%RH to +55°C, 95%RH 24 hours/cycle, 6 cycles	SUIN2012009687MR
Salt mist EN60068-2-52 (Kb)	500 hours	PH_TR0404
Degrees of protection IEC 60529	IP6xS, IP6xM	SHIN1607036235PS
Degrees of protection ISO 20653: 2013	IPx9K	SHIN1607036235PS
Resistance to chemical product	Reagent on the surface 3 days 100 hours 0# Diesel Mobile H46 antiwear hydraulic Hydraulic DOT brake oil 50% Ethyleneglycol solution Urea saturated solution DEF NPK (15-15-15)	SHIN2104020959MR-01

## Mechanical tests

Test and Standards	CAHB-20xE, CAHB-21xE, CAHB-22xE		CAHB-10		CAHB-30, CAHB-31	
	Performance	Report No.	Performance	Report No.	Performance	Report No.
<b>Vibration</b>	Test Item: Random vibration		SHIN1607036235PS		-	
<b>EN60068-2-6 (Fdb)</b>	Frequency (Hz)	Power spectral density level	SHIN1702007025PS			
<b>EN60068-w2-6(Fc)</b>	10	0,005				
	200	0,02				
	300	0,01				
	350	0,002				
	Test Direction: X/Y/Z axis					
	Test Duration: 2 hours/axis, Total 6 hours					
	Test Item: Sinusoidal vibration					
	Test Condition:					
	Frequency range: 5~25~200 Hz					
	Amplitude: 3,3 mm (p-p)					
	Acceleration: 4g					
	Sweep Rate: 10 ct/min					
	Test Direction: X/Y/Z axis					
	Test Duration: 2 hours/axis, Total 6 hours					
<b>Vibration</b>	-		Test Item:		SHIN1805034119SC	
<b>Ewellix Specified</b>	-		Vibration Set Point Dwell		SHIN1805032588SC	
<b>Conditions</b>			(Grms) Time(min)			
			5 10			
			10 10			
			15 10			
			20 10			
			20 20			
			20 30			
			Test Equipment Name			
			Halt Tester Typhoon-2,5+			

Mechanical tests

Test and Standard	CAHB-20xS, CAHB-21xS, CAHB-22xS Performance	Report No.
Mechanical shock	245~500 m/s2 3~100 impacts/axis	SUIN2106004489MR
Mechanical shock (Drop)	1m height onto concrete	PH_TR0430
Random vibration for AG/CE wheeled vehicle	24 hours/axis 5 Hz @ PSD 5.29 (m/s <sup>2</sup> ) <sup>2</sup> /Hz 100 Hz @ PSD 14.44 (m/s <sup>2</sup> ) <sup>2</sup> /Hz 1 000 Hz @ PSD 14.44 (m/s <sup>2</sup> ) <sup>2</sup> /Hz 2 000 Hz @ PSD 3.66 (m/s <sup>2</sup> ) <sup>2</sup> /Hz	SUIN2106004491MR-01
Vibration-random resistance	6.9 g RMS 2 hours/axis	SHIN2011076082PS

## Electrical tests

Test and Standards	CAHB-20xE, CAHB-21xE, CAHB-22xE		CAHB-10		CAHB-30, CAHB-31	
	Performance	Report No.	Performance	Report No.	Performance	Report No.
<b>Power supply 12 VDC</b> <b>ASAE EP455 (1990)</b>	Operating voltages: +10 V ~ +16 V Over voltage: +26 V / 5 min. Reverse polarity: -26 V / 5 min. Short circuit to ground: 16 V / 5 min. Short circuit to supply: 16 V	PH_TR0267 PH_TR0302	-	-	-	-
<b>Power supply 24 VDC</b> <b>ASAE EP455 (1990)</b>	Operating voltages: +21 V ~ +26 V Over voltage: +36 V / 5 min Reverse polarity: -36 V / 5 min Short circuit to ground: 32 V / 5 min Short circuit to supply: 32 V	PH_TR0267 PH_TR0302	-	-	-	-
<b>Safety Low Voltage Directive</b> <b>EN 60335-1: 2012 + A11: 2014</b>	-	-	-	-	Rated Voltage: 230 V AC Rated frequency: 50 Hz Rated Current: 1,5 A Degree of protection: IP65	UL 4787638796
<b>EN 60335-2-97: 2006 + A11: 2008 + A2:2010 + A12: 2015</b> <b>EN 62233: 2008</b>	-	-	-	-	Rated Voltage: 230 V AC Rated frequency: 50 Hz Rated Current: 1,5 A Degree of protection: IP65	UL 4787638796
<b>EMC, HF-immunity</b> <b>EN 61000-6-1</b>	-	-	Pass the test for 12 V / 24 V Motor	70.888.12.1063.02	-	-
<b>EN 61000-6-2</b>	Pass the test for 12 V / 24 V Motor	708881688102-00				
<b>EMC, Emission</b> <b>EN 61000-6-3</b>	-	-	Inside limits for 12 V / 24 V motor	70.888.12.1063.02	-	-
<b>EN 61000-6-4</b>	Inside limits for 12 V / 24 V motor	708881688102-00	-	-	-	-
<b>EN 50081-2 (1993)</b> <b>EN 55011 (1998)</b>	-	-	-	-	Class B	EM99777 (IA4=CAHB-30 CAHB-31 series)
<b>EMC, Automotive transients</b> <b>ISO 7637-2</b>	ISO 7637 Load dump test only accepted on motor power connection	708881688103-00	-	-	-	-
<b>UL certification</b>					UL 325 ANSI/CAN/UL-Door	20190822-E507157
<b>UL registration</b>	Cable flammability test VW-1 (UL758, UL1581, CSA C22.2 N°.210)	BELDEN E357312-S 2C14 SHIELDED BELDEN E357312-S 3C22 2C14 BELDEN E357312-S 2C14 4C26				

## Electrical tests

Test and Standard	CAHB-20xS, CAHB-21xS, CAHB-22xS Performance	Report No.
<b>Electrical Steady State 12 VDC</b> ISO16750-2 3rd edition	<ul style="list-style-type: none"> <li>Operating voltage: 14±0.2 (Engine running), 12±0.2 (Engine not running)</li> <li>Over Voltage: 18V/60mins</li> <li>Reverse Polarity: -26V/5mins</li> <li>Short circuit to ground: 16V/5mins</li> <li>Short circuit to supply: 16V/1mins/10times</li> <li>Jump Start: 24V/60±6s</li> <li>Ground Reference and Supply Offset: power line offset ±2 V, ground line offset ±1 V</li> <li>Ground Reference Disconnection</li> <li>Power Supply Disconnection</li> <li>Superimposed Alternating Voltage on Supply lines: 16 V/Upp 4 V/120s/5times</li> <li>Start Cycle: Level I to IV/Tol. -0.2V/Duration ±10%</li> <li>Slow Decrease and Increase of Supply Voltage: Us-min 6 - 10V, Us-max 16 - 21V, 0.5V/min</li> <li>Momentary drop in supply voltage: 100ms/4.5V</li> <li>Reset behavior after voltage drop: Us-min 4.5V decrease 0.5V/10s</li> <li>Load Dump: Test A(without centralized protection) 100V/400ms/1Ω (valid for 12 V version, Protection code "U")</li> </ul>	WTU21U03019493V-2 (valid for 12V version, Protection code "T" and "U")
<b>Electrical Steady State 24 VDC</b> ISO16750-2 3rd edition	<ul style="list-style-type: none"> <li>Operating voltage: 28±0.2 (Engine running), 24±0.2 (Engine not running)</li> <li>Over Voltage: 36V/60mins</li> <li>Reverse Polarity: -36V/5mins</li> <li>Short circuit to ground: 32V/5mins</li> <li>Short circuit to supply: 32V/1mins/10times</li> <li>Jump Start: 36V/60±6s</li> <li>Ground Reference and Supply Offset: power line offset ±2 V, ground line offset ±1 V</li> <li>Ground Reference Disconnection</li> <li>Power Supply Disconnection</li> <li>Superimposed Alternating Voltage on Supply lines: 32 V/Upp 4 V/120s/5times</li> <li>Start Cycle: Level I to III/Voltage tol. -0.2V/Duration ±10%</li> <li>Slow Decrease and Increase of Supply Voltage: Us-min 8 - 18V, Us-max 32V, 0.5V/min</li> <li>Momentary drop in supply voltage: 100ms/9V</li> <li>Reset behavior after voltage drop: Us-min 10V decrease 0.5V/10s</li> <li>Load Dump: Test B(with centralized protection) 58V/350ms/2Ω (valid for 24 V version, Protection code "T")</li> </ul>	WTU21U03019492V-2 (valid for 24V version, Protection code "T")
<b>Sinusoid Changes of Supply Voltage</b>	12V systems: Test level: Vb1: 12V, Vb2: 6V, Vb3: 8V 24V systems: Test level: Vb1: 24V, Vb2: 8V, Vb3: 10V	WTU21U03019493V-2 (valid for 12 version, Protection code "T") WTU21U03019492V-2 (valid for 24 version, Protection code "T")
<b>EMC Transient Conducted Disturbances</b> ISO7637-3	CCC, ICC	WTU21U03019493V-1 (valid for 12 version, Protection code "T") WTU21U03019492V-1 (valid for 24 version, Protection code "T")
<b>EMC Conducted Transient Immunity</b> Power Line ISO7637-2	Positive Inductance Transient Tests Pulse 2a 2b Positive and Negative Burst Coupling Tests Pulse 3a 3b Pulse 4, Cranking Test Cranking Test at Low Temperature Pulse 4	WTU21U03019493V-1 (valid for 12 version, Protection code "T") WTU21U03019492V-1 (valid for 24 version, Protection code "T")
<b>EMC Conducted Emissions/Interference</b> Test	Class 3	WTU21U08086163V (valid for 12 version, Protection code "T")
<b>EMC Conducted Emission</b> EN61000-6-4	0.15 to 0.5 MHz QP=79, AV=66 (dBµV) 0.5 to 30 MHz QP=73, AV=60 (dBµV)	EED39M000483 (valid for 12 version, Protection code "T")
<b>EMC Radiated Emissions/Interference</b> Test CISPR 25-2008	Class 3	WTU21U08086163V (valid for 12 version, Protection code "T")
<b>EMC Radiated Emission EN61000-6-4</b>	30 to 230 MHz QP=50 (dBµV/m) 230 to 1000 MHz QP=57 (dBµV/m)	EED39M000483 (valid for 12 version, Protection code "T") EED39M000482 (valid for 24 version, Protection code "T")
<b>EMC Radiated Emission EN55011</b>	Class A	WTU21U09098252E (valid for 24 version, Protection code "V")
<b>EMC ESD IEC61000-4-2</b>	Air discharge: ±8kV Contact discharge: ±4kV	EED39M000483 (valid for 12 version, Protection code "T") EED39M000482 (valid for 24 version, Protection code "T")
<b>EMC Electrical fast transient/burst immunity (EFT) IEC61000-4-4</b>	5kHz, 5/50 ns, 15ms, 300ms Power line ±2kV, signal line ±1kV	EED39M000483 (valid for 12 version, Protection code "T") EED39M000482 (valid for 24 version, Protection code "T")
<b>EMC Power-frequency magnetic field immunity IEC61000-4-8</b>	50Hz, 1min, XYZ, 30A/m	EED39M000483 (valid for 12 version, Protection code "T") EED39M000482 (valid for 24 version, Protection code "T")
<b>UL registration</b>	Cable flammability test VW-1 (UL758, UL1581, CSA C22.2 N°.210)	BELDEN E357312-S 1PR14 1PR26 2C26 BELDEN E357312-S







# CAR, CAP & CAT series

The CAR, CAP, CAT modular design concept makes it easy to interchange critical components such as motors, gears, screws, attachments, etc. Custom-built actuators are easily and cost efficiently built from standard parts. The CAT range flexibility makes it suitable for a high number of applications.



## Features

- Compact
- Robust
- Modular
- Lubricated for service life
- High efficiency

## Benefits

- Industrial reliable and robust actuator
- Wide range of components
- Right-hand and left-hand version
- Incremental or absolute position feedback option

# CAR 22

## Linear actuator

### Benefits

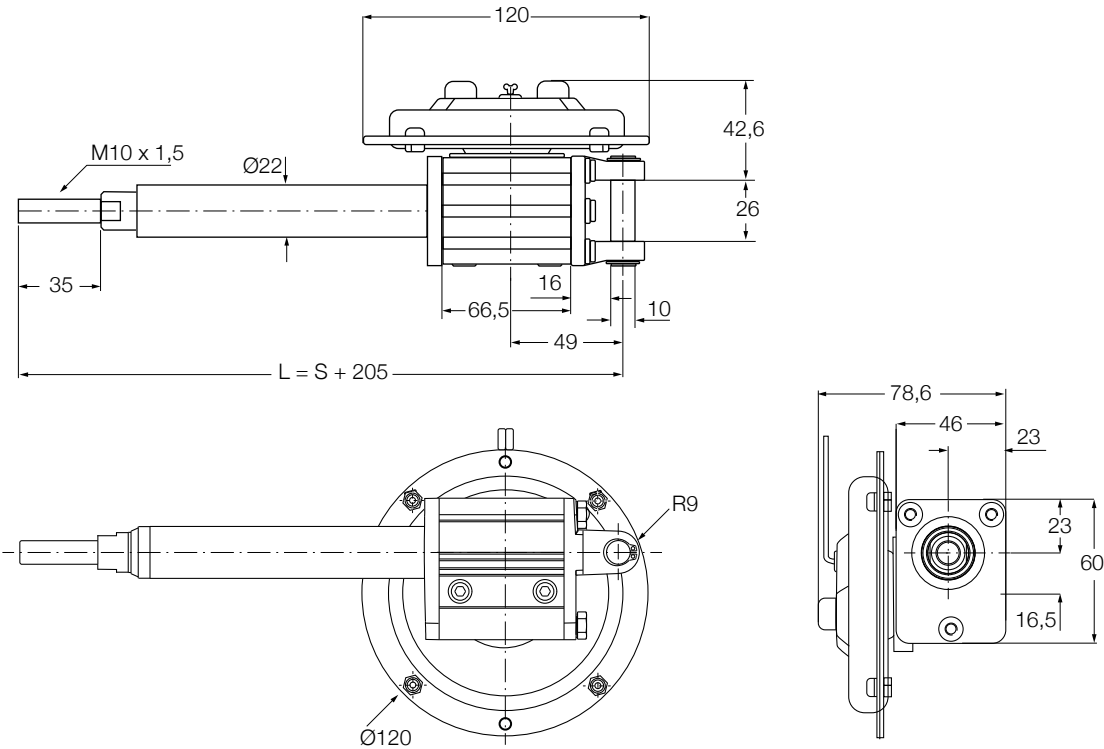
- Reliable and robust industrial actuator
- Right- and left-hand version
- Maintenance free



### Technical data

		Unit	CAR 22
Rated push load		N	1 000 to 1 500
Rated pull load		N	1 000 to 1 500
Speed (full load to no load)		mm/s	11 to 34
Stroke		mm	50 to 300
Retracted length		mm	S+ 205
Voltage		V AC	12 or 24
Power consumption		W	120
Current consumption	12 V DC	A	10
	24 V DC	A	4
Duty cycle		%	25
Ambient temperature		°C	-20 to +70
Degree of protection		IP	44
Weight		kg	1,2 to 1,6

Dimensional drawing

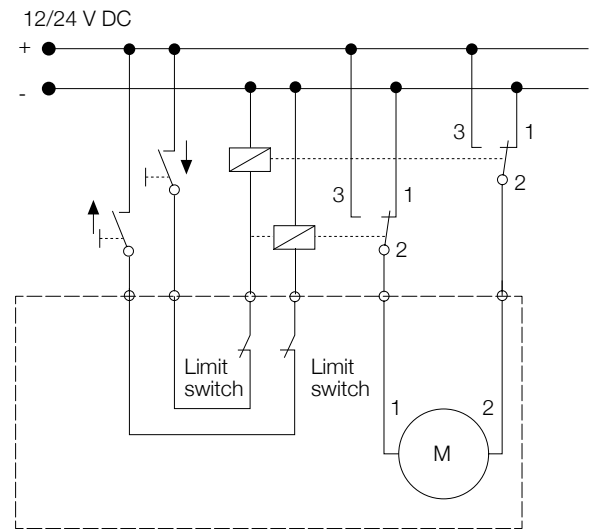


Legend:

S = stroke

L = retracted length

Connecting diagrams

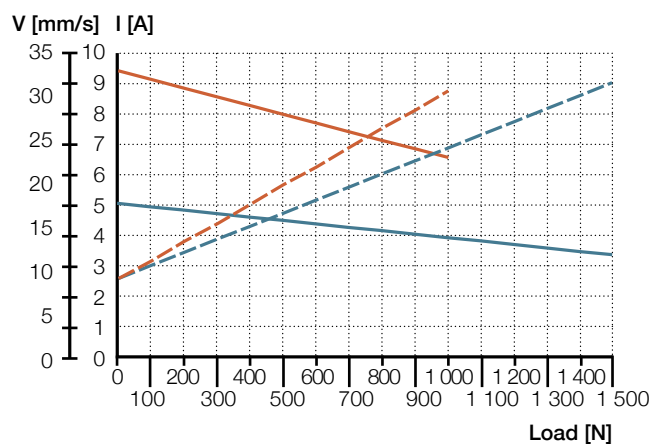


Suitable control units and accessories

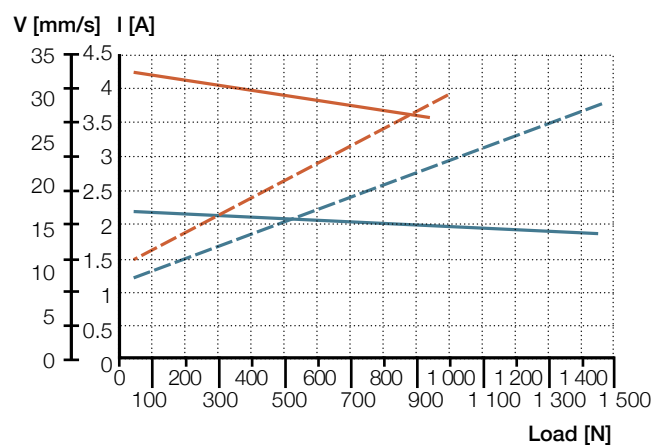
Limit switch	
	CAXE 22
P12B	•
P24B	•

## Performance diagrams

CAR 22.../P12B



CAR 22.../P24B



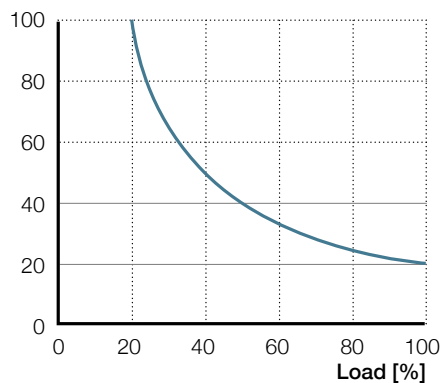
Gear 1 — V (mm/s) — I (A)

Gear 2 — V (mm/s) — I (A)

\*There may be deviations of +/-10% from the values in the chart.

## Duty cycle

Duty factor [%] at 20 °C



## Ordering key

Load [N] / Full Load Speed [mm/s]		Motor options	
1 500/xx	1 000/xx	No motor	0000
1 500/18–11	1 000/34–21	12 V DC, flat motor, IP44	P12B
1 500/17–14.5	1 000/33–28	24 V DC, flat motor, IP44	P24B

1                      2

Gear

**Type** \_\_\_\_\_

**Motor assembly**

R    Right

L    Left

**Stroke [S]** \_\_\_\_\_

050    50 mm

100    100 mm

150    150 mm

200    200 mm

300    300 mm

---    Other stroke lengths

■ Options shown in red are only available on request. Contact Ewellix for more information on minimum quantities and additional costs.

## CAR 22 – Type codes for accessories and spare parts

Item code	Type code	Order N°
12 VDC motor (flat motor)	P12B	M/0405516-V01
24 VDC motor (flat motor)	P24B	M/0405517-V01
Limit switch for stroke = 50 mm	CAXE 22 × 50	M/0412019
Limit switch for stroke = 100 mm	CAXE 22 × 100	M/0412020
Limit switch for stroke = 150 mm	CAXE 22 × 150	M/0412021
Limit switch for stroke = 200 mm	CAXE 22 × 200	M/0412022
Limit switch for stroke = 300 mm	CAXE 22 × 300	M/0412023
Proximity switch for CAXE	CAXE Proximity switch	M/0432369
Front mounting attachments type Rod-end	575-22	M/0430575-22
Front mounting attachments type Clevis	576-22	M/0430576-22
Rear mounting attachments type Single ear bracket	580-22	M/0430580-22
Rear mounting attachments type Ball-joint bracket	581-22	M/0430581-22

# CAP 32

## Linear actuator

### Benefits

- High efficiency ball screw
- Extension tube (stainless steel)
- Protection tube (steel)
- Enhanced corrosion resistance
- Mechanical overload protection (clutch)
- Lubricated for service life
- Robust, designed for tough environment
- No back driving
- Motor with thermal protection

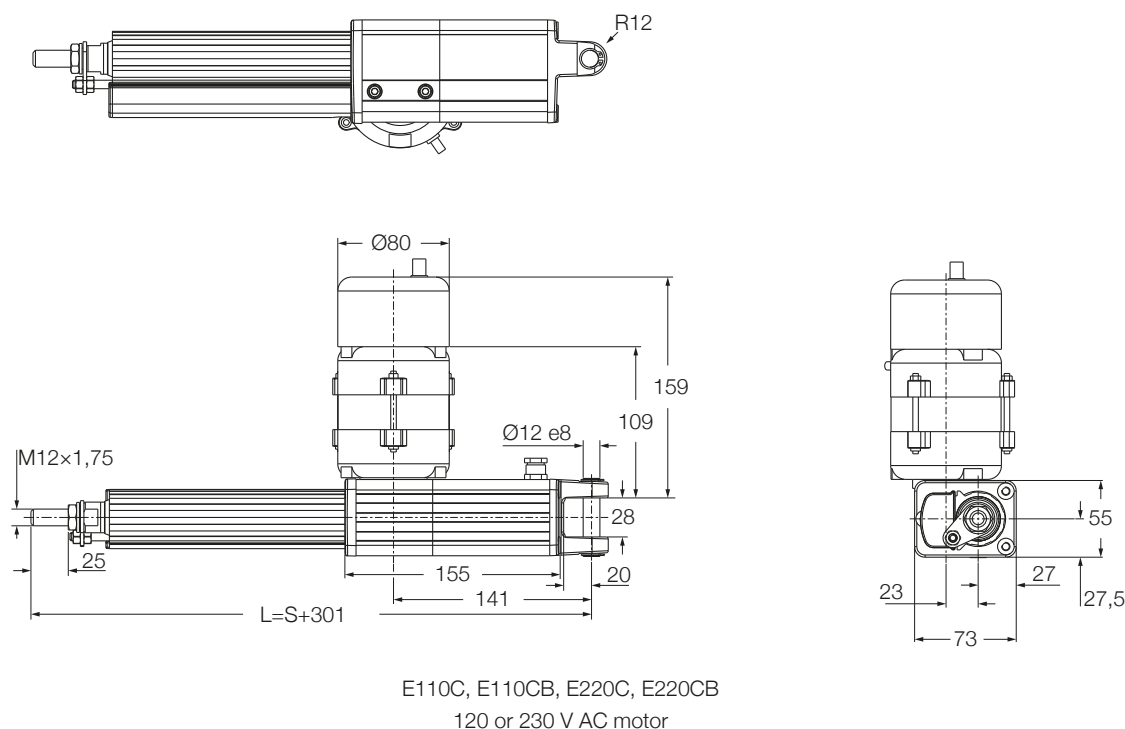


### Technical data

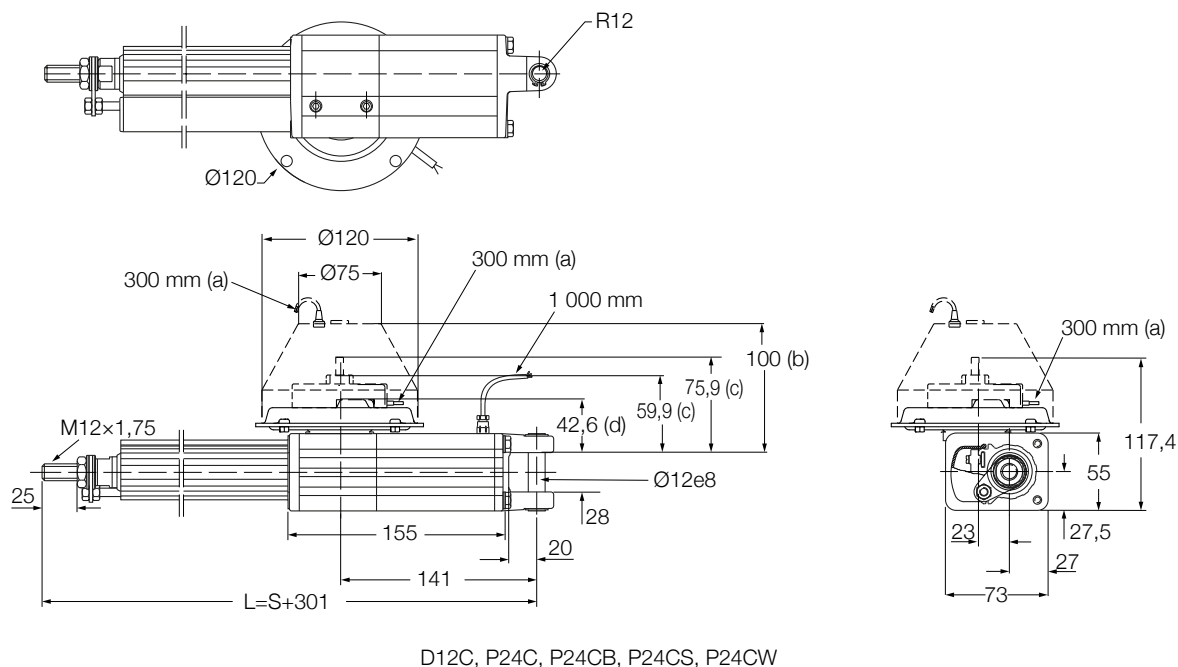
		Unit	CAP 32 – AC version	CAP 32 – DC version
Rated push load		N	1 500 to 3 500	1 000 to 3 500
Rated pull load		N	1 500 to 3 500	1 000 to 3 500
Speed (full load to no load)		mm/s	6 to 32 <sup>1)</sup>	6 to 66 <sup>1)</sup>
Stroke		mm	50 to 700	50 to 700
Retracted length		mm	S+301	S+301
Voltage		V AC	120 or 230	–
		V DC	–	12 or 24
Power consumption	120 V AC	W	98 (brake 133,2 W)	N/A
	230 V AC	W	92 (brake 117,3 W)	–
	12 or 24 V DC	W	–	N/A
Current consumption	120 V AC	A	0,82 (brake +0,29 A)	–
	230 V AC	A	0,4 (brake + 0,11 A)	–
	12 V DC	A	–	13
	24 V DC	A	–	9
	24 V DC	A	–	5 (for motor P24CW)
Duty cycle		%	30	25
Ambient temperature		°C	–20 to +50	–20 to +50
Degree of protection		IP	20/54	20/44
Weight		kg	2,9 to 5,0	2,9 to 5,0

<sup>1)</sup> Depending on selected motor

## Dimensional drawing – AC version



## Dimensional drawing – DC version



### Legend:

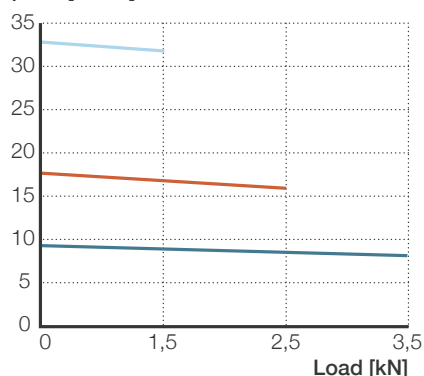
- S = stroke
- L = retracted length
- (a) = cable length
- (b) = cover for brake (P24CB)
- (c) = extended shaft (P24CS)
- (d) = motor (D12C, P24C, P24CW)



## Performance diagrams – AC version

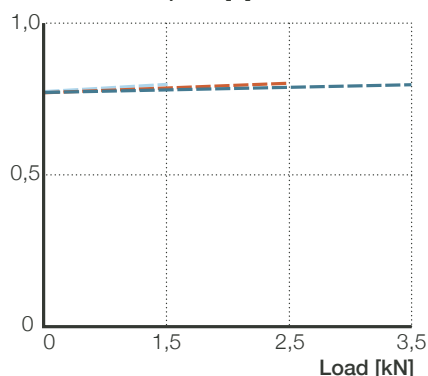
Speed-load diagram CAP 32 ... 120 V AC

Speed [mm/s]



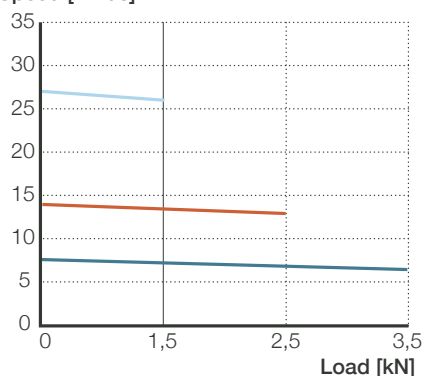
Current-load diagram CAP 32 ... 120 V AC

Current consumption [A]



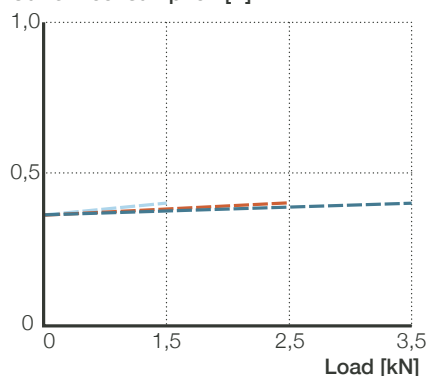
Speed-load diagram CAP 32 ... 230 V AC

Speed [mm/s]



Current-load diagram CAP 32 ... 230 V AC

Current consumption [A]



Gear 1 — V (mm/s) — I (A)

Gear 2 — V (mm/s) — I (A)

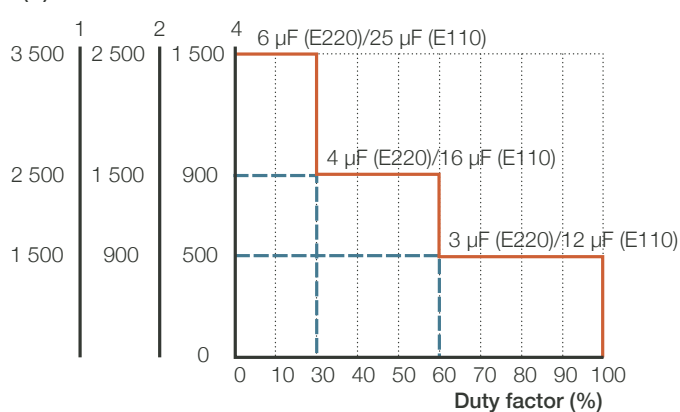
Gear 4 — V (mm/s) — I (A)

\*There may be deviations of +/-10% from the values in the chart.

## Duty cycle – AC version

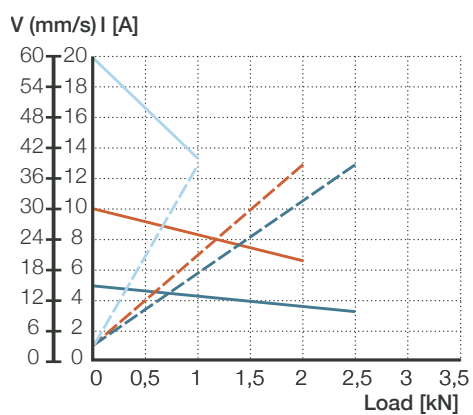
CAP 32 ... 230/120 V AC

F (N) Gear

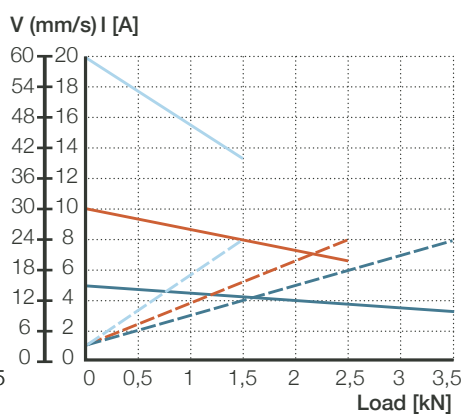


## Performance diagrams – DC version

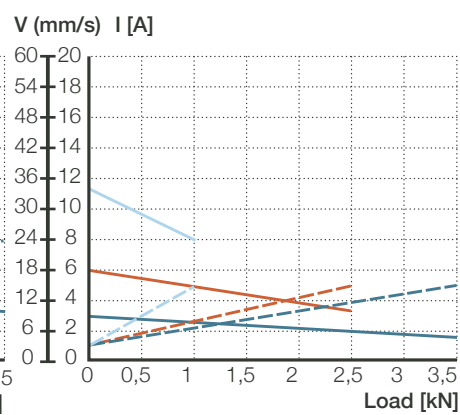
CAP 32.../D12C



CAP 32.../P24C/P24CS/P24CB



CAP 32.../P24CW



Gear 1 — V (mm/s) — I (A)

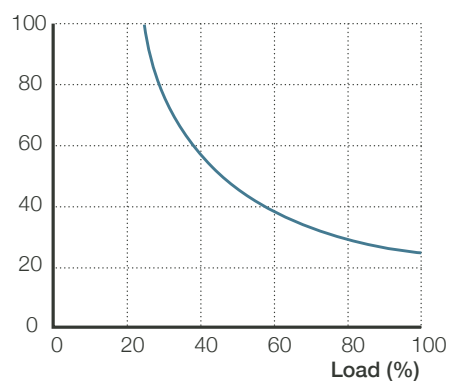
Gear 2 — V (mm/s) — I (A)

Gear 4 — V (mm/s) — I (A)

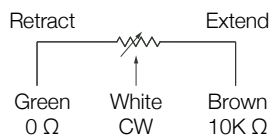
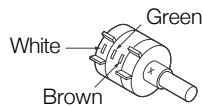
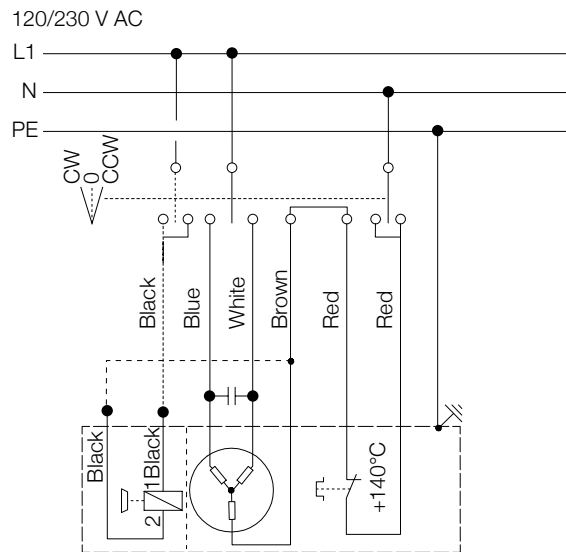
\*There may be deviations of +/-10% from the values in the chart.

## Duty cycle – DC version

Duty factor (%) at 20°C

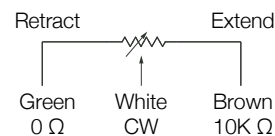
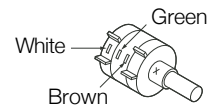
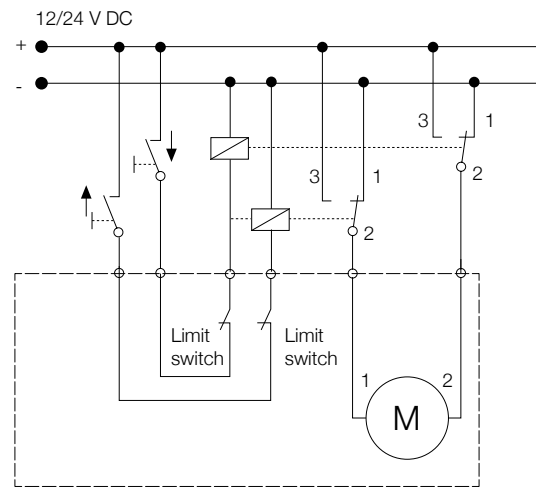


## Connecting diagrams – AC version



Connection diagram for  
rotating potentiometer

## Connecting diagrams – DC version



Connection diagram for  
rotating potentiometer

## CAP 32 – Type codes for accessories and spare parts

Item code	Type code	Order N°
12 V DC motor (flat motor)	D12C	M/0405518
24 V DC motor (flat motor)	P24C	M/0405519-V01
24 V DC motor (flat motor with brake)	P24CB	M/0405523-V01
24 V DC motor (flat motor with extended shaft)	P24CS	M/0405522-V01
24 V DC motor (flat motor with low speed)	P24CW	M/0405521-V01
120 V AC motor (cylindrical motor)	E110C	M/0405533
120 V AC motor (cylindrical motor with brake)	E110CB	M/0405534
230 V AC motor (cylindrical motor)	E220C	M/0405531
230 V AC motor (cylindrical motor with brake)	E220CB	M/0405532
Capacitor value 25 µF (120 V AC)	Capacitor 25 µF	M/0430670-16
Capacitor value 6 µF (230 V AC)	Capacitor 6 µF	M/0430670-03
Limit switch for stroke = 50 mm	CAXE 32 × 50	M/0412030
Limit switch for stroke = 100 mm	CAXE 32 × 100	M/0412031
Limit switch for stroke = 200 mm	CAXE 32 × 200	M/0412033
Limit switch for stroke = 300 mm	CAXE 32 × 300	M/0412034
Limit switch for stroke = 500 mm	CAXE 32 × 500	M/0412036
Limit switch for stroke = 700 mm	CAXE 32 × 700	M/0412037
Proximity switch for CAXE	CAXE Proximity switch	M/0432369
Front mounting attachments type Rod-end	575-32	M/0430575-32
Front mounting attachments type Clevis	576-32	M/0430576-32
Rear mounting attachments type Single ear bracket	580-32	M/0430580-32
Rear mounting attachments type Universal joint	582-32	M/0431780-32

## Ordering key

Dynamic load (N) / Speed (mm/s)			Motor options	
3 500xx	2 500/xx	1 500/xx	No motor	0000
3 500/8	2 500/16	1 500/32	120 V AC/60 Hz, 1-phase, IP54	E110C
3 500/8	2 500/16	1 500/32	120 V AC/60 Hz, 1-phase, brake, IP20	E110CB
3 500/6	2 500/13	1 500/26	230 V AC/50 Hz, 1-phase, IP54	E220C
3 500/6	2 500/13	1 500/26	230 V AC/50 Hz, 1-phase, brake, IP20	E220CB
3 500/xx	2 500/xx	1 500/xx	No motor	0000
2 500/15–10	2 000/30–20	1 000/60–40	12 V DC, flat motor, IP44	D12C
3 500/15–10	2 500/30–20	1 500/60–40	24 V DC, flat motor, IP44	P24C
3 500/10–6	2 500/18–12	1 500/36–26	24 V DC, flat motor, low speed, IP44	P24CW
3 500/15–10	2 500/30–20	1 500/60–40	24 V DC, flat motor, extended shaft, IP44	P24CS
3 500/15–10	2 500/30–20	1 500/60–40	24 V DC, flat motor, brake, IP20	P24CB

1	2	4
---	---	---

Gear

Type

Motor assembly

R Right

L Left

Stroke (S)

050 50 mm

100 100 mm

200 200 mm

300 300 mm

400 400 mm

500 500 mm

700 700 mm

--- Other stroke lengths

Option

S Back-up nut

3

# CAT 32B and CAP 43B

## Linear actuator

### Benefits

- Compact
- Robust
- Modular
- Lubricated for service life
- High efficiency
- Digital encoder feedback



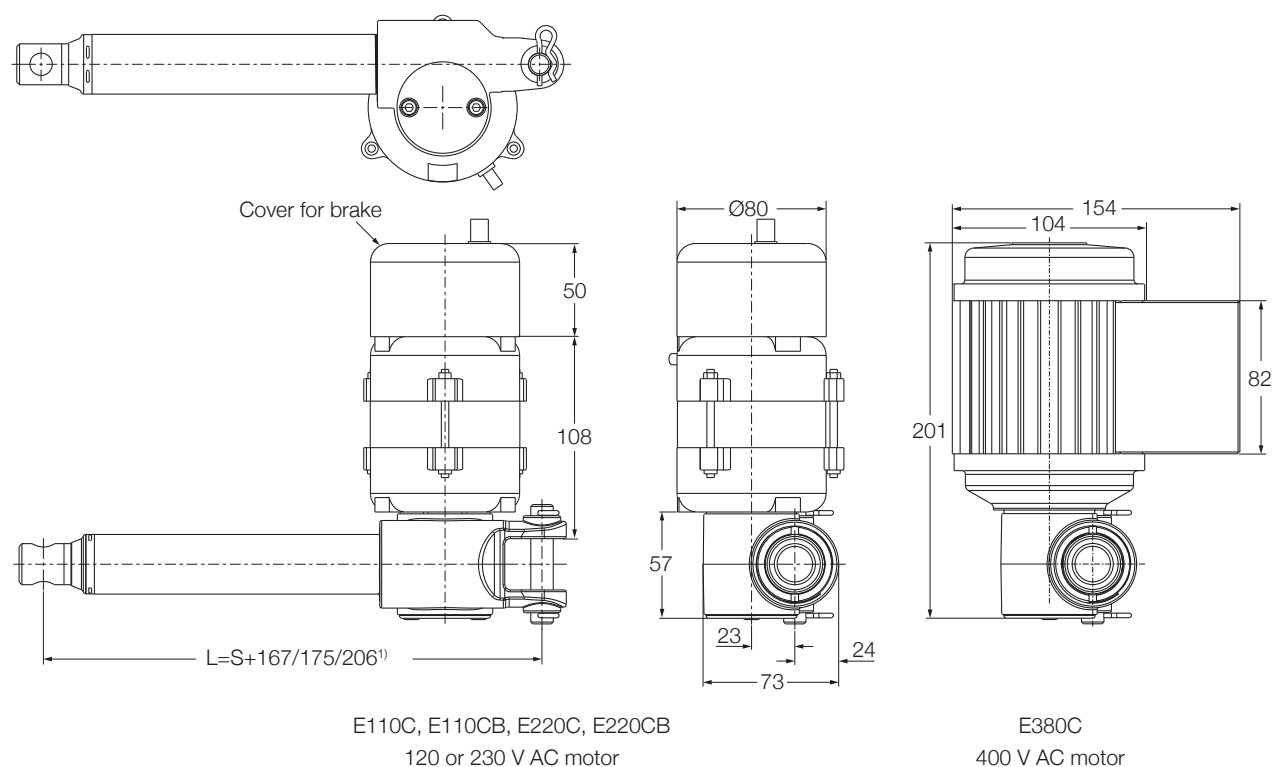
### Technical data

		Unit	CAT 32B – AC version	CAT 32B – DC version	CAP 43B
Rated push load		N	1 500 to 3 500	1 000 to 4 000	1 500 to 4 000
Rated pull load		N	1 500 to 3 500	1 000 to 4 000	1 500 to 4 000
Speed (at full load)		mm/s	6,5 to 32 <sup>1)</sup>	6 to 66 <sup>1)</sup>	6 to 66 <sup>1)</sup>
Stroke		mm	50 to 700	50 to 700	50 to 700
Retracted length		mm	S+167/175/206 <sup>2)</sup>	S+167/175/206 <sup>2)</sup>	S+167/175/206 <sup>2)</sup>
Voltage		V AC	120, 230 or 400	–	–
		V DC	–	12 or 24	24
Power consumption	120 V AC	W	98 (brake 133,2 W)	–	–
	230 V AC	W	92 (brake 117,3 W)	–	–
	400 V AC	W	80	–	–
	12 or 24 V DC	W	–	N/A	N/A
Current consumption	120 V AC	A	0,82 (brake +0,29 A)	–	–
	230 V AC	A	0,4 (brake +0,11 A)	–	–
	400 V AC	A	0,2	–	–
	12 V DC	A	–	18	–
	24 V DC	A	–	9	9
	24 V DC	A	–	5 (for motors C24CW and P24CW)	5 (for motors C24CW and P24CW)
Duty cycle		%	30	20	20
Ambient temperature		°C	–20 to +50	–20 to +50	–20 to +50
Degree of protection		IP	20/54/55	20/44/66 <sup>1)</sup>	44
Weight		kg	2 to 3,5	2 to 3,5	2,0 to 2,7

<sup>1)</sup> Depending on selected motor

<sup>2)</sup> Dimension depends on selected front attachment

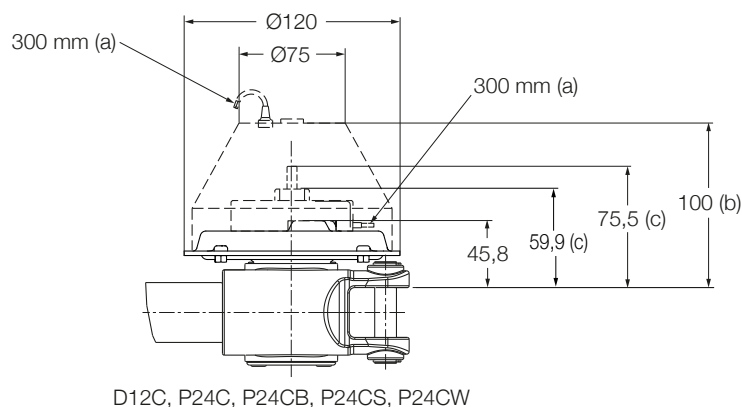
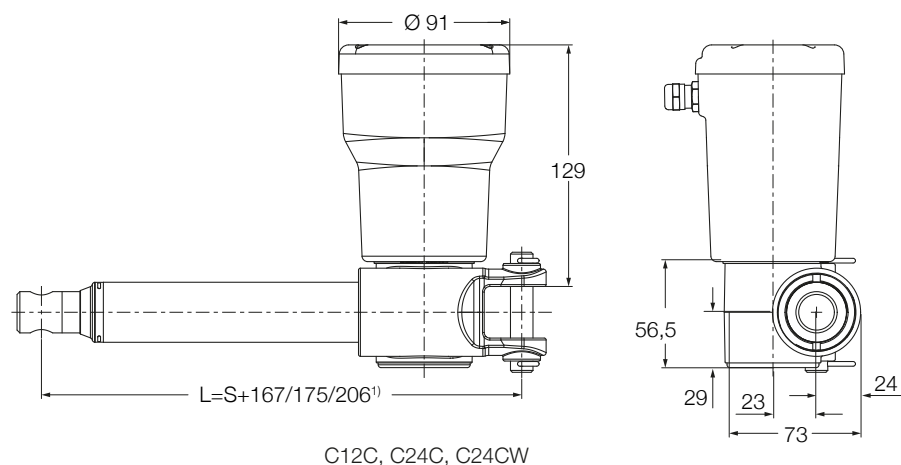
## Dimensional drawing – CAT 32B AC version



**Legend:**  
S = stroke  
L = retracted length

<sup>1)</sup> Dimension depends on selected front attachment

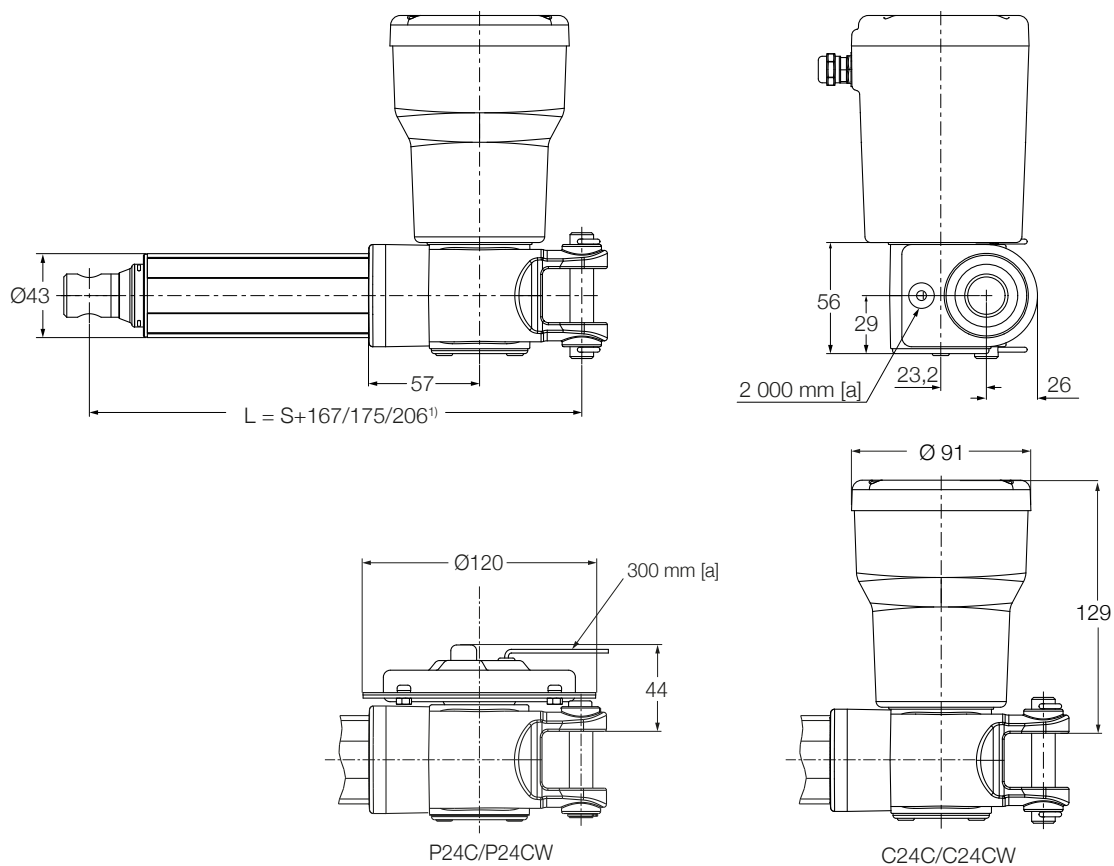
## Dimensional drawing – CAT 32B DC version



**Legend:**  
S = stroke  
L = retracted length  
(a) = cable length  
(b) = cover for brake (P24CB)  
(c) = extended shaft (P24CS)  
(d) = motor (D12C, P24C, P24CW)

<sup>1)</sup> Dimension depends on selected front attachment

## Dimensional drawing – CAP 43B



### Legend:

S = stroke

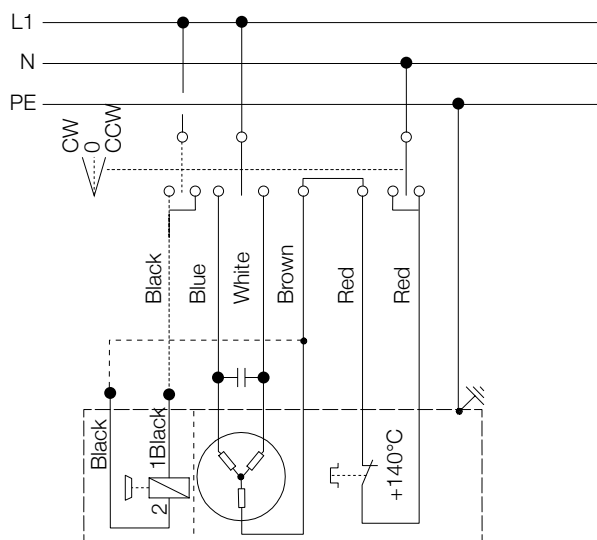
L = retracted length

[a] = cable length

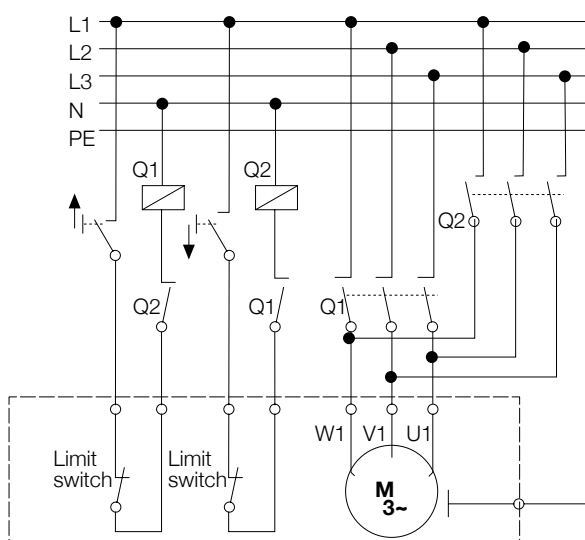
<sup>1)</sup> Dimension depends on selected front attachment

## Connecting diagrams – AC version

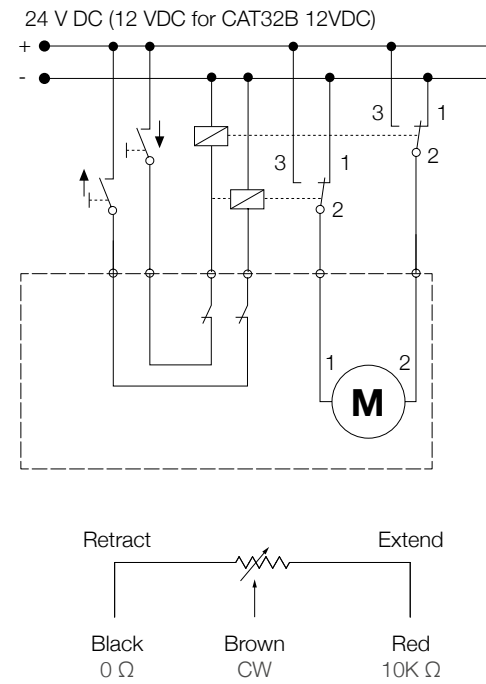
120/230 V AC



400 V AC



Connecting diagrams – DC version



Connection diagram for linear potentiometer only for CAP 43B.

3

Suitable control units and accessories  
AC version

	Limit switch	Encoder
	CAXE32B	E2
E110C	•	•
E110CB	•	•
E220C	•	•
E220CB	•	•
E380C	•	•

Suitable control units and accessories  
DC version

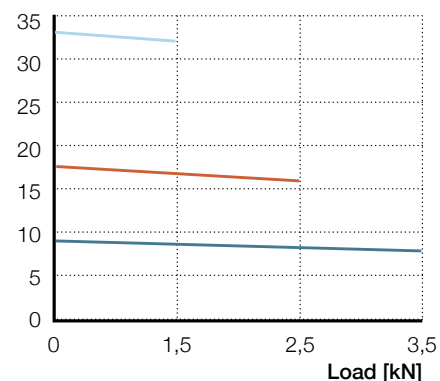
	Limit switch	Encoder
	CAXE32B	E2
C12C	•	•
D12C	•	•
C24C	•	•
C24CW	•	•
P24C	•	•
P24CB	•	•
P24CS	•	•
P24CW	•	•



## Performance diagrams – AC version

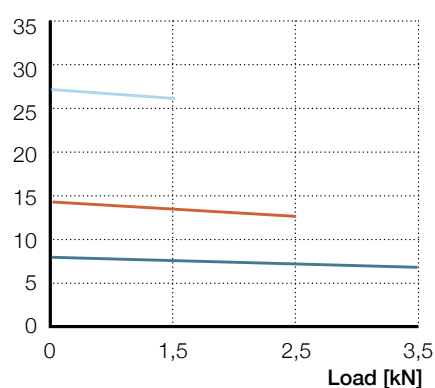
Speed-load diagram CAT 32B ... 120 V AC

Speed [mm/s]



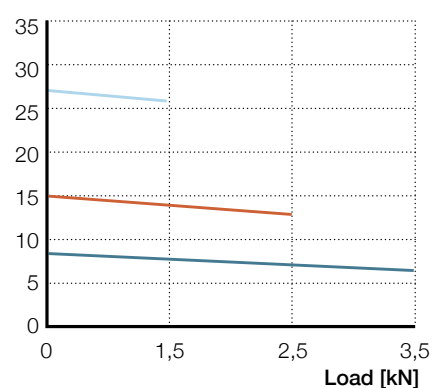
Speed-load diagram CAT 32B ... 230 V AC

Speed [mm/s]



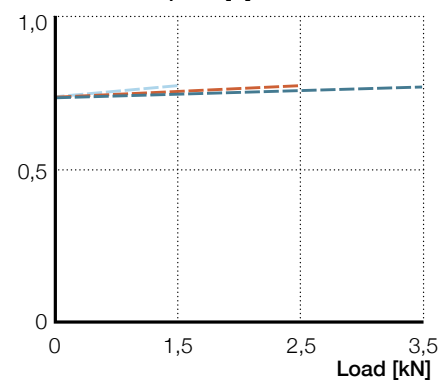
Speed-load diagram CAT 32B ... 400 V AC

Speed [mm/s]



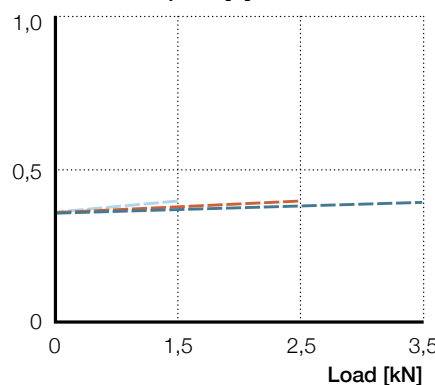
Current-load diagram CAT 32B ... 120 V AC

Current consumption [A]



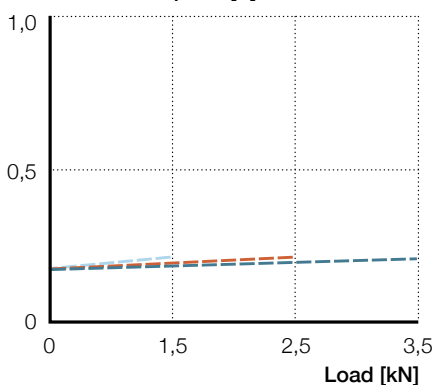
Current-load diagram CAT 32B ... 230 V AC

Current consumption [A]



Current-load diagram CAT 32B ... 400 V AC

Current consumption [A]



Gear 1 — V (mm/s) — I (A)

Gear 2 — V (mm/s) — I (A)

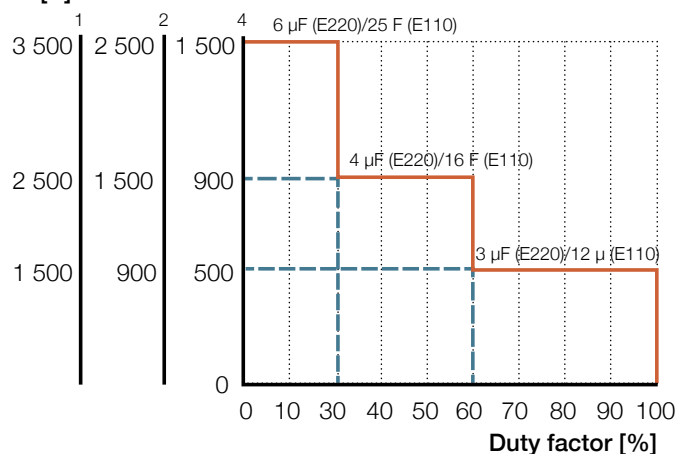
Gear 4 — V (mm/s) — I (A)

\*There may be deviations of +/-10% from the values in the chart.

## Duty cycle – AC version

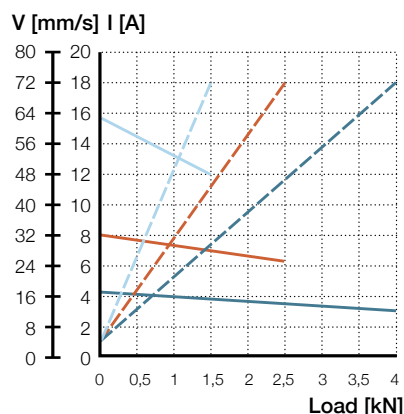
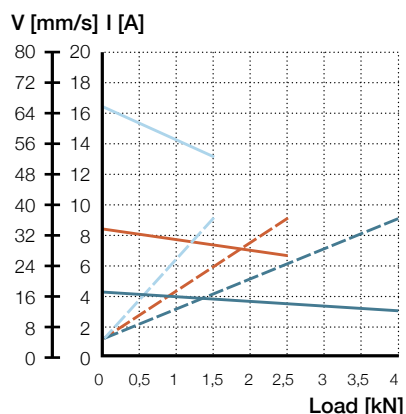
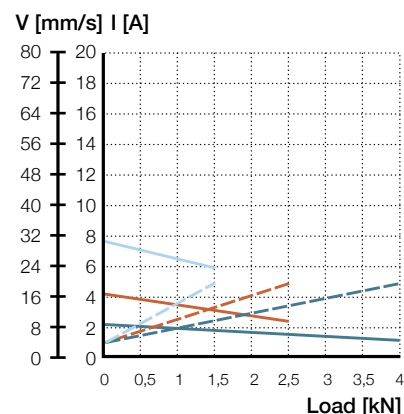
CAT 32B...230/120 V AC

F [N] Gear

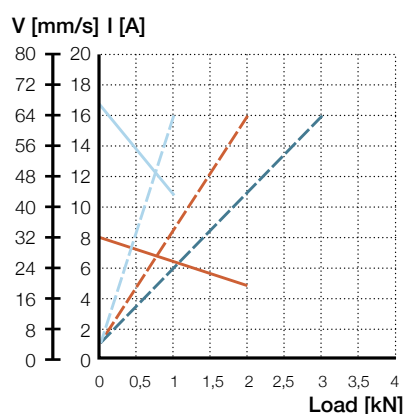
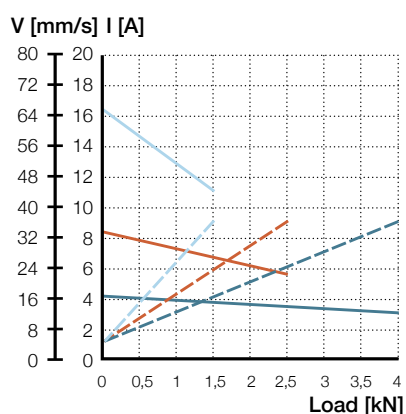
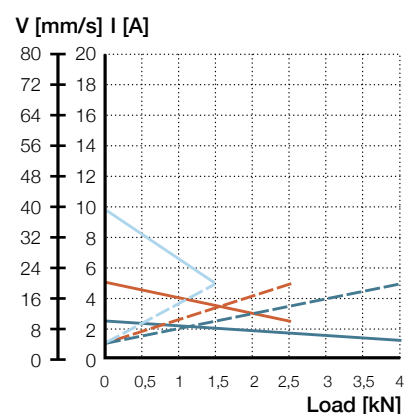


## Performance diagrams – DC version

CAT 32B.../C12C

CAT 32B.../C24C  
CAP 43B.../C24CCAT 32B.../C24CW  
CAP 43B.../C24CW

CAT 32B.../D12C

CAT 32B.../P24C/P24CB/P24CS  
CAP 43B.../P24CCAT 32B.../P24CW  
CAP 43B.../P24CW

Gear 1 — V (mm/s) — I (A)

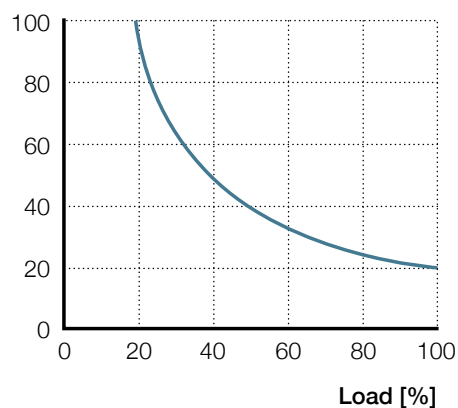
Gear 2 — V (mm/s) — I (A)

Gear 4 — V (mm/s) — I (A)

\*There may be deviations of +/-10% from the values in the chart.

## Duty cycle – DC version

Duty factor [%] at 20 °C



## CAT 32B – Type codes for accessories and spare parts

Item code	Type code	Order N°
12 V DC motor (cylindrical motor)	C12C	M/0405535
12 V DC motor (flat motor)	D12C	M/0405518
24 V DC motor (cylindrical motor)	C24C	M/0405536
24 V DC motor (cylindrical with low speed)	C24CW	M/0405537
24 V DC motor (flat motor)	P24C	M/0405519-V01
24 V DC motor (flat motor with brake)	P24CB	M/0405523-V01
24 V DC motor (flat motor with extended shaft)	P24CS	M/0405522-V01
24 V DC motor (flat motor with low speed)	P24CW	M/0405521-V01
120 V AC motor (cylindrical motor)	E110C	M/0405533
120 V AC motor (cylindrical motor with brake)	E110CB	M/0405534
230 V AC motor (cylindrical motor)	E220C	M/0405531
230 V AC motor (cylindrical motor with brake)	E220CB	M/0405532
400 V AC motor (cylindrical motor)	E380C	M/0411607
Capacitor value 25 µF (120 V AC)	Capacitor 25 µF	M/0430670-16
Capacitor value 6 µF (230 V AC)	Capacitor 6 µF	M/0430670-03
Limit switch for stroke = 50 mm	CAXE 32B × 50	M/0412070
Limit switch for stroke = 100 mm	CAXE 32B × 100	M/0412071
Limit switch for stroke = 200 mm	CAXE 32B × 200	M/0412073
Limit switch for stroke = 300 mm	CAXE 32B × 300	M/0412074
Limit switch for stroke = 400 mm	CAXE 32B × 400	M/0412075
Limit switch for stroke = 500 mm	CAXE 32B × 500	M/0412076
Limit switch for stroke = 700 mm	CAXE 32B × 700	M/0412077
Proximity switch for CAXE	CAXE Proximity switch	M/0432369
Front mounting attachments type Rod-end	575-32	M/0430575-32
Front mounting attachments type Clevis	576-32	M/0430576-32
Rear mounting attachments type Single ear bracket	580-32	M/0430580-32
Rear mounting attachments type Universal joint	582-32	M/0431780-32

## CAP 43B – Type codes for accessories and spare parts

Item code	Type code	Order N°
24 V DC motor (cylindrical motor)	C24C	M/0405536
24 V DC motor (cylindrical with low speed)	C24CW	M/0405537
24 V DC motor (flat motor)	P24C	M/0405519-V01
24 V DC motor (flat motor with low speed)	P24CW	M/0405521-V01
Front mounting attachments type Rod-end	575-32	M/0430575-32
Front mounting attachments type Clevis	576-32	M/0430576-32
Rear mounting attachments type Single ear bracket	580-32	M/0430580-32
Rear mounting attachments type Universal joint	582-32	M/0431780-32

Load [N] / Full Load Speed [mm/s]			Motor options	
4 000/xx	2 500/xx	1 500/xx	No motor	0000
3 000/17-11	2 000/34-19	1 000/67-43	12 V DC, flat motor, IP44	D12C
3 500/8	2 500/16	1 500/32	120 V AC/60 Hz, 1-phase, IP54	E110C
3 500/8	2 500/16	1 500/32	120 V AC/60 Hz, 1-phase, brake, IP20	E110CB
3 500/6,5	2 500/13	1 500/26	230 V AC/50 Hz, 1-phase, IP54	E220C
3 500/6,5	2 500/13	1 500/26	230 V AC/50 Hz, 1-phase, brake, IP20	E220CB
3 500/7	2 500/14	1 500/32	400 V AC/50 Hz, 3-phase, IP55	E380C
4 000/xx	2 500/xx	1 500/xx	No motor	0000
4 000/17-12	2 500/32-25	1 500/63-48	12 V DC, IP66	C12C
4 000/17-13	2 500/33-26	1 500/65-52	24 V DC, IP66	C24C
4 000/9-5	2 500/17-10	1 500/31-24	24 V DC, low speed motor, IP66	C24CW
4 000/16-12	2 500/33-22	1 500/65-44	24 V DC, flat motor, IP44	P24C
4 000/16-12	2 500/33-22	1 500/65-44	24 V DC, flat motor, brake, IP20	P24CB
4 000/16-12	2 500/33-22	1 500/65-44	24 V DC, flat motor, ext.shaft, IP44	P24CS
4 000/10-6	2 500/18-12	1 500/36-26	24 V DC, flat motor, low speed, IP44	P24CW

**1**                      **2**                      **4**

Gear \_\_\_\_\_

Type **C A T** **3 2 B X**     X             /              

Motor assembly \_\_\_\_\_  
R Right  
L Left

Stroke (S) \_\_\_\_\_  
050 50 mm  
100 100 mm  
200 200 mm  
300 300 mm  
400 400 mm  
500 500 mm  
700 700 mm  
--- Other stroke lengths

Rear attachment \_\_\_\_\_  
A1 Fork ear, Ø12,0 mm  
A2 Fork ear, Ø12,7 mm  
K1 Single ear, Ø12,0 mm  
K2 Single ear, Ø12,7 mm

Front attachment \_\_\_\_\_  
G1 Hole, Ø12,0 mm  
G2 Hole, Ø12,7 mm  
G3 Male thread, M12  
G4 Female thread, M12  
G5 Fork ear, Ø10,1 mm

Feedback \_\_\_\_\_  
No encoder (no code)  
E2 Encoder (for all standard motors)

Option \_\_\_\_\_  
F Friction clutch (not available with option encoder)  
Z No friction clutch  
S Back-up nut

Option for CxxC motors \_\_\_\_\_  
T2 Straight cable, 2,0 m, no plug  
T2P Straight cable, 2,0 m, jack plug  
T6 Straight cable, 6,0 m, no plug

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## Ordering key

Load [N] / Full Load Speed [mm/s]			Motor options	
4 000/xx	2 500/xx	1 500/xx	No motor	0000
4 000/17-13	2 500/33-26	1 500/65-52	24 V DC, IP44	C24C
4 000/9-5	2 500/17-10	1 500/31-24	24 V DC, low speed, IP44	C24CW
4 000/17-11	2 500/34-19	1 500/66-38	24 V DC, flat motor, IP44	P24C
4 000/10-6	2 500/18-12	1 500/36-26	24 V DC, flat motor, low speed, IP44	P24CW

1	2	4
Gear		

**Type** C A P 4 3 B X   X           /                

**Motor assembly**

R Right  
L Left

**Stroke [S]**

100 100 mm  
200 200 mm  
300 300 mm  
400 400 mm  
500 500 mm  
700 700 mm

**Rear attachment**

A1 Fork ear, Ø12,0 mm  
A2 Fork ear, Ø12,7 mm  
K1 Single ear, Ø12,0 mm  
K2 Single ear, Ø12,7 mm

**Front attachment**

G1 Hole, Ø12,0 mm  
G2 Hole, Ø12,7 mm  
G3 Male thread, M12  
G4 Female thread, M12  
G5 Fork ear, Ø10,1 mm

**Option**

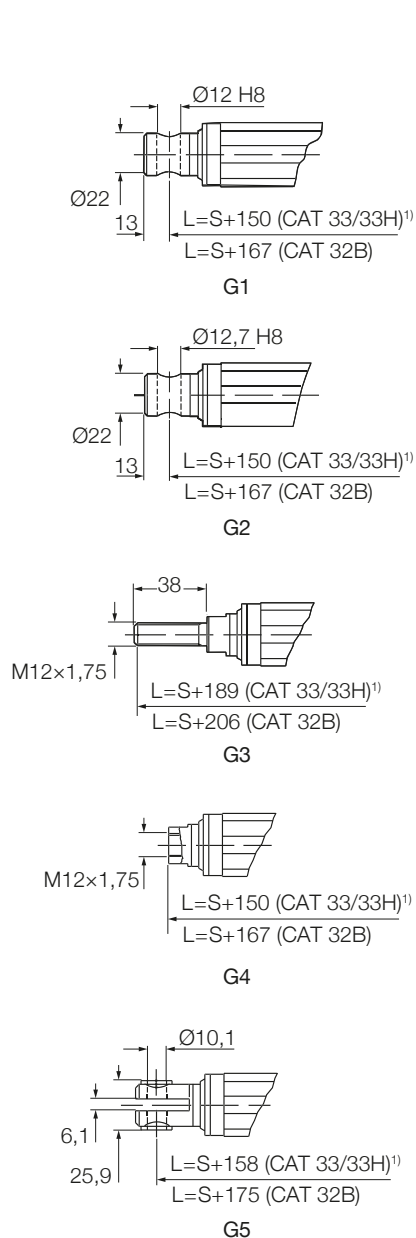
F Friction clutch  
S Back-up nut

**Cable option for C24C[W] motors**

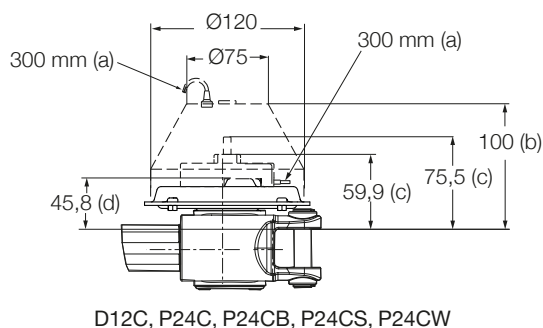
T2 Straight, 2,0 m  
T6 Straight cable, 6,0 m, no plug

## Detailed drawings of front and rear attachments for CAT and CAP 43 and motor options for CAT

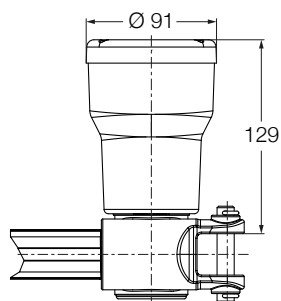
### Front attachments and retracted length



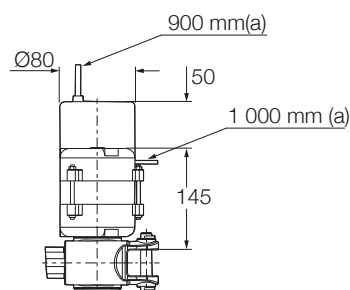
### Motor options for CAT



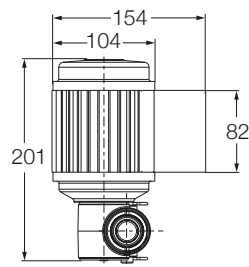
D12C, P24C, P24CB, P24CS, P24CW



C12XX/C24XX

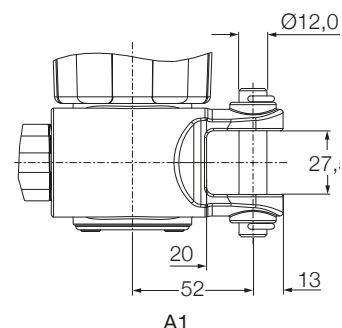


E110C, E110CB, E220C, E220CB

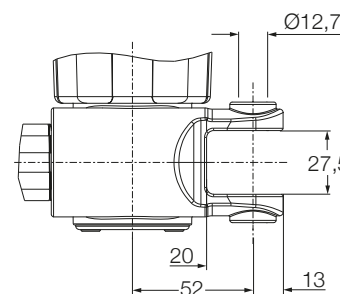


E380C

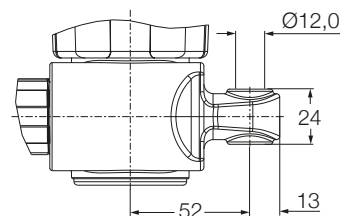
### Rear attachments



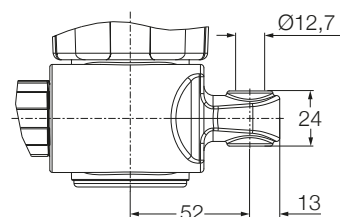
A1



A2



K1



K2

### Legend:

- S = stroke
- L = retracted length
- (a) = cable length
- (b) = cover for brake
- (c) = extended shaft
- (d) = motor

<sup>1)</sup> If S = 400, add 50 mm to retracted length.

# CAT 33 and CAP 43A

## Linear actuator

### Benefits

- Small
- Robust
- Highly efficient
- Lubricated for service life
- Digital encoder feedback



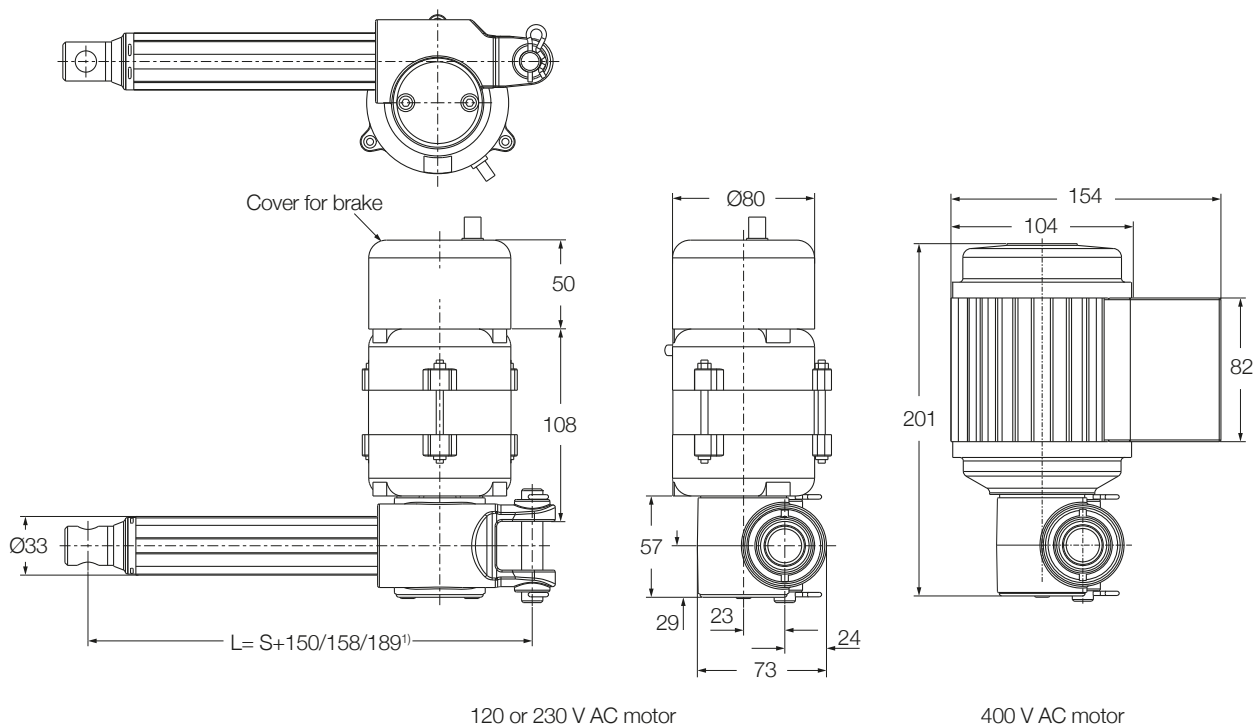
### Technical data

		Unit	CAT 33 - AC version	CAT 33 - DC version	CAP 43A
Rated push load		N	800 to 3 000	800 to 3 000	1 000 to 3 000
Rated pull load		N	800 to 3 000	800 to 3 000	1 000 to 3 000
Speed (at full load)		mm/s	5 to 24 <sup>1)</sup>	6 to 66 <sup>1)</sup>	6 to 66 <sup>1)</sup>
Stroke		mm	100 to 400	100 to 400	100 to 400
Retracted length		mm	S+150/158/189 <sup>2)</sup>	S+150/158/189 <sup>2)</sup>	S+150/158/189 <sup>2)</sup>
Voltage		V AC	120, 230 or 400	–	–
		V DC	–	12 or 24	24
Power consumption	120 V AC	W	98 (brake 133,2 W)	–	–
	230 V AC	W	92 (brake 117,3 W)	–	–
	400 V AC	W	80	–	–
	12 or 24 V DC	W	–	N/A	N/A
Current consumption	120 V AC	A	0,82 (brake +0,29 A)	–	–
	230 V AC	A	0,4 (brake + 0,11 A)	–	–
	400 V AC	A	0,2	–	–
	12 V DC	A	–	18	–
	24 V DC	A	–	9	9
	24 V DC	A	–	5 (for motors C24CW and P24CW)	5
Duty cycle		%	30	15	15
Ambient temperature		°C	–20 to +50	–20 to +50	–20 to +50
Degree of protection		IP	20/54/55	20/44/66 <sup>1)</sup>	44
Weight		kg	2 to 2,7	2 to 2,7	2,0 to 2,7

<sup>1)</sup> Depending on selected motor

<sup>2)</sup> Dimension depends on selected front attachment

## Dimensional drawing – CAT 33 AC version



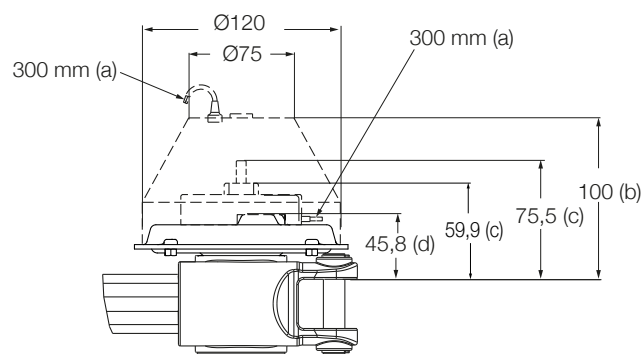
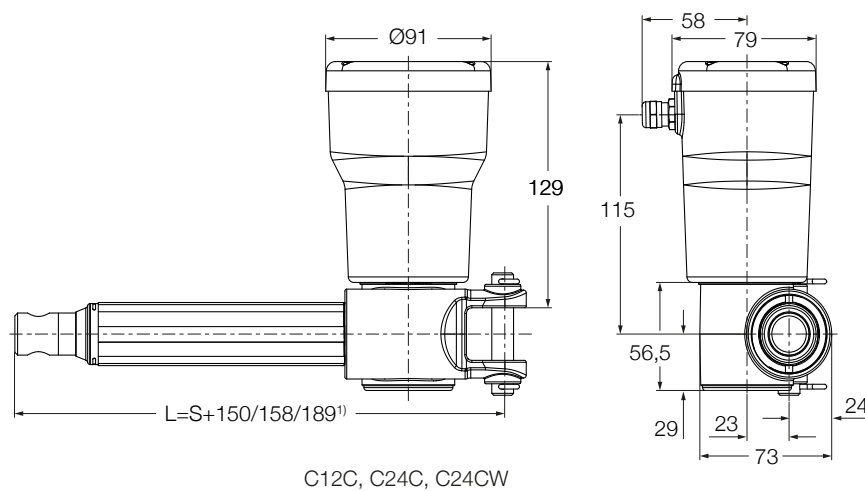
### Legend:

S = stroke

L = retracted length

<sup>1)</sup> Dimension depends on selected front attachment

## Dimensional drawing – CAT 33 DC version



### Legend:

S = stroke

L = retracted length

(a) = cable length

(b) = cover for brake (P24CB)

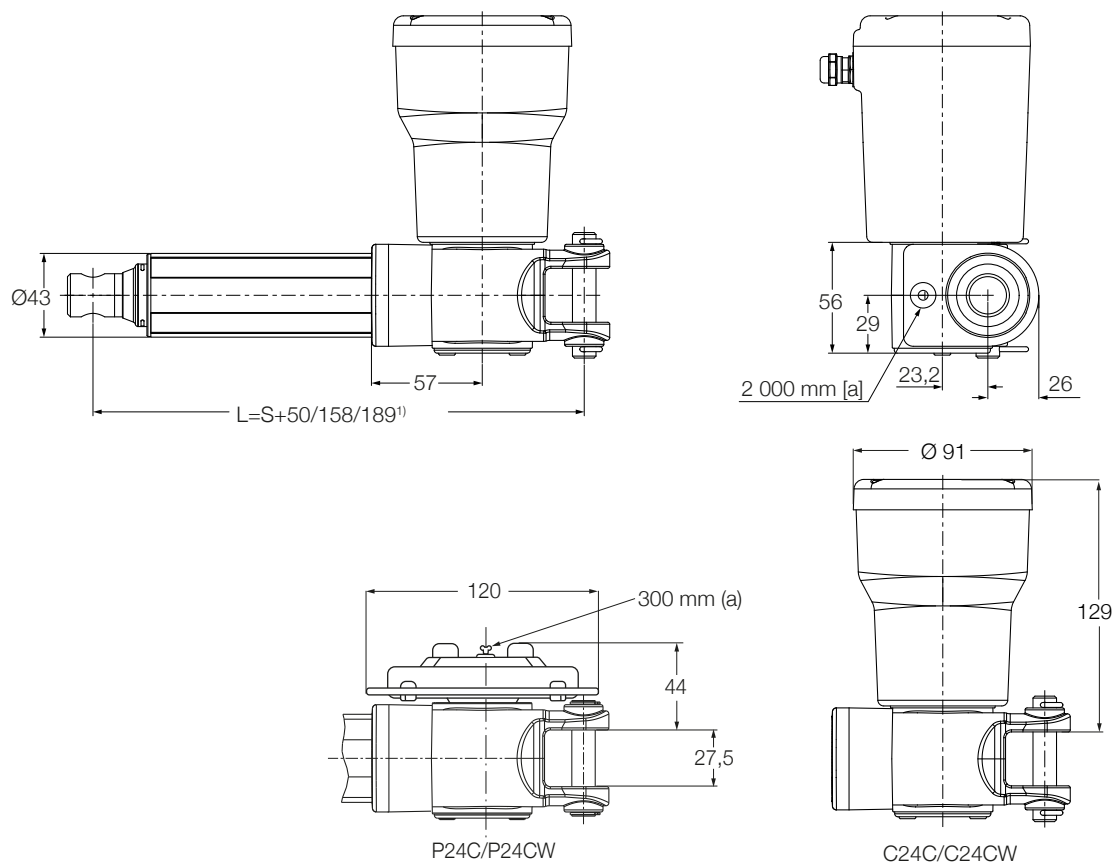
(c) = extended shaft (P24CS)

(d) = motor (P24C)

<sup>1)</sup> Dimension depends on selected front attachment



## Dimensional drawing – CAP 43A



### Legend:

S = stroke

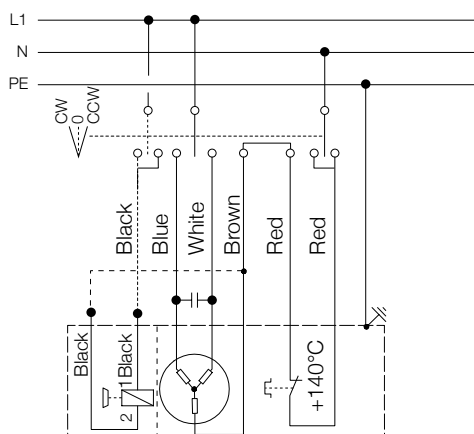
L = retracted length

(a) = cable length

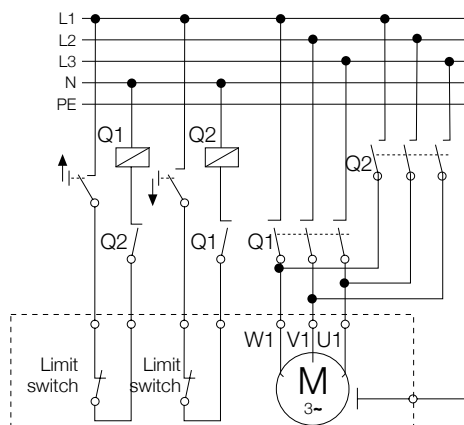
<sup>1)</sup> Dimension depends on selected front attachment

## Connecting diagrams – CAT 33 AC version

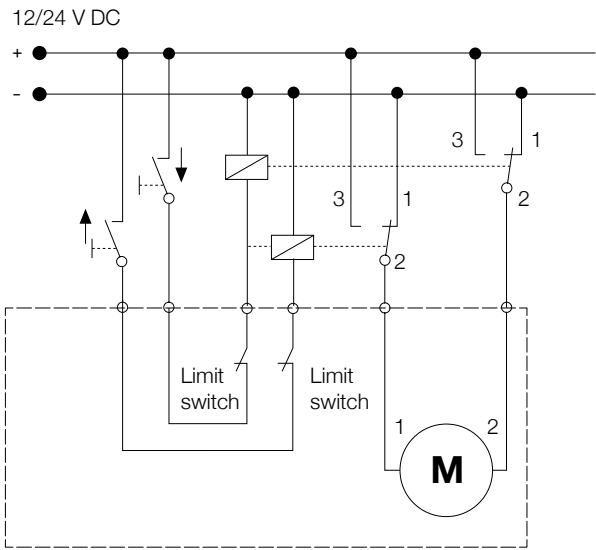
120/230 V AC



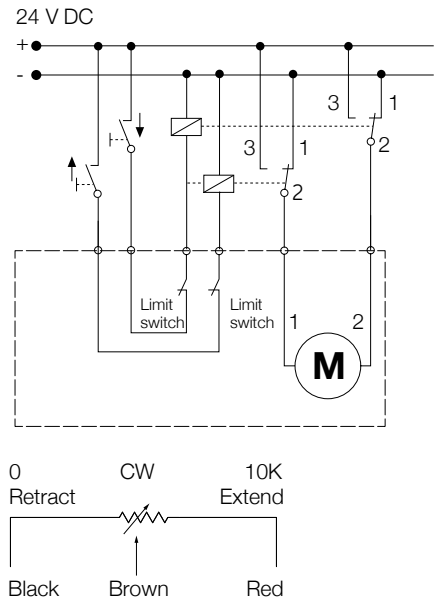
400 V AC



Connecting diagrams – CAT 33 DC version



Connecting diagrams – CAP 43A



Connection diagram for linear potentiometer

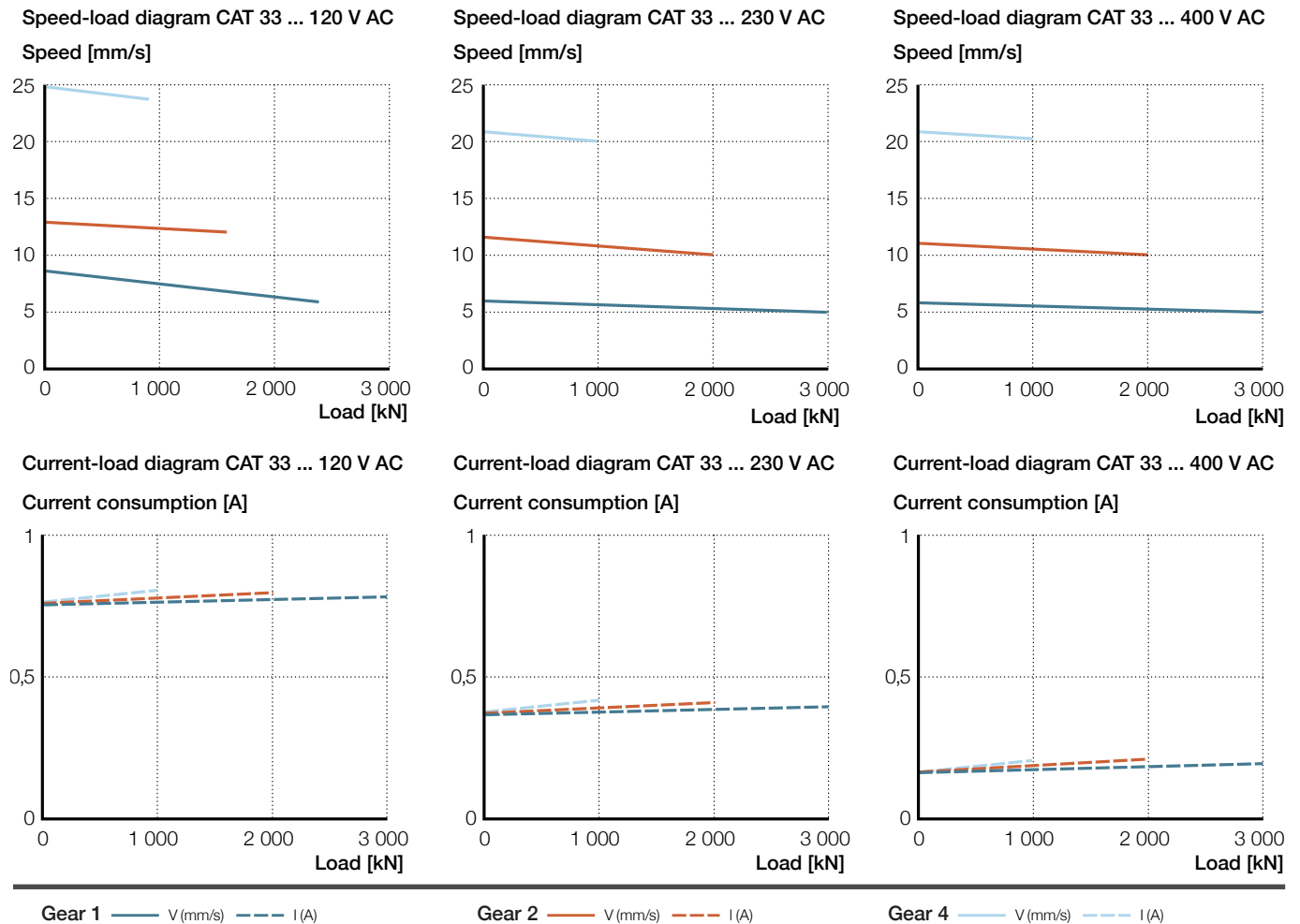
Suitable control units and accessories  
AC version

	Limit switch	Encoder
	CAXD33	E2
E110C	•	•
E110CB	•	•
E220C	•	•
E220CB	•	•
E380C	•	•

Suitable control units and accessories  
DC version

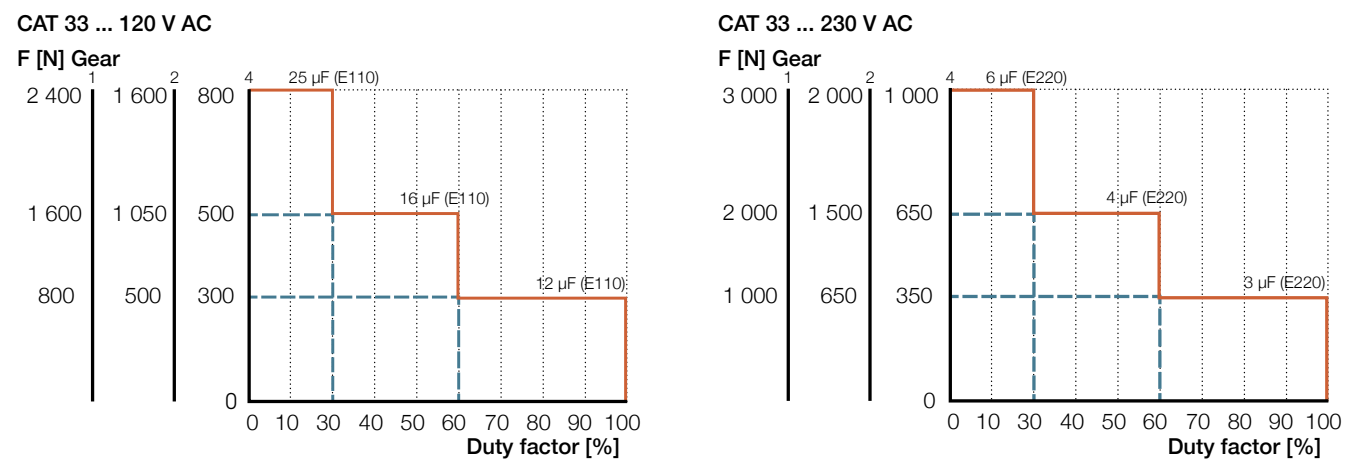
	Encoder
	E2
C12C	•
D12C	•
C24C	•
C24CW	•
P24C	•
P24CB	•
P24CS	•
P24CW	•

## Performance diagrams – AC version



\*There may be deviations of +/-10% from the values in the chart.

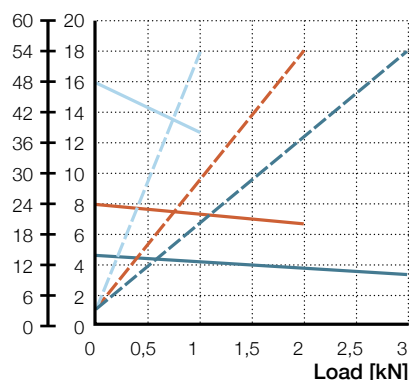
## Duty cycle



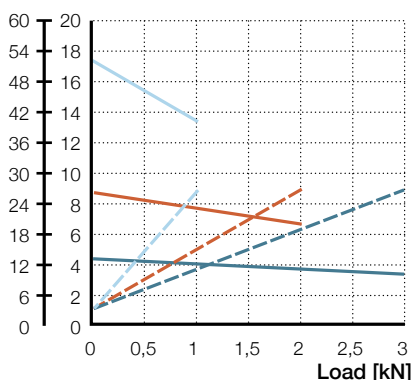
## Performance diagrams – DC version

CAT 33.../C12C

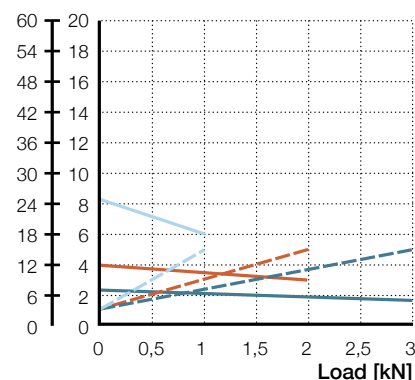
V [mm/s] I [A]

CAT 33.../C24C  
CAP 43A.../C24C

V [mm/s] I [A]

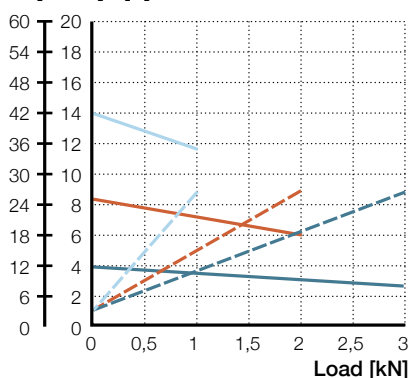
CAT 33.../C24CW  
CAP 43A.../C24CW

V [mm/s] I [A]

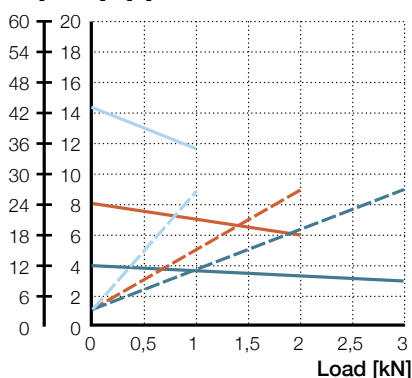


CAT 33.../D12C

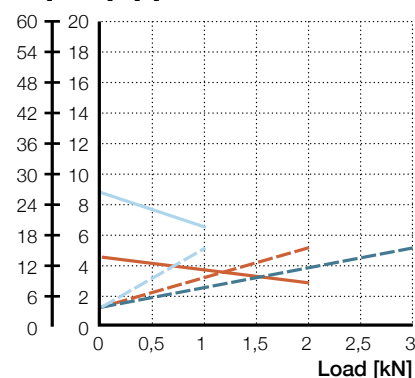
V [mm/s] I [A]

CAT 33.../P24C/P24CB/P24CS  
CAP 43A.../P24C

V [mm/s] I [A]

CAT 33.../P24CW  
CAP 43A.../P24CW

V [mm/s] I [A]



Gear 1 — V (mm/s) — I (A)

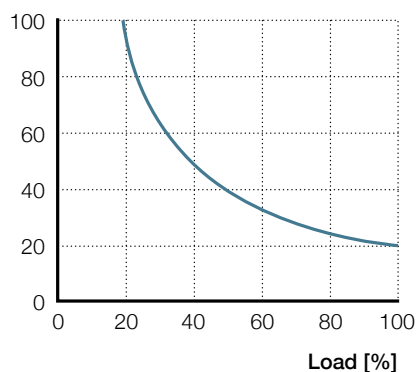
Gear 2 — V (mm/s) — I (A)

Gear 4 — V (mm/s) — I (A)

\*There may be deviations of +/-10% from the values in the chart.

## Duty cycle – DC version

Duty factor [%] at 20 °C



## CAT 33 – Type codes for accessories and spare parts

Item code	Type code	Order N°
12 V DC motor (cylindrical motor)	C12C	M/0405535
12 V DC motor (flat motor)	D12C	M/0405518
24 V DC motor (cylindrical motor)	C24C	M/0405536
24 V DC motor (cylindrical with low speed)	C24CW	M/0405537
24 V DC motor (flat motor)	P24C	M/0405519-V01
24 V DC motor (flat motor with brake)	P24CB	M/0405523-V01
24 V DC motor (flat motor with extended shaft)	P24CS	M/0405522-V01
24 V DC motor (flat motor with low speed)	P24CW	M/0405521-V01
120 V AC motor (cylindrical motor)	E110C	M/0405533
120 V AC motor (cylindrical motor with brake)	E110CB	M/0405534
230 V AC motor (cylindrical motor)	E220C	M/0405531
230 V AC motor (cylindrical motor with brake)	E220CB	M/0405532
400 V AC motor (cylindrical motor)	E380C	M/0411607
Capacitor value 25 µF (120 V AC)	Capacitor 25 µF	M/0430670-16
Capacitor value 6 µF (230 V AC)	Capacitor 6 µF	M/0430670-03
Limit switch for any stroke, normally closed	CAXD33, NC	M/0440054
Limit switch for any stroke, normally open	CAXD33, NO	M/0440053
Front mounting attachments type Rod-end	575-32	M/0430575-32
Front mounting attachments type Clevis	576-32	M/0430576-32
Rear mounting attachments type Single ear bracket	580-32	M/0430580-32
Rear mounting attachments type Universal joint	582-32	M/0431780-32

## CAP 43A – Type codes for accessories and spare parts

Item code	Type code	Order N°
24 V DC motor (cylindrical motor)	C24C	M/0405536
24 V DC motor (cylindrical with low speed)	C24CW	M/0405537
24 V DC motor (flat motor)	P24C	M/0405519-V01
24 V DC motor (flat motor with low speed)	P24CW	M/0405521-V01
Front mounting attachments type Rod-end	575-32	M/0430575-32
Front mounting attachments type Clevis	576-32	M/0430576-32
Rear mounting attachments type Single ear bracket	580-32	M/0430580-32
Rear mounting attachments type Universal joint	582-32	M/0431780-32

### Ordering key

Load [N] / Full Load Speed [mm/s]			Motor options	
3 000/xx	2 000/xx	1 000/xx	No motor	0000
2 400/6	1 600/12	800/24	120 V AC/60 Hz, 1-phase, IP54	E110C
2 400/6	1 600/12	800/24	120 V AC/60 Hz, 1-phase, brake, IP20	E110CB
3 000/5	2 000/10	1 000/20	230 V AC/50 Hz, 1-phase, IP54	E220C
3 000/5	2 000/10	1 000/20	230 V AC/50 Hz, 1-phase, brake, IP20	E220CB
3 000/5	2 000/10	1 000/20	400 V AC/50 Hz, 3-phase, IP55	E380C
3 000/xx	2 000/xx	1 000/xx	No motor	0000
3 000/13–10	2 000/24–20	1 000/48–38	12 V DC, IP66	C12C
2 400/ 11–7	1 600/21–15	800/39–21	12 V DC, flat motor, IP44	D12C
3 000/13–10	2 000/26–20	1 000/52–40	24 V DC, IP66	C24C
3 000/7–5	2 000/13–9	1 000/25–18	24 V DC, low speed, IP66	C24CW
3 000/17–11	2 000/34–19	1 000/66–38	24 V DC, flat motor, IP44	P24C
3 000/12–9	2 000/25–18	1 000/43–35	24 V DC, flat motor, brake, IP20	P24CB
3 000/17–11	2 000/34–19	1 000/66–38	24 V DC, flat motor, IP44, ext. shaft	P24CS
3 000/10–16	2 000/18–12	1 000/36–26	24 V DC, flat motor, low speed, IP44	P24CW

[illegible]

■ Options shown in red are only available on request. Contact Ewellix for more information on minimum quantities and additional costs.

## Ordering key

Load [N] / Full Load Speed [mm/s]			Motor options	
3 000/xx	2 000/xx	1 000/xx	No motor	0000
3 000/13-10	2 000/26-20	1 000/52-40	24 VDC, IP44	C24C
3 000/7-5	2 000/13-9	1 000/25-18	24 VDC, IP44	C24CW
3 000/17-11	2 000/34-19	1 000/66-38	24 VDC, flat motor, IP44	P24C
3 000/7-5	2 000/13-8	1 000/26-19	24 VDC, flat motor, low speed, IP44	C24CW

1	2	4
Gear		

**Type** \_\_\_\_\_

**Motor assembly** \_\_\_\_\_

R Right  
L Left

**Stroke [S]** \_\_\_\_\_

100 100 mm  
200 200 mm  
300 300 mm  
400 400 mm

**Rear attachment** \_\_\_\_\_

A1 Fork ear, Ø12,0 mm  
A2 Fork ear, Ø12,7 mm  
K1 Single ear, Ø12,0 mm  
K2 Single ear, Ø12,7 mm

**Front attachment** \_\_\_\_\_

G1 Hole, Ø12,0 mm  
G2 Hole, Ø12,7 mm  
G3 Male thread, M12  
G4 Female thread, M12  
G5 Fork ear, Ø10,1 mm

**Option** \_\_\_\_\_

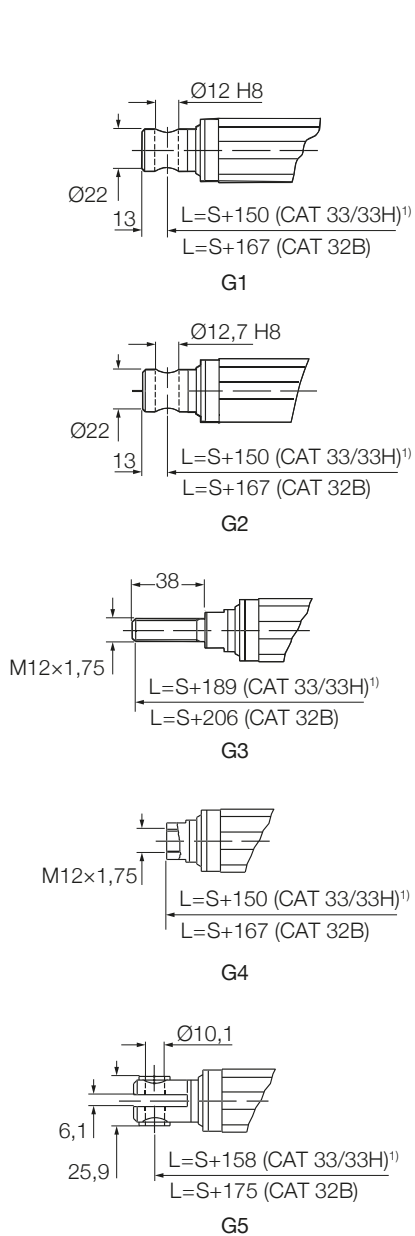
F Friction clutch

**Cable option for C24C[W] motors** \_\_\_\_\_

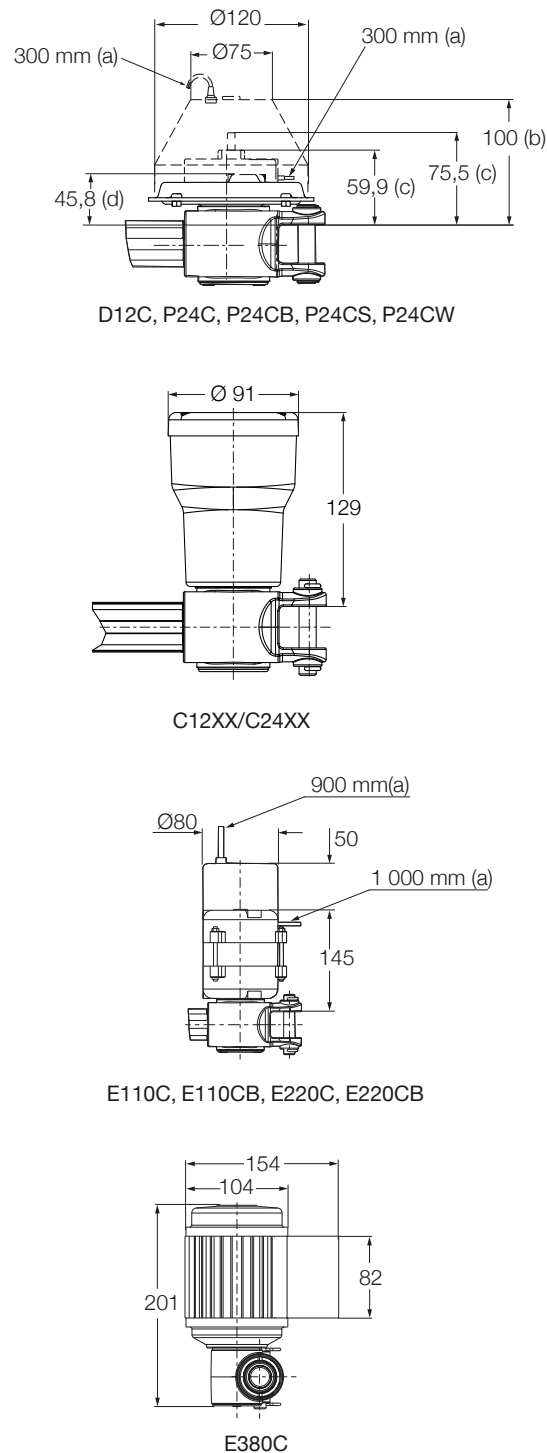
T2 Straight, 2,0 m  
T6 Straight cable, 6,0 m, no plug

## Detailed drawings of front and rear attachments for CAT and CAP 43 and motor options for CAT

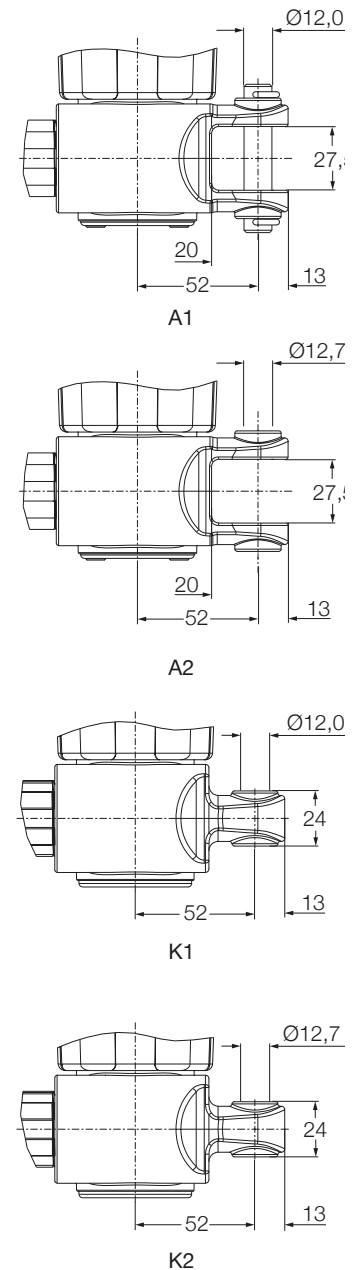
### Front attachments and retracted length



### Motor options for CAT



### Rear attachments



### Legend:

S = stroke  
 L = retracted length  
 (a) = cable length  
 (b) = cover for brake  
 (c) = extended shaft  
 (d) = motor

<sup>1)</sup> If S = 400, add 50 mm to retracted length.



# CAT 33H

## Linear actuator

### Benefits

- Compact
- Robust
- Modular
- Lubricated for service life
- High efficiency
- Digital encoder feedback



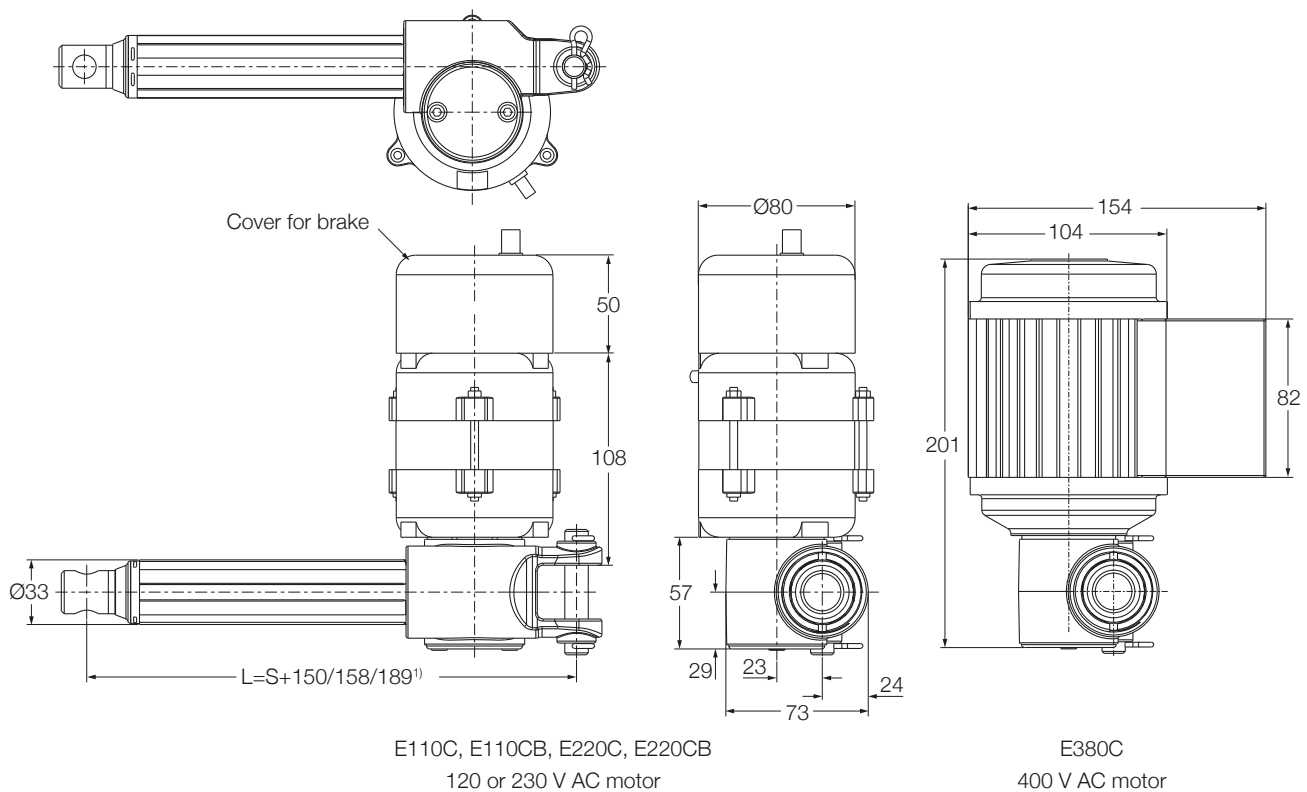
### Technical data

		Unit	CAT 33H – AC version	CAT 33H – DC version
Rated push load		N	500 to 1 200	400 to 1 200
Rated pull load		N	500 to 1 200	400 to 1 200
Speed (at full load)		mm/s	20 to 90 <sup>1)</sup>	17 to 193 <sup>1)</sup>
Stroke		mm	100 to 400	100 to 400
Retracted length		mm	S+150/158/189 <sup>2)</sup>	S+150/158/189 <sup>2)</sup>
Voltage		V AC	120, 230 or 400	–
		V DC	–	12 or 24
Power consumption	120 V AC	W	98 (brake 133,2 W)	–
	230 V AC	W	92 (brake 117,3 W)	–
	400 V AC	W	80	–
	12 or 24 V DC	W	–	N/A
Current consumption	120 V AC	A	0,82 (brake +0,29 A)	–
	230 V AC	A	0,4 (brake +0,11 A)	–
	400 V AC	A	0,2	–
	12 V DC	A	–	18
	24 V DC	A	–	9
	24 V DC	A	–	5 (for motors C24CW and P24CW)
Duty cycle		%	30	20
Ambient temperature		°C	–20 to +50	–20 to +50
Degree of protection		IP	20/54/55	20/44/66 <sup>1)</sup>
Weight		kg	2 to 2,7	2 to 2,7

<sup>1)</sup> Depending on selected motor

<sup>2)</sup> Dimension depends on selected front attachment

## Dimensional drawing – AC version



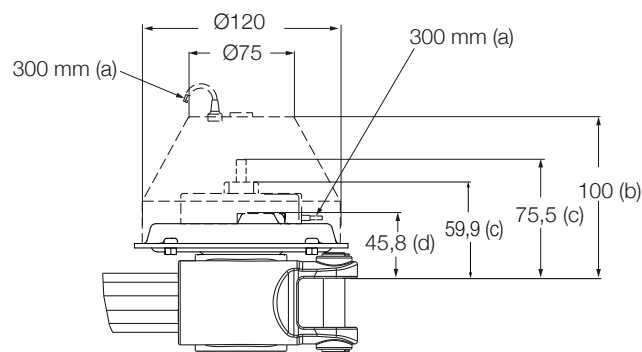
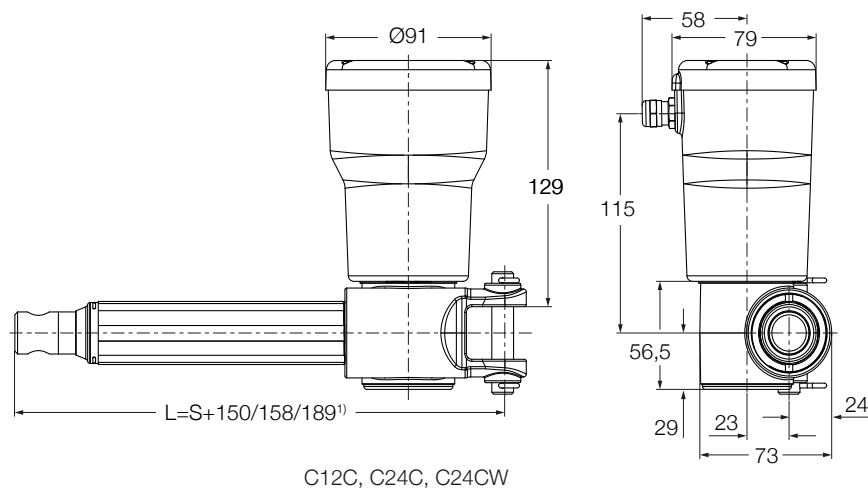
### Legend:

S = stroke

L = retracted length

<sup>1)</sup> Dimension depends on selected front attachment

## Dimensional drawing – DC version



### Legend:

S = stroke

L = retracted length

(a) = cable length

(b) = cover for brake (P24CB)

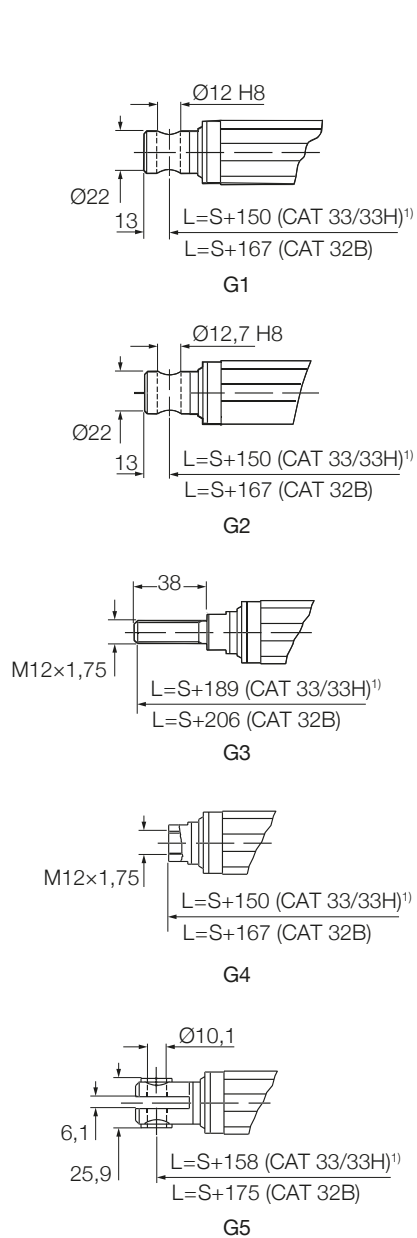
(c) = extended shaft (P24CS)

(d) = motor (D12C, P24C, P24CW)

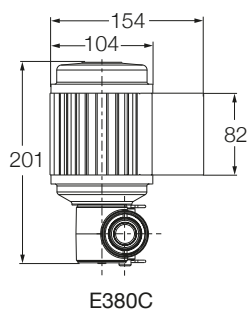
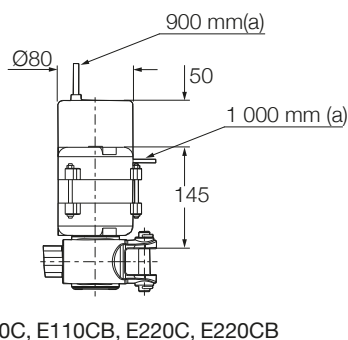
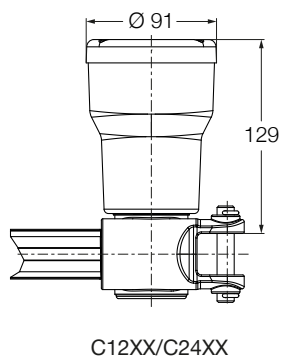
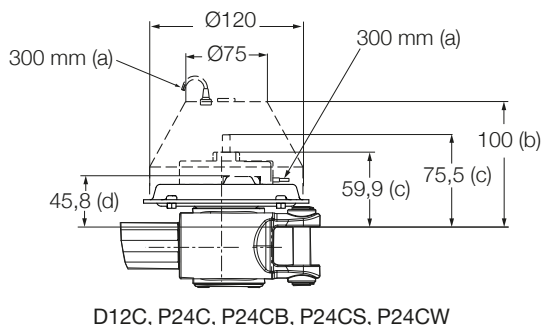
<sup>1)</sup> Dimension depends on selected front attachment

## Detailed drawings of front and rear attachments for CAT and CAP 43 and motor options for CAT

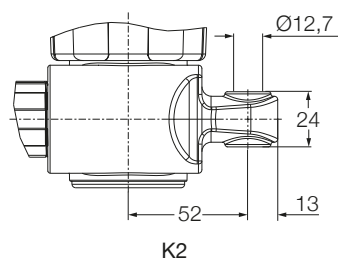
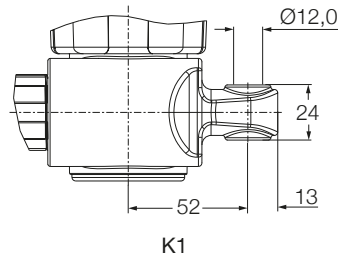
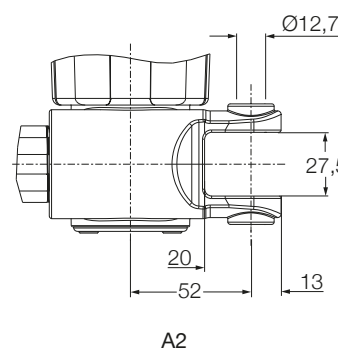
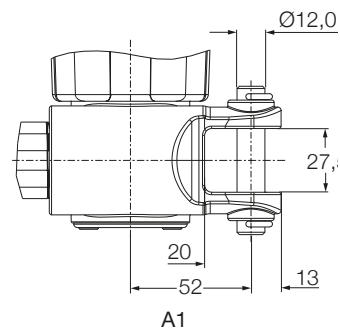
### Front attachments and retracted length



### Motor options for CAT



### Rear attachments



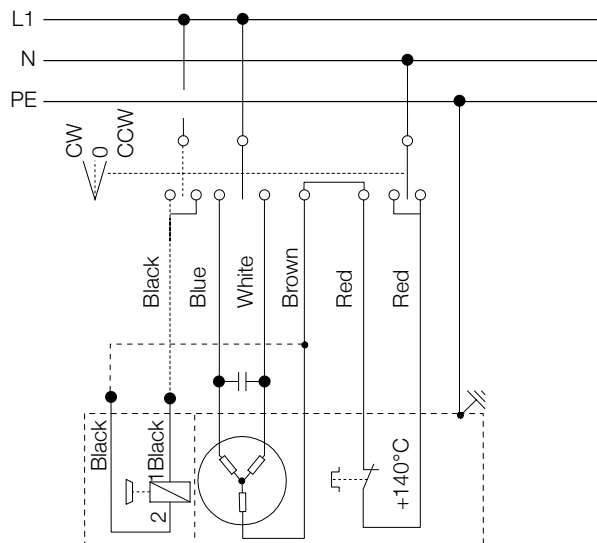
### Legend:

S = stroke  
L = retracted length  
(a) = cable length  
(b) = cover for brake  
(c) = extended shaft  
(d) = motor

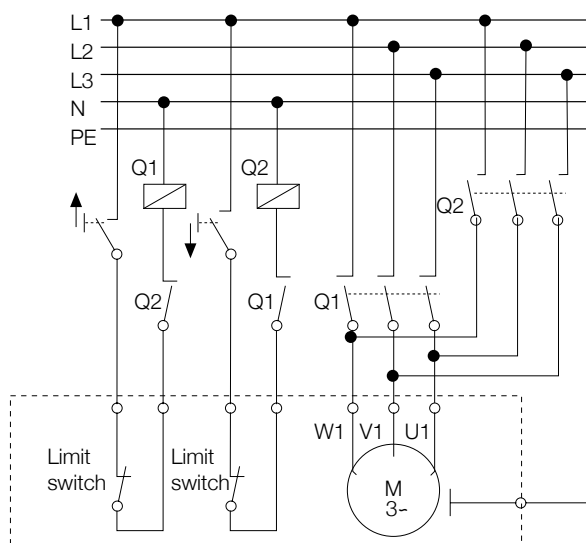
<sup>1)</sup> If S = 400, add 50 mm to retracted length.

## Connecting diagrams – AC version

120/230 V AC

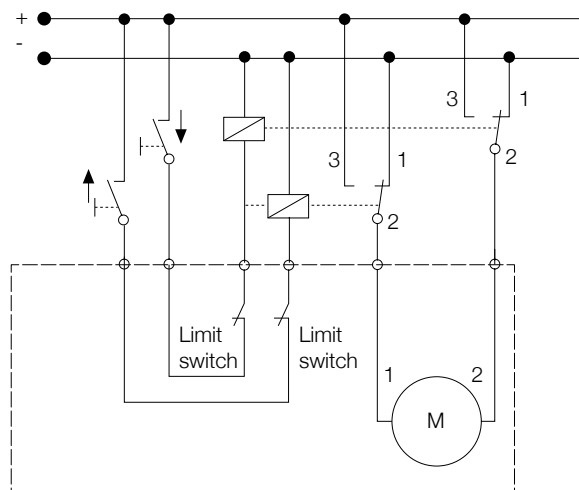


400 V AC



## Connecting diagrams – DC version

12/24 V DC



## Suitable control units and accessories AC version

	Encoder
	E2
E110C	•
E110CB	•
E220C	•
E220CB	•
E380C	•

## Suitable control units and accessories DC version

	Encoder
	E2
C12C	•
D12C	•
C24C	•
C24CW	•
P24C	•
P24CB	•
P24CS	•
P24CW	•

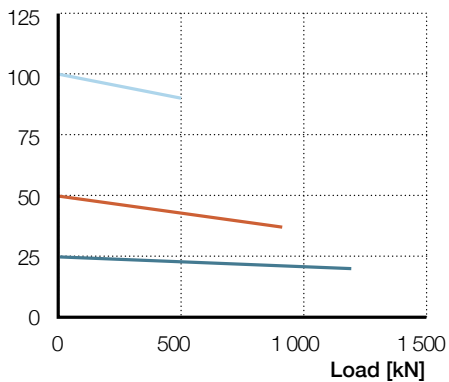
## CAT 33H – Type codes for accessories and spare parts

Item code	Type code	Order N°
12 V DC motor (cylindrical motor)	C12C	M/0405535
12 V DC motor (flat motor)	P24C	M/0405518-V01
24 V DC motor (cylindrical motor)	C24C	M/0405536
24 V DC motor (cylindrical with low speed)	C24CW	M/0405537
24 V DC motor (flat motor)	P24C	M/0405519-V01
24 V DC motor (flat motor with brake)	P24CB	M/0405523-V01
24 V DC motor (flat motor with extended shaft)	P24CS	M/0405522-V01
24 V DC motor (flat motor with low speed)	P24CW	M/0405521-V01
120 V AC motor (cylindrical motor)	E110C	M/0405533
120 V AC motor (cylindrical motor with brake)	E110CB	M/0405534
230 V AC motor (cylindrical motor)	E220C	M/0405531
230 V AC motor (cylindrical motor with brake)	E220CB	M/0405532
400 V AC motor (cylindrical motor)	E380C	M/0411607
Capacitor value 25 µF (120 V AC)	Capacitor 25 µF	M/0430670-16
Capacitor value 6 µF (230 V AC)	Capacitor 6 µF	M/0430670-03
Front mounting attachments type Rod-end	575-32	M/0430575-32
Front mounting attachments type Clevis	576-32	M/0430576-32
Rear mounting attachments type Single ear bracket	580-32	M/0430580-32
Rear mounting attachments type Universal joint	582-32	M/0431780-32

## Performance diagrams – AC version

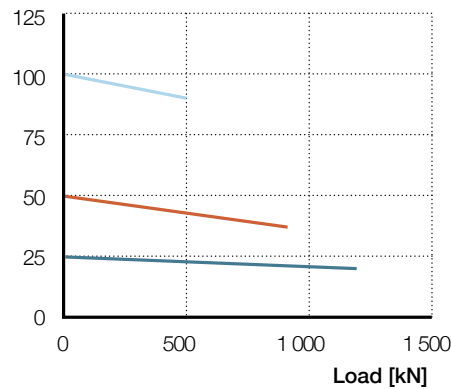
Speed-load diagram CAT 33H ... 120 V AC

Speed [mm/s]



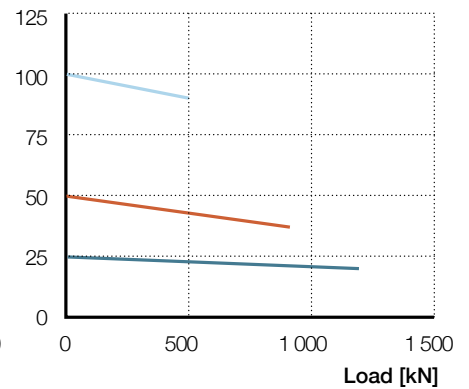
Speed-load diagram CAT 33H ... 230 V AC

Speed [mm/s]



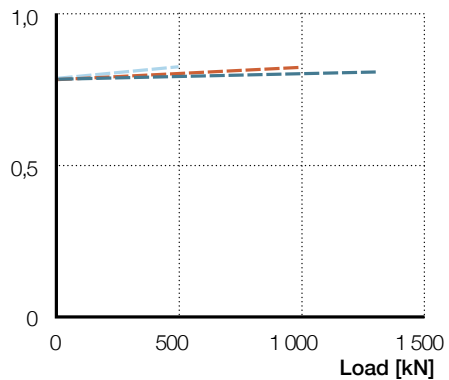
Speed-load diagram CAT 33H ... 400 V AC

Speed [mm/s]



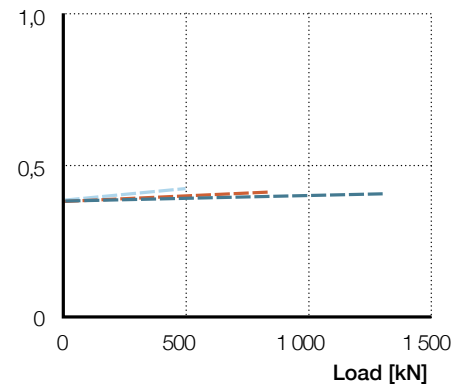
Current-load diagram CAT 33H ... 120 V AC

Current consumption [A]



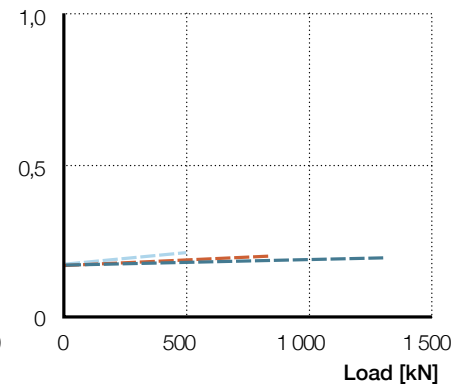
Current-load diagram CAT 33H ... 230 V AC

Current consumption [A]



Current-load diagram CAT 33H ... 400 V AC

Current consumption [A]



Gear 1 — V (mm/s) — I (A)

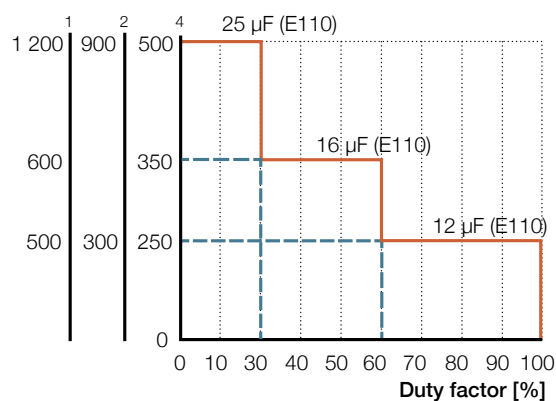
Gear 2 — V (mm/s) — I (A)

Gear 4 — V (mm/s) — I (A)

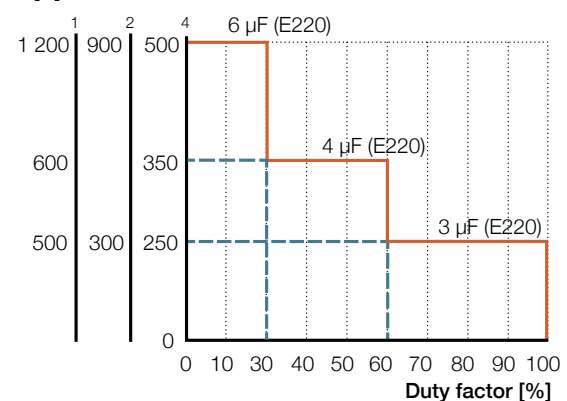
\*There may be deviations of +/-10% from the values in the chart.

## Duty cycle

F [N] Gear

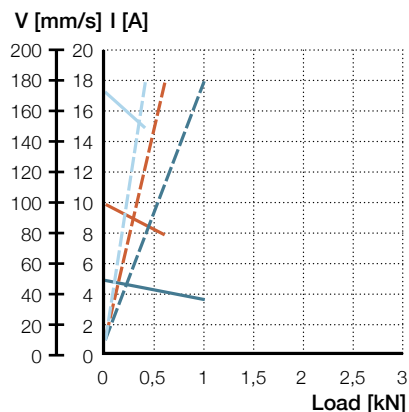


F [N] Gear

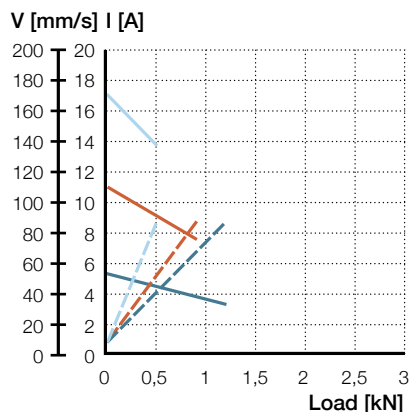


## Performance diagrams – DC version

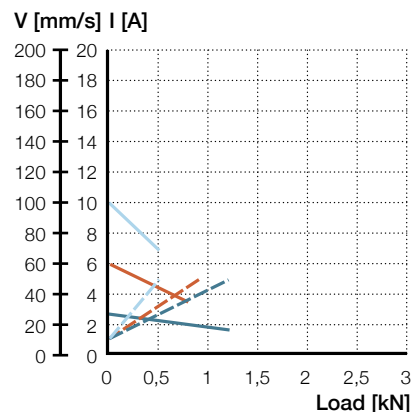
CAT 33H.../C12C



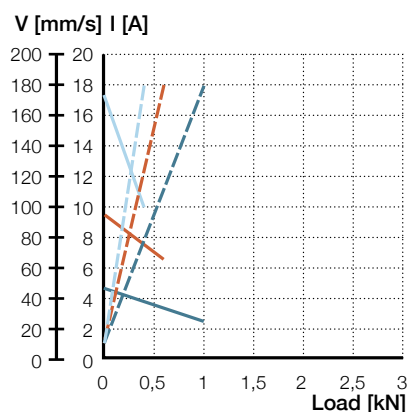
CAT 33H.../C24C



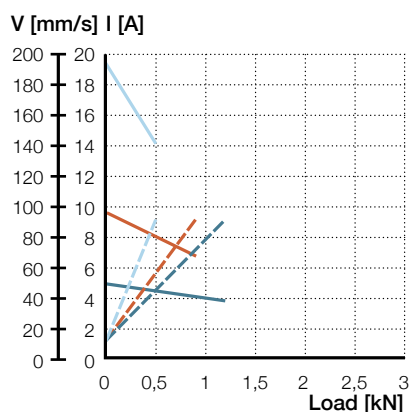
CAT 33H.../C24CW



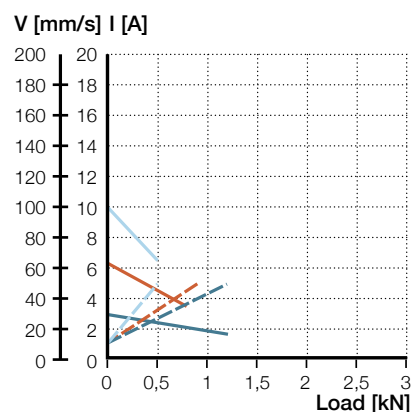
CAT 33H.../D12C



CAT 33H.../P24C/P24CB/P24CS



CAT 33H.../P24CW



Gear 1 — V (mm/s) — I (A)

Gear 2 — V (mm/s) — I (A)

Gear 4 — V (mm/s) — I (A)

\*There may be deviations of +/-10% from the values in the chart.

Load [N] / Full Load Speed [mm/s]			Motor options	
1 200/xx	900/xx	600/xx	No motor	0000
1 200/20	900/37	500/90	120 V AC/60 Hz, 1-phase, IP54	E110C
1 200/20	900/37	500/90	120 V AC/60 Hz, 1-phase, brake, IP20	E110CB
1 200/20	900/37	500/90	230 V AC/50 Hz, 1-phase, IP54	E220C
1 200/20	900/37	500/90	230 V AC/50 Hz, 1-phase, brake, IP20	E220CB
1 200/20	900/37	500/90	400 V AC/50 Hz, 3-phase, IP55	E380C
1 200/xx	900/xx	600/xx	No motor	0000
1 200/50-38	600/100-80	400/174-150	12 V DC, IP666	C12C
1 200/47-25	600/95-65	400/170-100	12 V DC, flat motor, IP44	D12C
1 200/56-36	900/113-79	500/174-140	24 V DC, IP66	C24C
1 200/27-17	900/60-35	500/100-69	24 V DC, low speed motor, IP66	C24CW
1 200/48-37	900/95-65	500/193-140	24 V DC, flat motor, IP44	P24C
1 200/48-37	900/95-65	500/193-140	24 V DC, flat motor, brake, IP20	P24CB
1 200/48-37	900/95-65	500/193-140	24 V DC, flat motor, ext.shaft, IP44	P24CS
1 200/30-17	900/63-35	500/100-65	24 V DC, flat motor, low speed, IP44	P24CW

1                  2                  4

The diagram illustrates how different configuration options are mapped to specific positions in a code string. Lines connect labels on the left to boxes in a sequence of code fields on the right.

- Gear:** Connects to position 1.
- Type:** Connects to positions 2, 3, and 4.
- Motor assembly:** Connects to positions 5 and 6.
- Stroke (S):** Connects to positions 7 through 10.
- Rear attachment:** Connects to positions 11 through 14.
- Front attachment:** Connects to positions 15 through 18.
- Feedback:** Connects to positions 19 through 22.
- Option:** Connects to positions 23 through 26.
- Option for CxxC motors:** Connects to positions 27 through 30.

The code string format shown is: **C A T | 3 3 H X | | | X | | | | | / | | | | | |**

3



# CAR 40

## Linear actuator

### Benefits

- Reliable and robust industrial actuator
- Wide range of components
- Right- and left-hand version

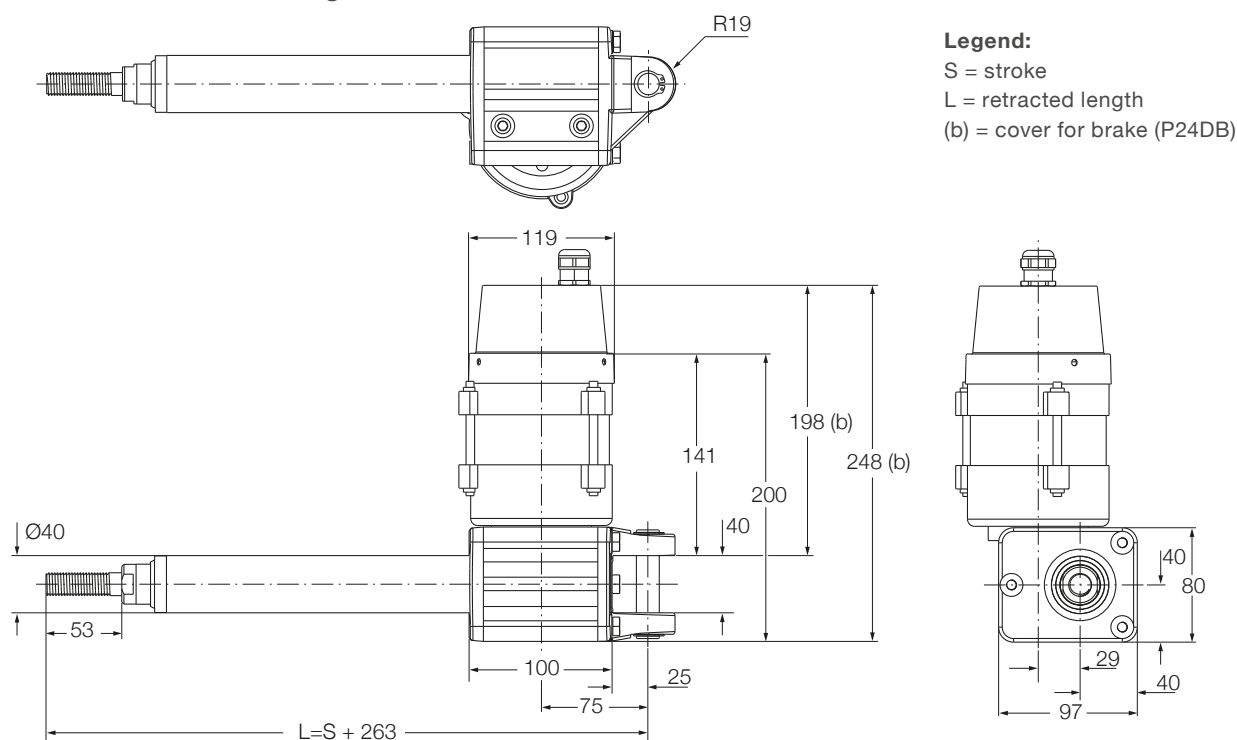


### Technical data - AC version

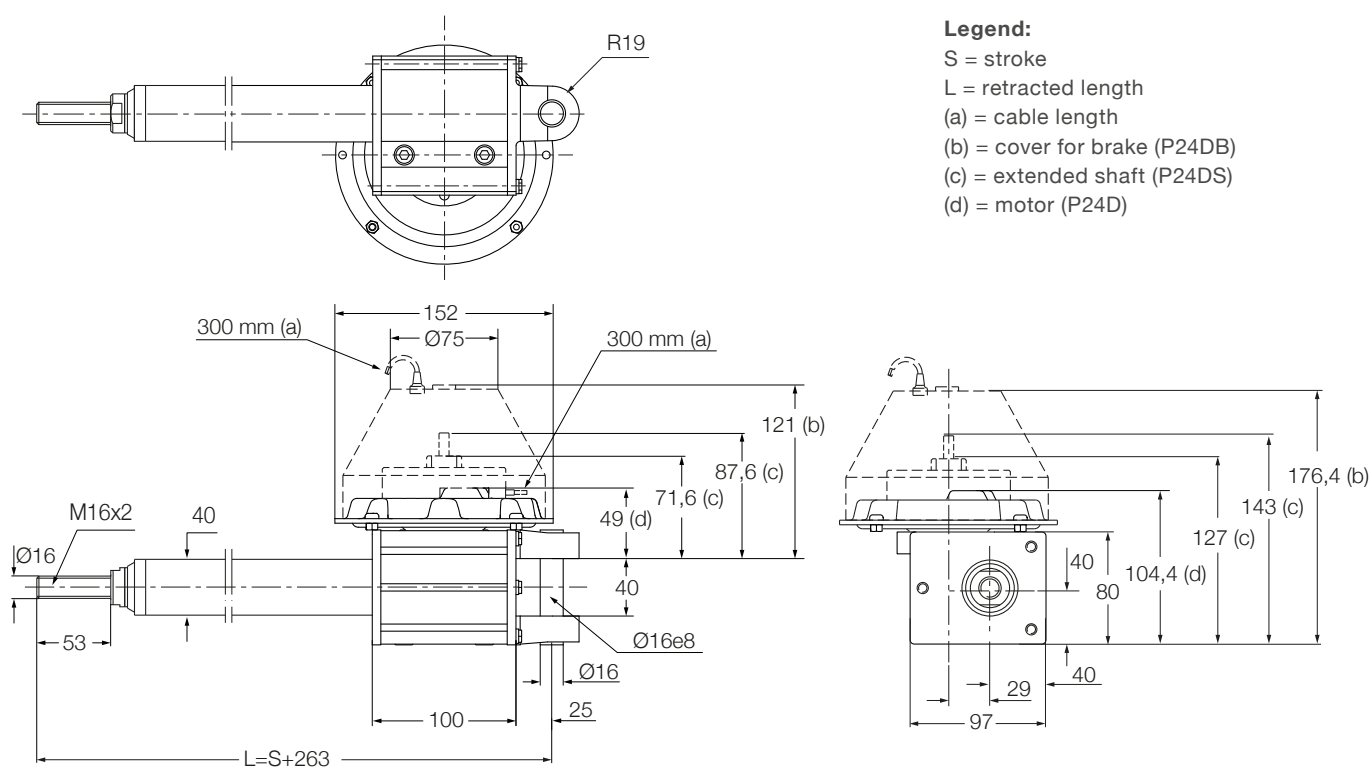
		Unit	CAR 40 - AC version	CAR 40 - DC version
Rated push load		N	2 000 to 6 000	2 000 to 6 000
Rated pull load		N	2 000 to 6 000	2 000 to 6 000
Speed (at full load)		mm/s	9 to 40 <sup>1)</sup>	8 to 50
Stroke		mm	100 to 700	100 to 700
Retracted length		mm	S+263	S+263
Voltage		V AC	120 or 230	–
		V DC	–	24
Power consumption	120 V AC	W	360	–
	230 V AC	W	299	–
	24 V DC	W	–	N/A
Current consumption	120 V AC	A	3 (brake +0,29 A)	–
	230 V AC	A	1,3 (brake +0,11 A)	–
	24 V DC	A	–	16
Duty cycle		%	40	25
Ambient temperature		°C	–20 to +70	–20 to +70
Degree of protection		IP	20/54	20/44
Weight		kg	5,8 to 8,4	5,8 to 8,4

<sup>1)</sup> Depending on selected motor

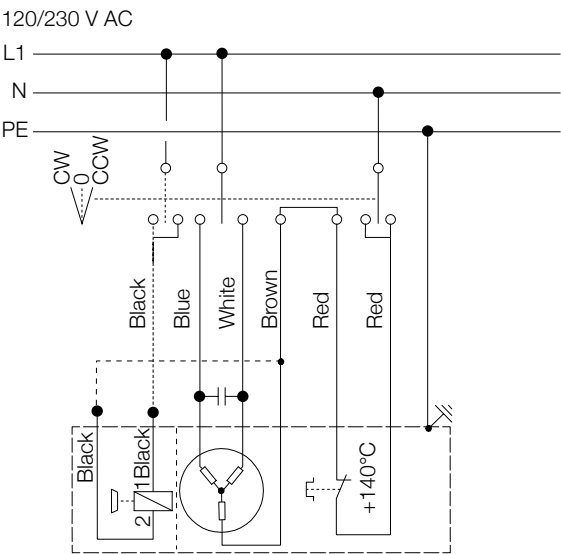
## Dimensional drawing – AC version



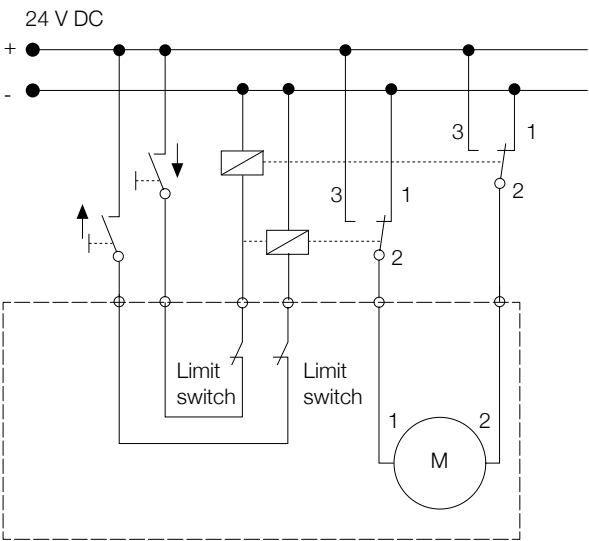
## Dimensional drawing – DC version



Connecting diagrams – AC version



Connecting diagrams – DC version



Suitable control unit and accessories  
AC version

	Limit switch
	CAXE40
E110D	•
E110DB	•
E220D	•
E220DB	•

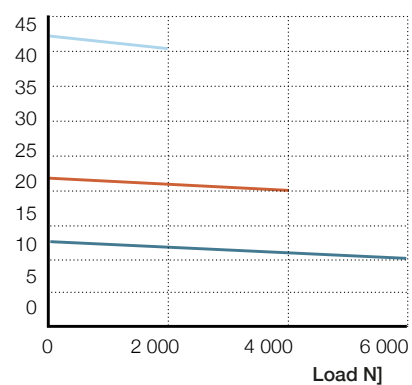
Suitable control unit and accessories  
DC version

	Limit switch
	CAXE40
P24D	•
P24DS	•
P24DB	•

## Performance diagrams – AC version

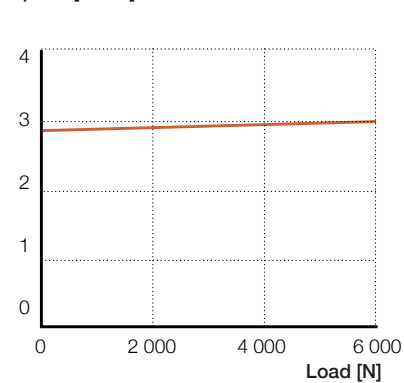
Speed-load diagram CAR 40 ... 120 V AC

Duty factor [%] at 20 °C



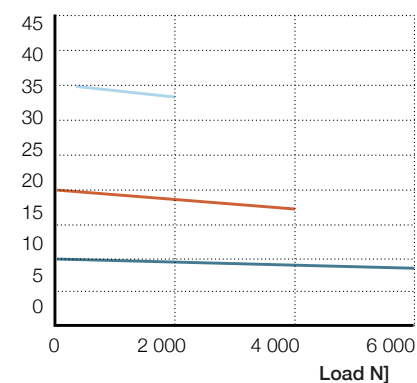
Speed-load diagram CAR 40 ... 230 V AC

Speed [mm/s]



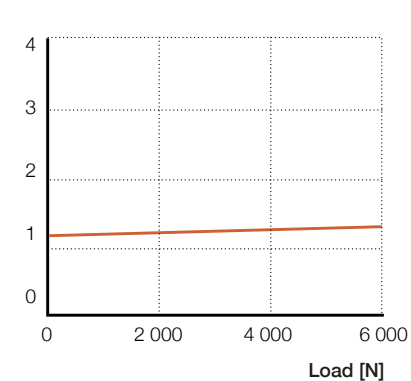
Current-load diagram CAR 40 ... 120 V AC

Current consumption [A]



Current-load diagram CAR 40 .. 230 V AC

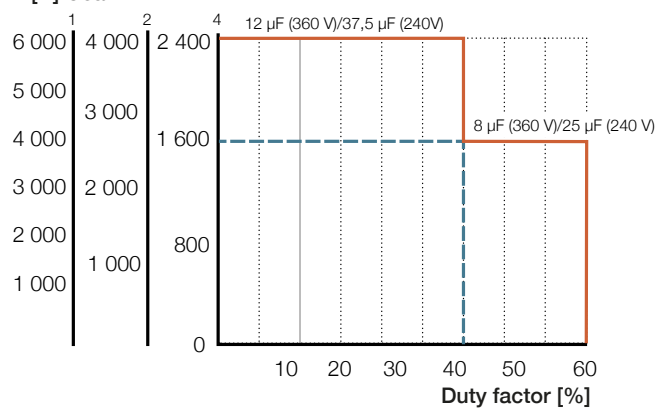
Current consumption [A]



\*There may be deviations of +/-10% from the values in the chart.

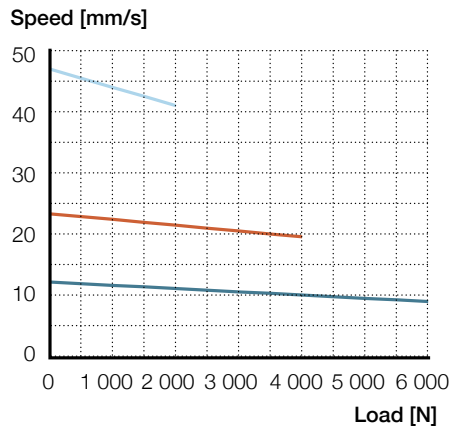
## Duty cycle – AC version

F [N] Gear

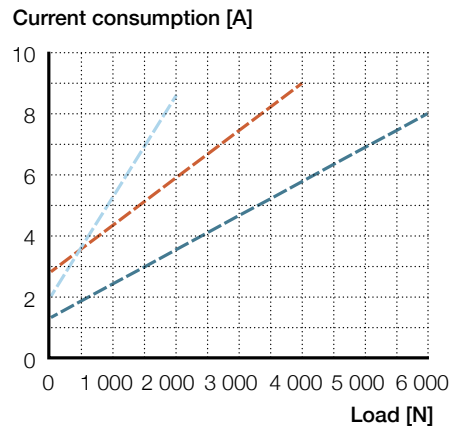


## Performance diagrams – DC version

Speed-load diagram CAR 40 ... 24 V DC



Current-load diagram CAR 40 ... 24 V DC

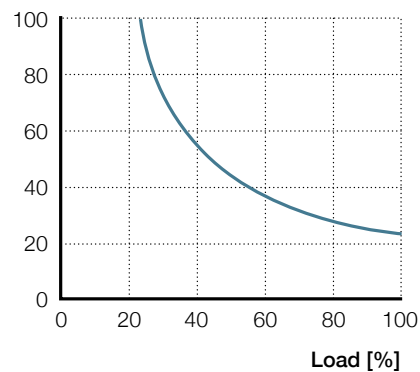


Gear 1 — V (mm/s) — I (A)    Gear 2 — V (mm/s) — I (A)    Gear 4 — V (mm/s) — I (A)

\*There may be deviations of +/-10% from the values in the chart.

## Duty cycle – DC version

Duty factor [%] at 20 °C



## CAR 40 – Type codes for accessories and spare parts

Item code	Type code	Order N°
24 V DC motor (flat motor)	P24D	M/0405524-V01
24 V DC motor (flat motor with extended shaft)	P24DS	M/0405526-V01
24 V DC motor (flat motor with brake)	P24DB	M/0405525-V01
120 V AC motor (cylindrical motor)	E110D	M/0405529
120 V AC motor (cylindrical motor with brake)	E110DB	M/0405530
230 V AC motor (cylindrical motor)	E220D	M/0405527
230 V AC motor (cylindrical motor with brake)	E220DB	M/0405528
Capacitor value 12 $\mu$ F (230 VAC-motor)	Capacitor 12 $\mu$ F	M/0430670-04
Limit switch for stroke =100 mm	CAXE 40 $\times$ 100	M/0412051
Limit switch for stroke =300 mm	CAXE 40 $\times$ 300	M/0412054
Limit switch for stroke =500 mm	CAXE 40 $\times$ 500	M/0412056
Limit switch for stroke =700 mm	CAXE 40 $\times$ 700	M/0412057
Proximity switch for CAXE	CAXE Proximity switch	M/0432369
Front mounting attachments type Rod-end	575-40	M/0430575-40
Front mounting attachments type Clevis	576-40	M/0430576-40
Rear mounting attachments type Single ear bracket	590-40	M/0430590-40
Rear mounting attachments type Ball-joint bracket	581-40	M/0430581-40

### Ordering key

Dynamic load [N] / Speed [mm/s]			Motor options	
6 000/xx	4 000/xx	2 000/xx	No motor	0000
6 000/10	4 000/20	2 000/40	120 V AC/60 Hz, 1-phase, IP54	E110D
6 000/10	4 000/20	2 000/40	120 V AC/60 Hz, 1-phase, brake, IP20	E110DB
6 000/9	4 000/17	2 000/34	230 V AC/50 Hz, 1-phase, IP54	E220D
6 000/9	4 000/17	2 000/34	230 V AC/50 Hz, 1-phase, brake, IP20	E220DB
6 000/xx	4 000/xx	2 000/xx	No motor	0000
6 000/13–8	4 000/25–18	2 000/50–38	24 V DC, flat motor, IP44	P24D
6 000/13–8	4 000/25–18	2 000/50–38	24 V DC, flat motor, extended shaft, IP44	P24DS
6 000/13–8	4 000/25–18	2 000/50–38	24 V DC, flat motor, brake, IP20	P24DB

1

2

4

Gear

C

A

R

4

0

X

X

F

S

/

Type

Motor assembly

R

Right

L

Left

Stroke (S)

100

100 mm

300

300 mm

500

500 mm

700

700 mm

---

Other stroke lengths

Option 1

F

Friction clutch

Z

No friction clutch

Option 2

-

No back-up nut

S

Back-up nut

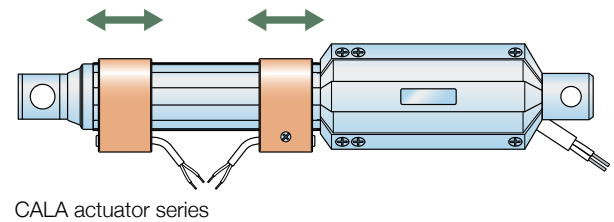
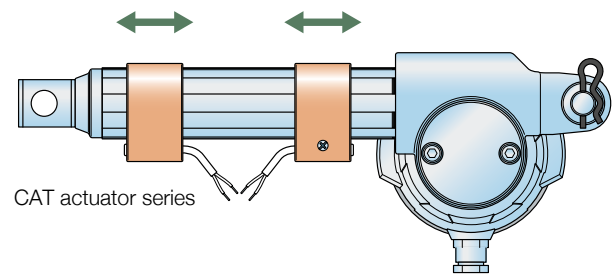
■ Options shown in red are only available on request. Contact Ewellix for more information on minimum quantities and additional costs.

# Spare parts

## CAXD 33 limit switch

Limit switches, combined with Ewellix control units, make it possible to set the stroke to any desired length.

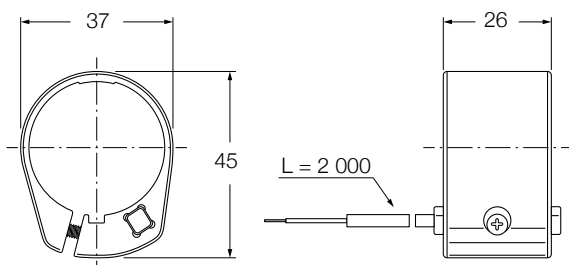
- CAXD 33 – designed for the following actuators:
  - CAT 33
  - CALA 36A
- One CAXD is needed for each limit position
- Use of limit switches reduce the effective stroke by 20 mm for CAT 33 and 25 mm for CALA 36A (retracted position is affected)



## Technical data

CAXD 33	
Operating voltage	5 to 30 V DC
Max. current	100 mA DC
Voltage drop	< 5 V
Voltage drop	< 5 V
Electrical function	Normally closed or normally open
Make/fall time	0,3 ms / 0,6 ms
Operating temperature	-20 °C to +50 °C
Ingress protection	IP 67 (sensor element)
Vibration/shock	According to IEC 90947-5-2 (sensor element)
Cable dimensions (L x D)	2 m x 3 mm (PUR)
Cable area	2 x 0,14 mm <sup>2</sup>
Housing colour	Black

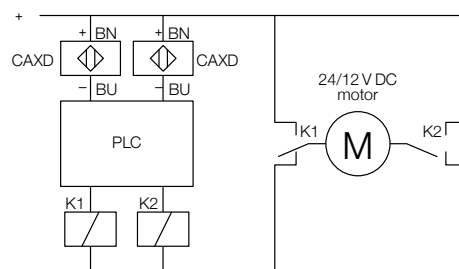
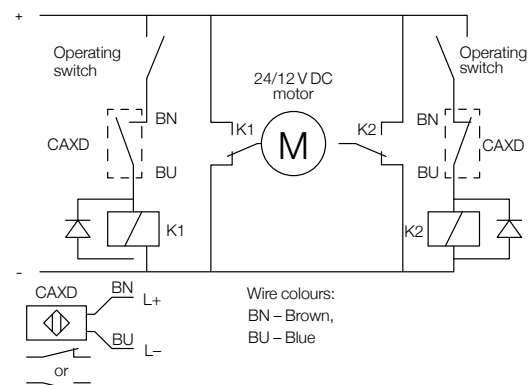
## Dimensional drawing



## Ordering key

Code	Description
CAXD 33 LIMIT SWITCH, NC	Normally Closed
CAXD 33 LIMIT SWITCH, NO	Normally Open

## Connecting diagrams



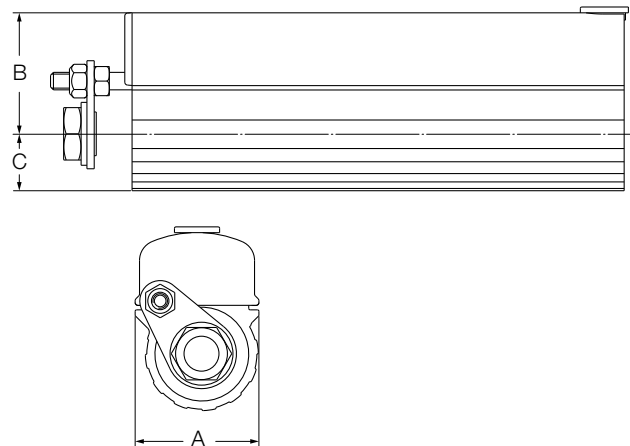
**Important!** For DC-supply only

## CAXE limit switch

Limit switches, combined with Ewellix control units, make it possible to set the stroke to any desired length.

- CAXE - designed for the following actuators:
  - CAR 22
  - CAR 32
  - CAR 40
  - CAT 32B
  - CARN 32
- It is recommended to place the limit switch at least 10 mm from the end stop to avoid mechanical failure
- Front attachment G3 must be selected for this option

## Dimensional drawing



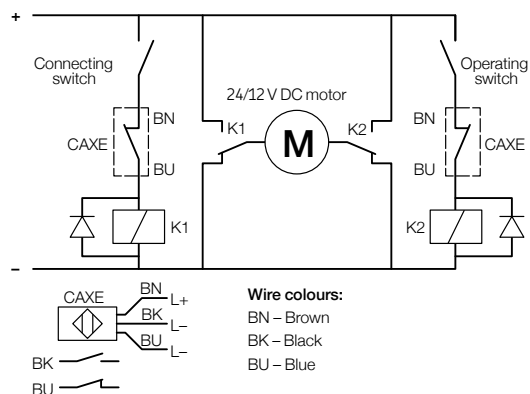
	A	B	C
CAXE 22	42,5	37	14
CAXE 32/32B	47,5	40	20
CAXE 40	46	46	23

## Technical data

CAXE	
Operating voltage	5 to 30 V DC
Max. current	100 mA DC
Protection class	III
Voltage drop	< 5 V
Electrical function	Normally Closed (NC) and Normally Open (NO)
Make/break time	0,3 ms / 0,6 ms
Operating temperature	-20 to +70 °C
Degree of protection	IP 67 (sensor element)
Vibration/shock	According to IEC 60947-5-1 (sensor element)
Cable dimensions (L x D)	2 000 x 3 mm (PUR)
Cable area	3 x 0,14 mm <sup>2</sup>

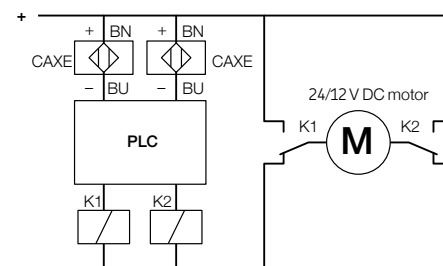
**Important!** The sensor has no overload protection and no reverse polarity protection.

## Connecting diagrams



## Ordering key

Type	Actuators stroke (mm)	
022 CAXE32 CAR 22	050 050	CAR 22, 32 CARN 32 and CAT 32B
032 CAXE32 CAR 32, CARN 32	100 100	CAR 22, 32, 40, CARN 32 and CAT 32B
32B CAXE32B CAT 32B	150 150	CAR 22
040 CAXE40 CAR 40	200 200	CAR 22, 32 CARN 32 and CAT 32B
	300 300	CAR 22, 32, 40, CARN 32 and CAT 32B
	400 400	CAT 32B
	500 500	CAR 32, 40, CARN 32 and CAT 32B
	700 700	CAR 32, 40, CARN 32 and CAT 32B



**Important!** For DC-supply only



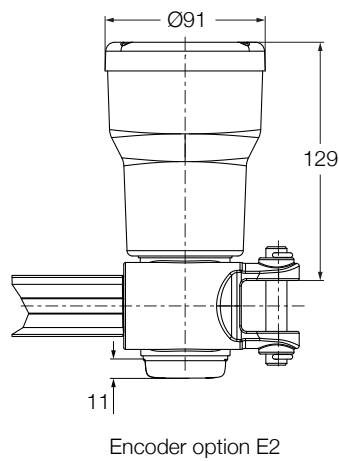
# Feedback for CAT series – Encoder E2

- Can be fitted to all standard motors
- Hall effect, two channels with 90° displacement
- Located on gear housing, see drawing
- 2 pulses/channel and motor revolution
- Supply voltage: 5–24 V DC
- Final resolution according to gear ratio and actuator basic type (see table)

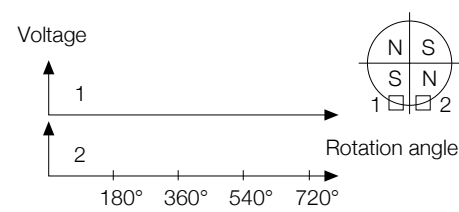
## Feedback

	Gear	Pulses at 1mm stroke	Resolution (mm) per pulse
CAT 33	1	16,67	0,06
	2	8,33	0,12
	4	4,17	0,24
CAT 33H	1	4,00	0,25
	2	2,00	0,50
	4	1,00	1,00
CAT 32B	1	12,50	0,08
	2	6,25	0,16
	4	3,13	0,32

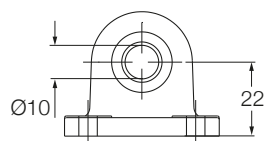
## Dimensional drawing



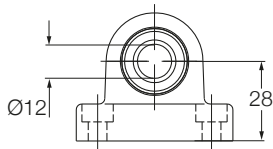
## Connecting diagrams



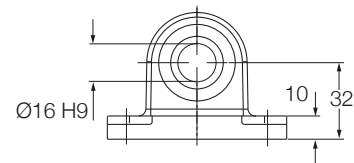
## Attachments



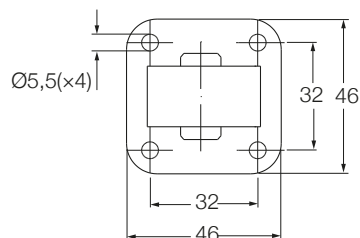
580-22



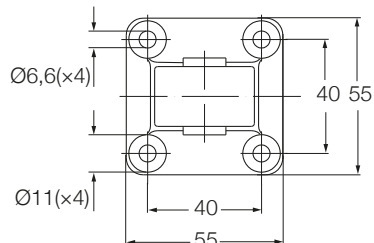
580-32



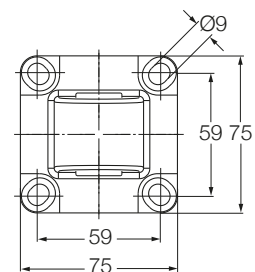
590-40



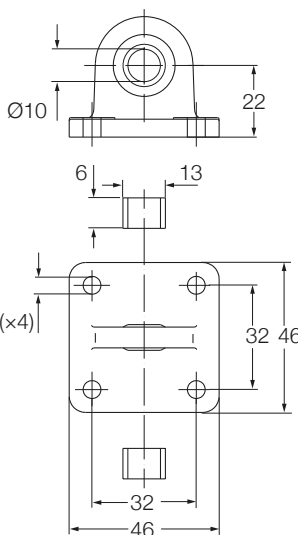
580-22



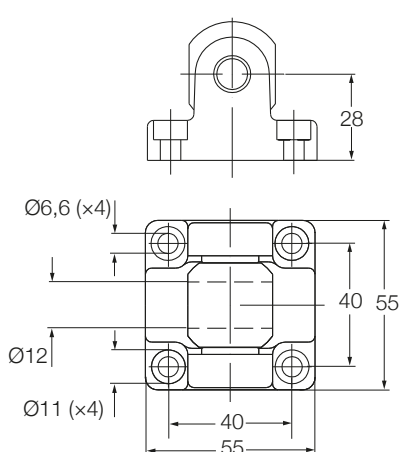
580-32



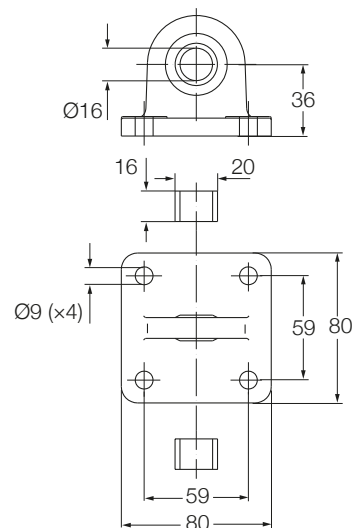
590-40



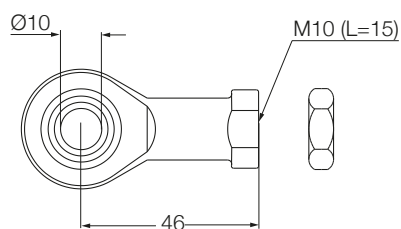
581-22



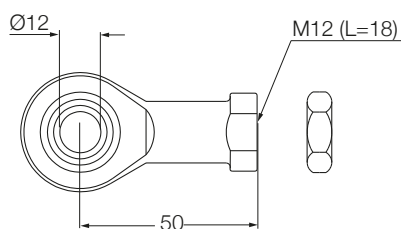
582-32



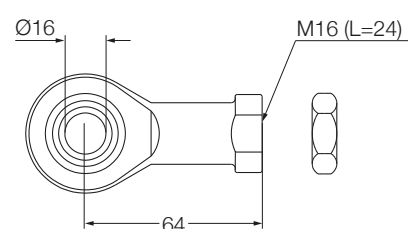
581-40



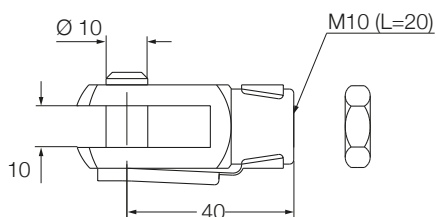
575-22



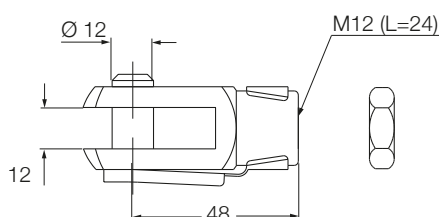
575-32



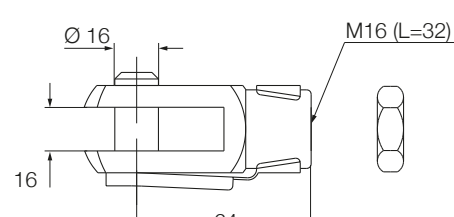
575-40



576-22



576-32



576-40



# CAHM series

The CAHM series consists of spindle lifting actuators with worm gears. They fulfil the highest demands for industrial and other applications. The actuators are available in several different motor versions. CAHM series offers strong (up to 50 000 N), fast and quiet movements with high safety and duty cycle. The actuators include many interface options as hall encoder, end-switch, extended shaft etc.



## Features

- Ideal for heavy load applications
- Wide speed/force range
- Robust design

All complete datasheet are available on [ewellix.com](http://ewellix.com).

If you request higher force than 12 kN, refer to **High performance actuator catalogue (PUB NUM IL-05001/3-EN-June 2022)**.



## Benefits

- Modular
- Robust
- Reliable
- High speed and/or high load
- All metal design

## Technical data

### 12 and 24 V DC

	Unit	CAHM-31XX-D1	CAHM-31XX-D3	CAHM-35XX-D2
Voltage	V DC	12	24	24
Screw type	–	LN and LS	LN and LS	LN and LS
Max rated push load	N	1 000 to 4 000	1 000 to 4 000	10 000 to 15 000
Max rated pull load	N	1 000 to 4 000	1 000 to 4 000	10 000 to 15 000
Max speed (at full load)	mm/s	5 to 50	5 to 45	3 to 27
Stroke	mm	100 to 700	100 to 700	100 to 700
Retracted length	mm	S+230	S+230	–
Power consumption	W	168 to 192	144 to 192	528 to 840
Current consumption	A	14 to 16	6 to 8	22 to 35
Duty cycle	%	10	10	10
Ambient temperature	°C	–10 to +40	–10 to +40	–10 to +40
Degree of protection	IP	44	44	54

### 230 V AC

	Unit	CAHM-31XX-A2	CAHM-35XX-A2
Voltage	V AC	230	230
Screw type	–	LN and LS	LS
Max rated push load	N	500 to 2 600	5 000 to 15 000
Max rated pull load	N	500 to 2 600	5 000 to 15 000
Max speed (at full load)	mm/s	5 to 50	2 to 12
Stroke	mm	100 to 700	100 to 700
Retracted length	mm	S+230	–
Power consumption	W	200 to 230	700 to 750
Current consumption	A	1 to 11	3,3 to 3,5
Duty cycle	%	25	10 to 15
Ambient temperature	°C	–10 to +40	–10 to +40
Degree of protection	IP	54	54

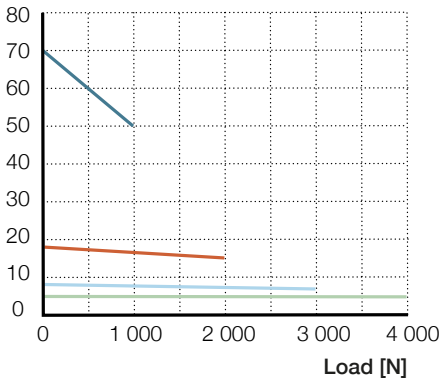
### 3x400 V AC

	Unit	CAHM-31XX-A4	CAHM-35XX-A4	CAHM-50XX-A4	CAHM-65XX-A4
Voltage	V AC	3x400	3x400	3x400	3x400
Screw type	–	LN and LS	LS and BN	BN	BN
Max rated push load	N	1 000 to 4 500	10 000 to 15 000	15 000 to 30 000	18 000 to 50 000
Max rated pull load	N	1 000 to 4 500	10 000 to 15 000	15 000 to 30 000	18 000 to 50 000
Max speed (at full load)	mm/s	5 to 50	2 to 25	9 to 45	9 to 74
Stroke	mm	100 to 700	100 to 700	100 to 700	100 to 700
Retracted length	mm	S+230	–	S+465	S+446
Power consumption	W	210 to 280	500 to 920	1 200 to 1 650	1 900 to 3 000
Current consumption	A	0,5 to 0,6	1,4 to 1,8	2,8 to 3,5	3,6 to 3,9
Duty cycle	%	40	10 to 25	10	10
Ambient temperature	°C	–10 to +40	–10 to +40	–10 to +40	–10 to +40
Degree of protection	IP	54	54	54	54

Performance diagrams

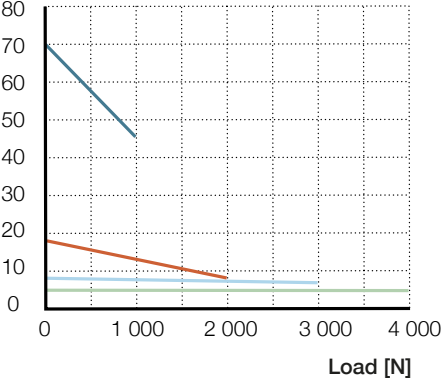
CAHM-31 - DC version

Motor: D1 - 12 V DC  
Speed [mm/s]



Speed load diagram

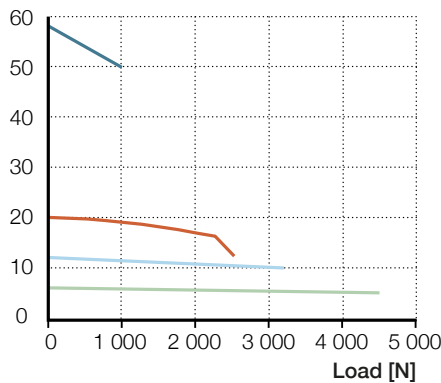
Motor: D2 - 24 V DC  
Speed [mm/s]



Speed load diagram

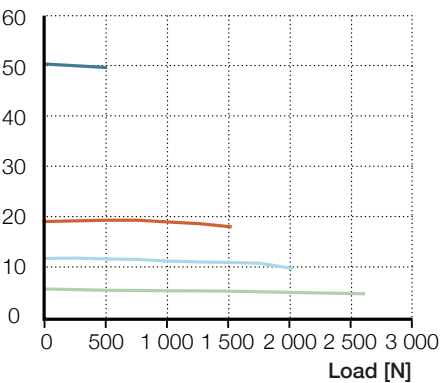
CAHM-31 - AC version

Motor: A4 - 3x400 V AC  
Speed [mm/s]



Speed load diagram

Motor: A2 - 230 V AC  
Speed [mm/s]



Speed load diagram

CAHM 3110-LN

CAHM 3130-LN

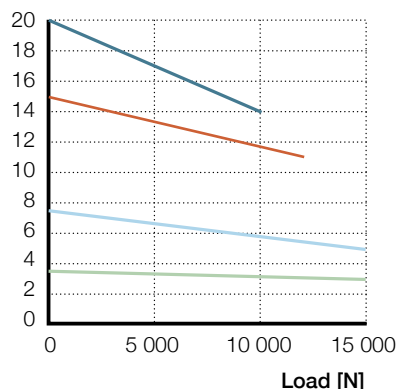
CAHM 3110-LS

CAHM 3150-LS

### CAHM-35 - DC version

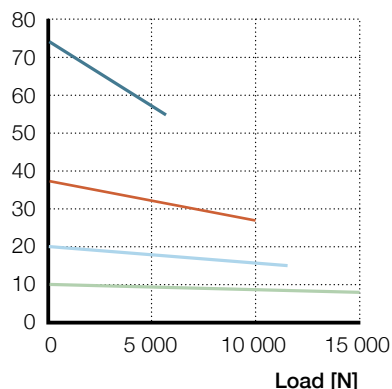
Motor: D2 - 24 V DC  
LS - Lead screw 20x4

Speed [mm/s]



Motor: D2 - 24 V DC  
BN - Ball screw 25x10

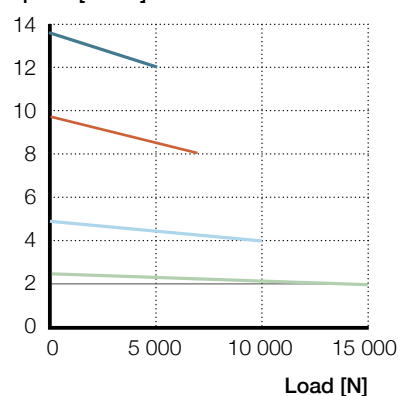
Speed [mm/s]



### CAHM-35 - AC version

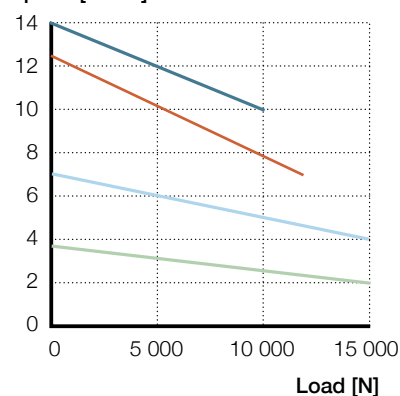
Motor: A2 - 230 V AC  
LS - Lead screw 20x4

Speed [mm/s]



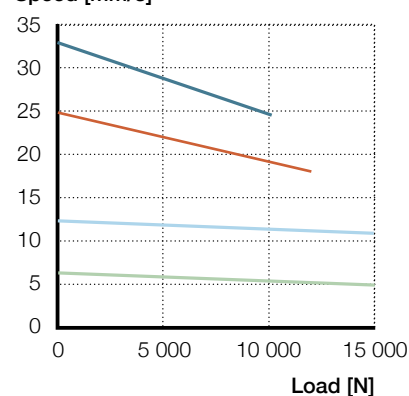
Motor: A4 - 3x400 V AC  
LS - Lead screw 25x10

Speed [mm/s]



Motor: A4 - 3x400 V AC  
BN - Ball screw 25x10

Speed [mm/s]



CAHM-3507

CAHM-3510

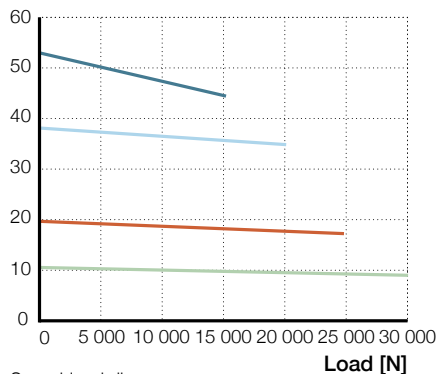
CAHM-3520

CAHM-3540

### CAHM-50 - AC version

Motor: A4 - 3x400 V AC

Speed [mm/s]



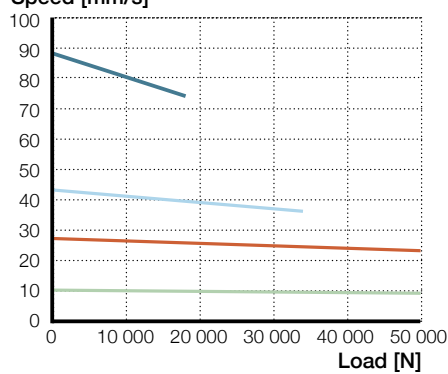
Speed-load diagram

CAHM-5004 CAHM-5012  
CAHM-5006 CAHM-5023

### CAHM-65 - AC version

Motor: A4 - 3x400 V AC

Speed [mm/s]



Speed-load diagram

CAHM-6506 CAHM-6520  
CAHM-6513 CAHM-6550





4

## Lifting columns

Up to 2,8 kNm bending load



# Chapter contents

CPMA ..... 194

CPMB ..... 202

CPMT ..... 210

TFG ..... 216

THG ..... 220

TLC ..... 224

TLG ..... 228

TLT ..... 232

TXG ..... 236

FRE ..... 240

# CPMA

For ophthalmic equipment



## Benefits

- Universal power supply
- Plug and play
- Soft start and stop control
- Multiple outlet socket accessories
- Cable through column

## Standards

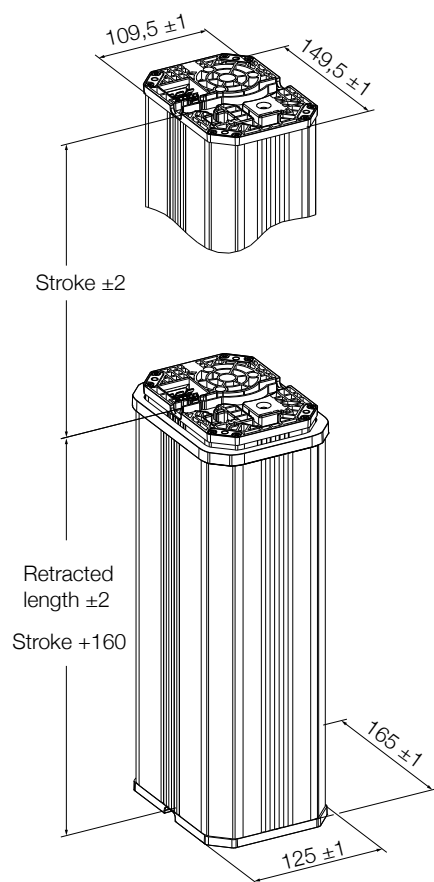
- IEC 60601-1:2005  
(3rd edition) compliant

## Technical data

	Unit	CPMA1-1	CPMA1-2	CPMA2-2
Rated push load (with self locking)	N	1 000	2 000	2 000
Rated pull load	N	0	0	0
Bending moment (dynamic)	Nm	up to 115 <sup>1)</sup>	up to 250 <sup>1)</sup>	up to 250 <sup>1)</sup>
Speed (full load to no load)	mm/s	14 to 15	11 to 15	11 to 15
Lifting column version	# of section	2-section	2-section	2-section
Stroke	mm	230 to 400	230 to 400	200 to 400
Retracted length	mm	S+160	S+160	S+160
Static Load (Max) in push way	N	8 000	8 000	8 000
Static bending moment (Max)	Nm	500	500	500
Voltage (rated)	V	100–240 AC 50/60 Hz	100–240 AC 50/60 Hz	24 DC
Input current (rated)	A	1,5	1,6	5
Duty cycle: intermittent operation	on/off	1 min./9 min.	1 min./9 min.	1 min./9 min.
Ambient temperature	°C	+10 to +40	+10 to +40	+10 to +40
Degree of protection	IP	30	30	30
Protection class	–	I	I	–
Type of control	–	electrical	electrical	electrical
Noise level (Max)	dB(A)	45	45	45
Weight	kg	8 to 11	9 to 12	8 to 11
Standby power (Max)	W	2,1	1,9	–

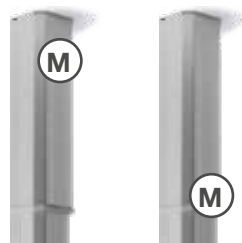
<sup>1)</sup> For details, see offset load diagrams (→ page 196)

## Dimensional drawing



## More flexibility with Series CPMA design options

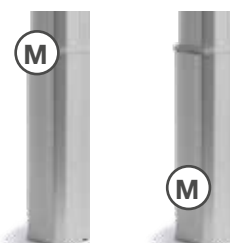
Built-in with outer tube on top  
More hygienic and easy-to-clean design



Motor  
orientation B

Motor  
orientation A

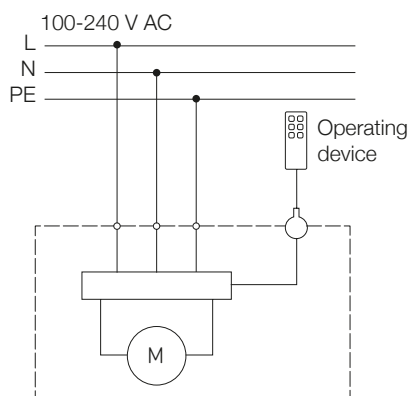
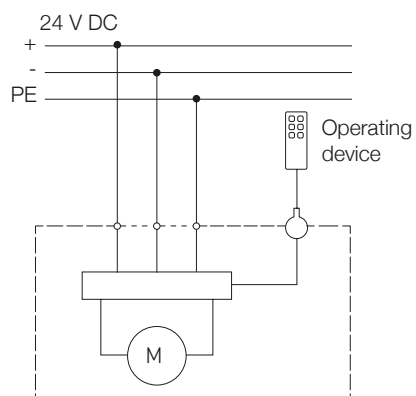
Built-in with outer tube on bottom  
More aesthetic design


























Motor  
orientation A

Motor  
orientation B

## Connecting diagrams

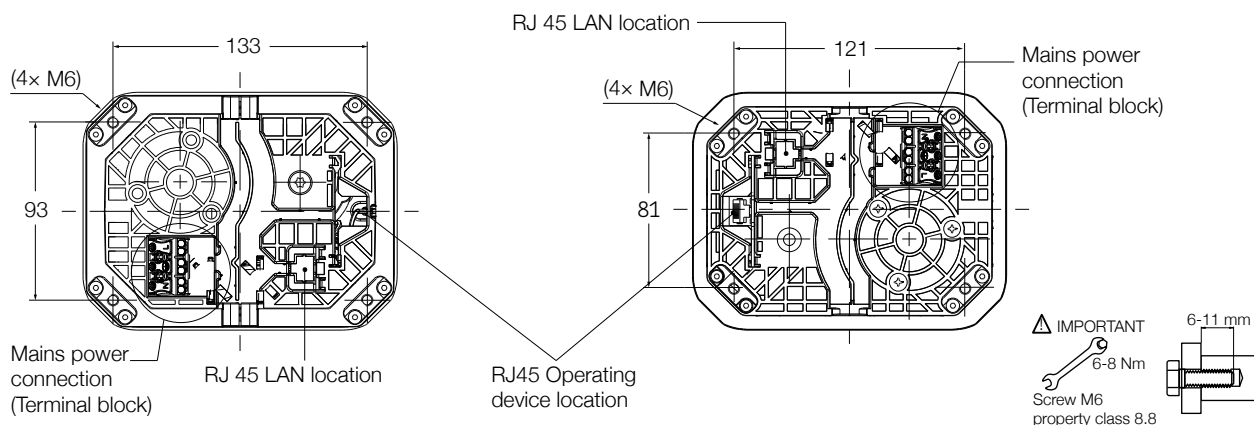


## Suitable products

	External power supply 24 V DC																	
	EHA4	STL	STK	ZDV-348220-002	ZDV-348221-002	ZKA-140449-2500	ZKA-140450-2500	ZKA-140451-2500	ZKA-140452-2500	ZKA-140458-2500	ZKA-140460-2500	ZKA-140453-2500	ZKA-140454-2500	ZKA-140455-2500	ZKA-140456-2500	ZKA-140459-2500	ZKA-140461-2500	
CPMA1-1	•	•	•	•	•	•	•	•	•	•	•							
CPMA1-2	•	•	•	•	•	•	•	•	•	•	•							
CPMA2-2	•	•	•	•														
 Hand switch	 Foot switch	 Desk switch		 Socket box		 Mains cable		 Detachable mains cord										

 Hand switch
  Foot switch
  Desk switch
  Socket box
  Mains cable
  Detachable mains cord

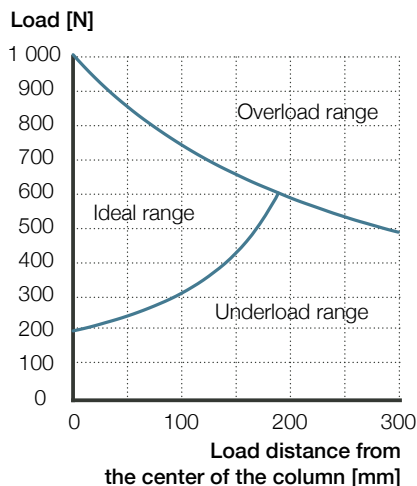
## Connections and fastening



Column must be attached on plane and rigid surface by 4 screws M6 with a depth of 6 to 11 mm in the column. The total length of the screw must be adjusted to the height of the fixture.

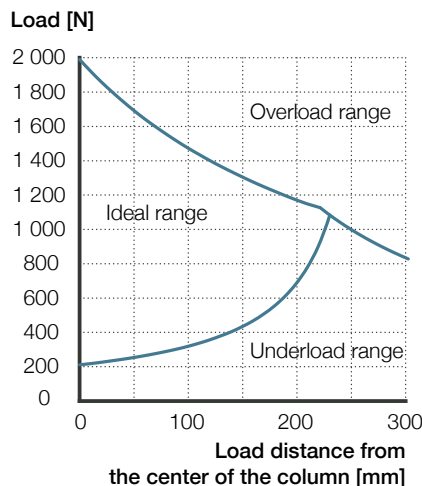
## Offset load diagrams

### CPMA1-1



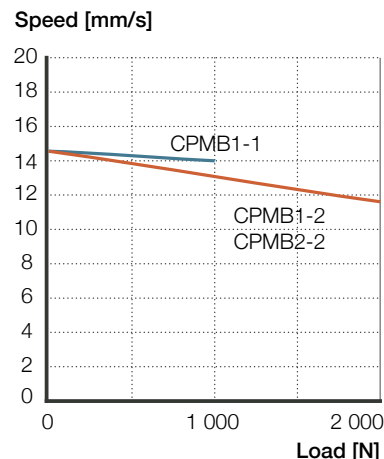
Offset load at full extension in the best axis

### CPMA1-2 and CPMA2-2



Offset load at full extension in the best axis

## Performance diagram



— CPMA1-1
 — CPMA1-2, CPMA2-2

## Inlet socket box – ZDV



### Benefits

- Multifunction plug and play accessory
- Detachable mains power cord
- Replaceable fuses
- LAN Connector
- Easy to use
- Cord strain relief

### Standards

- IEC 60601-1:2005 (3rd edition) compliant

## Outlet socket box – ZDV



### Benefits

- Multifunction plug and play accessory
- 3 IEC outlet sockets
- Replaceable fuses
- Integrated mounting plate
- LAN Connector
- Easy to use

### Standards

- IEC 60601-1:2005 (3rd edition) compliant

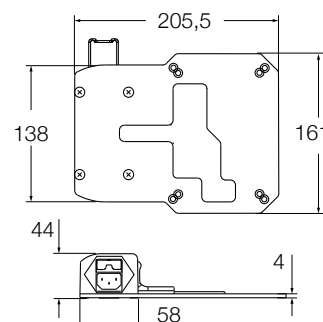
### Suitable operating devices

	Columns			Hand switches	Foot switches	Desk switches	Mains cables						Detachable mains cords						
	CPMA1-1	CPMA1-2	CPMA2-2	EHA41-13N10N-000	STL01-GW1000-X190	STK01-SW3000-X100	STK01-UW3000-X100	ZKA-140449-2500	ZKA-140450-2500	ZKA-140451-2500	ZKA-140452-2500	ZKA-140458-2500	ZKA-140460-2500	ZKA-140453-2500	ZKA-140454-2500	ZKA-140455-2500	ZKA-140456-2500	ZKA-140459-2500	ZKA-140461-2500
ZDV-348220-002	●	●		●	●	●	●							●	●	●	●	●	●

### Technical data

- IEC inlet mains power socket with retainer
- 1 RJ45 for operating device
- 1 RJ45 for LAN
- 2 replaceable fuses 8 A
- Plate with holes as the plates of the column CPMA
- Can be fastened on inner and outer tube

### Dimensional drawing



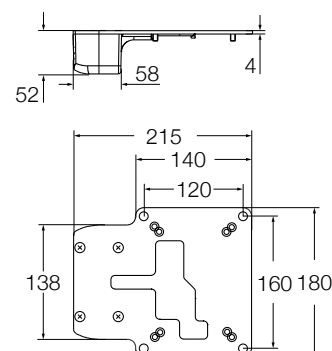
### Suitable operating devices

	Columns			Hand switches	Foot switches	Desk switches	Mains cables			Detachable mains cords									
	CPMA1-1	CPMA1-2	CPMA2-2	EHA41-13N10N-000	STL01-GW1000-X190	STK01-SW3000-X100	STK01-UW3000-X100	ZKA-140449-2500	ZKA-140450-2500	ZKA-140451-2500	ZKA-140452-2500	ZKA-140458-2500	ZKA-140460-2500	ZKA-140453-2500	ZKA-140454-2500	ZKA-140455-2500	ZKA-140456-2500	ZKA-140459-2500	ZKA-140461-2500
ZDV-348221-002	●	●		●	●	●	●												

### Technical data

- 3 IEC mains power outlet sockets
- 1 RJ45 for operating device
- 1 RJ45 for LAN
- 2 replaceable fuses 8 A
- Integrated mounting plate with 4 holes 9 mm diameter
- 4 screws to fasten on column CPMA
- Can be fastened on inner and outer tube

### Dimensional drawing



## Mounting plate – ZPL



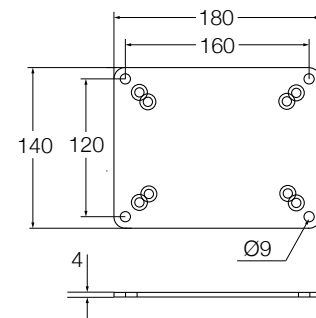
### Benefits

- Easy to use

### Suitable operating devices

	Columns		
	CPMA1-1	CPMA1-2	CPMA2-2
ZPL-348382	•	•	•

### Dimensional drawing



### Technical data

- Can be fastened on inner and outer tube
- Mounting plate with 4 holes 9 mm diameter

## Mains cable and detachable mains cord – ZKA

### Mains cable



### Detachable mains cord



### Mains cable

	Columns			Socket boxes	
	CPMA1-1	CPMA1-2	CPMA2-2	ZDV-348220-002	ZDV-348221-002
ZKA-140449-2500	•	•			
ZKA-140450-2500	•	•			
ZKA-140451-2500	•	•			
ZKA-140452-2500	•	•			
ZKA-140458-2500	•	•			
ZKA-140460-2500	•	•			

### Detachable mains cord

	Columns			Socket boxes	
	CPMA1-1	CPMA1-2	CPMA2-2	ZDV-348220-002	ZDV-348221-002
ZKA-140453-2500	•	•			
ZKA-140454-2500	•	•			
ZKA-140455-2500	•	•			
ZKA-140456-2500	•	•			
ZKA-140459-2500	•	•			
ZKA-140461-2500	•	•			

### Benefits

- Easy to use
- Identification by a product label

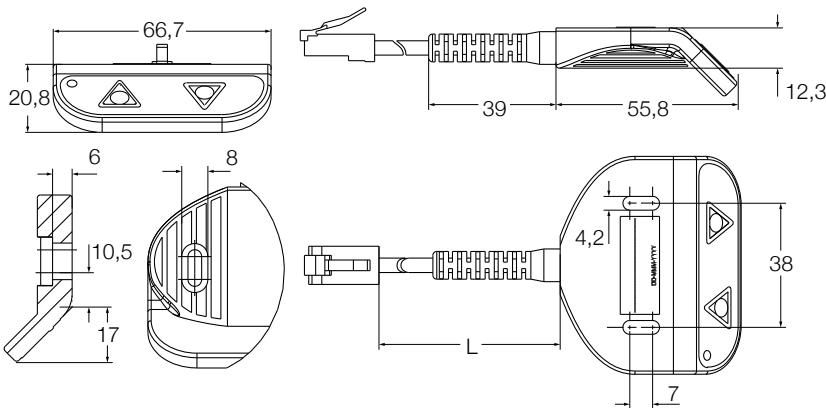
### Standards

- IEC 60601-1:2005 (3rd edition) compliant

# Desk switch – STK



## Dimensional drawing



### Benefits

- Easy and precise
- Stylish design
- Tactile buttons with finger guide
- 2 colors LED for power and feedback status

### Standards

- IEC 60601-1:2005 (3rd edition) compliant

## Suitable operating devices

	Columns			Socket boxes	
	CPMA1-1	CPMA1-2	CPMA2-2	ZDV-348220-002	ZDV-348221-002
STK01-SW3000-X100	•	•	•	•	•
STK01-UW3000-X100	•	•	•	•	•

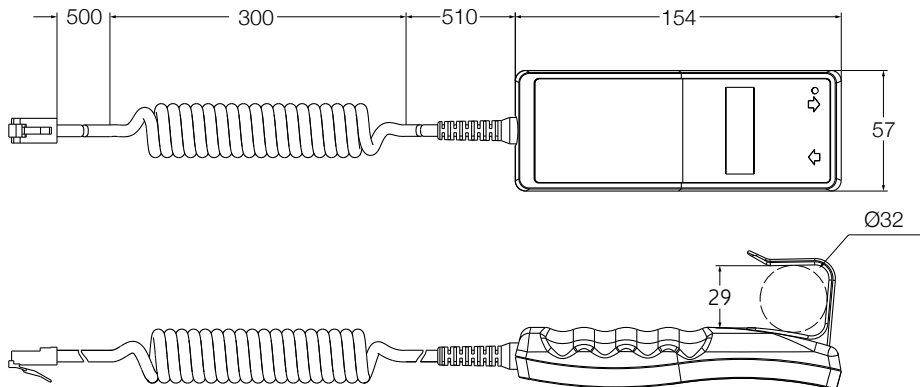
Designation	L [mm]
STK01-SW3000-X100	500
STK01-UW3000-X100	1 000

See **page 200** and **201** for technical data and ordering key

# Hand switch – EHA



## Dimensional drawing



### Benefits

- Robust ergonomic design
- Tactile buttons
- Easy mountable fastening hook
- 2 colors LED for power and feedback status

### Standards

- IEC 60601-1:2005 (3rd edition) compliant

## Suitable operating devices

	Columns			Socket boxes	
	CPMA1-1	CPMA1-2	CPMA2-2	ZDV-348220-002	ZDV-348221-002
EHA	•	•	•	•	•

See **page 200** and **201** for technical data and ordering key



Foot switch –  
STL



Benefits

- Easy to use
- Ergonomic design

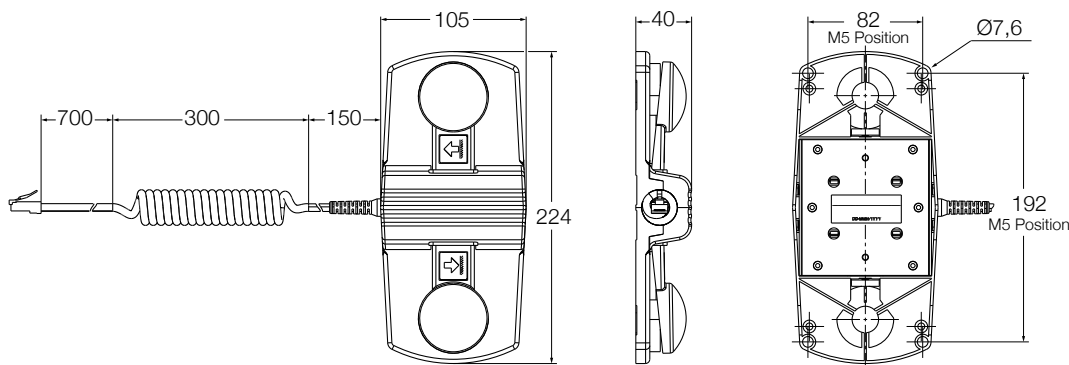
Standards

- IEC 60601-1:2005 (3rd edition) compliant

Suitable operating devices

	Columns			Socket boxes	
	CPMA1-1	CPMA1-2	CPMA2-2	ZDV-348220-002	ZDV-348221-002
STL01	•	•	•	•	•

Dimensional drawing



Switches technical data

	Unit	EHA4	STL	STK
Max. operating channels	n°	1	1	1
Operating power	V DC/mA	5/20	5/20	5/20
Degree of protection	IP	67	x2	–
Color	–	Grey	Grey and anthracite	Grey
Indicator	–	LED 2 colors for power and feedback status	–	LED 2 colors for power and feedback status
Plug	–	RJ45	RJ45	RJ45
Hook	–	with hook	–	–
Symbols	–	with arrows up/down	with arrows up/down	with arrows up/down

## Accessories

Description	Plug	Country	Part number	Order Number
Mains cable straight 2,5 m	Schuko	Germany, France, ...	ZKA-140449-2500	130015
	Typ-L	Italy	ZKA-140450-2500	130016
	British standard	UK	ZKA-140451-2500	130017
	NEMA	USA, Japan, ...	ZKA-140452-2500	130018
	SEV	CH	ZKA-140458-2500	130256
	AS 3112	PRC, Australia, ...	ZKA-140460-2500	130391
Detachable mains cord straight 2,5 m (to plug in socket box Inlet)	Schuko	Germany, France, ...	ZKA-140453-2500	130019
	Typ-L	Italy	ZKA-140454-2500	130020
	British standard	UK	ZKA-140455-2500	130021
	NEMA	USA, Japan, ...	ZKA-140456-2500	130022
	SEV	CH	ZKA-140459-2500	130257
	AS 3112	PRC, Australia, ...	ZKA-140461-2500	130392
Desk switch with LED, cable 0,5 m			STK01-SW3000-X100	130025
Desk switch with LED, cable 1,0 m			STK01-UW3000-X100	130026
Handset with LED, cable coiled 1,3 m			EHA41-13N00N-000	131033
Foot switch, cable coiled 1,3 m			STL01-GW1000-X100	131873
Mounting plate			ZPL-348382	130024
Socket box inlet: IEC, RJ45 LAN, RJ45 op. device			ZDV-348220-002	130030
Socket box outlet: 3xIEC, RJ45 LAN, RJ45 op. device			ZDV-348221-002	130032

## Ordering key

C P M A - 2 - 0 0 0

### Type

### Voltage

- 1 100–240 V AC 50/60 Hz
- 2 24 V DC

### Load

- Push
- 1 1 000 N Only for AC version
- 2 2 000 N

### Tube set

- 2 2-section

### Stroke length

- 200 200 mm Only for DC version
- 230 230 mm
- 250 250 mm
- 300 300 mm
- 400 400 mm
- Other per 10 mm from 200 mm or 230 mm for AC version up to 400 mm

### Motor orientation <sup>1)</sup>

- A Motor in inner tube
- B Motor in outer tube

### Operating device orientation

- A Operating device socket as the motor
- B Operating device socket at both sides

### LAN cable through

- 0 No
- 1 LAN cable through Not compatible with op. device socket at both sides

<sup>1)</sup> Column can be placed with outer tube on the top or bottom (→ page 195)

■ Options shown in red are only available on request. Contact Ewellix for more information on minimum quantities and additional cost.

# CPMB

For infant care



## Benefits

- Universal power supply
- Plug and play
- Soft start and stop control
- Low noise level
- Cable through column
- Grounding continuity

## Standards

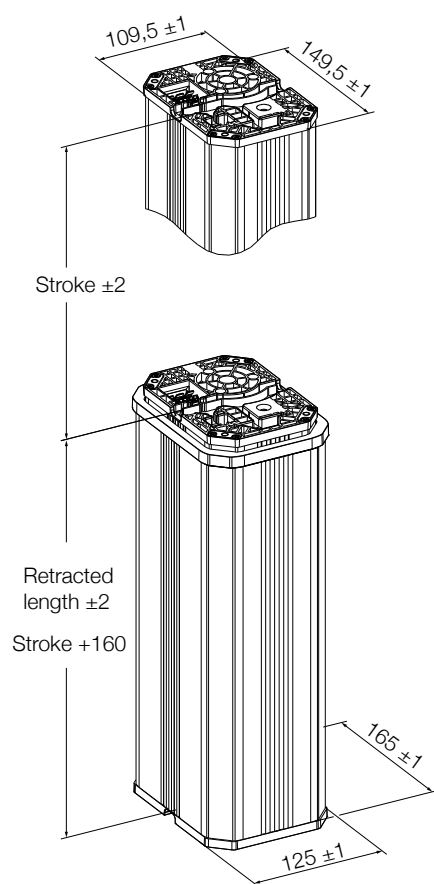
- IEC 60601-1:2005  
(3rd edition) compliant

## Technical data

	Unit	CPMB1-1	CPMB1-2	CPMB2-2
Rated push load (with self locking)	N	1 000	2 000	2 000
Rated pull load	N	0	0	0
Bending moment (dynamic)	Nm	up to 115 <sup>1)</sup>	up to 250 <sup>1)</sup>	up to 250 <sup>1)</sup>
Speed (full load to no load)	mm/s	14 to 15	11 to 15	11 to 15
Lifting column version	# of section	2-section	2-section	2-section
Stroke	mm	230 to 400	230 to 400	200 to 400
Retracted length	mm	S+160	S+160	S+160
Static Load (Max) in push way	N	8 000	8 000	8 000
Static bending moment (Max)	Nm	500	500	500
Voltage (rated)	V	100–240 AC 50/60 Hz	100–240 AC 50/60 Hz	24 DC
Input current (rated)	A	1,5	1,6	5
Duty cycle: intermittent operation	on/off	1 min./9 min.	1 min./9 min.	1 min./9 min.
Ambient temperature	°C	+10 to +40	+10 to +40	+10 to +40
Degree of protection	IP	30	30	30
Protection class	–	I	I	–
Type of control	–	electrical	electrical	electrical
Noise level (Max)	dB(A)	45	45	45
Weight	kg	8 to 11	9 to 12	8 to 11

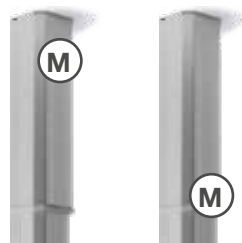
<sup>1)</sup> For details, see offset load diagrams (→ page 204)

## Dimensional drawing



## More flexibility with Series CPMB design options

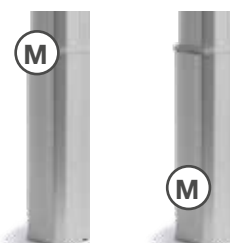
Built-in with outer tube on top  
More hygienic and easy-to-clean design



Motor  
orientation B

Motor  
orientation A

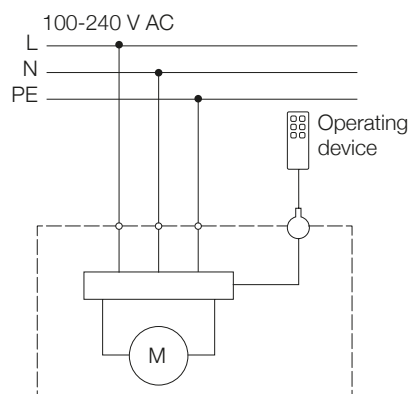
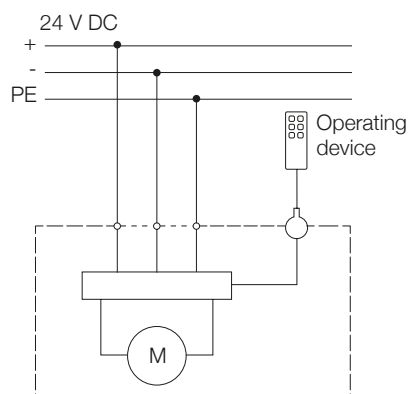
Built-in with outer tube on bottom  
More aesthetic design



Motor  
orientation A




Motor  
orientation B

## Connecting diagrams

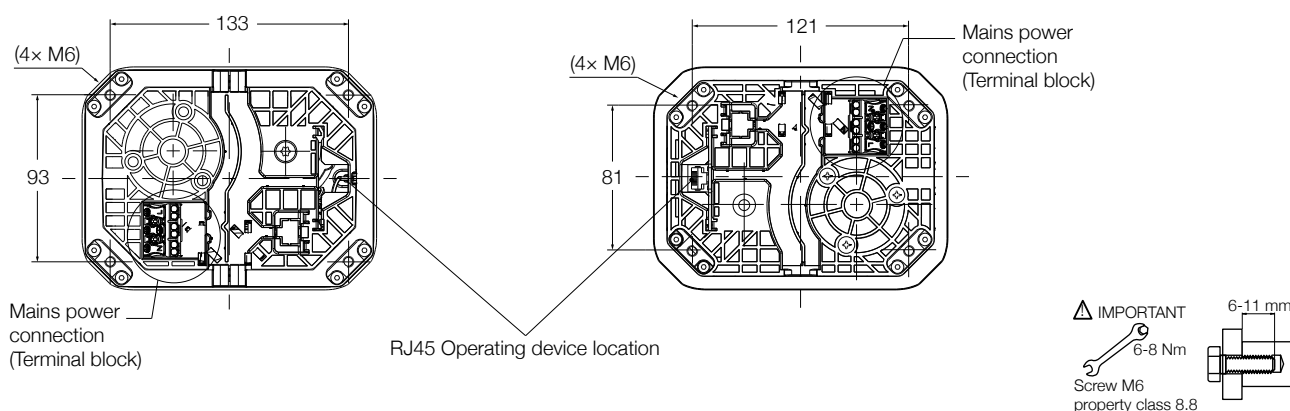


## Suitable operating devices

	External power supply 24 V DC	Hand switch	Foot switch	Desk switch
		EHA4	STL	STK
CPMB1-1		•	•	•
CPMB1-2		•	•	•
CPMB2-2	•	•	•	•

 Hand switch
  Foot switch
  Desk switch

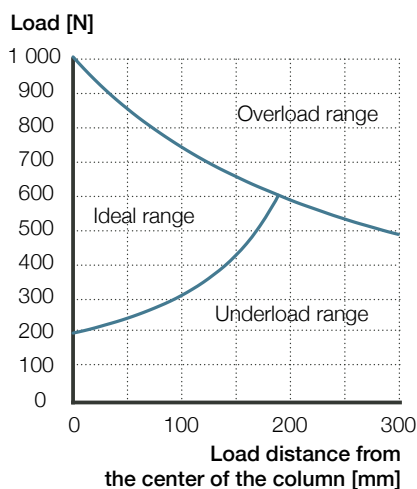
## Connections and fastening



Column must be attached on plane and rigid surface by 4 screws M6 with a depth of 6 to 11 mm in the column. The total length of the screw must be adjusted to the height of the fixture.

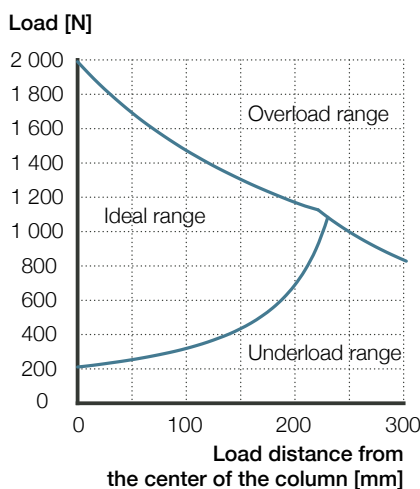
## Offset load diagrams

### CPMA1-1



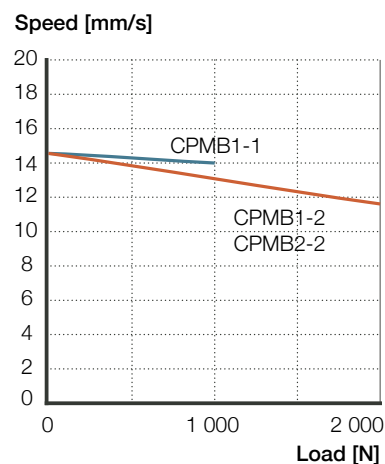
Offset load at full extension in the best axis

### CPMA1-2 and CPMA2-2



Offset load at full extension in the best axis

## Performance diagram



— CPMA1-1 — CPMA1-2, CPMA2-2

## Inlet socket box – ZDV



### Benefits

- Multifunction plug and play accessory
- Detachable mains power cord
- Replaceable fuses
- LAN Connector
- Easy to use
- Cord strain relief

### Standards

- IEC 60601-1:2005 (3rd edition) compliant

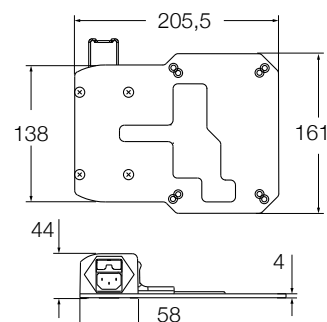
### Suitable operating devices

	Columns			Hand switches	Foot switches	Desk switches	Mains cables						Detachable mains cords						
	CPMB1-1	CPMB1-2	CPMB2-2	EHA41-13N10N-000	STL01-GW1000-X190	STK01-SW3000-X100	STK01-UW3000-X100	ZKA-140449-2500	ZKA-140450-2500	ZKA-140451-2500	ZKA-140452-2500	ZKA-140458-2500	ZKA-140460-2500	ZKA-140453-2500	ZKA-140454-2500	ZKA-140455-2500	ZKA-140456-2500	ZKA-140459-2500	ZKA-140461-2500
ZDV-348220-002	●	●		●	●	●	●							●	●	●	●	●	●

### Technical data

- IEC inlet mains power socket with retainer
- 1 RJ45 for operating device
- 1 RJ45 for LAN
- 2 replaceable fuses 8 A
- Plate with holes as the plates of the column CPMA
- Can be fastened on inner and outer tube

### Dimensional drawing



## Outlet socket box – ZDV



### Benefits

- Multifunction plug and play accessory
- 3 IEC outlet sockets
- Replaceable fuses
- Integrated mounting plate
- LAN Connector
- Easy to use

### Standards

- IEC 60601-1:2005 (3rd edition) compliant

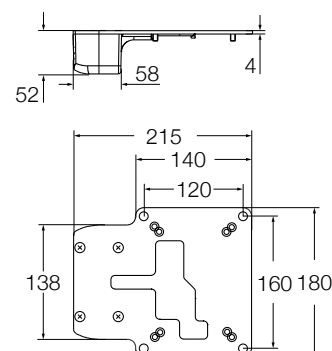
### Suitable operating devices

	Columns			Hand switches	Foot switches	Desk switches	Mains cables					Detachable mains cords							
	CPMB1-1	CPMB1-2	CPMB2-2	EHA41-13N10N-000	STL01-GW1000-X190	STK01-SW3000-X100	STK01-UW3000-X100	ZKA-140449-2500	ZKA-140450-2500	ZKA-140451-2500	ZKA-140452-2500	ZKA-140458-2500	ZKA-140460-2500	ZKA-140453-2500	ZKA-140454-2500	ZKA-140455-2500	ZKA-140456-2500	ZKA-140459-2500	ZKA-140461-2500
ZDV-348221-002	●	●		●	●	●	●												

### Technical data

- 3 IEC mains power outlet sockets
- 1 RJ45 for operating device
- 1 RJ45 for LAN
- 2 replaceable fuses 8 A
- Integrated mounting plate with 4 holes 9 mm diameter
- 4 screws to fasten on column CPMA
- Can be fastened on inner and outer tube

### Dimensional drawing



## Mounting plate – ZPL



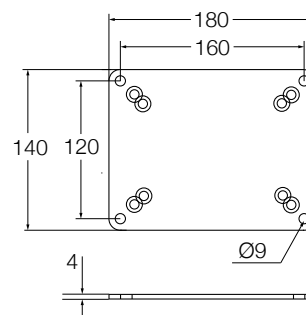
### Benefits

- Easy to use

### Suitable operating devices

	Columns		
	CPMA1-1	CPMA1-2	CPMA2-2
ZPL-348382	•	•	•

### Dimensional drawing



### Technical data

- Can be fastened on inner and outer tube
- Mounting plate with 4 holes 9 mm diameter

## Mains cable and detachable mains cord – ZKA

Mains cable



Detachable mains cord



### Mains cable

	Columns			Socket boxes	
	CPMB1-1	CPMB1-2	CPMB2-2	ZDV-348220-002	ZDV-348221-002
ZKA-140449-2500	•	•			
ZKA-140450-2500	•	•			
ZKA-140451-2500	•	•			
ZKA-140452-2500	•	•			
ZKA-140458-2500	•	•			
ZKA-140460-2500	•	•			

### Detachable mains cord

	Columns			Socket boxes	
	CPMB1-1	CPMB1-2	CPMB2-2	ZDV-348220-002	ZDV-348221-002
ZKA-140453-2500	•	•			
ZKA-140454-2500	•	•			
ZKA-140455-2500	•	•			
ZKA-140456-2500	•	•			
ZKA-140459-2500	•	•			
ZKA-140461-2500	•	•			

### Benefits

- Easy to use
- Identification by a product label

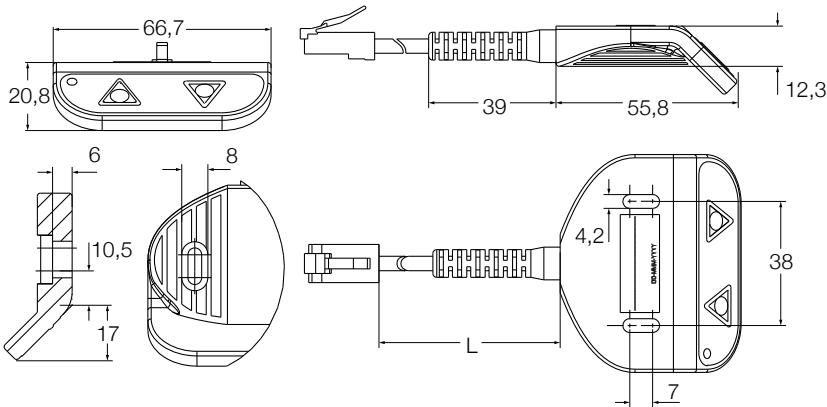
### Standards

- IEC 60601-1:2005 (3rd edition) compliant

# Desk switch – STK



Dimensional drawing



Benefits

- Easy and precise
- Stylish design
- Tactile buttons with finger guide
- 2 colors LED for power and feedback status

Standards

- IEC 60601-1:2005 (3rd edition) compliant

Suitable operating devices

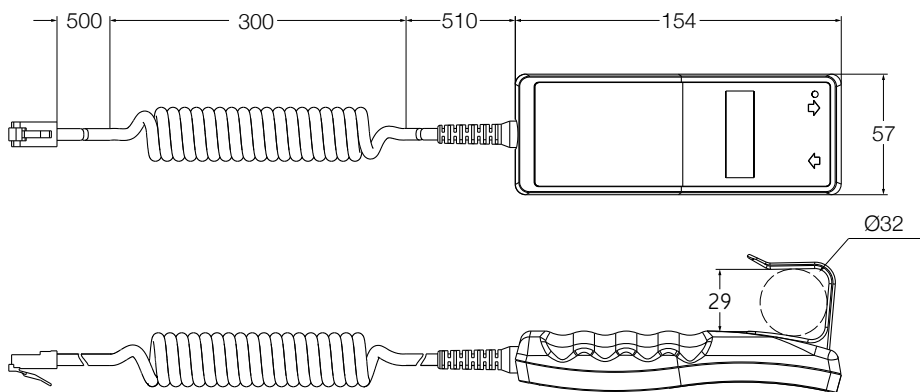
					Designation	L [mm]
Columns					Socket boxes	
	CPMA1-1	CPMA1-2	CPMA2-2	ZDV-348220-002	ZDV-348221-002	
STK01-SW3000-X100	•	•	•	•	•	500
STK01-UW3000-X100	•	•	•	•	•	1 000

See page 208 and 209 for technical data and ordering key

# Hand switch – EHA



Dimensional drawing



Benefits

- Robust ergonomic design
- Tactile buttons
- Easy mountable fastening hook
- 2 colors LED for power and feedback status

Standards

- IEC 60601-1:2005 (3rd edition) compliant

Suitable operating devices

					Columns	Socket boxes
	CPMB1-1	CPMB1-2	CPMB2-2	ZDV-348220-002	ZDV-348221-002	
EHA	•	•	•	•	•	

See page 208 and 209 for technical data and ordering key



Foot switch –  
STL



Benefits

- Easy to use
- Ergonomic design

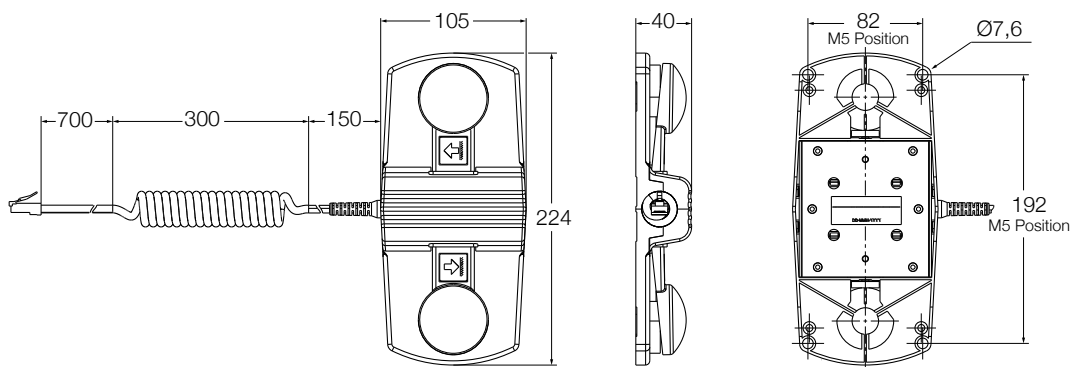
Standards

- IEC 60601-1:2005 (3rd edition) compliant

Suitable operating devices

	Columns			Socket boxes	
	CPMB1-1	CPMB1-2	CPMB2-2	ZDV-348220-002	ZDV-348221-002
STL01	•	•	•	•	•

Dimensional drawing



Switches technical data

	Unit	EHA4	STL	STK
Max. operating channels	n°	1	1	1
Operating power	V DC/mA	5/20	5/20	5/20
Degree of protection	IP	67	x2	–
Color	–	Grey	Grey and anthracite	Grey
Indicator		LED 2 colors for power and feedback status	–	LED 2 colors for power and feedback status
Plug	–	RJ45	RJ45	RJ45
Hook	–	with hook	–	–
Symbols	–	with arrows up/down	with arrows up/down	with arrows up/down

## Accessories

Description	Plug	Country	Part number	Order Number
Mains cable straight 2,5 m	Schuko	Germany, France, ...	ZKA-140449-2500	130015
	Typ-L	Italy	ZKA-140450-2500	130016
	British standard	UK	ZKA-140451-2500	130017
	NEMA	USA, Japan, ...	ZKA-140452-2500	130018
	SEV	CH	ZKA-140458-2500	130256
	AS 3112	PRC, Australia, ...	ZKA-140460-2500	130391
Detachable mains cord straight 2,5 m (to plug in socket box Inlet)	Schuko	Germany, France, ...	ZKA-140453-2500	130019
	Typ-L	Italy	ZKA-140454-2500	130020
	British standard	UK	ZKA-140455-2500	130021
	NEMA	USA, Japan, ...	ZKA-140456-2500	130022
	SEV	CH	ZKA-140459-2500	130257
	AS 3112	PRC, Australia, ...	ZKA-140461-2500	130392
Desk switch with LED, cable 0,5 m			STK01-SW3000-X100	130025
Desk switch with LED, cable 1,0 m			STK01-UW3000-X100	130026
Handset with LED, cable coiled 1,3 m			EHA41-13N00N-000	131033
Foot switch, cable coiled 1,3 m			STL01-GW1000-X100	131873
Mounting plate			ZPL-348382	130024
Socket box inlet: IEC, RJ45 LAN, RJ45 op. device			ZDV-348220-002	130030
Socket box outlet: 3xIEC, RJ45 LAN, RJ45 op. device			ZDV-348221-002	130032

## Ordering key

C P M B - 2 - 0 - 0 0 0

### Type

### Voltage

- 1 100–240 V AC 50/60 Hz
- 2 24 V DC

### Load

- Push
- 1 1 000 N Only for AC version
- 2 2 000 N

### Tube set

- 2 2-section

### Stroke length

- 200 200 mm Only for DC version
- 230 230 mm
- 250 250 mm
- 300 300 mm
- 400 400 mm
- Other per 10 mm from 200 mm or a mm for AC version up to 400 mm

### Motor orientation <sup>1)</sup>

- A Motor in inner tube
- B Motor in outer tube

### Operating device orientation

- A Operating device socket as the motor
- B Operating device socket at both sides

<sup>1)</sup> Column can be placed with outer tube on the top or bottom (→ page 203)

Options shown in red are only available on request. Contact Ewellix for more information on minimum quantities and additional cost.

# CPMT

For medical procedure equipment

## Benefits

- Low retracted height
- High stroke
- High load capacity
- High safety and reliability
- Design flexibility

## Standards

- IEC 60601-1:2005
- ANSI/AAMI ES60601-1:2005
- IEC 60601-1-2:2007

## Technical data

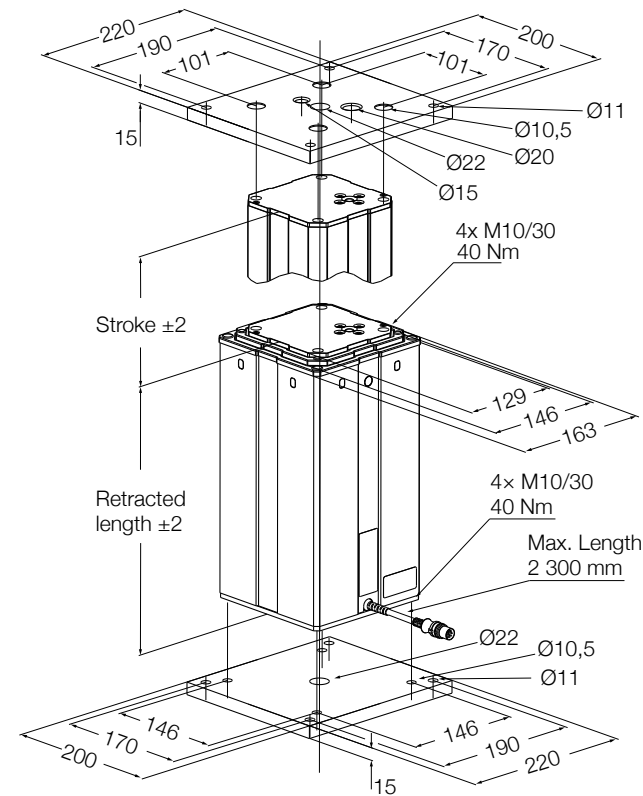
	Unit	CPMT1-1S	CPMT1-1M	CPMT1-2S	CPMT1-2M
Rated push load	N	5 000	5 000	6 000	6 000
Rated pull load	N	4 000	4 000	4 000	4 000
Static load (push) <sup>1)</sup>	N	15 000	15 000	15 000	15 000
Safety factor on rated load <sup>2)</sup>		4	4	4	4
Dynamic bending moment	Nm	up to 450 <sup>3)</sup>	up to 1 200 <sup>3)</sup>	up to 550 <sup>3)</sup>	up to 1 400 <sup>3)</sup>
Static bending moment (max.)	Nm	1 000	3 000	1 000	3 000
Retracted length	mm	stroke/2 + 120 mm	stroke/2 + 240 mm	stroke/2 + 120 mm	stroke/2 + 240 mm
Stroke (S)	mm	400 to 600	300 to 600	400 to 600	300 to 600
Speed	mm/s	14 to 34	14 to 34	12 to 26	12 to 26
Voltage	V DC	24 to 30	24 to 30	24 to 30	24 to 30
Current (push, max.)	A	12	12	10	10
Current (pull, max.)	A	10	10	7	7
Duty cycle	on/off	1 min./9 min.	1 min./9 min.	1 min./9 min.	1 min./9 min.
Ambient temperature	°C	+10 to +40	+10 to +40	+10 to +40	+10 to +40
Degree of protection		20	20	20	20
Weight	kg	16,5 to 20	19 to 23,5	16,5 to 20	19 to 23,5

<sup>1)</sup> Compliant with static load according to IEC 60601-2-46:2010

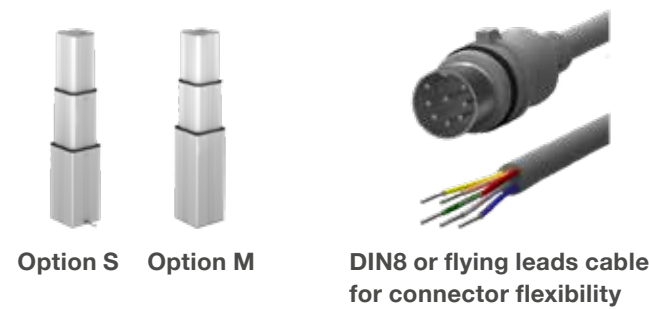
<sup>2)</sup> Static tensile safety factor to prevent mechanical hazard according to IEC 60601-1:2005

<sup>3)</sup> For details, see offset load diagrams (→ page 211)







Dimensional drawing



Configuration options



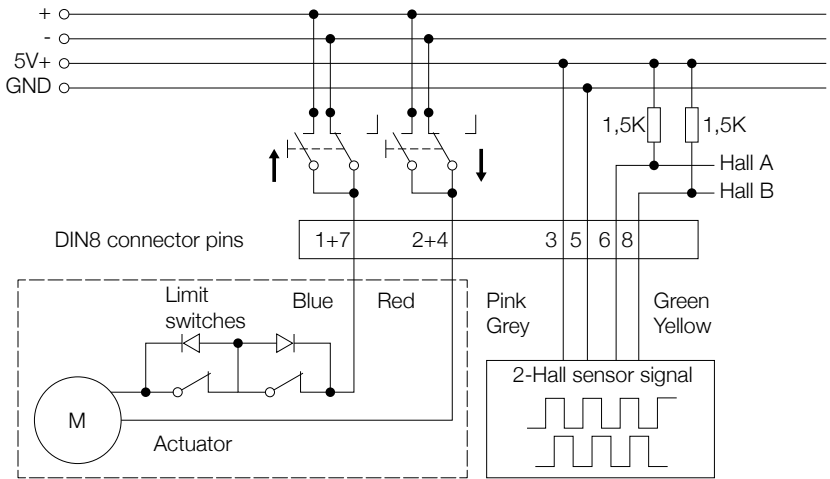
Suitable control units and accessories

	Control units		
	SCU	VCU	BCU <sup>1)</sup>
<b>CPMT</b>	•	•	•
<b>Operating switches</b>			
EHA 3 	•	•	•
STJ 	•	•	•
STE 	•	•	•
 Hand switch		 Foot switch	 Desk switch

<sup>1)</sup> Reduced load capacity:  
CPMT1-1 up to 3 000 N  
CPMT1-2 up to 4 000 N

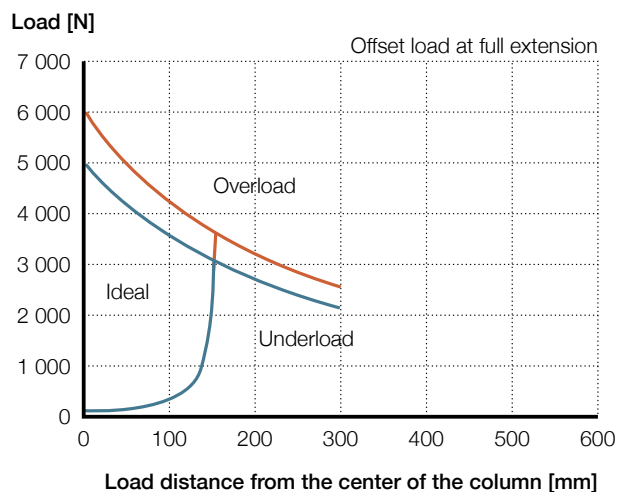
Connecting diagrams

24–30 V DC

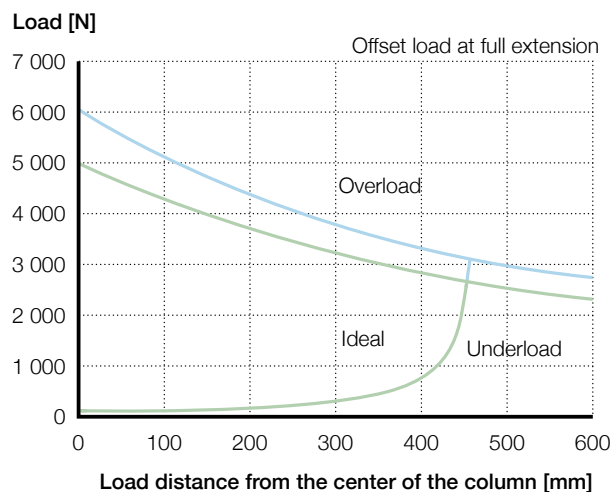


## Offset load diagrams

CPMT1-1S, -2S



CPMT1-1M, -2M



CPMT1-1S

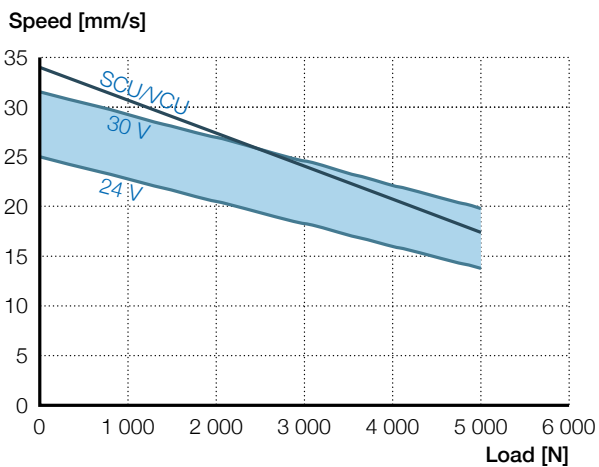
CPMT1-2S

CPMT1-2M

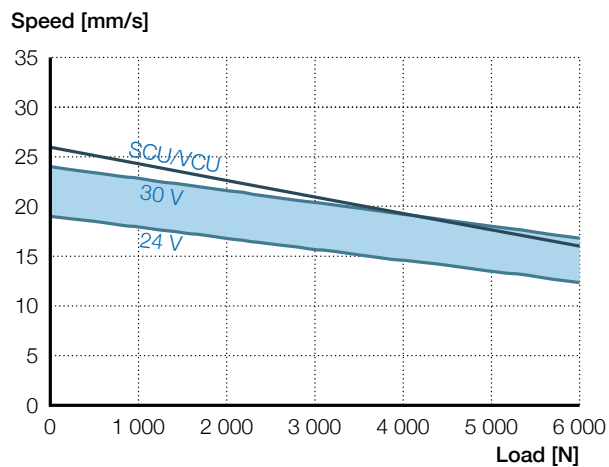
CPMT1-1M

## Speed-load diagrams

CPMT1-1

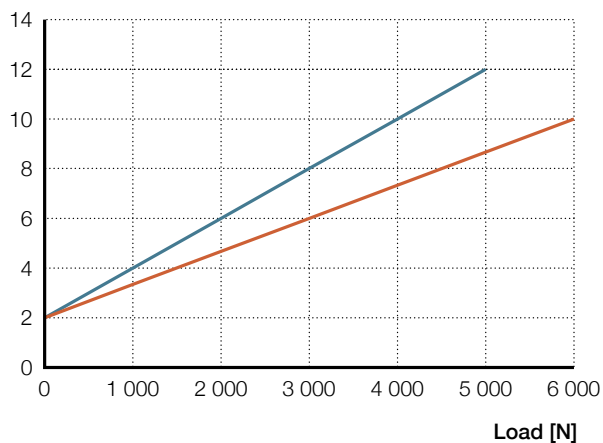


CPMT1-2



## Current-load diagram

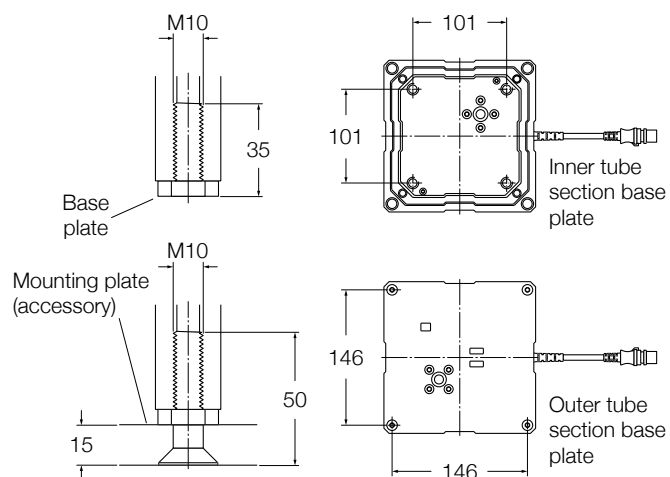
Current consumption [A]



CPMT1-1

CPMT1-2

## Mounting details



The column must be mounted on a plane and rigid surface by 4 screws M10 (accessory) with a screw in depth of 25 to 35 mm in the column.

## Additional attachment options

Optional threads on outer tube section can be configured for additional attachment options. Please contact Ewellix for more details.

- Choice in size and position
- High strength to support attached actuators



## Accessories

Description	Part number
Control Unit SCU (3 or 6 ports)	SCUXX-003XXX-000
Control Unit VCU (3 or 5 ports)	VCUXX-003XXX0-000
Control Unit BCU (3 ports)	BCUX3-XX3100-0000
Foot switch STJ (1-3 channels)	STJ0X-XXXXXX-XX00
Hand switch EHA3 (1-5 channels)	EHA3X-23MXXN-000
Top mounting plate	ZPL-290268
Bottom mounting plate	ZPL-290265
Screw (4/plate) for mounting plate	ZBE-510707

Ordering key

C

P

M

T

1

-

0

-

0

0

0

Type

Voltage

124–30 V DC

Load

Push (N)

Pull (N)

1

5 000

4 000

2

6 000

4 000

Retracted length

S

Stroke/2 + 120 mm

M

Stroke/2 + 240 mm

Stroke length (mm)

300

300 mm

Only for retracted length M

350

350 mm

Only for retracted length M

400

400 mm

450

450 mm

500

500 mm

550

550 mm

600

600 mm

---

Other

per 10 mm from 300 mm (or 400 mm for retracted length S) to 600 mm

Electrical options

F2-Hall encoder, end limit switches

Cable options

1

1 m DIN8 cable

2

2,3 m DIN8 cable

3

2,3 m flying leads cable

Options shown in red are only available on request. Contact Ewellix for more information on minimum quantities and additional cost.





# TFG

## Telemag

### Benefits

- Push or pull load
- Compact design
- Fast movement
- Powerful
- Plug and play

### Standards

- EN/IEC 60601-1
- UL 60601-1

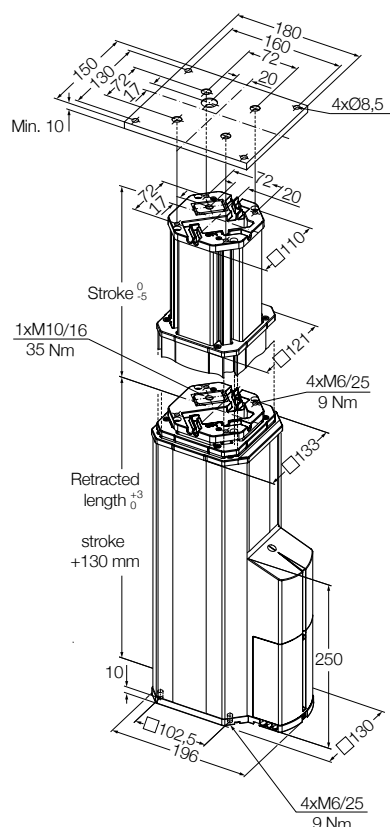


### Technical data

	Unit	TFG 10	TFG 50	TFG 90
Rated push load	N	2 500	2 500	2 500
Rated pull load	N	2 500	2 500	2 500
Bending load	Nm	up to 500	up to 500 <sup>1)</sup>	up to 500 <sup>1)</sup>
Speed (full load to no load)	mm/s	15 to 19	15 to 19	15 to 19
Lifting column version	# of section	3-section	3-section	3-section
Stroke	mm	200 to 700	200 to 700	200 to 700
Retracted length	mm	S+130	S+130	S+130
Voltage	V AC	24	120	230
Power	W	120	160	160
Current	A	5	1,8	1
Duty cycle: intermittent operation	min.	1 min./9 min.	1 min./9 min.	1 min./9 min.
Duty cycle: short-time operation	min.	3	3	3
Ambient temperature	°C	+10 to +40	+10 to +40	+10 to +40
Degree of protection	IP	30	30	30
Protection class	-	SELV	I	I
Type of control	-	electrical	electrical	electrical
Weight	kg	8 to 19	8 to 19	8 to 19

<sup>1)</sup> For details, please see bending load diagrams (→ page 218)

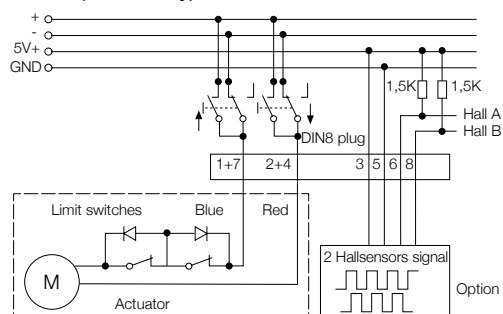
## Dimensional drawing



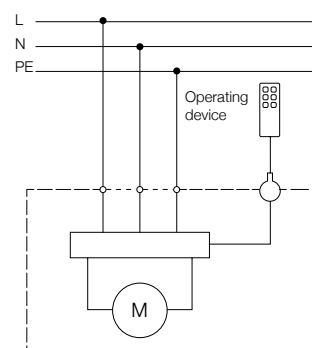
Note: mounting plates are not included.  
To be ordered separately.

## Connecting diagrams







24 V DC (TFG10 only)





## 120/230 V AC




## Suitable control units and accessories

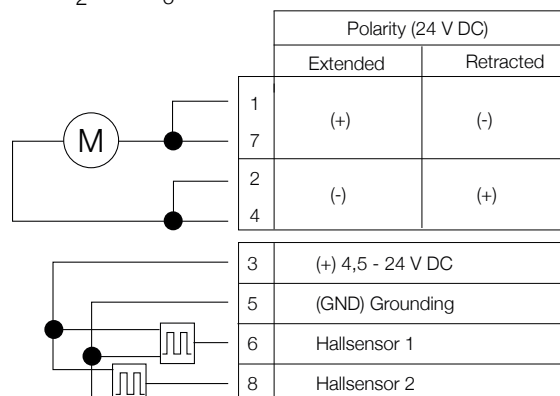
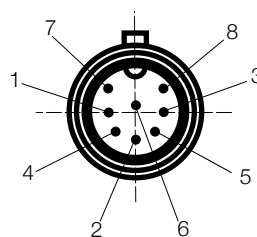
		Control units				
		SCU	VCU	BCU	COMPACT	SEM
TFG1		●	●	●	●	●
<b>Operating switches</b>						
EHA 3		●	●	●		
EHE						●
STJ		●	●	●		
STE		●	●	●		
HSM					●	
HSF					●	

 Hand switch

 Foot switch

 Desk switch

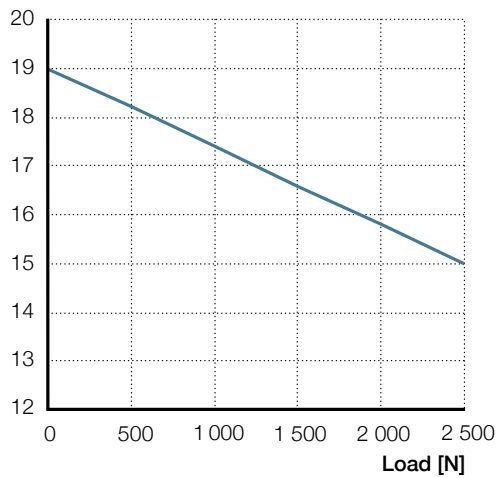
**TFG 10: pin assignment for DIN 8 plug  
fixed assembled cable with a length of 1,5 m**



## Performance diagrams

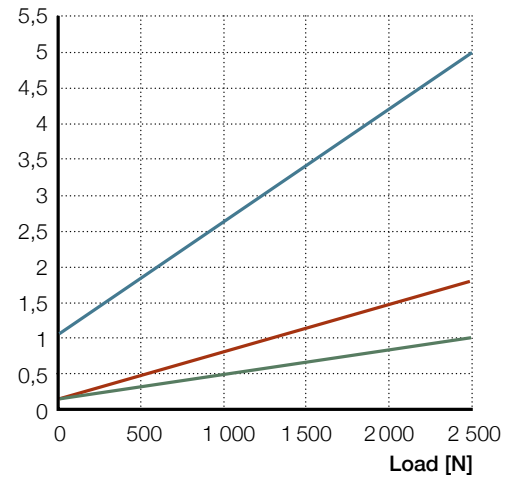
Speed-load diagram

Speed [mm/s]



Current-load diagram

Current consumption [A]



TFG 10

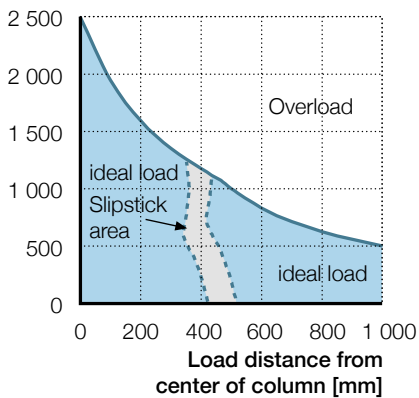
TFG 50

TFG 90

## Bending load diagrams

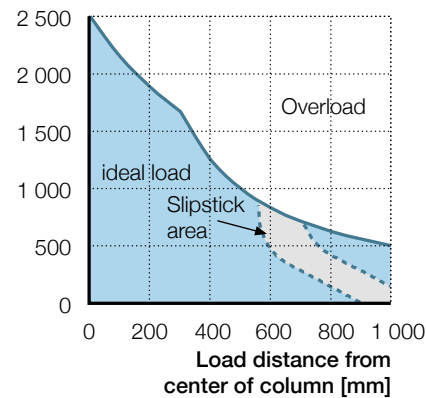
200 mm stroke

Load [N]



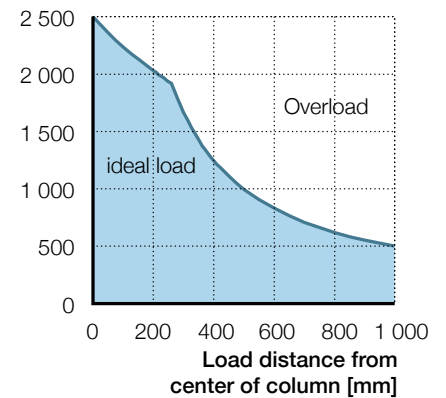
300 mm stroke

Load [N]



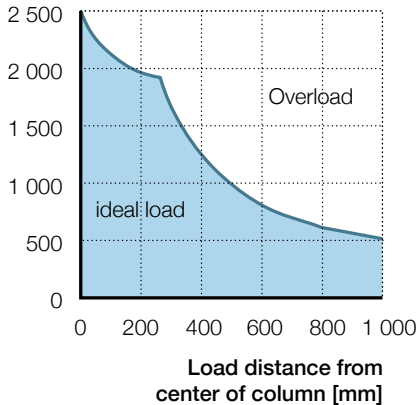
400 mm stroke

Load [N]



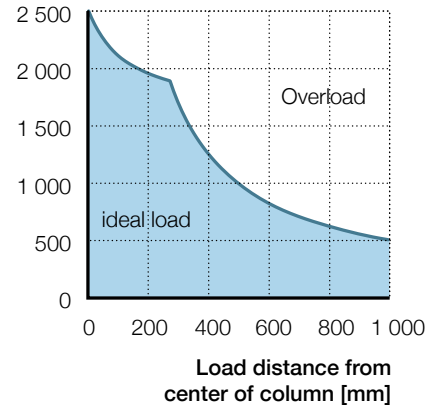
500 mm stroke

Load [N]



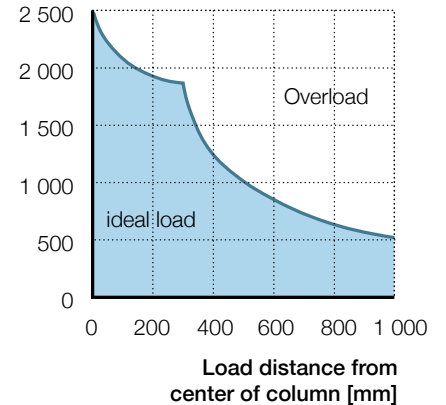
600 mm stroke

Load [N]



700 mm stroke

Load [N]



## Accessories

	Designation	Order N°
Top mounting plate Bore 72 × 72 mm	ZPL-333360	0124808
Bottom mounting plate Bore 102,5 × 102,5 mm	ZPL-264363	0124814
Screw for top mounting plate M10 × 25 (1 screw required)	ZBE-510978	0125359
Screw for top mounting plate M6 × 30 (4 screws required)	ZBE-510709	0125560
Screw for bottom mounting plate M6 × 30 (4 screws required)	ZBE-510709	0125560
Mains cable SEV plug 3 000 mm, black, 3 × 0.75 mm <sup>2</sup>	ZKA-304345-3000	0128699
Mains cable Schuko plug 3 000 mm, black, 3 × 0.75 mm <sup>2</sup>	ZKA-304346-3000	0121729
Mains cable US plug 3 000 mm, black, 3 × 0.75 mm <sup>2</sup>	ZKA-304347-3000	0121762
Mains cable British Standard plug 3 000 mm, black, 3 × 0.75 mm <sup>2</sup>	ZKA-304355-3000	0121755

## Ordering key

T F G 0 - 2 3 - 0 0 0

### Type

### Voltage

- 1 24 V DC
- 5 120 V AC (50/60 Hz)
- 9 230 V AC (50 Hz)

### Stroke [S]

- 200 200 mm
- 250 250 mm
- 300 300 mm
- 350 350 mm
- 400 400 mm
- 500 500 mm
- 700 700 mm

### Option

- 000 No option
- E\_ \_ With 2-Hall encoder, 14 pulses per 9 mm travel
- \_C\_ With mains cable feedthrough (3xAWG16)
- \_ \_H With control cable feedthrough (10xAWG28)

# THG

## Telemag lifting column

### Benefits

- Compact design
- Robust

### Standards

- EN/IEC 60601-1
- UL 60601-1



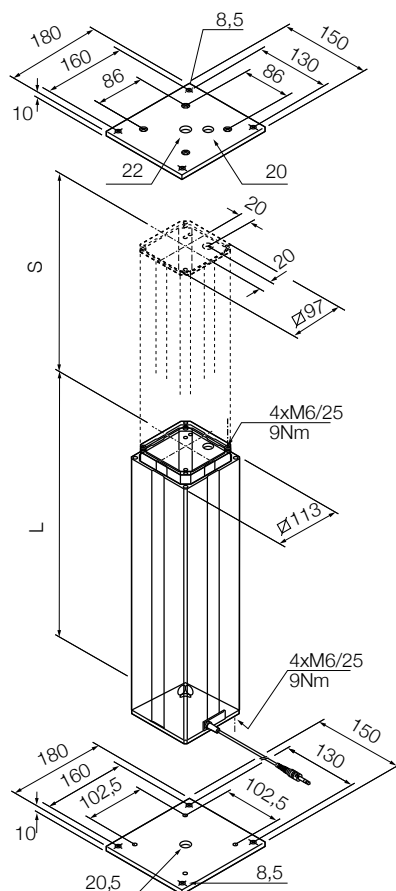
### Technical data

	Unit	THG 10/11-BA	THG 10/11-CA	THG 10/11-BD	THG 10/11-CD
Rated push load	N	2 000	1 000	2 000	1 000
Rated pull load	N	0	0	0	0
Bending load	Nm	up to 250 <sup>1)</sup>	up to 120 <sup>1)</sup>	up to 1 000 <sup>1)</sup>	up to 450 <sup>1)</sup>
Speed (full load to no load)	mm/s	5 to 7	12 to 15	5 to 7	12 to 15
Lifting column version	# of section	2-section	2-section	3-section	3-section
Stroke	mm	200 to 700	200 to 700	200 to 700	200 to 700
Retracted length	mm	S+270	S+270	S+180	S+180
Voltage	V DC	24	24	24	24
Power	W	120	120	120	120
Current	A	5	5	5	5
Duty cycle: intermittent operation	min.	1 min./9 min	1 min./9 min	1 min./9 min	1 min./9 min
Ambient temperature	°C	+10 to +40	+10 to +40	+10 to +40	+10 to +40
Degree of protection	IP	30	30	30	30
Protection class	–	SELV	SELV	SELV	SELV
Type of control	–	electrical	electrical	electrical	electrical
Weight	kg	8 to 14	8 to 14	8 to 14	8 to 14

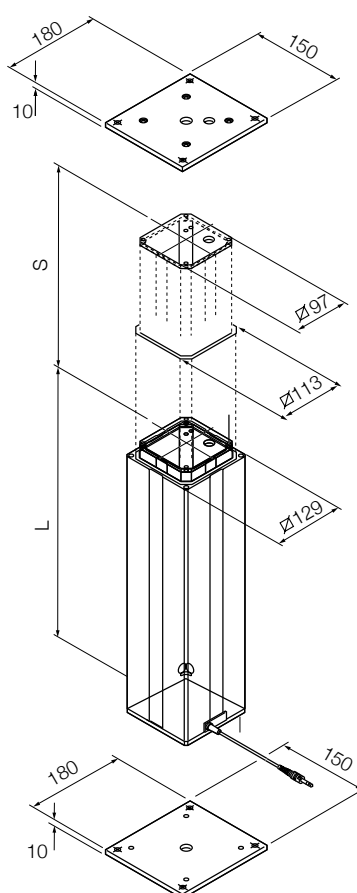
<sup>1)</sup> For details, please see bending load diagrams (→ page 222)

## Dimensional drawing

2-section

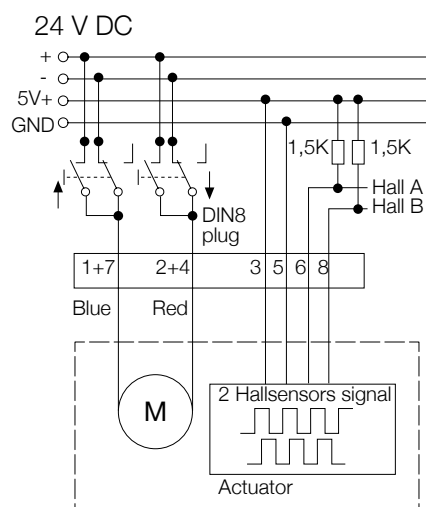


3-section









Note: mounting plates are not included.  
To be ordered separately.


### Connection diagram <sup>1)</sup>





<sup>1)</sup> Only valid with THG11. THG10 must be operated by a BCU, SCU or VCU control unit.

## Suitable control units and accessories

		Control units			
		SCU	VCU	BCU	MCU
THG		•	•	•	•
<b>Operating switches</b>					
EHA 1					•
EHA 3		•	•	•	
STF					•
STJ		•	•	•	
STA					•
STE		•	•	•	

 Hand switch

 Foot switch

 Desk switch

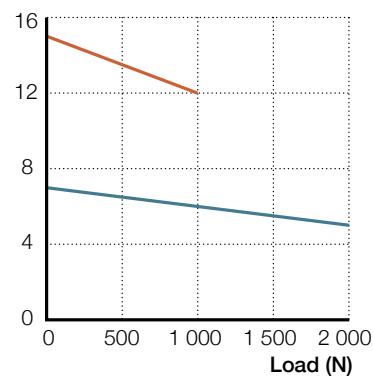
 Hand switch

 Foot switch Desk switch

## Performance diagrams

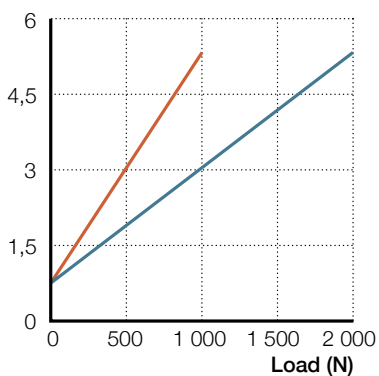
Speed-load diagram

Speed (mm/s)



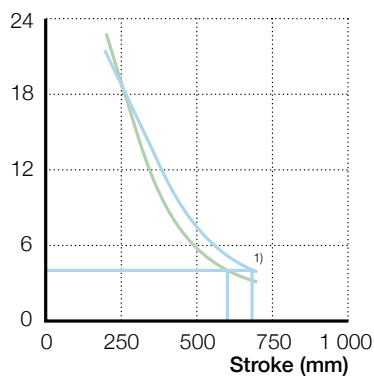
Current-load diagram

Current consumption (A)



## Safety factor load conditions

Safety factor (screw buckling)



1) Safety factor = 4

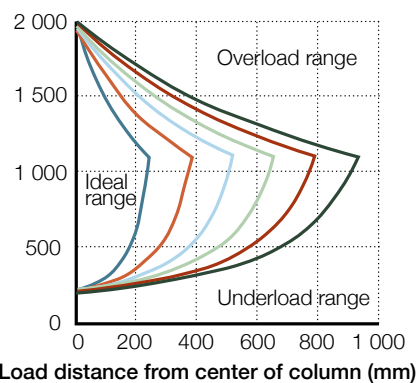
— THG...B. — THG...C.

— B/Tr 15x5 — C/Tr 12,5x5

## Bending load diagrams

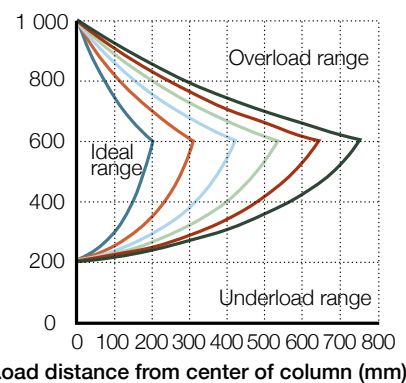
Bending load diagram THG...BD

Load [N]



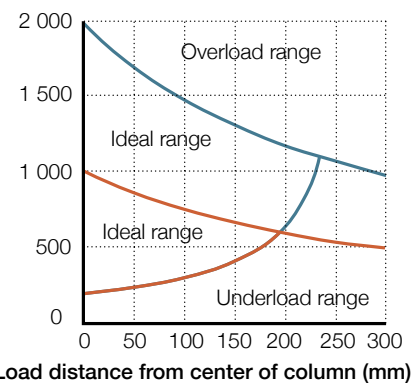
Bending load diagram THG...CD

Load [N]



Bending load diagram THG...BA/CA

Load [N]



Stroke: — 200 — 300 — 400 — 500 — 600 — 700

— THG...BA — THG...CA

## Accessories

	Designation	Order number
Top mounting plate for 2× tube set	SPL-264265	0125688
Bottom mounting plate for 2× tube set	SMT-264363	0124814
Top mounting plate for 3× tube set	SPL-264265	0125688
Bottom mounting plate for 3× tube set	SPL-264237	0125622
Screw M6x30 (4/plate) for mounting plate	ZBE-510709	0125560

## Ordering key

T H G 1 - - - - - 0 0 0

### Type

### Voltage

0 24 V DC

1 24 V DC with integrated current cut-off

### Load

B 2 000 N

C 1 000 N

### Tube set

A Tube set 2×

D Tube set 3×

### Stroke (S)

2 200 mm

3 300 mm

4 400 mm

5 500 mm

6 600 mm

7 700 mm

### Cable / connecting plug

1 Straight, 1,0 m / jack plug

2 Straight, 2,3 m / jack plug

A Coiled, 0,6 m / jack plug

3 Straight, 1,0 m / DIN8 plug

4 Straight, 2,3 m / DIN8 plug

B Coiled, 0,6 m / DIN8 plug

### Option

0 No option 0

A 1-Hall encoder, 8 pulses, cable with jack plug

B Potentiometer, 1 k, 2 Watt, 0,25 % linearity, 10 turns (tube set 3 × only)

C Cable feedthrough, 5 × 0,75 mm<sup>2</sup>, top +160 mm, bottom +800 mm

D Cable feedthrough, 1-Hall encoder, 8 pulses, cable with jack plug

E Cable feedthrough, potentiometer (tube set 3 × only)

F 2-Hall encoder, cable with DIN8 plug

G Cable feedthrough, 2-Hall encoder, cable with DIN8 plug

■ Options shown in red are only available on request. Contact Ewellix for more information on minimum quantities and additional cost.



# TLC

## Telemag lifting column



### Benefits

- Push or pull load
- High bending load
- Quiet
- Powerful
- Plug and play

### Standards

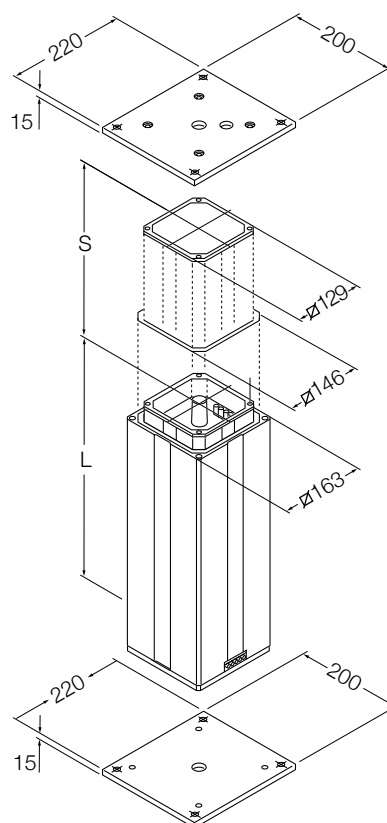
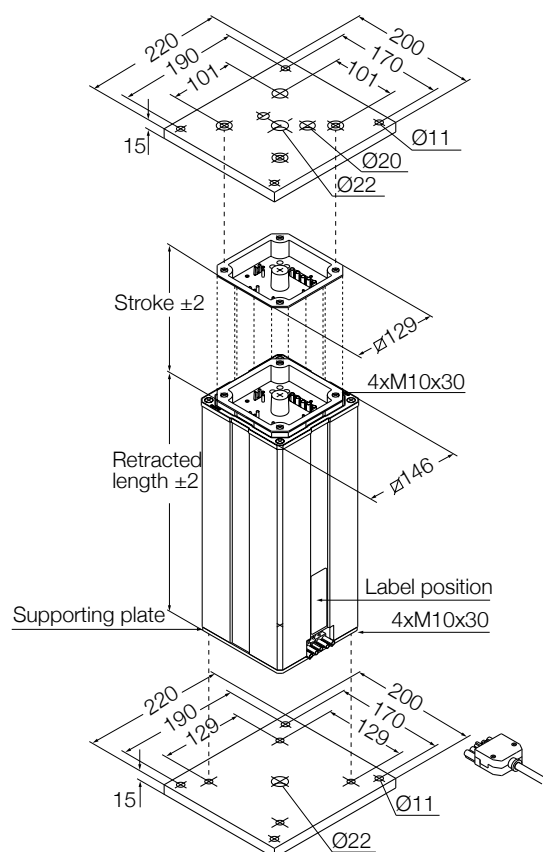
- EN/IEC 60601-1
- UL 60601-1

### Technical data

		Unit	TLC 12ZWAS	TLC 12ZWAK	TLC 12ZWDS	TLC 12ZWDK
Rated push load		N	4 000	4 000	4 000	4 000
Rated pull load		N	4 000	4 000	4 000	4 000
Bending load		Nm	up to 630 <sup>1)</sup>	up to 630 <sup>1)</sup>	up to 2 100 <sup>1)</sup>	up to 2 100 <sup>1)</sup>
Speed (full load to no load)	120 V AC	mm/s	16 to 22	16 to 22	16 to 22	16 to 22
	230 V AC	mm/s	11 to 17	11 to 17	11 to 17	11 to 17
Lifting column version		# of section	2-section	2-section	3-section	3-section
Stroke		mm	100 to 700	100 to 700	255 to 700	255 to 700
Retracted length (push version)		mm	S+175	S+175	S+60	S+60
Retracted length (pull version)		mm	S+185	S+185	S+70	S+70
Voltage		V AC	120 or 230	120 or 230	120 or 230	120 or 230
Power	120 V AC	W	1 200	1 200	1 200	1 200
	230 V AC	W	890	890	890	890
Current	120 V AC	A	10	10	10	10
	230 V AC	A	4,1	4,1	4,1	4,1
Duty cycle: intermittent operation	120 V AC	min.	0,8 min./37 min.	0,8 min./37 min.	0,8 min./37 min.	0,8 min./37 min.
	230 V AC	min.	1 min./37 min.	1 min./37 min.	1 min./37 min.	1 min./37 min.
Duty cycle: short-time operation	120 V AC	min.	1,2	1,2	1,2	1,2
	230 V AC	min.	2	2	2	2
Ambient temperature		°C	+10 to +40	+10 to +40	+10 to +40	+10 to +40
Degree of protection		IP	20/30	20/30	20/30	20/30
Protection class		–	I	I	I	I
Type of control		–	electrical	pneumatic	electrical	pneumatic
Weight		kg	15,2-24,5	15,2-24,5	18,3-30,5	18,3-30,5

<sup>1)</sup> For details, please see bending load diagrams (→ page 226)

## Dimensional drawing

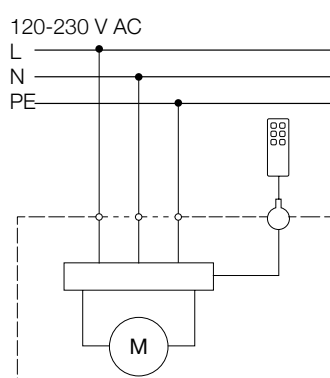
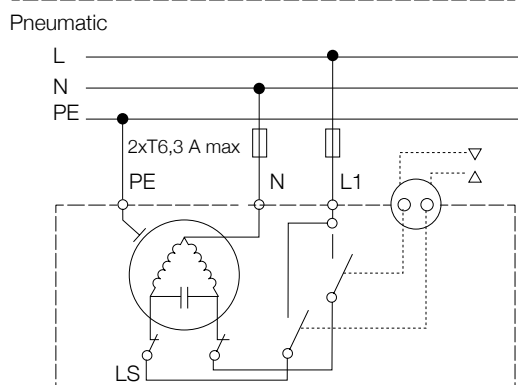
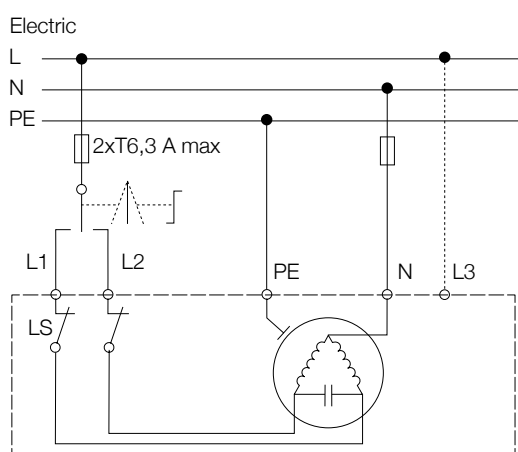


**Note:** mounting plates are not included.  
To be ordered separately.

**Legend:**

S = stroke  
L = retracted length

## Connecting diagrams



## Suitable control units and accessories

	PHC	PFP	PAM
TLC pneumatic*	●	●	●

\* Integrated control unit

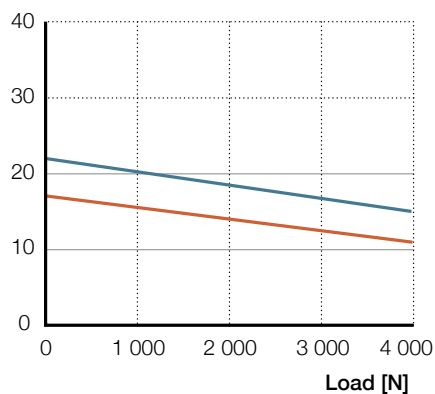
 Hand switch

 Foot switch Desk switch

## Performance diagram

Speed-load diagram

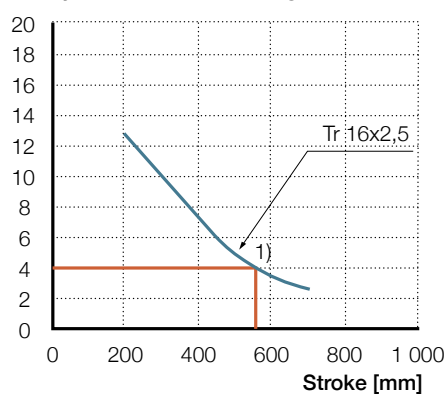
Speed [mm/s]



— 120 V AC version — 230 V AC version

## Safety factor load conditions

Safety factor [screw buckling]

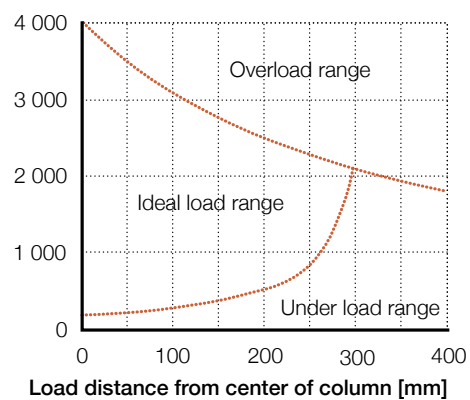


<sup>1)</sup> Safety factor = 4

## Bending load diagrams

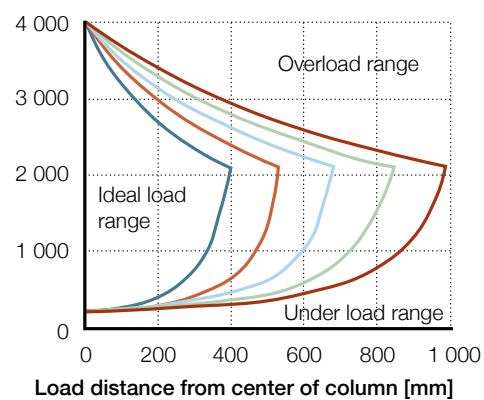
Bending load diagram 2-section

Load [N]



Bending load diagram 3-section

Load [N]



— 300 — 400 — 500 — 600 — 700

## Accessories

	Designation	Order number
Top mounting plate for 2× tube set	ZPL-290268	0125624
Bottom mounting plate for 2× tube set	ZPL-290351	0125625
Top mounting plate for 3× tube set	ZPL-290268	0125624
Bottom mounting plate for 3× tube set	ZPL-290265	0125623
Screw (4/plate) for mounting plate	ZBE-510707	0125360
Plug AC Telemag 3 pin	ZEL-265518	0124866
Plug AC Telemag 5 pin	ZEL-265519	0124864

## Ordering key

T	L	C	1	2	W					-	0	
---	---	---	---	---	---	--	--	--	--	---	---	--

### Type

### Load

Z 4 000 N

### Tube set

A Tube set 2×  
D Tube set 3×

### Control

S Electrical control  
K Pneumatic control  
**N Low-voltage control**

### Voltage

- 230 V AC/50 Hz (no code)  
2U 120 V AC/60 Hz

### Construction

0 Push load  
**1 Customer-specific**  
3 Pull load

### Stroke [S]

1 100 mm, only for tube set 2×, push  
1 255 mm, only for tube set 3×, push  
2 200 mm, only for tube set 2×  
3 300 mm  
4 400 mm  
5 500 mm  
6 600 mm  
7 700 mm

# TLG

## Telemag lifting column

### Benefits

- High bending load
- Powerful

### Standards

- EN/IEC 60601-1
- UL 60601-1

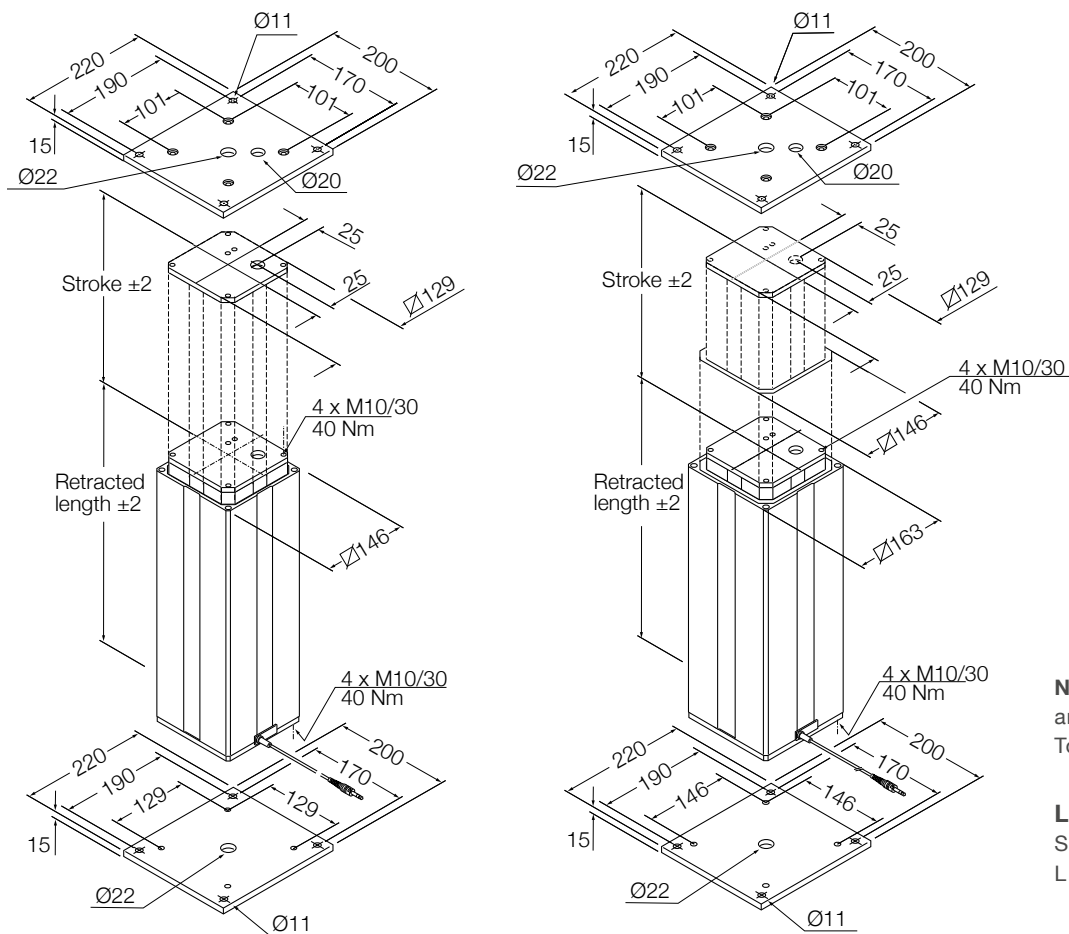


### Technical data

	Unit	TLG 10/11-A	TLG 10-B	TLG 10/11-C
Rated push load	N	4 000	2 500	1 500
Rated pull load	N	0	0	0
Bending load	Nm	up to 2 800 <sup>1)</sup>	up to 1 750 <sup>1)</sup>	up to 950 <sup>1)</sup>
Speed (full load to no load)	mm/s	10 to 14	13 to 17	25 to 33
Lifting column version	# of section	2 or 3-section	2 or 3-section	2 or 3-section
Stroke	mm	200 to 700	200 to 700	200 to 700
Retracted length	mm	S+180	S+180	S+180
Voltage	V DC	24	24	24
Power	W	156	156	156
Current	A	6	6	6
Duty cycle: intermittent operation	min.	1 min./9 min	1 min./9 min	1 min./9 min
Ambient temperature	°C	+10 to +40	+10 to +40	+10 to +40
Degree of protection	IP	30	30	30
Protection class	–	SELV	SELV	SELV
Type of control	–	electrical	electrical	electrical
Weight	kg	15 to 30	15 to 30	15 to 30

<sup>1)</sup> For details, please see bending load diagrams (→ page 230)

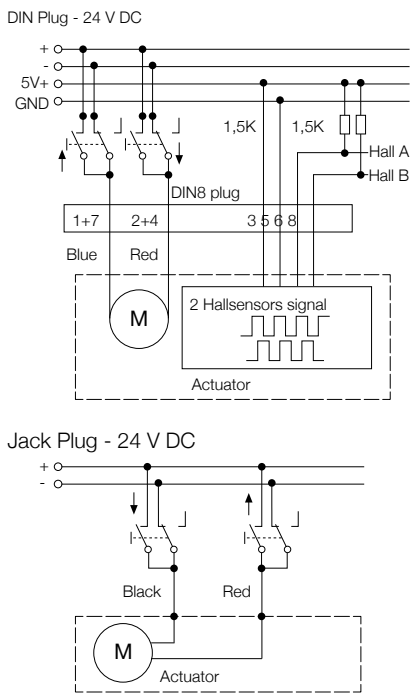
Dimensional drawing



**Note:** mounting plates are not included. To be ordered separately.

**Legend:**  
S = stroke  
L = retracted length

Connecting diagrams



Suitable control units and accessories

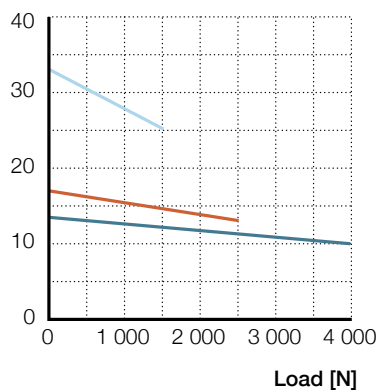
Control units				
	SCU	VCU	BCU	MCU
TLG	•	•	•	•
Operating switches				
EHA 1				•
EHA 3	•	•	•	
STF				•
STJ	•	•	•	
STA				•
STE	•	•	•	
Hand switch     Foot switch     Desk switch				

<sup>1)</sup> Only valid with TLG11. TLG10 must be operated by a BCU, MCU, SCU or VCU control unit.

## Performance diagrams

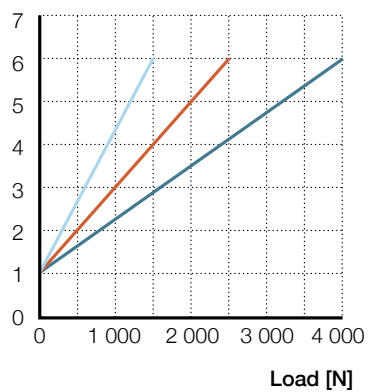
Speed-load diagram

Speed [mm/s]



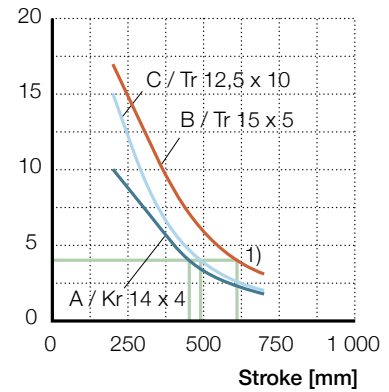
Current-load diagram

Current consumption [A]



## Safety factor load conditions

Safety factor



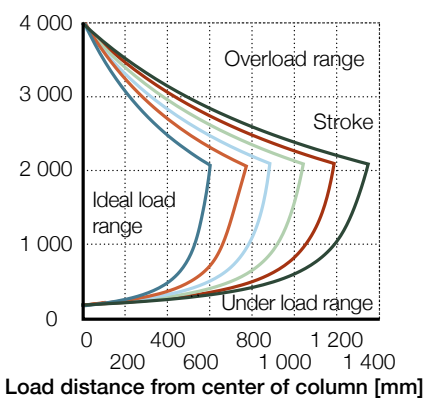
1) Safety factor =4

— A — B — C

## Bending load diagrams

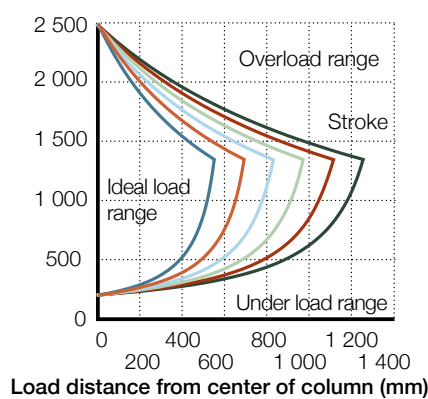
Bending load diagram TLG ...AD

Load [N]



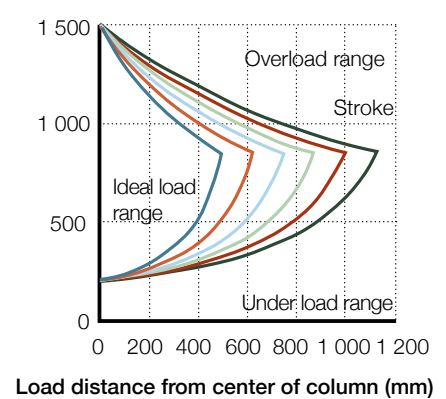
Bending load diagram TLG ...BD

Load [N]



Bending load diagram TLG ...CD

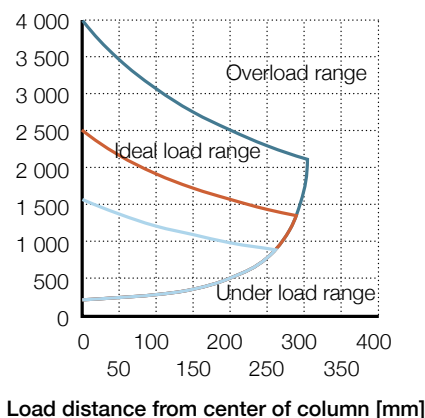
Load [N]



Stroke: — 200 — 300 — 400 — 500 — 600 — 700

Bending load diagram TLG...AA/BA/CA

Load [N]



— TLG1-AA  
— TLG1-BA  
— TLG1-CA

## Accessories

	Designation	Order number
Top mounting plate for 2 × tube set	ZPL-290268	0125624
Bottom mounting plate for 2 × tube set	ZPL-290351	0125625
Top mounting plate for 3 × tube set	ZPL-290268	0125624
Bottom mounting plate for 3 v tube set	ZPL-290265	0125623
Screw (4/plate) for mounting plate	ZBE-510707	0125360

## Ordering key

T L G 1 - - - - - 0 0 0

### Type

### Voltage

0 24 V DC

1 24 V DC with integrated current cut-off (only for 4 000 N and 1 500 N load version)

### Load

A 4 000 N

B 2 500 N

C 1 500 N

### Tube set

A Tube set 2×

D Tube set 3×

### Stroke [S]

2 200 mm

3 300 mm

4 400 mm

5 500 mm

6 600 mm

7 700 mm

### Cable / connecting plug

1 Straight, 1,0 m / jack plug

2 Straight, 2,3 m / jack plug

A Coiled, 0,6 m / jack plug

3 Straight, 1,0 m / DIN8 plug

4 Straight, 2,3 m / DIN8 plug

B Coiled, 0,6 m / DIN8 plug

### Option

0 No option

A 1-Hall encoder, 8 pulses, cable with jack plug

B Potentiometer, 1 kΩ, 2 Watt, 0,25 % linearity, 10 turns

C Cable feedthrough, 5 × 0,75 mm<sup>2</sup>, led out, top +160 mm, bottom +800 mm

D Cable feedthrough, 1-Hall encoder, 8 pulses, cable with jack plug

E Cable feedthrough, potentiometer

F 2-Hall encoder, cable with DIN8 plug

G Cable feedthrough, 2-Hall encoder, cable with DIN8 plug



# TLT

## Telemag lifting column

### Benefits

- Very small built-in dimension
- Powerful

### Standards

- EN/IEC 60601-1
- UL 60601-1

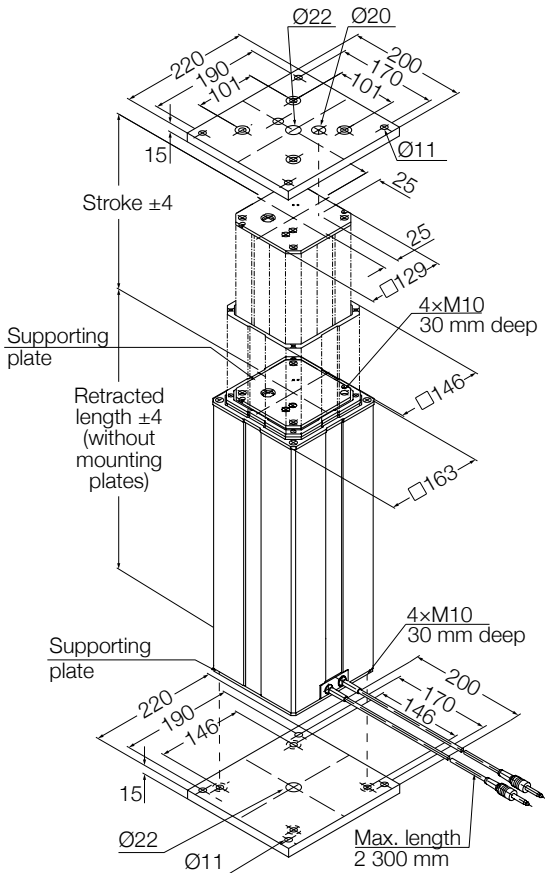


### Technical data

	Unit	TLT10-A1	TLT10-A2	TLT10-B1	TLT10-C1	TLT10-C2
Rated push load	N	3 000	4 000	2 000	1 000	2 000
Rated pull load	N	0	0	0	0	0
Bending load	Nm	up to 400 <sup>1)</sup>	up to 1 000 <sup>1)</sup>	up to 250 <sup>1)</sup>	up to 110 <sup>1)</sup>	up to 480 <sup>1)</sup>
Speed (full load to no load)	mm/s	11 to 16	13 to 19	13 to 19	25 to 36	25 to 42
Lifting column version	# of section	3-section	3-section	3-section	3-section	3-section
Stroke	mm	300 to 700	300 to 700	300 to 700	300 to 700	300 to 700
Retracted length	mm	0,5 × S+170	0,5 × S+240	0,5 × S+170	0,5 × S+170	0,5 × S+240
Voltage	V DC	24	24	24	24	24
Power	W	168	168	192	192	216
Current	A	2×3,5	2×3,5	2×4,5	2×4,5	2×4,5
Duty cycle: intermittent operation	min.	1 min./9 min	1 min./9 min	1 min./9 min	1 min./9 min	1 min./9 min
Ambient temperature	°C	+10 to +40	+10 to +40	+10 to +40	+10 to +40	+10 to +40
Degree of protection	IP	40	40	40	40	40
Protection class	–	SELV	SELV	SELV	SELV	SELV
Type of control	–	electrical	electrical	electrical	electrical	electrical
Weight	kg	15 to 30	15 to 30	15 to 30	15 to 30	15 to 30

<sup>1)</sup> For details, please see bending load diagrams (→ page 234)

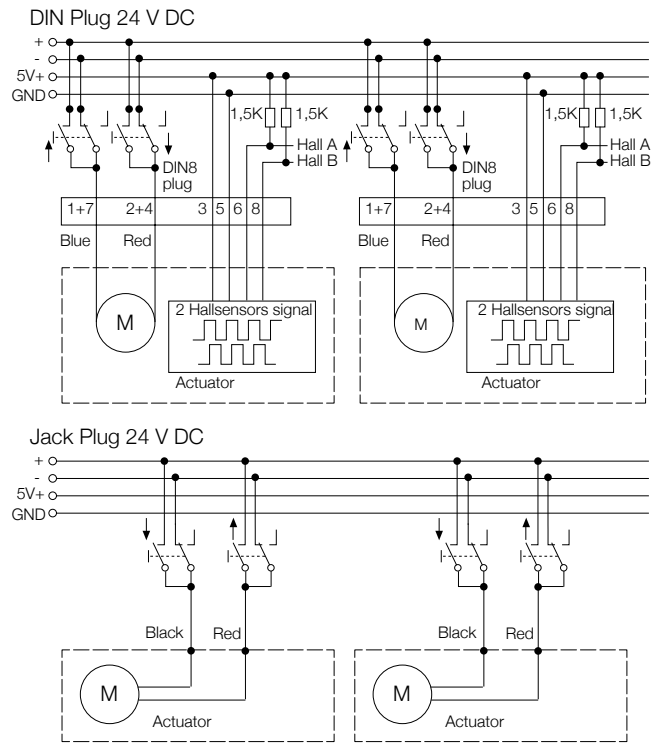
Dimensional drawing



Note: mounting plates are not included.  
To be ordered separately.

**Legend:**  
S = stroke  
L = retracted length

Connecting diagrams



Suitable control units and accessories

	Control units			
	SCU	VCU	BCU	MCU
TLT	•	•	•	•
Operating switches				
EHA 1				•
EHA 3	•	•	•	
STF				•
STJ	•	•	•	
STA				•
STE	•	•	•	

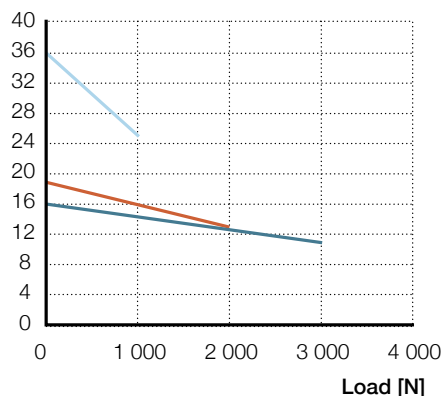
Hand switch      Foot switch      Desk switch

<sup>1)</sup> Only valid with TLG11. TLG10 must be operated by a BCU, MCU, SCU or VCU control unit.

## Performance diagrams

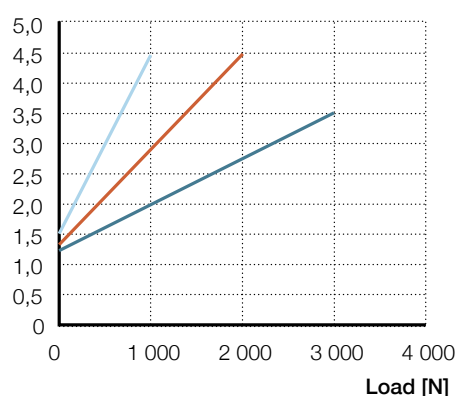
Speed-load diagram

Speed [mm/s]



Current-load diagram

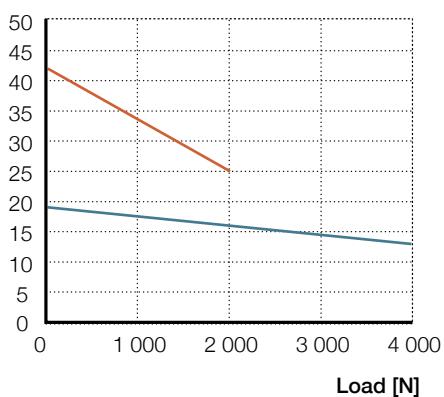
Current consumption [A]



— A1 — B1 — C1

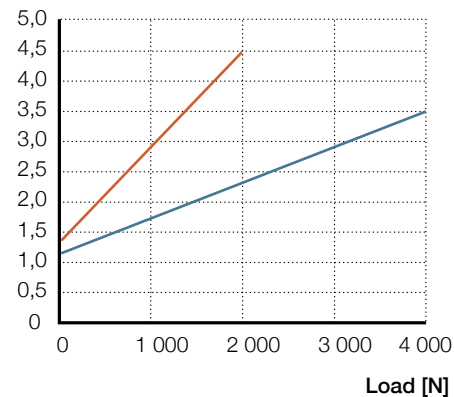
Speed-load diagram

Speed [mm/s]



Current-load diagram

Current consumption [A]

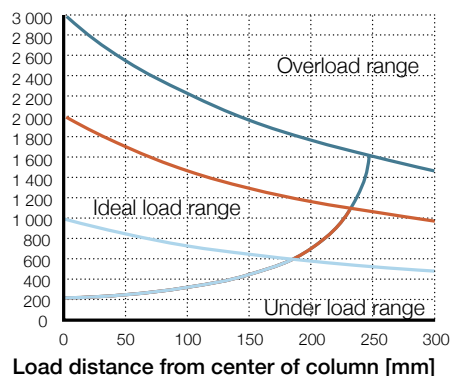


— A2 — C2

## Bending load diagrams

Bending load diagram A1, B1, C1

Load [N]

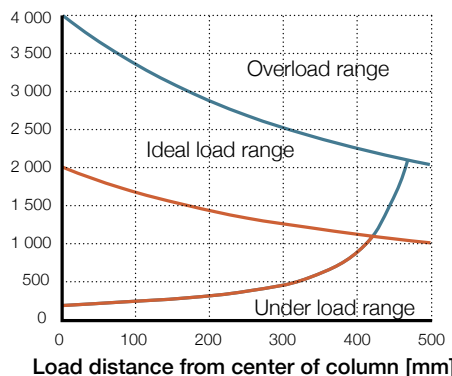


Load distance from center of column [mm]

— TLT1 A-1 — TLT1 B-1 — TLT1 C-1

Bending load diagram A2, C2

Load [N]



Load distance from center of column [mm]

— TLT1 A-2 — TLT1 C-2

Accessories

	Designation	Order number
Top mounting plate	ZPL-290268	0125624
Bottom mounting plate	ZPL-290265	0125623
Screw (4/plate) for mounting plate	ZBE-510707	0125360

Ordering key

T

L

T

1

-

-

0

0

0

Type

Voltage

024 V DC

124 V DC with integrated current cut-off (only for A2 and C2)

Load / Speed

A24 000 N

A13 000 N

B12 000 N / 19 to 13 mm/s

C22 000 N / 42 to 25 mm/s

C11 000 N

Stroke [S]

3300 mm

4400 mm

5500 mm

6600 mm <sup>1)</sup>

7700 mm <sup>1)</sup>

Cable / connecting plug

1Straight, 1,0 m / jack plug

2Straight, 2,3 m / jack plug

A Coiled, 0,6 m / jack plug

3Straight, 1,0 m / DIN8 plug

4Straight, 2,3 m / DIN8 plug

B Coiled, 0,6 m / DIN8 plug

Option

0No option

A1-Hall encoder, 8 pulses, cable with jack plug

C Cable feedthrough, 3x1,5 mm<sup>2</sup>, top +160 mm, bottom +800 mm

D Cable feedthrough, 1-Hall encoder, 8 pulses, cable with jack plug

F2-Hall encoder, cable with DIN8 plug

<sup>1)</sup> Reduced safety factor  
■ Options shown in red are only available on demand. Contact Ewellix for more information on minimum quantities and additional cost.

# TXG

## Telesmart lifting column



### Benefits

- Powerful and fast lifting
- Aesthetic design

### Standards

- EN/IEC 60601-1
- UL 60601-1

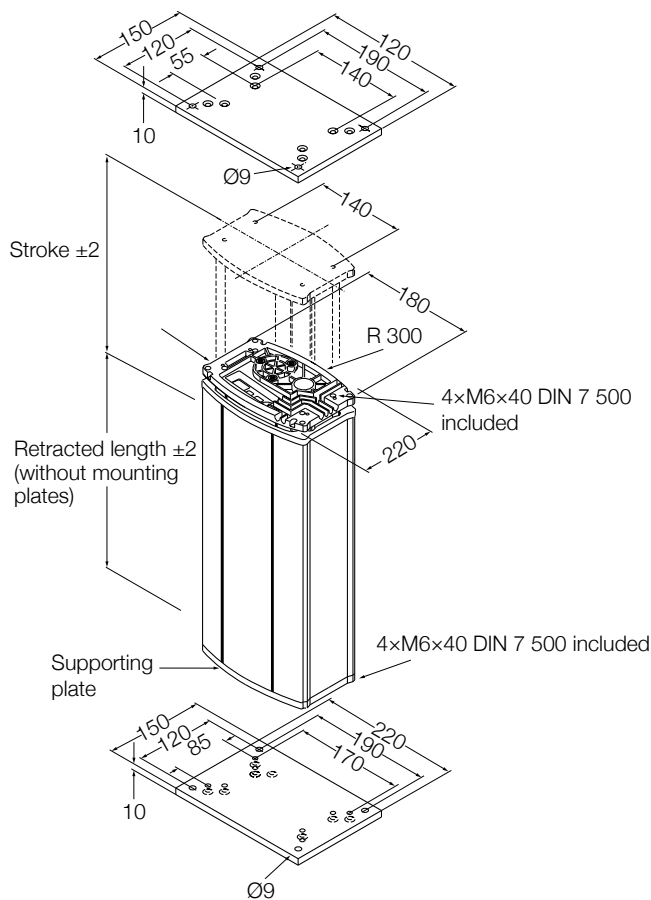
### Technical data

	Unit	TXG1	TXG4/5	TXG8/9
Rated push load	N	1 500	1 500	1 500
Rated pull load	N	0	0	0
Bending load	Nm	up to 210 <sup>1)</sup>	up to 210 <sup>1)</sup>	up to 210 <sup>1)</sup>
Speed (full load to no load)	mm/s	17 to 23	17 to 23	17 to 23
Lifting column version	# of section	2-section	2-section	2-section
Stroke	mm	200 to 600	200 to 600	200 to 600
Retracted length	mm	S+180	S+180	S+180
Voltage	–	24 V DC	120 V AC	230 V AC
Power	W	–	N/A	N/A
Current	A	5	1,8	0,9
Duty cycle: intermittent operation	min.	1 min./9 min.	1 min./9 min.	1 min./9 min.
Duty cycle: short-time operation	min.	–	N/A	N/A
Ambient temperature	°C	+10 to +40	+10 to +40	+10 to +40
Degree of protection	IP	30	30	30
Protection class	–	SELV	II/(I)2	II/(I)2
Type of control	–	electrical	electrical	electrical
Weight	kg	8 to 13	9 to 14	9 to 14

<sup>1)</sup> For details, please see bending load diagrams (→ page 238)

<sup>2)</sup> Mandatory for cable feedthrough option

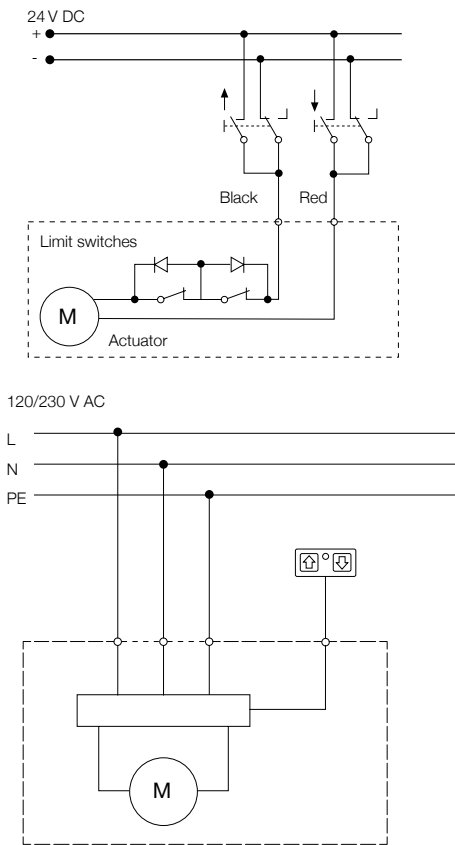
Dimensional drawing



Note: mounting plates are not included.  
To be ordered separately.

**Legend:**  
S = stroke  
L = retracted length

Connecting diagrams



Suitable control units and accessories

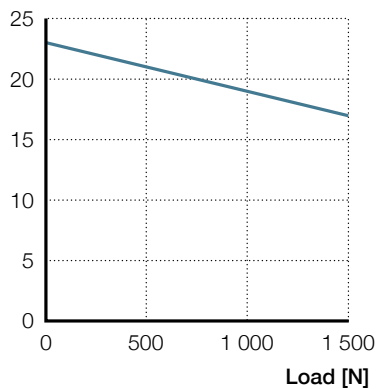
Control units		
TXG 10	COMPACT	
Operating switches		
EHA		
HSM		
HSF		

Hand switch Foot switch Desk switch

## Performance diagram

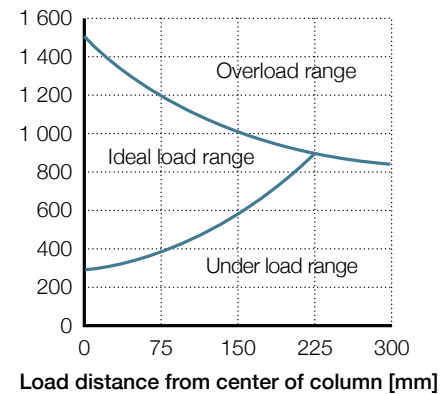
### Speed-load diagram

Speed [mm/s]



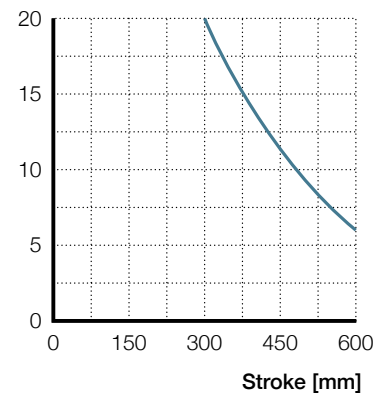
## Bending load diagram

Load [N]



## Safety factor load conditions

Safety factor (screw buckling)



## Accessories

Mains cable	Plug	Country	Order number	Comment
Straight cable 3 m	Euro	General	0121730	2-pole
Straight cable 3 m	Schuko	General	0121729	3-pole
Straight cable 3 m	UL	USA	0126322	2-pole
Straight cable 3 m	SEV	Switzerland	0128699	3-pole
Straight cable 3 m	UL	USA	0121762	3-pole
Top or bottom mounting plate			0124874	

Mounting screws are included in the TXG.

Ordering key

T

X

G

0

-

0

0

-

0

0

Type

Voltage

1

24 V DC (slave actuator)

4

120 V AC, 50/60 Hz, class II

5

120 V AC, 50/60 Hz, class I (mandatory for cable feedthrough option)

8

230 V AC, 50 Hz, class II

9

230 V AC, 50 Hz, class I (mandatory for cable feedthrough option)

Color

5

Natural anodized coating

Option

000

None

EYX

Control connection feedthrough

EYF

Mains cable feedthrough

EYS

1-Hall encoder for Compact/slave use

2AA

Control connection feedthrough, mains cable feedthrough

EXG

Connection of TXG to BCU/VCU

KKK

Customer-specific

Stroke (S) / Retr. length (L=S+180 or L= S+160 mm)

L=S+180

L=S+160

200

4CY

200 mm

300

4DY

300 mm

400

4EY

400 mm

500

4FY

500 mm

600

4GY

600 mm

Options shown in red are only available on demand. Contact Ewellix for more information on minimum quantities and additional cost.



# FRE

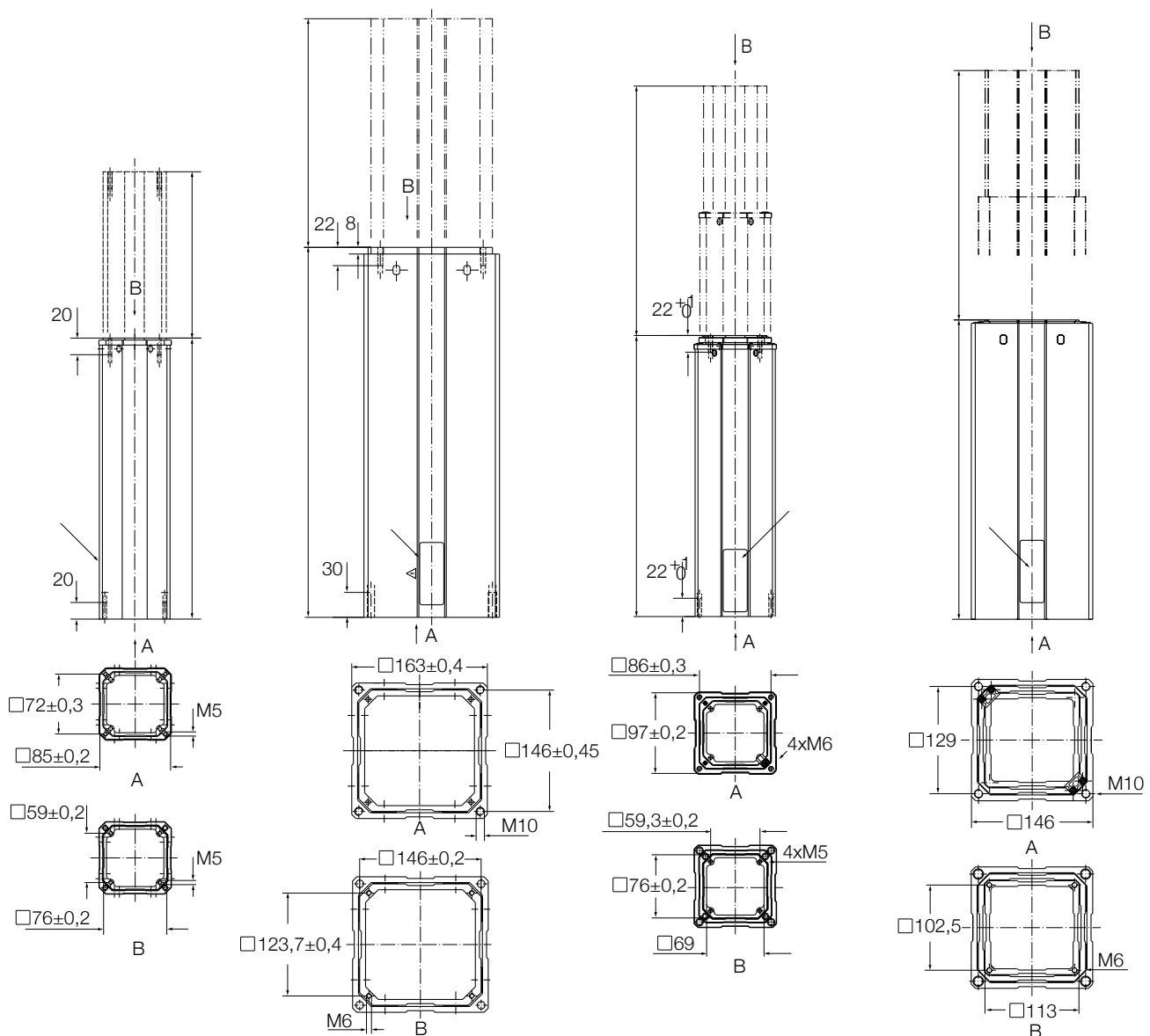
## Lifting column

### Benefits

- Attractive design
- Stable
- Universal use



### Dimensional drawing



Type	Sections		Profile dimensions in mm							Retracted length in mm
	2 sections	3 sections	76 x 76	85 x 85	97 x 97	113 x 113	129 x 129	146 x 146	163 x 163	
FRE-A085	•									Stroke + 138
FRE-A113	•									Stroke + 148
FRE-A146	•									Stroke + 168
FRE-D097		•								Stroke + 38
FRE-D129		•								Stroke + 53
FRE-D163		•								Stroke + 53
FRE-B097	•									N/A
FRE-B129	•									N/A
FRE-B163	•									N/A
FRE-E113		•								N/A
FRE-E146		•								N/A

■ Options shown in red are only available on demand. Please contact Ewellix.

### Ordering key

F

R

E

-

-

-

0

0

0

Type

Combination

2 sections tube-set /Largest tube size

A085 85×85 mm

A113 113×113 mm

A146 146×146 mm

B097 97×97 mm

B129 129×129 mm

B163 163×163 mm

3 sections tube-set /Largest tube size

D097 97×97 mm

D129 129×129 mm

D163 163×163 mm

E113 113×113 mm

E146 146×146 mm

V\_ 4 sections tube-set (on request)

F\_ 5 sections tube-set (on request)

S\_ 6 sections tube-set (on request)

Z\_ 7 sections tube-set (on request)

Color

5 Natural anodized

6 Black anodized

Option

000 No option

MCM Cover

MCN Pull version

2EA Pull version, with cover

Stroke

20 200 mm

30 300 mm

40 400 mm

50 500 mm

60 600 mm

70 700 mm

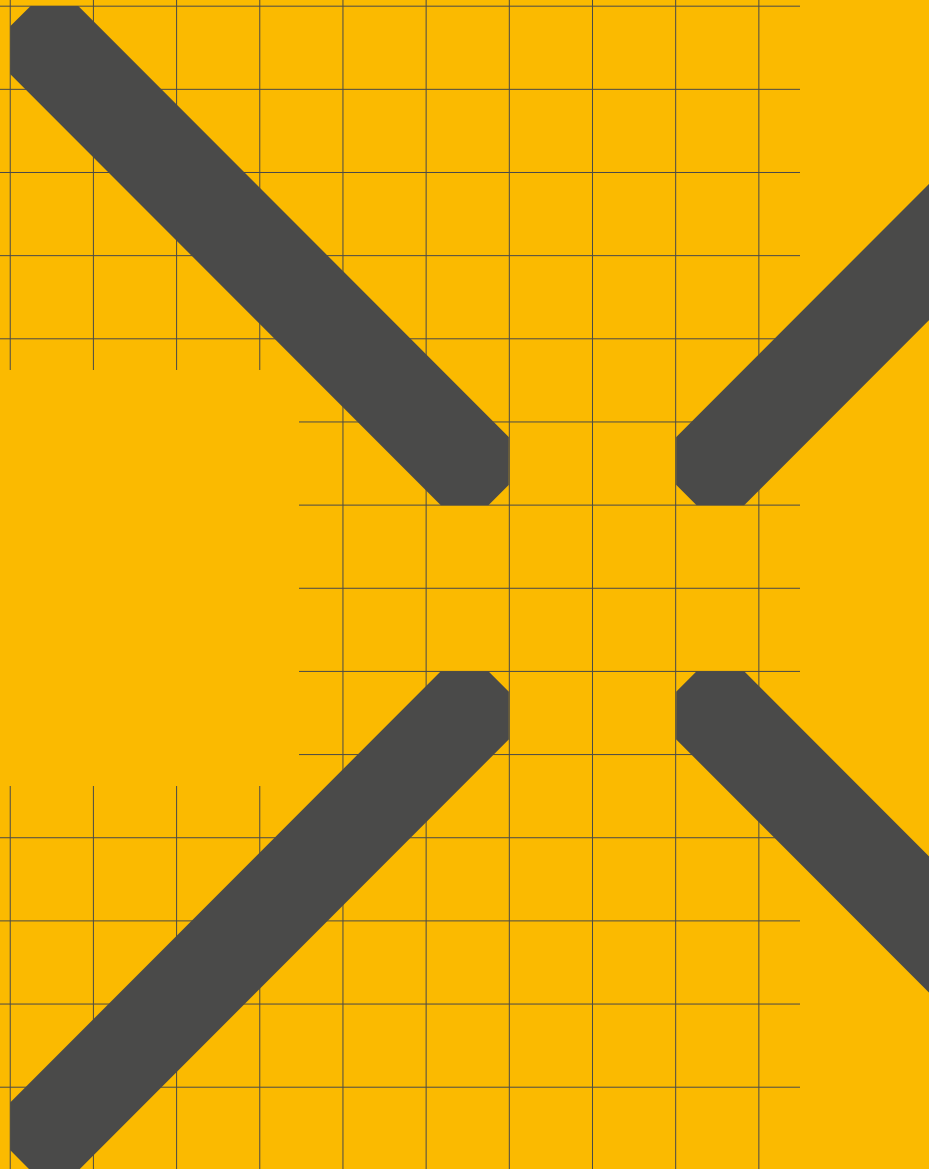
--- Other stroke lengths

■ Options shown in red are only available on demand. Contact Ewellix for more information on minimum quantities and additional cost.

5

## Control units

Up to 6 channels



# Chapter contents

BCU.....244

VCU .....248

SCU.....252

MCU .....256

COMPACT.....260

SEM.....264

# BCU

## Control unit



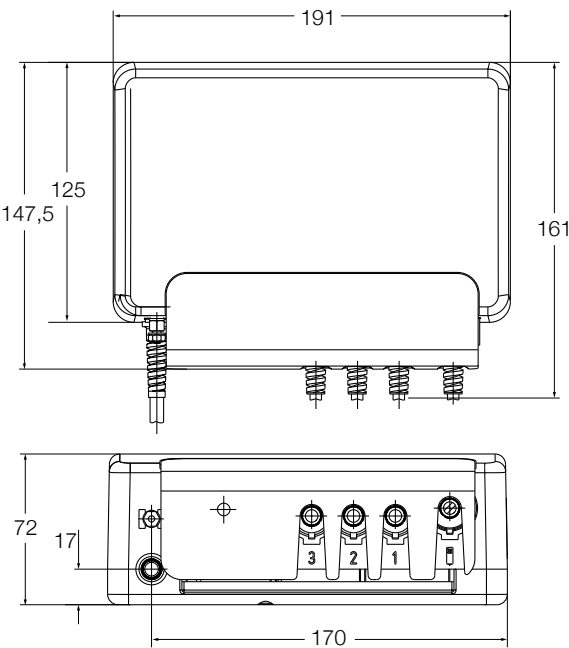
### Benefits

- Compact 3-channel actuator control unit
- Single fault safety
- Overload and over-temperature protection
- Approved for medical applications
- Easy to clean
- Low standby current

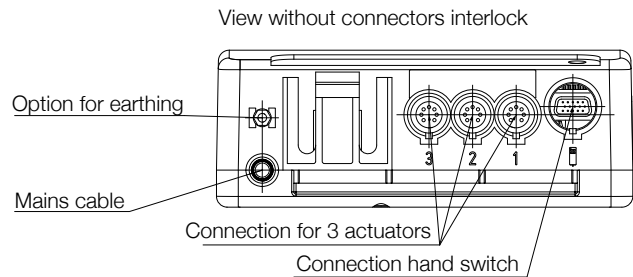
### Technical data

	Unit	BCU 5	BCU 8
Motor ports (DIN8)	#	3	3
Operating device ports (HD15)	#	1	1
Battery ports	#	0	0
Limit switch ports	#	0	0
Single fault safety	yes/no	yes	yes
Encoder processing	yes/no	no	no
Input voltage	V AC	120	230
Frequency	Hz	60	50
Input current (max)	A	2,5	1,3
Standby power	W	1,2	1,5
Output voltage	V DC	24	24
Output current (max)	A	7	7
Duty cycle: intermittent	min.	1 min./9 min.	1 min./9 min.
Duty cycle: short time	min.	2	2
Ambient temperature	°C	0 to +40	0 to +40
Humidity	%	5 to 85	5 to 85
Degree of protection	IP	×4	×4
Approvals		IEC 60601-1(ed.3)	IEC 60601-1(ed.3)
Weight	kg	2,3	2,3































Dimensional drawing



Connecting diagrams



Suitable control units and accessories

		Columns								Operating switches			
		RU20, RU21, RU22	MAX 10, MAX 30	ECOMAG	THG 10	TLG 10	TLT 10	TFG 10	CPMT1	TXG 10	 EHA3	 STJ	 STE
BCU 5													
BCU 8													
									 Hand switch			 Foot switch	 Desk switch

Ordering key

BCU control unit

Voltage

Mains power supply cable

B

C

U

3

-

3

1

0

0

-

0

0

0

0

5

120 V AC, 60 Hz, class I

8

230 V AC, 50 Hz, class II

2J

Class II, straight 3,5 m, 2-pole plug, EU (for voltage type 8)

2H

Class II, straight 3,5 m, 2-pole plug, UK (for voltage type 8)

2L

Class I, straight 3,5 m, 3-pole plug, UL (for voltage type 5)

Each BCU needs a BCP

BCU parameterization

Functionality

Motors

Soft start/stop

B

C

P

-

0

0

0

-

0

0

0

11

All channels individually

21

Channel 2+1

30

All channels simultaneously

T1

Trendelenburg

A

ECO2, ECO3, ECO4, ECO5

3,7 A

Actuator 1

-

C

TLT10 <sup>1)</sup>, TXG10 (EXG)

4,7 A

Actuator 2

-

E

TFG, ECO6, ECO8, ECO9

5,7 A

Actuator 3

-

M

MAX10, MAX30, THG10, TLG10

6,7 A

R

RU20, RU21, RU22

8,5 A

S

CPMT1-1 <sup>2)</sup>

8,5 A

T

CPMT1-2 <sup>2)</sup>

8,5 A

0

Hard

3

Medium

6

Soft (on request)

<sup>1)</sup> TLT is a 2-motor actuator. If simultaneous run is needed, BCP21-CC... is recommended.  
<sup>2)</sup> Reduced lift capability : CPMT1-1 up to 3 000 N, CPMT1-2 up to 4 000 N





# VCU

## Control unit

### Benefits

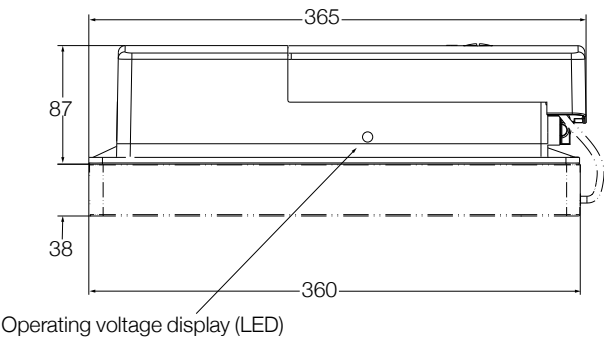
- Compact 5-channel actuator control unit
- Single fault safety
- Overload and over-temperature protection
- Approved for medical applications
- Easy to clean
- Low standby current






### Technical data

	Unit	VCU 5	VCU 8	VCU 9
Motor ports (DIN8)	#	3 or 5	3 or 5	3 or 5
Operating device ports (HD15)	#	2	2	2
Battery ports (DSub9)	#	1	1	1
Limit switch ports (HD15)	#	2	2	2
Single fault safety	yes/no	yes	yes	yes
Encoder processing	yes/no	no	no	no
Input voltage	V AC	120	230	230
Frequency	Hz	60	50	50
Input current (max)	A	2,5 resp. 6,5	1,3 resp. 3,3	1,3 resp. 3,3
Standby power	W	2,6 resp. 3,9	2,6 resp. 3,9	2,6 resp. 3,9
Output voltage	V DC	24	24	24
Output current (max)	A	7 resp. 18	7 resp. 18	7 resp. 18
Duty cycle: intermittent	min.	1 min./9 min.	1 min./9 min.	1 min./9 min.
Duty cycle: short time	min.	2	2	2
Ambient temperature	°C	+5 to +40	+5 to +40	+5 to +40
Humidity	%	5 to 85	5 to 85	5 to 85
Degree of protection	IP	×4	×4	×4
Approvals	EN/UL	EN 60601-1 UL 60601-1	EN 60601-1 UL 60601-1	EN 60601-1 UL 60601-1
Weight without battery	kg	2,4 resp. 3,8	2,4 resp. 3,8	2,4 resp. 3,8
Weight with battery	kg	5,4 resp. 8,8	5,4 resp. 8,8	5,4 resp. 8,8

Dimensional drawing

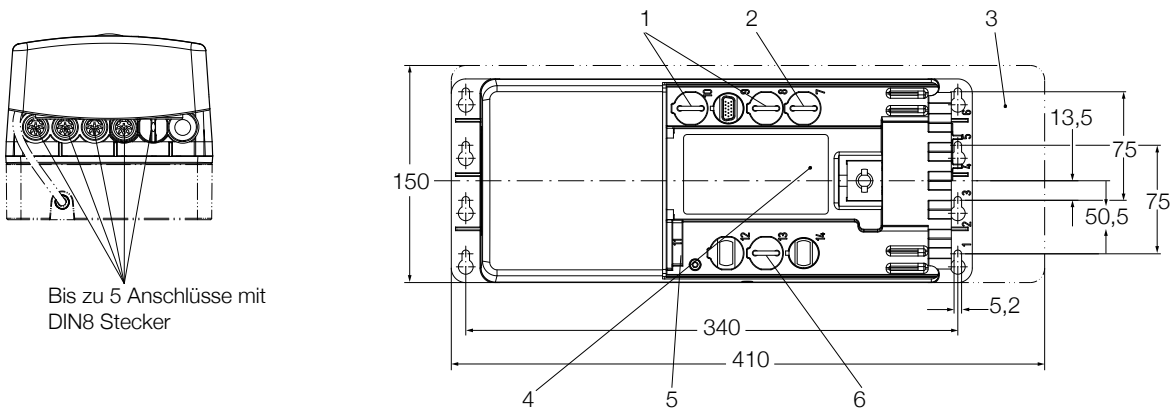


Suitable control units and accessories

	Columns										Operating switches		
	RU20, RU21, RU22	RU23, RU24, RU25	MAX 10, MAX 30	ECOMAG	THG 10	TLG 10	TLT 10	TFG 10	TXG 10	CPMT1	 EHA3	 STJ	 STE
VCU 5	•	•	•	•	•	•	•	•	•	•	•	•	•
VCU 8	•	•	•	•	•	•	•	•	•	•	•	•	•
VCU 9	•	•	•	•	•	•	•	•	•	•	•	•	•

 Hand switch    Foot switch    Desk switch

Connecting diagrams



- 1. Two connections for HD15 operating devices
- 2. HD15 limit switch connection
- 3. Additional space for mounting
- 4. Data plate software
- 5. Mains connection
- 6. D-Sub 9 battery connection (optional)

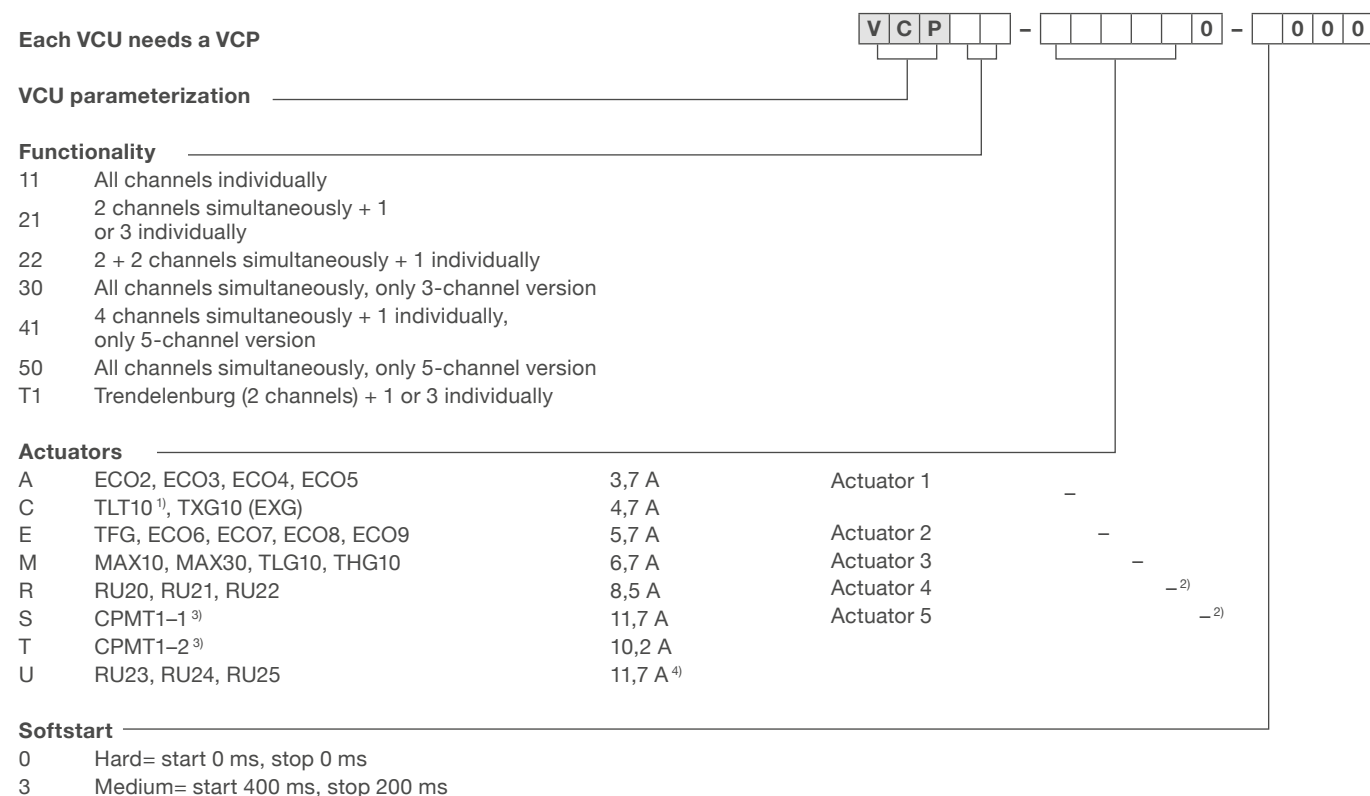
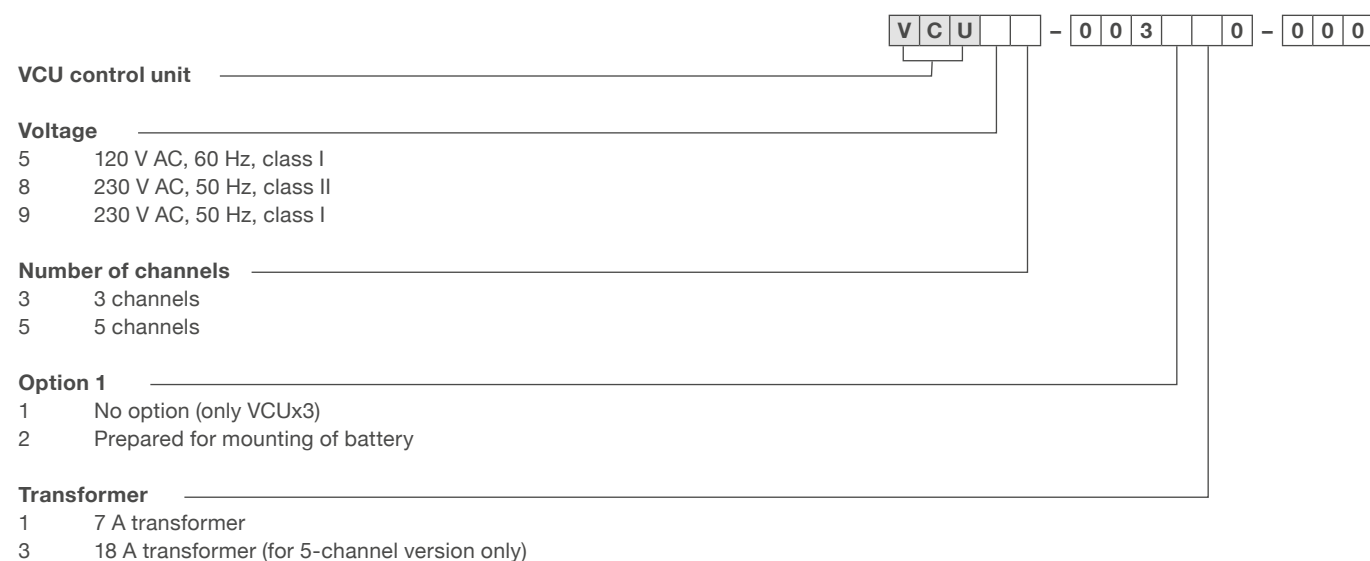
Pinning of HD15 limit switch connection

Function	Pin	Wire color (ZKA-160627-2500)	Connecting diagram
24 V DC (common)	1,3,5,7,9	white/yellow, white/green, grey–pink, black, blue	
Switch 1	2	brown–green	
Switch 2	4	red–blue	
NC	6,8,10,11,12,14	violet, red, pink, grey, yellow, brown	
20–40 V DC, max. 50 mA	13	green	
GND	15	white	

Accessories

	Plug	Designation	Order number
Mains cable, 2 pole	Euro	ZKA-160608-3500	0105726
Mains cable, 3 pole	Schuko	ZKA-160637-3500	0118821
Mains cable, 3 pole	SEV	ZKA-160638-3500	0118822
Mains cable, 3 pole	UL	ZKA-160639-3500	0105588
Mains cable, 3 pole	UK	ZKA-160609-3500	0105631
Mains cable, 3 pole	UL, hospital grade	ZKA-160640-3500	0118823
Mains cable, 3 pole	Australian, China	ZKA-160661-3500	0129953
Battery pack 2,7 Ah		ZBA-160208-0400	0118806
Rack for 4,5 Ah battery		ZBA-160207-1000	0121266
Detachable battery 4,5 Ah		ZBA-160209	0119846

### Ordering key



The SCU solution offers many more possibilities than those given in the type keys. Please feel free to ask for more functions like “virtual limit switches”, “external limit switches” and so on.

<sup>1)</sup> TLT is a 2-motor actuator. If simultaneous run is needed, VCP21-CC... is recommended

<sup>2)</sup> for VCUx3: insert zero

<sup>3)</sup> Reduced lift capability: CPMT-1 up to 3 000 N, CPMT1-2 up to 4 000 N when using transformer with 7A

<sup>4)</sup> Reduced lift capability: only 8.5A when using transformer with 7A

# SCU

## Control unit

### Benefits

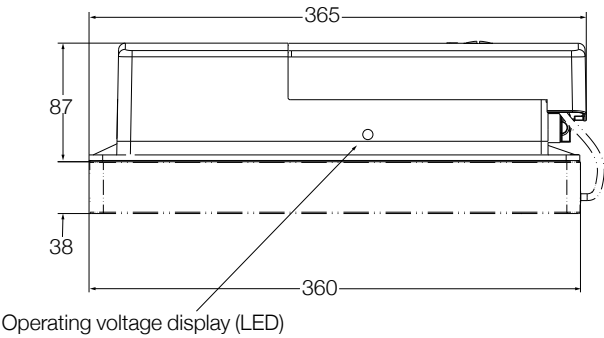
- Compact 6-channel actuator control unit
- Single fault safety
- Overload and over-temperature protection
- Approved for medical applications
- Easy to clean
- Low standby current
- Remote control RS232






### Technical data


	Unit	SCU 1	SCU 5	SCU 9
Motor ports (DIN8)	#	6	3 or 6	3 or 6
Operating device ports (HD15)	#	3	3	3
Battery ports (DSub9)	#	1	1	1
Limit switch ports (HD15)	#	4	4	4
Single fault safety	yes/no	yes	yes	yes
Encoder processing	yes/no	yes	yes	yes
Input voltage	V	24 DC	120 AC	230 AC
Frequency	Hz	N/A	60	50
Input current (max)	A	30	6,5	3,3
Standby power	W	0,8	4,3	4,3
Output voltage	V DC	24	24	24
Output current (max)	A	30	18	18
Duty cycle: intermittent	min.	1 min./9 min.	1 min./9 min.	1 min./9 min.
Duty cycle: short time	min.	2	2	2
Ambient temperature	°C	+5 to +40	+5 to +40	+5 to +40
Humidity	%	5 to 85	5 to 85	5 to 85
Degree of protection	IP	×4	×4	×4
Approvals	EN/UL	EN 60601-1 UL 60601-1	EN 60601-1 UL 60601-1	EN 60601-1 UL 60601-1
Weight without battery	kg	1,2	3,8	3,8
Weight with battery	kg	4,2	6,8	6,8


Dimensional drawing




Suitable control units and accessories

	Columns									Operating switches			
	RU20, RU21, RU22	RU23, RU24, RU25	MAX 10, MAX 30	ECO4F, ECO5F, ECO8F, ECO9F	CAJA35C	THG 10	TLG 10	TLT 10	TFG 10	CPMT1	 EHA3	 STJ	 STE
SCU 1	•	•	•	•	•	•	•	•	•	•	•	•	•
SCU 5	•	•	•	•	•	•	•	•	•	•	•	•	•
SCU 9	•	•	•	•	•	•	•	•	•	•	•	•	•

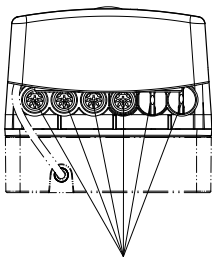
 Hand switch

 Foot switch

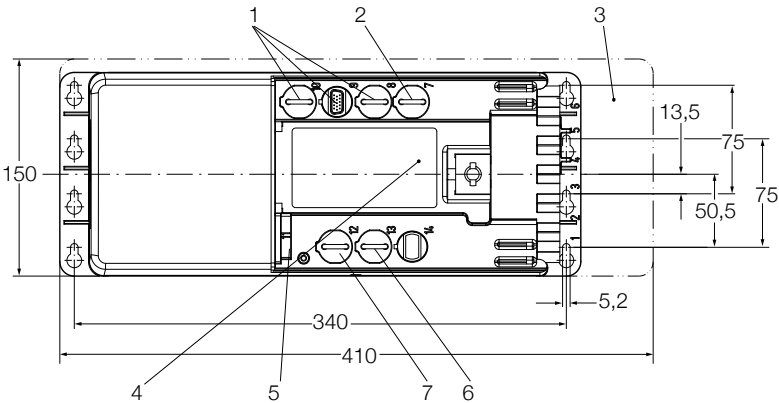
 Desk switch

Hand switch      Foot switch      Desk switch

Connecting diagrams

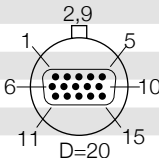
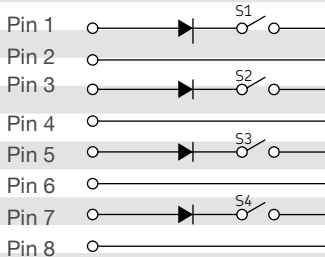


Up to 6 connections with DIN8 plug



- 1. Two connections for HD15 operating devices
- 2. HD15 limit switch connection
- 3. Additional space for mounting
- 4. Data plate software
- 5. Mains connection
- 6. D-Sub 9 battery connection (optional)
- 7. Communication interface (optional)

## Pinning of HD15 limit switch connection on request (needs a customized SCP)

Function	Pin	Wire color (ZKA-160627-2500)	Connecting diagram
Switch 1	2	brown/green	
Switch 2	4	red/blue	
Switch 3	6	violet	
Switch 4	8	red	
24 V DC (com)	1, 3, 5, 7	white/yellow, white/green, grey/pink, black	
Optional external power supply for binary outputs	9	blue	
Binary output 1 (22-40 V DC/1 A)	10	pink	
Binary output 2 (22-40 V DC/1 A)	11	grey	
GND for binary outputs	12	yellow	
20-24 V DC, max. 50 mA	13	green	
5 V DC pulsed	14	brown	
GND	15	white	

## Accessories

	Plug	Designation	Order number
Mains cable, 3 pole	Schuko	ZKA-160637-3500	0118821
Mains cable, 3 pole	SEV	ZKA-160638-3500	0118822
Mains cable, 3 pole	UL	ZKA-160639-3500	0105588
Mains cable, 3 pole	UK	ZKA-160609-3500	0105631
Mains cable, 3 pole	UL, hospital grade	ZKA-160640-3500	0118823
Mains cable, 3 pole	Australian, China	ZKA-160661-3500	0129953
Battery pack 2,7 Ah		ZBA-160208-0400	0118806
Rack for 4,5 Ah battery		ZBA-160207-1000	0126155
Detachable battery 4,5 Ah		ZBA-160209	0126154

Ordering key

SCU

-

003

-

0000

SCU control unit

Voltage

1

24 V DC (only for 6-channel version)

5

120 V AC, 60 Hz, class I

9

230 V AC, 50 Hz, class I

Number of channels

3

3 channels

6

6 channels

Battery

1

None (only for SCU16)

2

Prepared for mounting of battery

3

Under floor 2.7 Ah battery mounted

Transformer

0

None (only for SCU16)

3

Standard (AC version)

Interface

0

Without RS232

1

With RS232 (only for 6-channel version)

SCP

-

-

000

Each SCU needs a SCP

SCU parameterization

Functionality

11

All channels individually

21

Channel 2+1(+1+1+1)

22

Six (6) channel version 2+2+1+1

30

Three (3) channel version, all channels synchronously

31

Six (6) channel version 3+1+1+1

41

Six (6) channel version 4+1+1

60

Six (6) channel version, all channels synchronously

T1

Trendelenburg T+1 (+1+1)

Actuators

A

ECO4F, ECO5F

3,7 A

Actuator 1 –

C

TLT 10<sup>1)</sup>

4,7 A

Actuator 2 –

E

TFG10, ECO8F, ECO9F

5,7 A

Actuator 3 –

M

MAX10, MAX30, TLG10, THG10

6,7 A

Actuator 4 –<sup>2)</sup>

R

RU20, RU21, RU22

8,5 A

Actuator 5 –<sup>2)</sup>

D

MD22, MD23

8,5 A

Actuator 6 –<sup>2)</sup>

U

RU23, RU24, RU25

11,7 A

S

CPMT1-1

11,7 A

T

CPMT1-2

10,2 A

Softstart

0

Hard

3

Medium

6

Soft (on request)

The SCU solution offers many more possibilities than those given in the type keys.  
Please feel free to ask for more functions like “virtual limit switches”, “external limit switches” and so on.

<sup>1)</sup> TLT is a 2-motor actuator. If simultaneous run is needed, VCP21-CC... is recommended  
<sup>2)</sup> For SCUx3: insert zero



# MCU

## Control unit

### Benefits

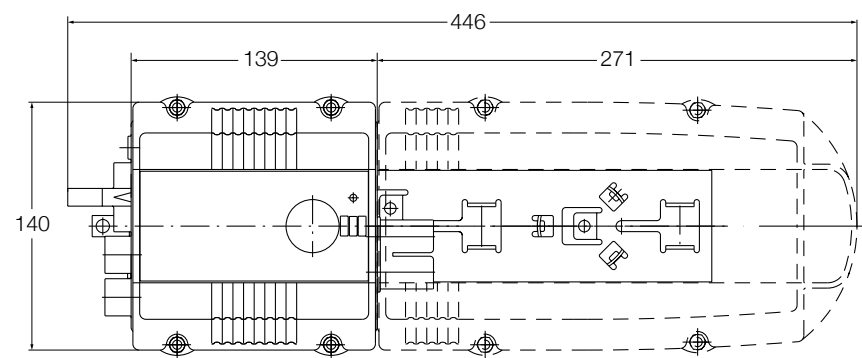
- Suitable for mobile applications
- LED indication for battery charge level
- Audible signal for low charge condition



### Technical data


	Unit	MCU
Motor ports	#	2
Operating device ports	#	1
Battery ports	#	1
Limit switch ports	#	0
Single fault safety	yes/no	no
Encoder processing	yes/no	no
Input voltage	V DC	28
Frequency	Hz	N/A
Input current (max)	A	0,5
Standby power	W	N/A
Output voltage	V DC	24
Output current (max)	A	9,5
Duty cycle: intermittent	min.	1 min./9 min.
Duty cycle: short time	min.	N/A
Ambient temperature	°C	+10 to +40
Humidity	%	85
Degree of protection	IP	TM4
Approvals	EN/UL	EN 60601-1/EN 60601-1-2/ UL 2601/EN ISO 10535
Weight	kg	4,9


Dimensional drawing




Suitable control units and accessories

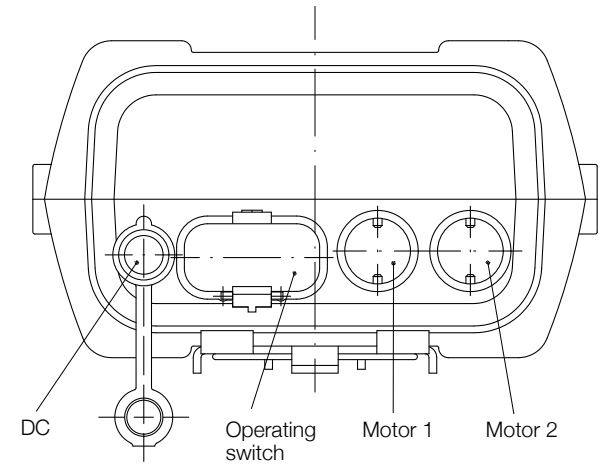
	Linear actuators		Columns		Operating switches			
	MAX1	MAX3	ECOMAG	THG	TLG	EHA 1	STF	STA
MCU	•	•	•	•	•	•	•	•

 Hand switch

 Foot switch

 Desk switch

Connecting diagrams



## Accessories

Description	Plug	Designation	Order number
Battery unit 4,5 Ah		ZBA-142211	0100667
Mains adapter 100-240 V AC	Euro	ZDV-142378-2500	0132841
Mains adapter 100-240 V AC	UL	ZDV-142381-2500	0132843
Mains adapter 100-240 V AC	UK	ZDV-142380-4000	0132842
Wall charging station		ZLA-142221	0126159
Tool for connectors (Jack/D-Sub/Mains)		ZWS-140375	0125322

## Ordering key

M
C
U
1
 
-
0
0
3
 
 
 
 
-
0
0
0
0

Type

Number of channels

- 1 1 channel
- 2 2 channels

Option

- 000 Current cut-off 6 A
- EXP Current cut-off 9 A
- EYE Current cut-off 6 A, electric emergency lowering of channel 1
- 2AT Current cut-off 9 A, electric emergency lowering of channel 1
- EYR Individual current cut-off 6 A (only for 2-channel version)



# COMPACT

## Control unit



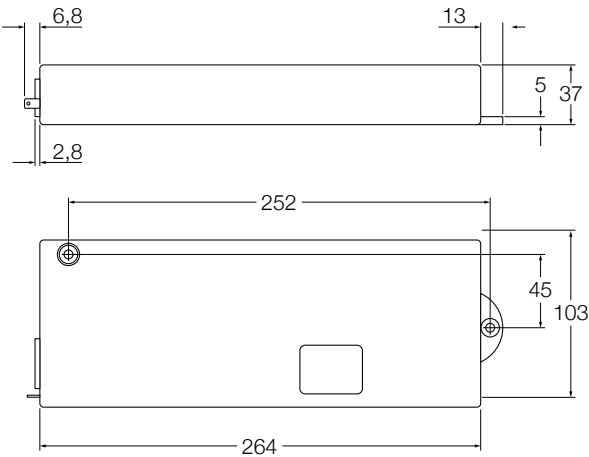
### Benefits

- Synchronized movement of 3 actuators possible
- Up to 4 memory positions (depending on handset)
- Linking possibility of up to 4 control boxes
- Enhanced drive comfort
- Adjustable container – and shelf-stop positions
- Low speed area
- High efficient switch mode power supply (SMPS)
- Low standby power consumption, low field emission

### Technical data

	Unit	COMPACT
Motor ports (DIN8)	#	3
Operating device ports (DIN7)	#	1
Battery ports	#	0
Limit switch ports (LogicConnector DATA)	#	1
Single fault safety	yes/no	no
Encoder processing	yes/no	yes
Supply voltage / Frequency	V AC/Hz	EU: 207 - 254,4 / 50 US: 90 -127 / 50-60
Nominal voltage / Frequency	V AC/Hz	EU: 230 / 50 US: 120 / 60
Input current (max)		
120 V AC	A	10
230 V AC	A	5
Standby power	W	0,5
Output voltage (rated)	V DC	24
Output sum current (rated)	A	15
Output current per channel (max)	A	8
Ambient temperature	°C	0 to +30
Humidity	%	5 to 85
Degree of protection	IP	20
Protection class	–	I
Approvals	EN/UL	EN 60335-1 / UL 60950-1
Weight	kg	0,5

Dimensional drawing



Suitable control units and accessories

Operating switches					
	TFG10	TXG10	TOUCH-UD-MDF-4M2-LD	HSM-OD-2-LD	HSF-MDF-4M4-LD
COMPACT	•	•	•	•	•

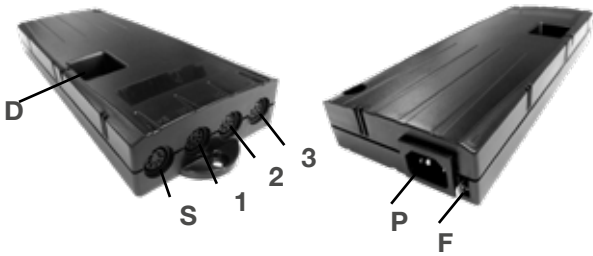
Hand switch

Foot switch

Desk switch

Switching cycles

High-Power cycle:	20 s Up	19 A @20 V, 380 W
	20 s Down	7 A @33 V, 231 W
	Pause:	9 min
Normal cycle 1/9:	30 s Up:	15 A @ 24 V, 360 W
	30 s Down:	7 A @ 33 V, 231 W
	Pause:	9 min
Normal cycle 2/18	2 min run:	7 A @ 33 V, 231 W
	Pause:	18 min



- 1 Motor socket 1 (M1)
- 2 Motor socket 2 (M2)
- 3 Motor socket 3 (M3)
- S Handswitch socket (HS)
- P Mains socket
- F Functional earth
- D LogicConnector DATA for sensors, squeeze lines and cascading

## Desk switches

Description	Designation	Order number
Extra simple desk switch (up/down)	HSM-OD-2-LD	123247
Desk switch with display for 2 motorgroups (up/down and memory)	HSF-MDF-4M4-LD	123246
Desk switch with smart touch display (up/down and memory)	TOUCH-UD-MDF-4M2-LD	131740

## Accessories

Description	Designation	Order number
Mains cable straight 3 m, Schuko plug (Germany, France, ...)	LOG-CBL-PWK	131665
Mains cable straight 3 m, UK plug (UK)	LOG-CBL-PWK-UK	131825
Mains cable straight 3 m, UL plug (US)	LOG-CBL-PWK-US-SJT	131666
Cascading cable 0,5 m length	LOG-CBL-HT-SYNC-500	131678
Cascading cable 1,5 m length	LOG-CBL-HT-SYNC-1500	132061

## Ordering key

**C O M P A C T** - **E** - **3** - **D I N** -  -  -

Type

Number of used motors (optional, depending on parameter)

3 motors (no additional designation required)

2 2 motors

1 1 motor

Actuator type

TFG TFG10

TXG TXG10

Voltage

US 120 VAC, 60 Hz, class I

EU 230 VAC, 50 Hz, class I





# SEM

Control unit

Benefits

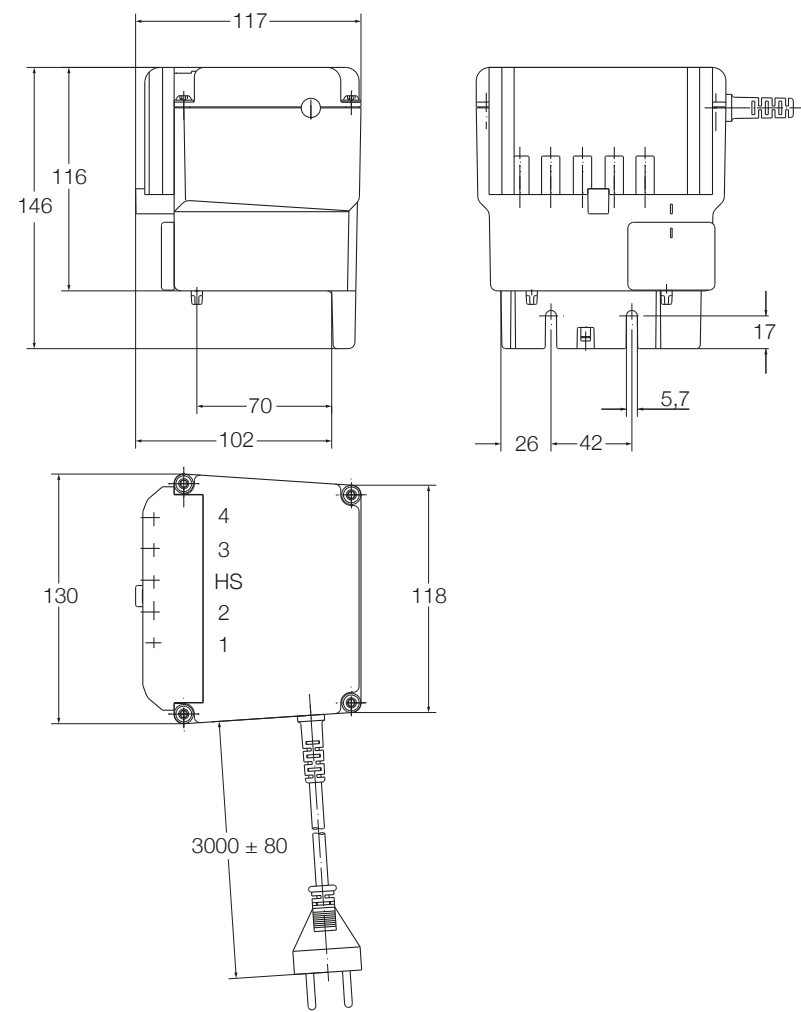
- Controls up to 4 actuators
- Suitable for homecare and nursing beds



Technical data




	Unit	SEM1
Motor ports	#	4
Operating device ports	#	1
Input voltage/Frequency	V AC	230/50 HZ
	V AC	120/60 HZ
Output voltage rating	V DC	24
Output current (max)	A (DC)	5
Duty cycle	min.	1 min./9 min.
Ambient temperature	°C	+10 to +40
Degree of protection	IP	×4
Approvals	UL	UL60601-1 (1st edition)
Weight	kg	1,8

Dimensional drawing

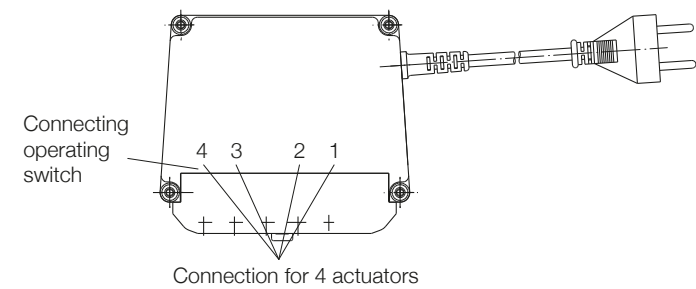


Suitable control units and accessories

	Linear Actuators	Operating switches
	ECOMAG	EHE1
SEM1	•	•

-  Hand switch
-  Foot switch
-  Desk switch

Connecting diagrams



Ordering key

S

E

M

1

-

-

0

0

0

Type

Number of channels

22 channel

44 channels

Voltage / Frequency

1230V / 50Hz

2120V / 60Hz

Mains plug

1Protection class II 2-pin mains plug (Euro standard)

2Protection class II 2-pin mains plug (British standard)

3Protection class II 2-pin mains plug (US)

BProtection class I 3-pin mains plug (Schuko)

EProtection class I 3-pin mains plug (US)

Colours

ABlack

BGrey RAL 7035


Options, electrical

0None

Fastening

0Piggyback on Ecomag





6

## Operating switches

Up to 10 keys

# Chapter contents

CAES ..... 270

EHA1 ..... 272

EHA3 ..... 274

EHE1 ..... 276

HSM, HSF ..... 278

PHC ..... 280

PFP ..... 282

ST ..... 284

ST ..... 286

STK ..... 288

PAM ..... 290

# CAES

## Hand switch

### Benefits

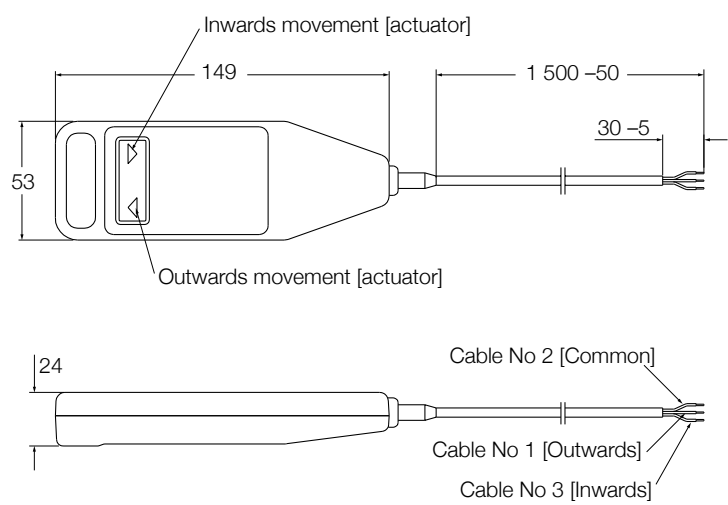
- Robust ergonomic design
- Membrane keyboard
- Clearly marked keys



### Technical data

	Unit	CAES 31C
Max. operating channels	n°	1
Operating power	V DC/mA	30/33
Degree of protection	IP	54
Color	–	Black

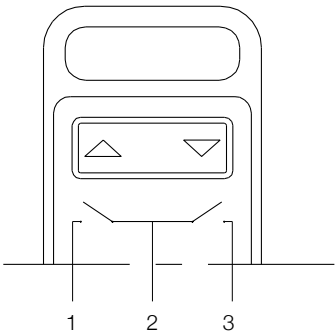
### Dimensional drawing



Suitable control units

	Control units			
	CAED 3-24R	CAED 5-24R	CAED 9-24R	CAEV 110/220
CAES 31C	•	•	•	•

Connecting diagrams



Ordering key

CAES 31C (No connector, 2 buttons)
------------------------------------



# EHA1

Hand switch

Benefits

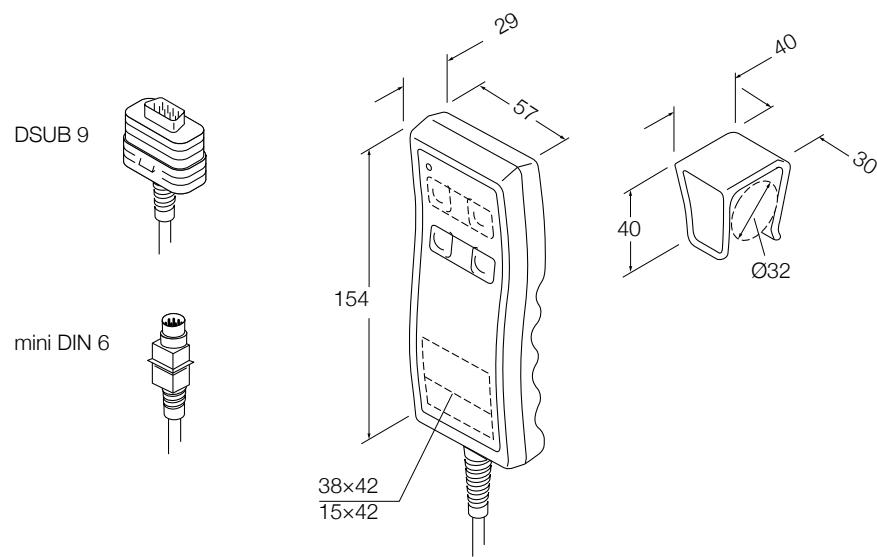
- Robust ergonomic design
- Tactile buttons, clearly marked
- Easy mountable fastening hook



Technical data

	Unit	EHA 1
Max. operating channels	n°	2
Operating power	V DC/mA	12/50
Degree of protection	IP	67
Color	–	Grey

Dimensional drawing



Suitable control units and linear actuators

	Linear actuators	Control units
	MAX7	MCU
EHA1	<div></div>	<div></div>

Accessories

Description	Designation	Order number
Hook with sticker	ZBG-145361-000	0125538

Ordering key

EHA1

-

1

N

-

0

0

0

Type

Number of channels

11 channel

22 channels

Hook

1Yes mounted with hook

2Hook supplied separately

Cable / connecting plug

BCoiled, 1,3 m/2,5 m / D-sub 9-pin plug

CStraight 2,5 m (min DIN 6-pin plug)

DCoiled 1,0 m/2,0 m (min DIN 6-pin plug)

FCoiled 2,5 m/3,5 m / D-sub 9-pin plug

Symbols

00None

101 channel:Head

202 channels:Arrow up/down

# EHA3

Hand switch

**Benefits**

- Robust ergonomic design
- Tactile buttons, clearly marked
- Easy mountable fastening hook

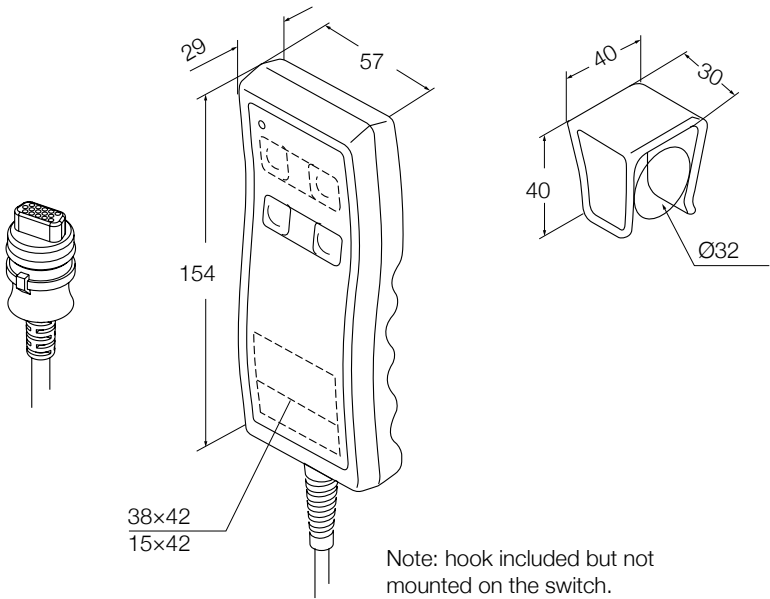


**Technical data**

	Unit	EHA 3
Max. operating channels	n°	5
Operating power	V DC/mA	12/50
Degree of protection	IP	67
Color	–	Grey
Cable: Coiled 1,3 m/2,5 m	–	D-sub 15-pin

**Dimensional drawing**

High density  
D-Sub 15



Suitable control units and columns

	Columns		Control units							
	TFG 50	TFG 90	SCU 1	SCU 5	SCU 9	VCU 5	VCU 8	VCU 9	BCU 5	BCU 8
EHA3	•	•	•	•	•	•	•	•	•	•

Accessories

Description	Designation	Order number
Hook with sticker	ZBG-145361-000	0125538

Ordering keys

Type

Number of channels

- 1 1 channel
- 2 2 channels
- 3 3 channels
- 4 4 channels
- 5 5 channels
- A 1 channel with 3 memory positions (only for SCU)
- B 2 channels with 3 memory positions (only for SCU)
- C 3 channels with 3 memory positions (only for SCU)

Symbols

- 00 None
- 10 1 channel: 2nd row from top
  - Arrow up/down
  - Head
  - Foot
  - Level
  - Anti-Trendelenburg
- 20 2 channels: 1st-2nd row from top
  - Arrow up/down
  - Head/foot
  - Head/level
  - Level/head
  - Level/Anti-Trendelenburg
- 30 3 channels: 1st-3rd row from top
  - Arrow up/down
  - Head/foot/level
  - Level/head/foot
  - Level/Anti-Trendelenburg/Head
- 40 4 channels: 1st-4th row from top
  - Arrow up/down
  - Level/Anti-Trendelenburg/Head/Foot
- 47
- 50 5 channels: 1st-5th row from top
  - Arrow up/down



Options shown in red are only available on demand. Please contact Ewellix.

# EHE1

Hand switch

**Benefits**

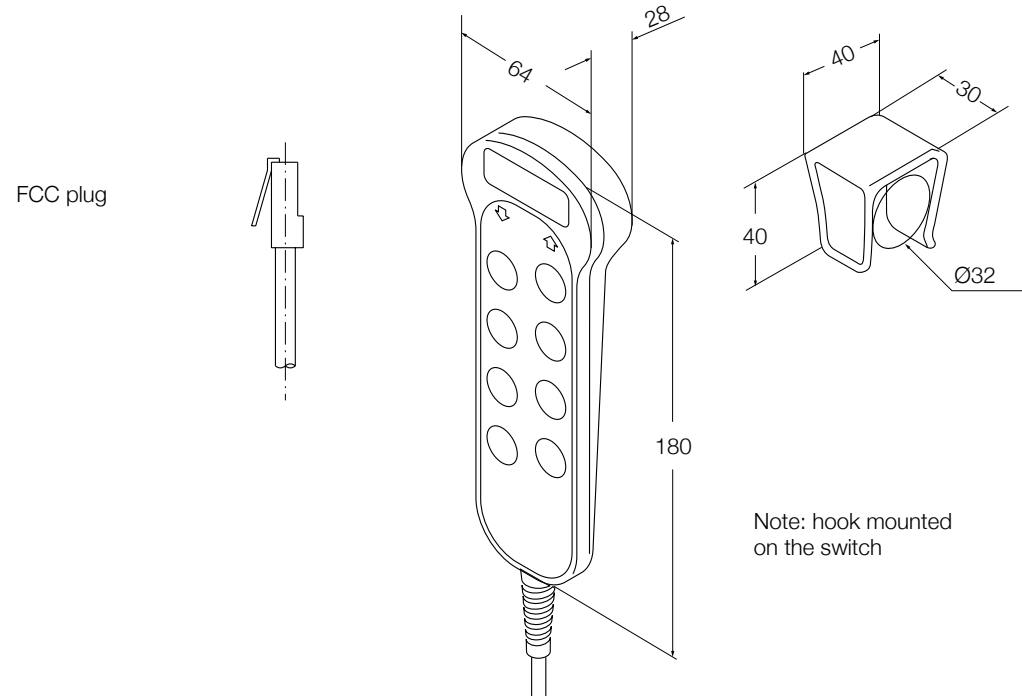
- Easy and precise
- Flexible and remote operation
- Ergonomic design



**Technical data**

	Unit	EHE 1
Max. operating channels	n°	2
Operating power	V DC/mA	38/50
Degree of protection	IP	×67
Color	–	Grey
Cable: Coiled 1,1 m/2,5 m	–	FCC plug

**Dimensional drawing**



Suitable control units and columns

	Columns				Control units	
	TXG 4 <sup>1)</sup>	TXG 5 <sup>1)</sup>	TXG 8 <sup>1)</sup>	TXG 9 <sup>1)</sup>	SEM1 2	SEM1 4
EHE1	•	•	•	•	•	•

<sup>1)</sup> Only with FCC plug

Accessories

Description	Designation	Order number
Hook	ZBG-145361-000	0125538

Ordering key

Type

Number of channels

- 1 1 channel
- 2 2 channels

Symbols

- 10 1 channel: Arrow up/down
- 20 2 channels: Arrow up/down



# HSM, HSF

## Hand switch

### Benefits

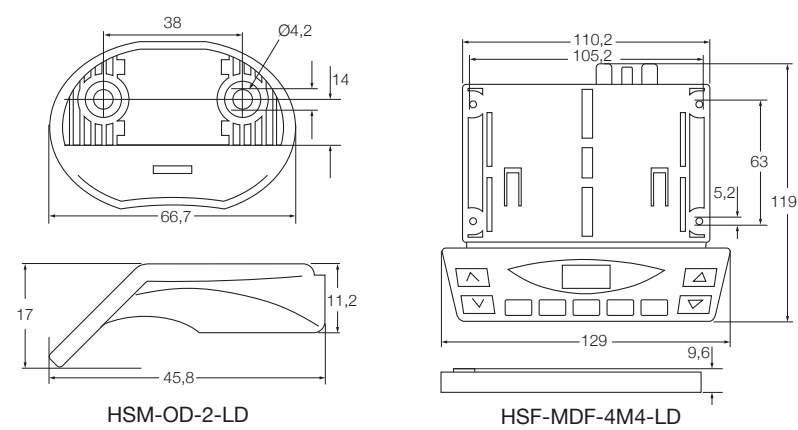
- Easy and precise
- Stylish design
- Different functions



### Technical data

	Unit	HSM-OD-2-LD	HSF-MDF-4M4-LD
Max. operating channels	n°	1	1 or 2
Operating power	V DC/mA	5/50	5/50
Degree of protection	IP	32	32
Color	–	Black	Black

### Dimensional drawing



Suitable control units and columns

Control units	
	COMPACT
HSM-OD-2-LD	•
HSF-MDF-4M4-LD	•

Ordering key

HSM-OD-2-LD (DIN7 plug)
HSF-MDF-4M4-LD (DIN7 plug)



# PHC

Hand switch

**Benefits**

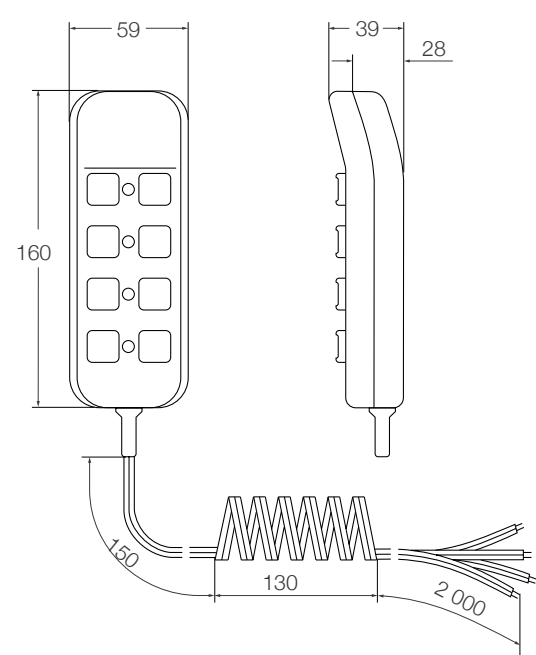
- Easy and precise
- Flexible and remote operation
- Ergonomic design



**Technical data**

	Unit	PHC
Max. operating channels	n°	4
Operating power	V DC/mA	N/A
Degree of protection	IP	66
Color	–	Grey

**Dimensional drawing**



Suitable linear actuators and columns

	Linear actuators		Columns		
	MAX 7	MAX 7	TLC pneumatic	TGC pneumatic	THC pneumatic
PHC	•	•	•	•	•

Ordering key

PHC 1 – 130517 (1 channel with arrows up/down, without hook)
PHC 2 – 130625 (2 channels with arrows up/down, without hook)
PHC 3 – 130756 (3 channels with arrows up/down, without hook)
PHC 4 – 130955 (4 channels with arrows up/down, without hook)

Other symbols / with hook on demand.

# PFP

## Foot switch

### Benefits

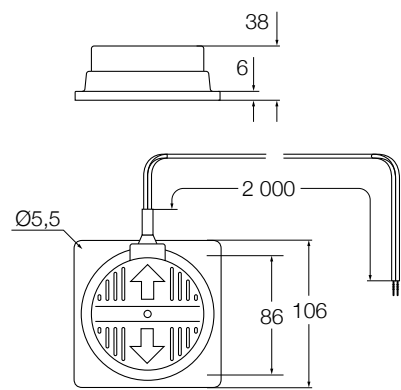
- Robust ergonomic design
- Easy and precise
- Flexible and remote operation



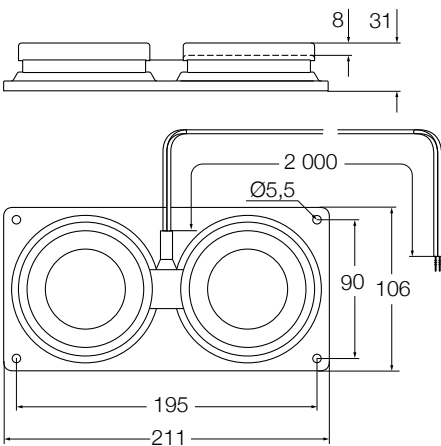
### Technical data

	Unit	PFP 1K	PFP 1
Max. operating channels	n°	1	1
Operating power	V DC/ mA	N/A	N/A
Degree of protection	IP	21	21
Color	–	Grey	Anthracite

### Dimensional drawing



PFP 1K-130652



PFP 1-121545

Suitable linear actuators and columns

	Linear actuators		Columns		
	MAX 7	MAX 7	TLC pneumatic	TGC pneumatic	THC pneumatic
PFP	•	•	•	•	•

Ordering key

PFP 1K – CAES 31C (No connector, 2 buttons) 130652  
PFP 1 – 121545

Other versions on request.

# ST

Foot switch

Benefits

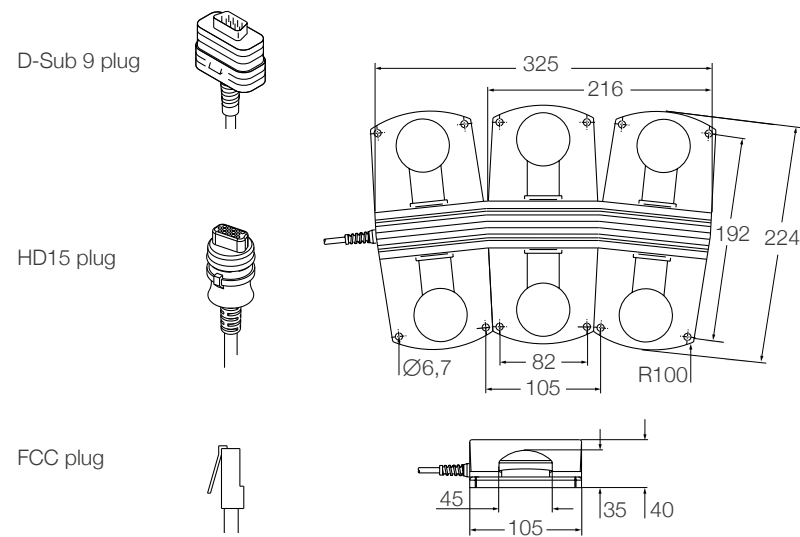
- Easy and precise
- Ergonomic design
- Different plug options



Technical data

	Unit	ST
Max. operating channels	n°	3
Operating power	V DC/mA	12/50
Degree of protection	IP	×5
Color	–	Blue/anthracite

Dimensional drawing



Suitable columns, linear actuators and control units

	Columns		Linear Actuators	Control units								
	TFG 50/90	TXG 4/5/8/9 <sup>1)</sup>	MAX 7	SCU 1	SCU 5	SCU 9	VCU 5	VCU 8	VCU 9	BCU 5	BCU 8	MCU
STJ	•			•	•	•	•	•	•	•	•	
STF		•	•									•

<sup>1)</sup> Only with FCC plug

Accessories

Description	Designation	Order number
Rubber feet (100 pcs.)	ZBE-135310	0102879
Sticker arrow up	ZKL-135309-0001	0124871
Sticker arrow down	ZKL-135309-0002	0124870

Ordering key

S

T

0

-

-

-

0

0

Type

Product group:

F Classic, D-Sub9 or FCC plug

J Standard, single-fault safety, HD15 plug

Number of channels:

1 One (1) channel

2 Two (2) channels

3 Three (3) channels

Cable / connecting plug:

LU Coiled cable 1,3-2,5 m / D-sub plug

LW Coiled cable 1,3-2,5 m / HD15 plug

OU Straight cable 2,5 m / D-sub plug

OV Straight cable 2,5 m / FCC plug (only for STF01 and STF02)

OW Straight cable 2,5 m / HD15 plug

Color:

1 Anthracite

4 Blue

Option:

000 None

MAY Mounted with rubber feet

Symbols:

X1 Arrow up/down (on each pair of buttons), 1–3 channels

37 Arrow up/down, M/1, 2/3 (3 memory buttons) only for STJ03

6

# ST

Desk switch

Benefits

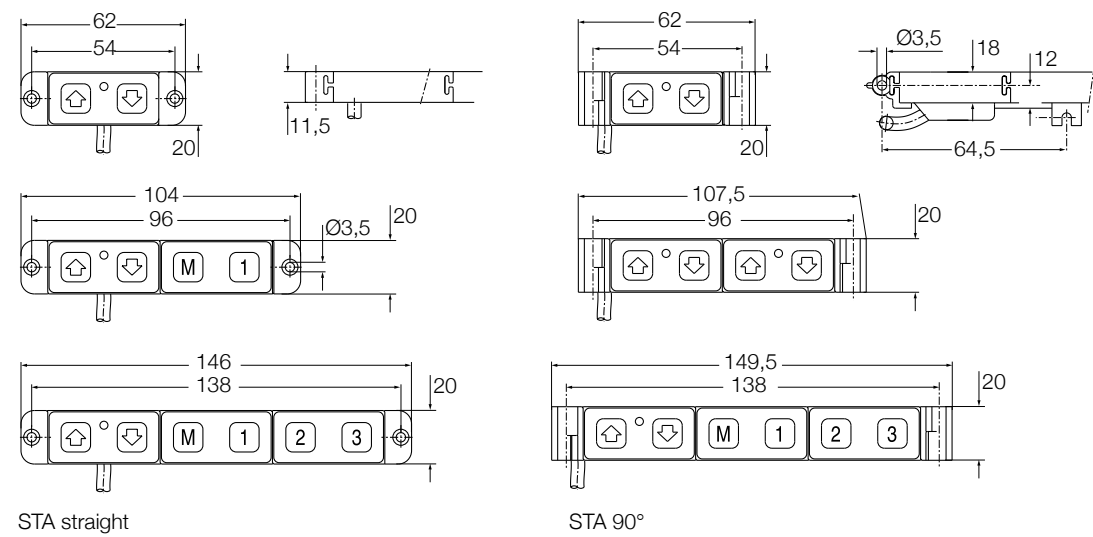
- Easy and precise
- Stylish design
- Memory position



Technical data

	Unit	ST
Max. operating channels	n°	3
Operating power	V DC/mA	12/50
Degree of protection	IP	x0
Color	–	Black

Dimensional drawing



Suitable columns, linear actuators and control units

	Columns <sup>1)</sup>		Linear Actuators <sup>1)</sup>	Control units								
	TFG 50/90	TXG 4/5/8/9 <sup>2)</sup>	MAX 7	SCU 1	SCU 5	SCU 9	VCU 5	VCU 8	VCU 9	BCU 5	BCU 8	MCU
STA		•	•									•
STE	•			•	•	•	•	•	•	•	•	

<sup>1)</sup> With integrated control units

<sup>2)</sup> Only with FCC plug

Ordering key

Type

Product group:

Number of channels:

Cable / connecting plug:

Option:

Symbols:

S

T

0

-

6

-

0

0

A

E

1

2

3

0U

WV

0W

000

MAU

X1

37

Classic, D-Sub9 or FCC plug

Standard, single-fault safety wiring, HD15 plug

One (1) channel

Two (2) channels

Three (3) channels

Straight cable 2,5 m / D-sub plug

Straight cable 1,5 m / FCC plug

Straight cable 2,5 m / HD15 plug

No option

Mounted on or underneath desktop, at a 90° angle

Up/down arrow on each pair of keys (1-3 channels)

Up/down arrow, 3 memory functions M/1, M/2, M/3 (3 channels)



# STK

## Desk switch

### Benefits

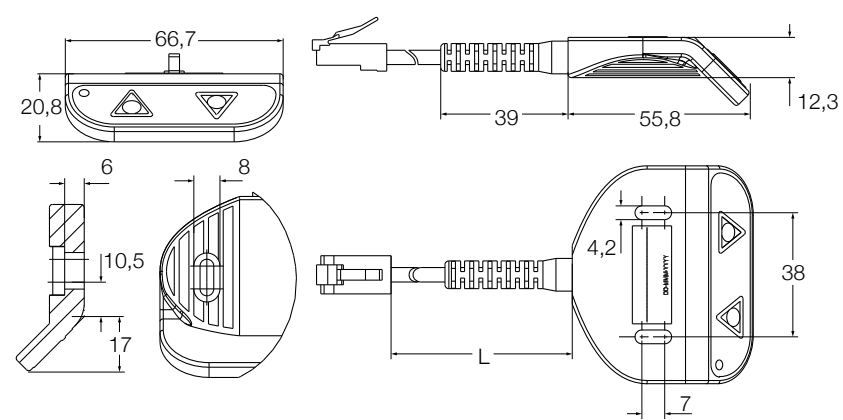
- Easy and precise
- Stylish design
- Tactile buttons with finger guide
- 2 colors LED for power and feedback status



### Technical data

	Unit	STK
Max. operating channels	n°	1
Operating power	V DC/mA	12/50
Color	–	Grey
Indicator	–	2 colors LED for power and feedback status
Plug	–	RJ45
Symbols	–	with arrows up/down

### Dimensional drawing



	STK01-SW3000-X100	STK01-UW3000-X100
L [mm]	500	1 000

Suitable columns and accessories

	Columns		Socket boxes		
	CPMA1-1	CPMA1-2	CPMA2-2	ZDV-348220-002	ZDV-348221-002
STK01-SW3000-x100	•	•	•	•	•
STK01-UW3000-x100	•	•	•	•	•

Ordering key

Description	Part number	Order number
Desk switch with LED, cable 0,5 m	STK01-SW3000-x100	130025
Desk switch with LED, cable 1 m	STK01-UW3000-x100	130026

# PAM

## Pneumatic desk switch

### Benefits

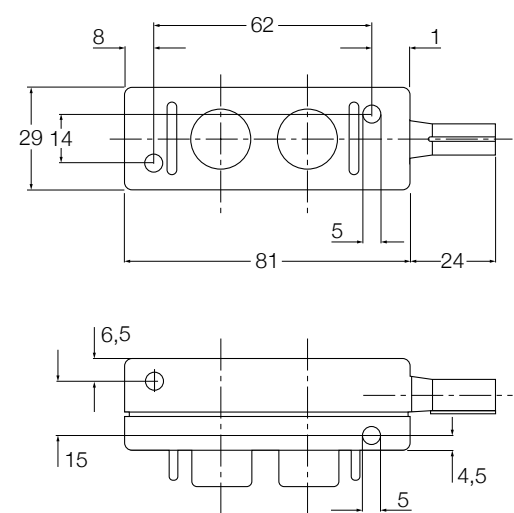
- Operation with air (no electricity)
- Stylish design



### Technical data

	Unit	PAM –130256
Max. operating channels	n°	1
Operating power	V DC/ mA	N/A
Degree of protection	IP	N/A
Tube	–	Straight, 1,50 m
Color	–	Anthracite

### Dimensional drawing



### Suitable linear actuators and control units

	Linear actuators		Control units		
	MAX7	MAX7	TLC pneumatic	TGC pneumatic	THC pneumatic
PAM	•	•	•	•	•

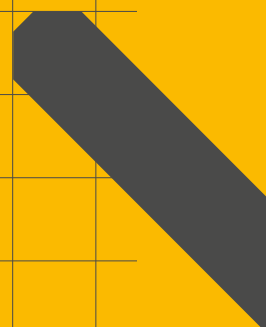
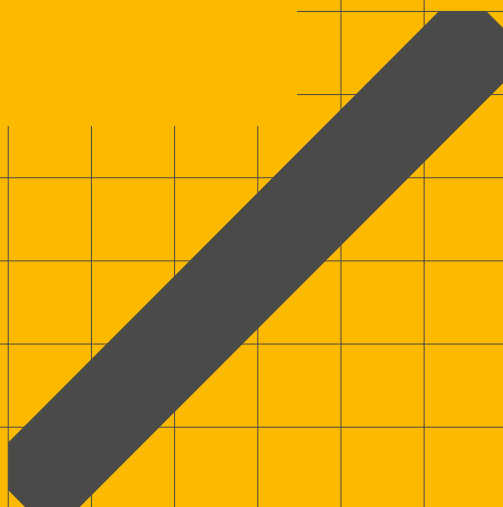
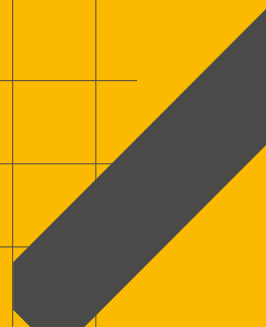
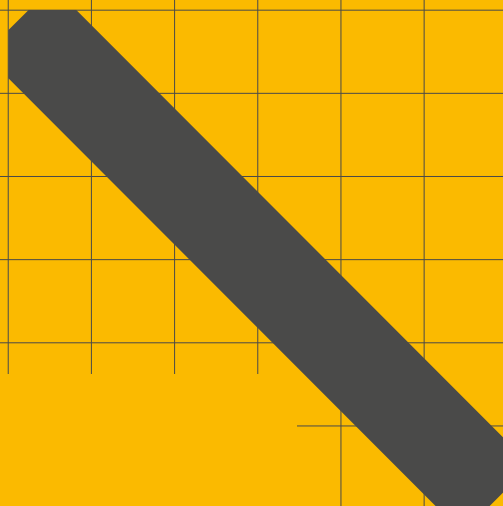
### Ordering key

PAM–130256
------------



7

New medical  
solution



# CAMT

Linear actuator for surgical tables and procedure chairs

**Benefits**

- Play free motion
- Easy installation
- Compact design

**Standards**

- IEC/UL 60601-1 (Edition 3.1)
- IEC/UL 60601-1-2 (Edition 4)



**Technical data**

	Unit	CAMT20
Rated push load	N	6 000
Rated pull load	N	6 000
Static load (push/pull) <sup>1)</sup>	N	13 200
Safety factor on rated load <sup>2) 3)</sup>	–	4
Speed (full load to no load) <sup>4)</sup>	mm/s	5 to 6,5
Stroke	mm	50 to 250
Voltage	VDC	24
Current consumption	A	10
Duty cycle	%	10 (1/9 minutes)
Ambient temperature	°C	+10 to +40
Degree of protection	–	IP20
Noise level (max)	dB	≤ 55
Weight <sup>5)</sup>	Kg	5,8

<sup>1)</sup> Compliant with static load according to IEC/UL 60601-2-46  
<sup>2)</sup> Static safety factor to prevent mechanical hazards according to IEC/UL 60601-1  
<sup>3)</sup> Depending on stroke and attachment type, safe work load in push direction is reduced. For details, see diagram **Safety factor load conditions**  
<sup>4)</sup> Speed with 24 V DC, speed with V/SCU is higher. For details, see diagram **Load-Speed**  
<sup>5)</sup> For stroke 250 mm, without attachment

## Product benefits

### Play free motion – Extra comfort

Feel the smooth movement introduced by CAMT because all parts are play-free. Unlike common actuators which shake when the load direction changes, CAMT keeps the movement smooth throughout the whole process (→ **diagram 1**).

### Easy installation – Simplicity

It is easy to install thanks to the new design with extra front and rear attachment with 1 or 2 DOF in motion (→ **fig. 1 and 2**).

### Compact design – Perfect system integration

The compact design enables a perfect system integration. It can be installed as a single actuator or be combined with other CAMT actuators and a column (e.g. CPMT) to achieve combined motion in any direction (→ **fig. 3**).

Fig. 1

Front attachment: play-free



Fig. 2

Rear attachment: play-free

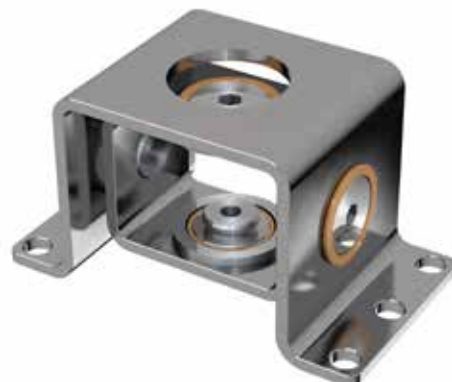
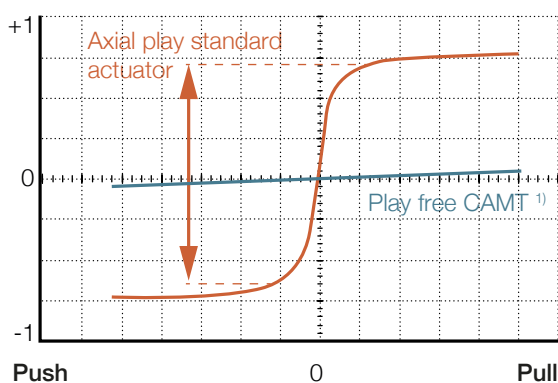


Diagram 1

Displacement [mm]



CAMT actuator — Standard actuator —

<sup>1)</sup> Actuator after service life of 10 years in a typical medical procedure equipment application, with the meaning of 60 000 cycles at average load of 3 000 N and average stroke of 100 mm.

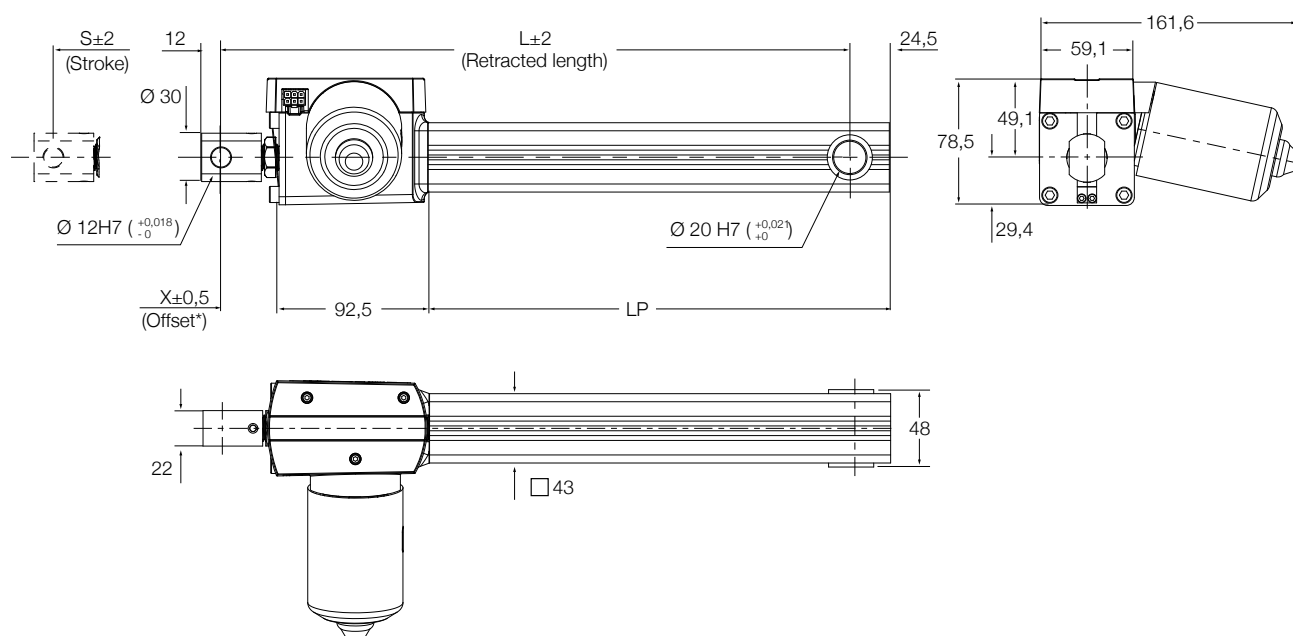
Fig. 3

Surgical module



## Dimensional drawing

### Clevis attachment (CAMT20-xxxxx-00L-AA-AFx-000)

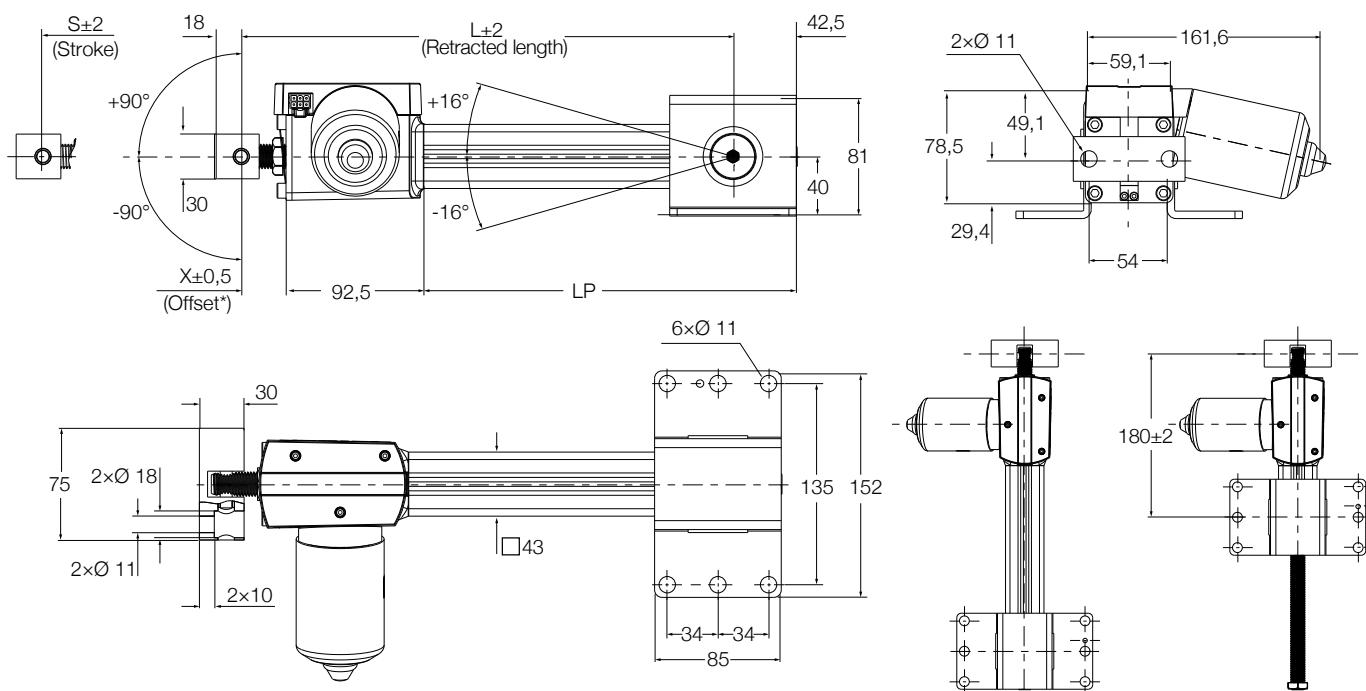


#### Retracted length:

$$L = \text{Stroke (S)} + \text{Offset (X)} + 104$$

\* Standard Offset = 36

### 1 DOF attachment (CAMT20-xxxxx-00x-BB-AFx-000)



#### Retracted length:

$$L = \text{Stroke (S)} + \text{Offset (X)} + 50 \text{ (long protection tube)}$$

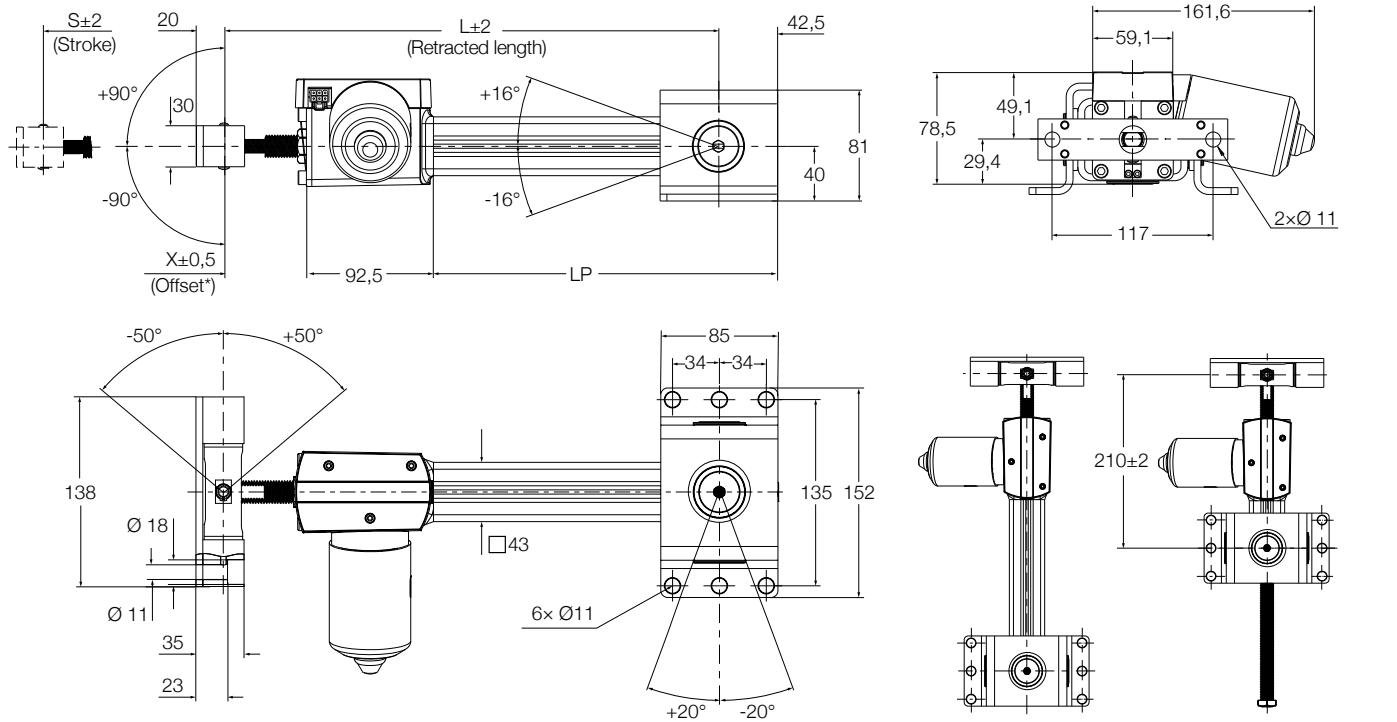
$$L = \text{Offset (X)} + 150 \text{ (short protection tube)}$$

\* Standard Offset = 30

Long protection tube    Short protection tube



## 2 DOF attachment (CAMT20-xxxxx-00x-CC-AFx-000)



### Retracted length:

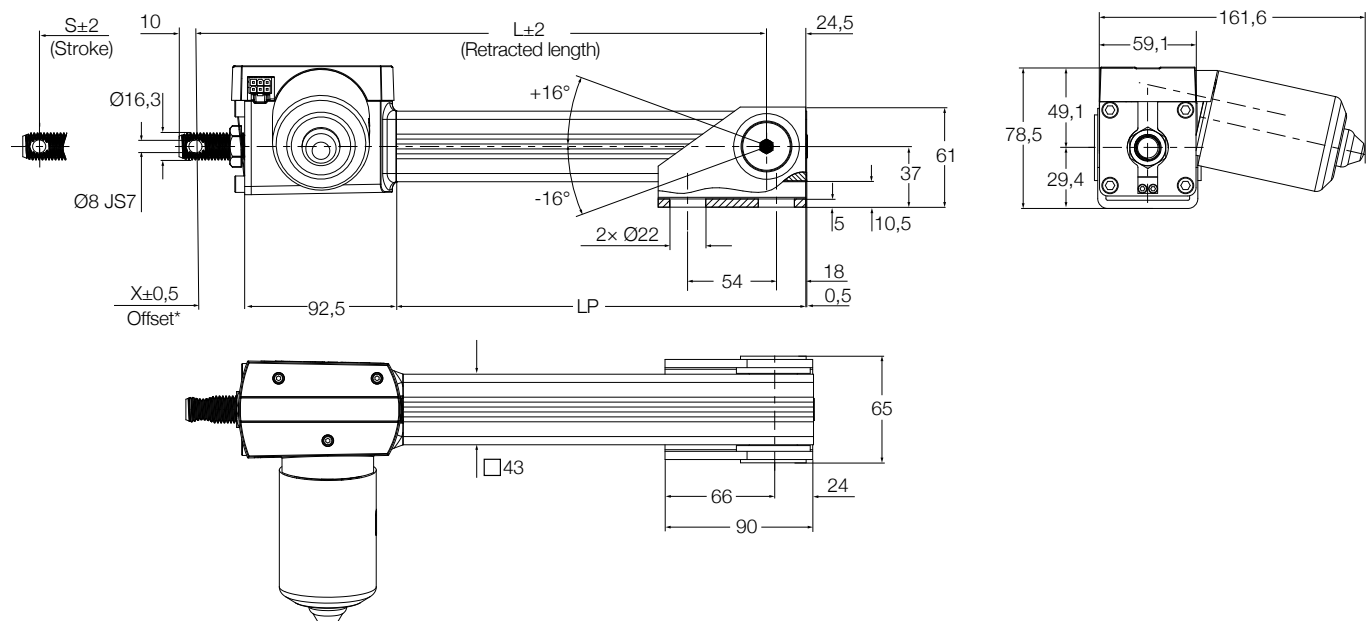
$L = \text{Stroke (S)} + \text{Offset (X)} + 50$  (long protection tube)

$L = \text{Offset (X)} + 150$  (short protection tube)

\* Standard Offset = 60

Long protection tube    Short protection tube

## Rod with D8 JS7 bore (CAMT20-xxxxx-00x-DF-AFx-000)



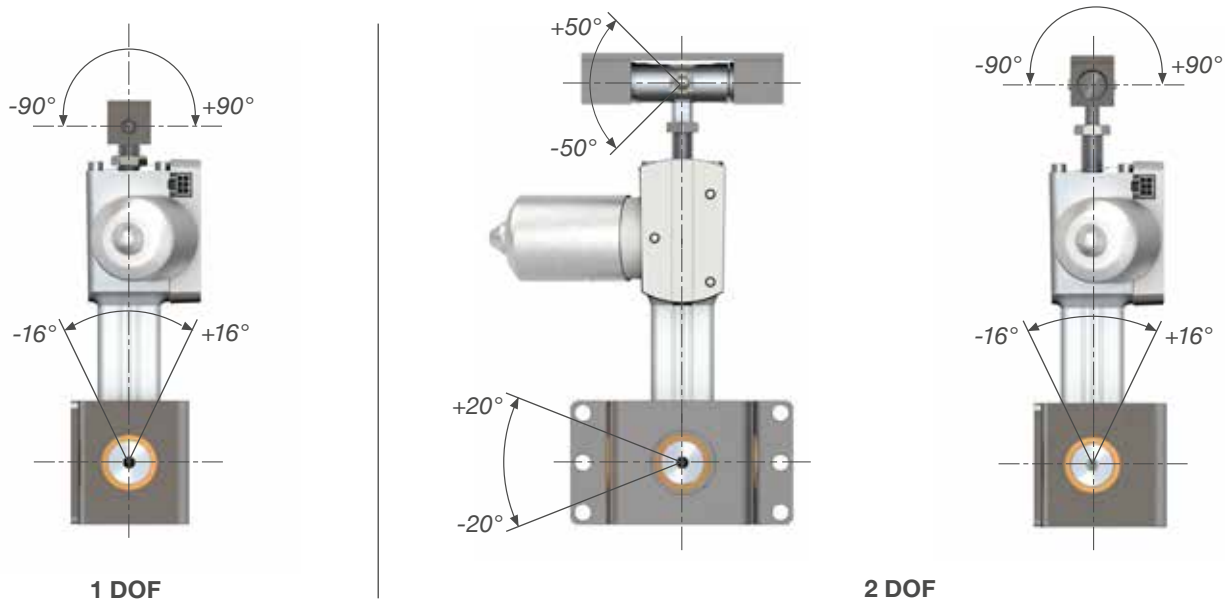
### Retracted length:

$L = \text{Stroke (S)} + \text{Offset (X)} + 68$  (long protection tube)

$L = \text{Offset (X)} + 168$  (short protection tube)

\* Standard Offset = 30

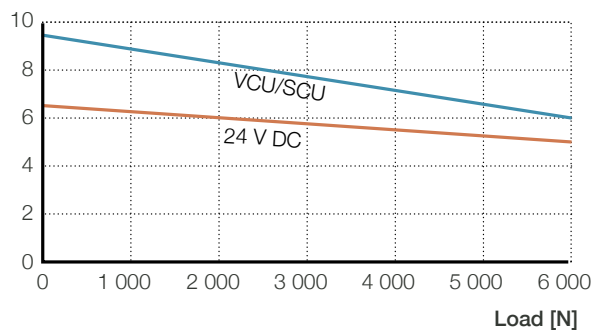
## Motion angles of play front and rear attachments



## Performance diagrams

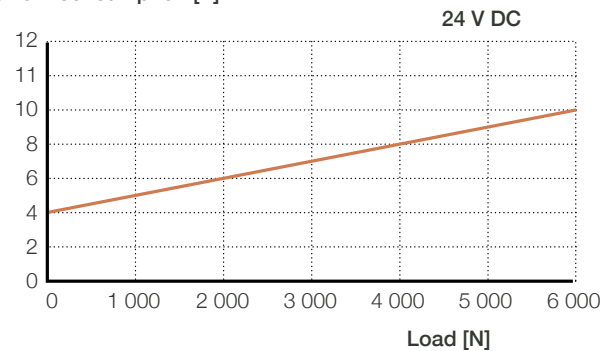
### Speed-load diagram

Speed [mm/s]



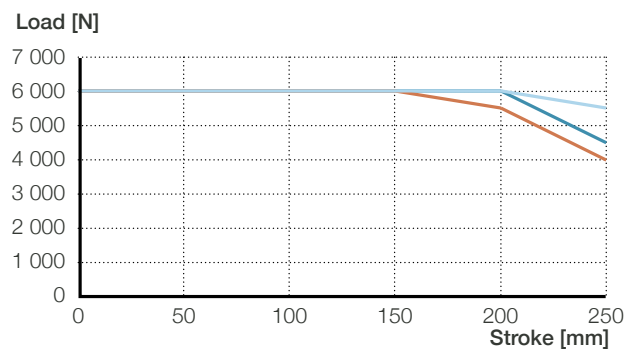
### Current-load diagram

Current consumption [A]

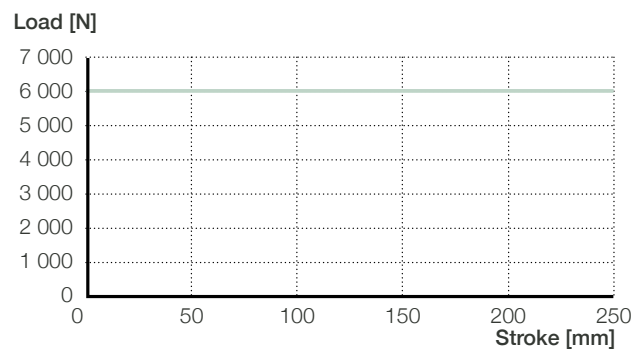


## Safety factor load conditions

Push load reduction for static safety factor  $S=4$   
(IEC/UL 60601-1)



Safe push and pull load for static safety factor  $S=2.2$   
(IEC/UL 60601-2-46)



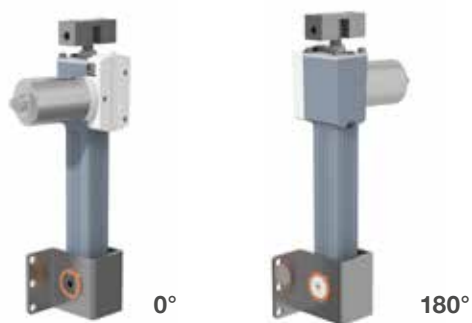
— Clevis attachment  
— 1 DOF attachment, with long protection tube <sup>1) 2)</sup>

— 2 DOF attachment, with long protection tube <sup>1)</sup>  
— Valid for all CAMT configurations

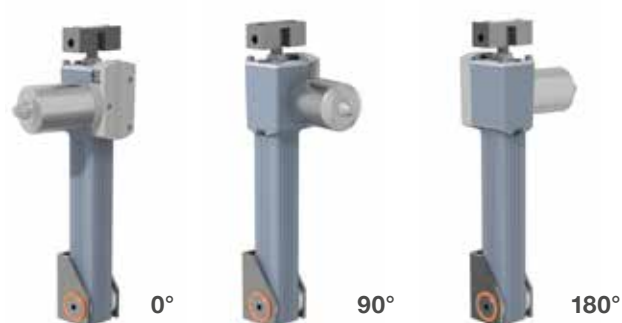
<sup>1)</sup> No load reduction with short protection tube

<sup>2)</sup> No load reduction for 1DOF U-bracket

## Rear attachment orientation



Standard bracket (1 DOF and 2 DOF)



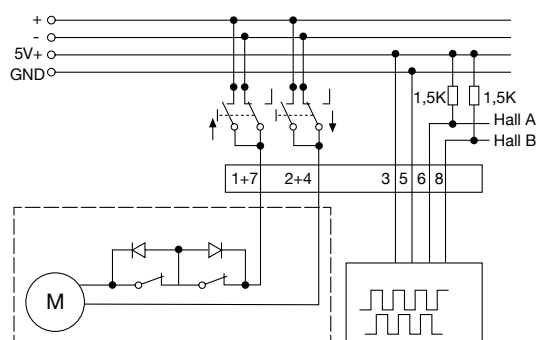
U-bracket (1 DOF)

## Suitable control units and accessories

		Control units							
		SCU 1	SCU 5	SCU 9	VCU 5	VCU 8	VCU 9	*BCU 5	*BCU 8
<b>CAMT</b>		•	•	•	•	•	•	•	•
<b>Operating switches</b>									
EHA 3		•	•	•	•	•	•	•	•
STJ		•	•	•	•	•	•	•	•
STE		•	•	•	•	•	•	•	•
	Hand switch								
	Foot switch								
	Desk switch								

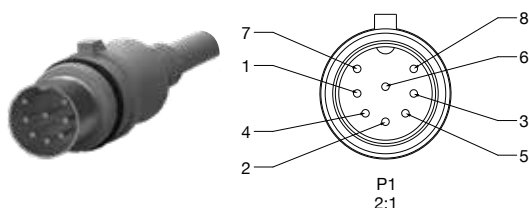
## Connecting diagram

### 24 V DC

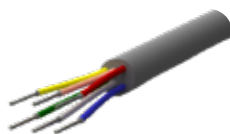


Encoder resolution 0,02127 mm/edge

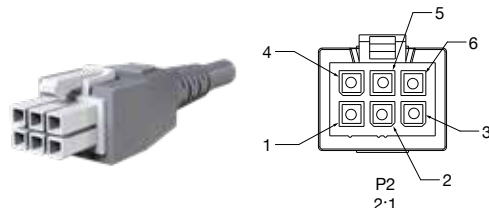
## Electrical connection



Plug P1: DIN-8 connector



Flying leads



Plug P2: Molex Mini-fit Jr. 6-pole

Plug P1	Wire color	Section	Function	Plug P2
1+7	Blue	AWG 16	- on, + off	4
2+4	Red	AWG 16	+ on, - off	1
3	Pink	AWG 24	+ 5 V	2
5	Grey	AWG 24	gnd	5
6	Yellow	AWG 24	hall sensor 1 signal	3
8	Green	AWG 24	hall sensor 2 signal	6

### Ordering key

		C A M T 2 0		-			-			-			-	A F		-		
<b>Type</b>																		
<b>Load</b>																		
2	6 000 N																	
<b>Voltage</b>																		
0	24 VDC																	
<b>Stroke length</b>																		
0	5	0	50 mm															
1	0	0	100 mm															
1	5	0	150 mm															
2	0	0	200 mm															
2	5	0	250 mm															
x	x	x	Customised (10 mm steps)															
<b>Distance between front pivot and gear box (Offset "X", see dimensional drawing)</b>																		
0	0	Standard																
x	x	Customised (10 mm steps)																
<b>Protection tube length (LP, see dimensional drawing)</b>																		
0	0	S	Short (shortest possible length)															
0	0	L	Long (lead screw covered when retracted)															
x	x	x	Customised (10 mm steps)															
<b>Front attachment</b>																		
A	Rod clevis D12 H7 bore																	
B	1 DOF attachment																	
C	2 DOF attachment																	
D	Rod with D8 JS7 bore																	
<b>Rear attachment</b>																		
A	Rear clevis D20 H7 bore 0° (only with long protection tube)																	
B	1 DOF attachment 0°																	
C	2 DOF attachment 0°																	
D	Rear clevis D20 H7 90° (only with long protection tube)																	
E	1 DOF attachment 180°																	
F	1 DOF U-bracket attachment 0°																	
G	1 DOF U-bracket attachment 90°																	
H	1 DOF U-bracket attachment 180°																	
I	2 DOF attachment 180°																	
<b>Mechanical options</b>																		
A	Backup nut																	
<b>Electrical options</b>																		
F	End limit switches																	
<b>Cable options</b>																		
A	1 m straight with DIN8 plug																	
B	2,3 m straight with DIN8 plug																	
C	2,3 m straight with flying leads																	
0	Without cable																	

■ Options shown in red are only available on request. Contact Ewellix for more information on minimum quantities and additional costs.

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## Glossary and symbols

# Glossary

A	
<b>Absolute movement</b>	A move referenced from a fixed absolute zero position
<b>Acceleration</b>	The change in velocity as a function of time, going from a lower speed to a higher speed
<b>Accuracy</b>	An absolute measurement defining the difference between expected and actual position
<b>Actuator</b>	An actuator is a device that is responsible for moving or controlling a mechanism or system also known as cylinder, electromechanical cylinder or linear actuator
<b>Ambient temperature</b>	The temperature of the cooling medium, usually air, immediately surrounding the actuator or another device
<b>Angular contact ball bearing</b>	Angular contact ball bearings have raceways in the inner and outer rings that are displaced relative to each other in the direction of the bearing axis. This means that they are designed to accommodate combined loads, i.e. simultaneously acting radial and axial loads.
<b>Anodized</b>	Protective treatment for aluminium that involves subjecting the metal to electrolytic action in a chemical bath, to create a protective film of aluminium oxide with a very smooth finish
<b>Axial load</b>	Load where the force is acting along the axis of actuator (bearing) in any direction
B	
<b>Backlash</b>	The amount of play between a set of moveable parts when changing the direction of travel. Typically seen in drive trains, ball/ lead screws and bearings
<b>Ball bearing</b>	A support device which allows a smooth low friction motion between two surfaces loaded against each other with balls as rolling elements
<b>Ball screw</b>	A screw assembly which uses a ball nut which contains one or more circuits of recirculating steel balls which roll between the nut and the screw
<b>Bearing</b>	A support device which allows a smooth low friction motion between two surfaces loaded against each other
<b>Brushless DC motor</b>	Synchronous motor type that are powered by a DC electric supply through an inverter that produce an AC signal to drive the motor
<b>Bushing</b>	A cylindrical sleeve inserted into a machine part to reduce friction between moving parts
C	
<b>Configurator (product)</b>	Name given to the software that uses the configuration string to build-up a specific actuator from an existing list of components and options
<b>Continuous torque</b>	Is the torque that the motor is able to provide continuously with no limitation in time
<b>Current</b>	The flow of charge through a conductor
<b>Cycle</b>	A complete motion of an actuator from the start position via intermediate positions and back to the start position
<b>Cycle time</b>	Time for one complete motion cycle, from the start of the cycle until the start of the next cycle
<b>Cylinder</b>	A mechanical device which produces a linear force to achieve a reciprocating linear motion. There three common types: pneumatic, hydraulic and electromechanical (or electric). The first two use the power of compressed media (gas or liquid) while the latter uses a mechanical device (screw) to transform the rotational input movement of a motor into a linear one.
D	
<b>Deceleration</b>	The change in velocity as a function of time, going from a higher speed to a lower speed
<b>Duty cycle</b>	The ratio of motor on time and total cycle time within a given cycle of operation
<b>Dynamic load rating</b>	Constant that is used to calculate the service life of a screw drive. The value for the dynamic load rating represents the load under which 90 % of a sufficient large number of identical screw drives can achieve a service life of one million revolutions
E	
<b>Efficiency</b>	Ratio of output power versus input power

<b>Electric cylinder</b>	A self-contained system which converts rotary motion (from a motor) to linear motion
<b>Electromechanical cylinder</b>	A self-contained system which converts rotary motion (from a motor) to linear motion
<b>Electrode</b>	The part of a resistance welding gun that facilitates the high voltage current path to the parts being welded
<b>Equivalent dynamic axial load</b>	Load of constant magnitude over a full motion cycle which has the same influence on the linear unit's service life as the actual fluctuating load
<b>F</b>	
<b>Foot mount</b>	Mounting plates, attached to front and end of a cylinder, to mount the cylinder in parallel to a flat surface
<b>Force</b>	The action of one body on another which tends to change the state of motion of that body. Typically described in terms of magnitude, direction and point of application
<b>Friction</b>	The resistance to motion of two surfaces that are in direct contact
<b>G</b>	
<b>Gear ratio</b>	This relates to the transmission and conversion of movements, linear and rotary speeds, forces and torques in a geared mechanism. The gear ratio (also known as reduction ratio) is the ratio between the input and output variable, e.g. the ratio of input speed to output speed
<b>H</b>	
<b>Hall effect sensor</b>	A magnetically controlled transistor switch controlling DC power. It has no moving parts and theoretically unlimited contact life.
<b>Holding force</b>	Maximum external force that can be applied to a stopped actuator, without causing any linear movement. It is usually given by the holding torque of an electromechanical brake applied on the motor
<b>Humidity (relative)</b>	A ratio that indicates the amount of water vapor in the air. It is usually expressed as a percentage. At any temperature, it is the amount of water vapor in the air, divided by the amount that would be present at saturation
<b>I</b>	
<b>Inertia</b>	Property of an object that resists a change in motion. It is dependent on the mass and shape of the object. The greater an object's mass, the greater its inertia and the more force is necessary to accelerate and decelerate it
<b>IP</b>	Degrees of protection provided by enclosures, according with IEC standard 60529
<b>K</b>	
<b>Keyway</b>	An axially-located groove in the length of a shaft along which a key may be located
<b>L</b>	
<b>Lead</b>	Describes the axial distance a nut is moving on a screw at one full rotation of either the screw or the nut
<b>Lead screw</b>	A screw which uses a threaded screw design (e.g. with trapezoidal shaped thread) with sliding surfaces between the screw and nut
<b>Lifetime</b>	Service life in km that 90 % of a sufficiently large group of apparently identical cylinders can be expected to reach or exceed.
<b>Limit switch</b>	A switch that is actuated by some part of motion of a machine or equipment to alter the electrical circuit associated with it
<b>Linear speed</b> <b>Max. linear speed</b>	The linear speed is the change in position as a function of time. Maximum linear speed, a linear unit or a cylinder can reach without damaging the mechanical system. Limiting factors can be the recirculating system of the balls or rollers, or the heat dissipation when using lead screws, or others. If the motor of the cylinder could turn faster, it needs to be limited
<b>Load</b>	A mass or weight of an application acting on the in axial direction on the push tube

M		
<b>Mass</b>		The quantity of matter that an object contains
<b>Moment</b>		Rotational forces applied to a linear axis, typically expressed as yaw, pitch and roll
<b>Motion profile</b>		A method of describing a move operation in terms of time, position and velocity. Typically, velocity is characterized as a function of time or distance which results in a triangular or trapezoidal profile
<b>Motor</b>		A device which converts electrical energy into mechanical energy
O		
<b>O-ring</b>		A ring of synthetic rubber with a circular cross-section, used as a gasket or seal
<b>Overheating</b>		The heat in a system is mostly dissipated into the surrounding air. Dissipation can be accelerated by various forms of ventilation. In case the dissipation level is lower than the heat generation, overheating takes place
P		
<b>Peak force</b>		The peak force is the maximum force an actuator can push or pull for a short time (peak), without being mechanically damaged or overheating
<b>Peak torque</b>		The peak force is the maximum torque a motor can provide for pull for a short time (peak), without being mechanically damaged or overheating
<b>PLC (programmable logic controller)</b>		An industrial digital computer that is used to control machines and processes by continuously monitoring analog and digital inputs and making decisions based on customer programs
<b>Positioning accuracy</b>		Is the maximum deviation between the actual position and the target position, as defined in VDI/DGQ 3441 norms
<b>Power</b>		How much work is done in a specific amount of time
<b>Proximity sensor</b>		A device for sensing a position of an actuator or application. Proximity sensors supply either a sourcing or sinking signal to a device such as a programmable logic controller
R		
<b>Radial load</b>		Load where the force is acting perpendicular to the axis of the actuator
<b>Repeatability</b>		The ability of a positioning system to return to an exact location during operation (from the same direction with the same load and speed)
<b>Resolver</b>		A feedback device consisting of a stator and rotor that provides position and velocity information to the drive for motor commutation
<b>RMS</b>		The root mean square is the square root of a mean square value
<b>Rod cylinder</b>		A cylinder using a rod attached to its piston to transmit force
<b>Roller screw</b>		A screw assembly which uses a roller nut which contains guided steel rollers which are rotating around their own axis and around the screw (planetary rollers)
S		
<b>Screw assembly</b>		Device which converts rotary motion into linear motion
<b>Service life</b>		The nominal life is expressed by the number of revolutions (or number of operating hours at constant rotary speed) that will be attained or exceeded by 90 % of a sufficiently large number of identical screw drives before the first signs of material fatigue become evident
<b>Servomotor</b>		A motor which is used in closed loop systems where feedback is used to control motor velocity, position or torque
<b>Spur gear</b>		Is a gear or a system of gearing having radial teeth parallel to the axle
<b>Static axial force</b>		Maximum axial force which can be applied on a linear unit only if it is not moving
<b>Stiffness</b>		Is the rigidity of an object, representing its resistance to deformation from an applied force
<b>Stroke length</b>		The linear distance that the push tube of a cylinder can extend or retract



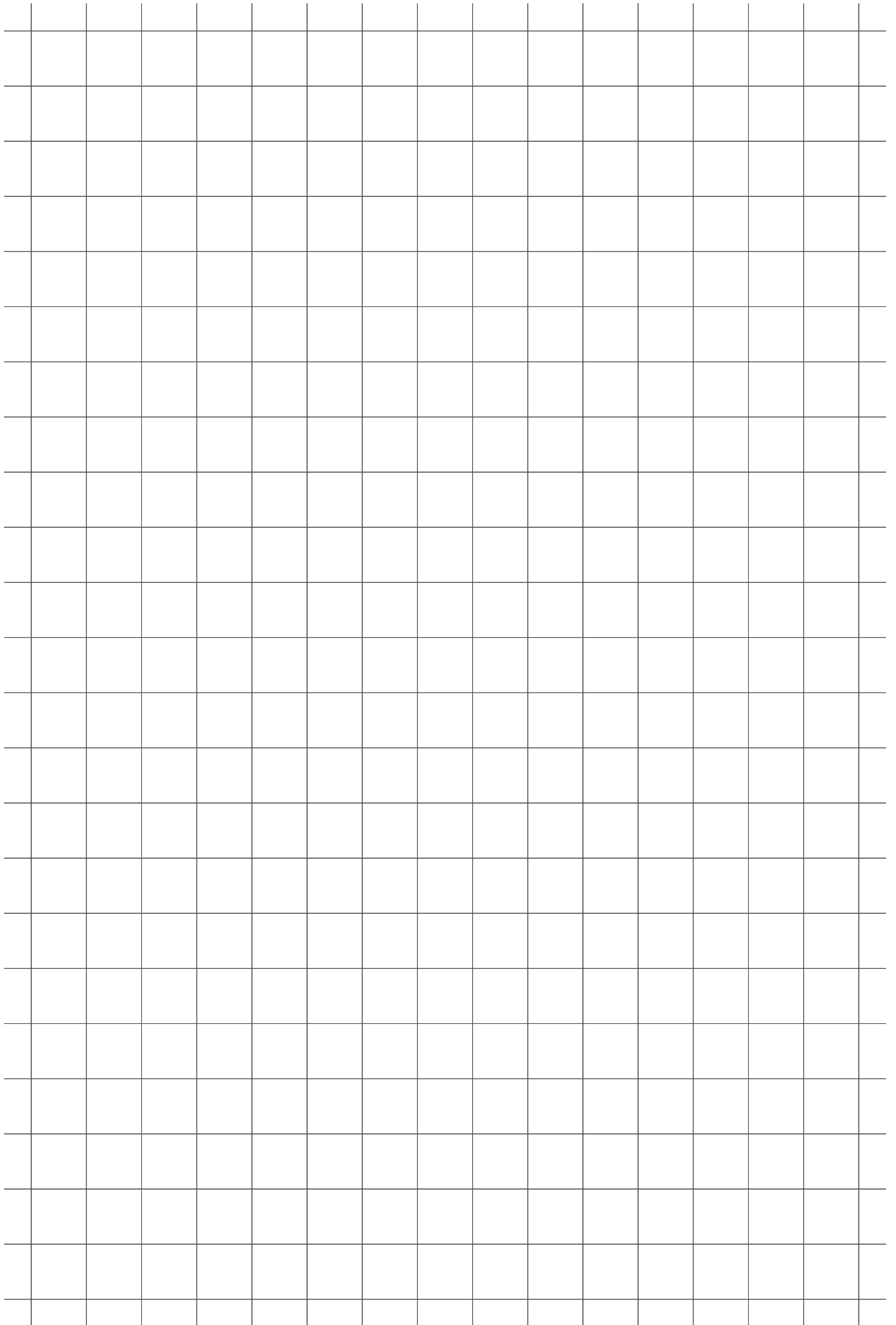
T		
	<b>Thermal load</b>	The thermal load describes the force which the actuator can permanently move without overheating. The thermal load is calculated by a formula in respect of changing load conditions over different time phases of a full motion cycle.
	<b>Torque</b>	A measure of angular force which produces rotational motion
U		
	<b>Units (metric)</b>	A decimal system of weights and measures based on the kilogram and meter
V		
	<b>Volt</b>	Difference in electrical potential between two points
W		
	<b>Watt</b>	A unit of power or a rate of doing work. The power dissipated by a one-ohm resistor with one ampere of current is one watt
	<b>Weight</b>	Force of gravity acting on a body. Determined by multiplying the mass of the object by the acceleration due to gravity

# Symbols description

A				
a	m/s <sup>2</sup>	Acceleration	The change in velocity as a function of time, going from a lower speed to a higher speed	
a <sub>max</sub>	m/s <sup>2</sup>	Max. acceleration	The maximum allowed change in velocity as a function of time from a lower speed to a higher speed. Exceeding this value can cause damages.	
C				
C	kN	Dynamic load capacity	Constant that is used to calculate the service life of a ball or roller screw. The value for the dynamic load rating represents the load under which 90 % of a sufficient large number of identical screws can achieve a service life of one million revolutions	
D				
D	%	Duty cycle of the cylinder	The ratio of active time at full load and total cycle time within a given cycle of operation	
D <sub>unit</sub>	%	Duty cycle of the linear unit	The ratio of active time and total cycle time within a given cycle of operation	
d <sub>screw</sub>	mm	Screw diameter	Describes the outer diameter of the screw shaft	
E				
η	%	Efficiency	Ratio of output power versus input power	
η <sub>lu</sub>	%	Efficiency of the linear unit	Ratio of output power versus input power of the linear unit.	
F				
F	N	Force (cylinder) or load (application)	The action of one body on another which tends to change the state of motion of that body. Typically described in terms of magnitude, direction and point of application. The force is related to the capability of the cylinder while the load is related to the mass or weight of an application acting on the axial direction on the push tube.	
F <sub>Amax</sub>	N	Maximum dynamic axial load of the application	Maximum axial push or pull load which is needed to fulfill the specifications of the application.	
F <sub>c</sub>	N	Continuous force at max speed	The continuous force at max speed describes the force the cylinder can permanently move at maximum allowed linear speed, without overheating.	
F <sub>c0</sub>	N	Continuous force at zero speed	The continuous force at zero speed describes the force the cylinder can permanently hold without overheating and without using a brake.	
F <sub>cont</sub>		Continuous force curve	A curve that represents the continuous force an actuator can permanently move at maximum allowed linear speed, without overheating.	
F <sub>Hold</sub>	kN	Holding force of the brake	Describes the maximum axial load the engaged brake (optional motor brake) can hold if the motor is disabled. This value must not exceed the maximum axial force of the cylinder	
F <sub>m</sub>	N	Equivalent dynamic axial load	Load of constant magnitude over a full motion cycle which has the same influence on the linear unit's service life as the actual fluctuating load	
F <sub>max</sub>	N	Maximum dynamic axial force	The maximum dynamic axial force describes the maximum force an electric cylinder can deliver during movements without damaging parts. The acceleration/ deceleration of masses need to be considered.	
F <sub>max0</sub>	N	Max. static axial force	Maximum axial force which can be applied on a linear unit only if it is not moving.	
F <sub>p</sub>	N	Peak force	The peak force describes the maximum force the cylinder can push or pull for a short time, without being mechanically destroyed or by overheating. The length of the peak is depending on the temperature of the system when the peak is initiated.	
F <sub>p0</sub>	N	Peak force at zero speed	The peak force at zero speed is the maximum force the cylinder can hold for a short time without using a brake.	
F <sub>peak</sub>		Peak force curve	A curve that represents the continuous force an actuator can push or pull for a short time, without being mechanically destroyed or by overheating. The length of the peak is depending on the temperature of the system when the peak is initiated.	

I				
i	#	<b>Gear reduction</b>	Describes the factor between the number of revolutions of the input of the gear divided by the number of revolutions of the output of the gear. A gear reduction 2 means that the output of the gear (linear unit side) is turning with half speed compared to the input of the gear (motor side). Using a gear reduction enables for using smaller motors with less torque to bring higher force but with lower speed	
I	A	<b>Nominal Current</b>	Is the nominal current consumption of the motor	
I <sub>peak</sub>	A	<b>Peak current</b>	Is the maximum current consumption of the motor for a short period of time.	
IP		<b>Degree of protection</b>	International protection (also ingress protection) describes the protection of a product with two digits. The first digit describes the protection against dust, the second against water. The higher the value the better the protection.	
J				
J	10 <sup>-4</sup> kgm <sup>2</sup>	<b>Inertia</b>	Property of an object that resists a change in motion. It is dependent on the mass and shape of the object. The greater an object's mass, the greater its inertia and the more force is necessary to accelerate and decelerate. As an electric cylinder is available in different lengths, the inertia is typically given for stroke 0, followed by an inertia indication ΔJ for each additional 100 mm.	
J <sub>brake</sub>	10 <sup>-4</sup> kgm <sup>2</sup>	<b>Inertia of the brake</b>	Property of an object that resists a change in motion. It is dependent on the mass and shape of the object. The greater an object's mass, the greater its inertia and the more force is necessary to accelerate and decelerate. As the brake is typically an option, this value has to be added to the Inertia of the electric cylinder.	
J <sub>lu</sub>	10 <sup>-4</sup> kgm <sup>2</sup>	<b>Inertia of the linear unit</b>	Property of an object that resists a change in motion. It is dependent on the mass and shape of the object. The greater an object's mass, the greater its inertia and the more force is necessary to accelerate and decelerate. As the linear unit is available in different lengths, the inertia is typically given for stroke 0, followed by an inertia indication ΔJ for each additional 100 mm.	
L				
L <sub>10 dist</sub>	km	<b>Lifetime distance</b>	Service life in km that 90 % of a sufficiently large group of apparently identical cylinders can be expected to reach or exceed.	
M				
m	kg	<b>Weight</b>	Force of gravity acting on a body. Determined by multiplying the mass of the object by the acceleration due to gravity	
Δm	kg	<b>Weight difference</b>	As electric cylinders are available in different lengths, the weight is typically given for stroke 0, followed by a weight indication Δm for each additional 100 mm.	
m <sub>arot0</sub>	kg	<b>Weight of the anti-rotation device</b>	The weight of the optional anti-rotation device has to be added to the weight of the cylinder.	
m <sub>brake</sub>	kg	<b>Weight of the brake</b>	The weight of the optional brake has to be added to the weight of the cylinder	
m <sub>lu</sub>	kg	<b>Weight of the linear unit</b>	As the linear unit is available in different lengths, the weight is typically given for stroke 0, followed by a weight indication Δm for each additional 100 mm.	
M	Nm	<b>Torque</b>	A measure of angular force applied to a linear axis to produce rotational motion	
M <sub>Ac</sub>	Nm	<b>Required continuous torque</b>	A measure of continuous angular force (torque) a motor has to deliver without overheating	
M <sub>Amax</sub>	Nm	<b>Required maximum torque of the motor</b>	Maximum angular force (torque) of a motor which is required that the cylinder is able to push or pull the maximum load of the application	
M <sub>max</sub>	Nm	<b>Maximum torque</b>	The maximum torque is the upper limitation of the torque. Exceeding this value can cause damages of related parts.	
N				
n <sub>cycles</sub>	#	<b>Number of cycles</b>	The number of motion cycles a cylinder has to have without damage during the expected life of the application	
n <sub>max</sub>	1/min	<b>Max. rotational speed</b>	Describes the maximum allowed number of full rotations of an axis. Exceeding this value can cause damages.	

P				
	P	W	Nominal Power	Nominal power of the motor, given by multiplying the nominal voltage and the nominal current
	$p_{\text{screw}}$	mm	Screw lead	Describes the axial distance a nut is moving on a screw at one full rotation of either the screw or the nut
R				
	R	$\Omega$	Resistance	The opposition to the flow of charge through a conductor
S				
	s	mm	Stroke	The linear distance that the push tube of a cylinder can extend or retract
	$s_0$	mm	Internal over stroke	Additional stroke which is not part of the specified stroke length of the cylinder. It is used to prevent the screw nut touching the mechanical end stops when moving over the full specified stroke.
	$s_{\text{backlash}}$	mm	Backlash	Axial play that the cylinder push tube has without turning the screw. It's equivalent with the mechanical axial play of the inner parts of the cylinder.
	$s_{\text{cycle}}$	m	Distance travelled per motion cycle	Travelled distance of a push tube for a full motion cycle, from the start to the next start in both directions.
	$s_{\text{max}}$	mm	Maximum stroke	The maximum stroke describes the mechanical limitation which a cylinder can extend or retract. Limiting factors are side loads (buckling), speed (wobbling of the screw inside), limitations in the manufacturing process and others
T				
	t	s	Time	Time in seconds which is needed for a certain activity.
	$t_{\text{cycle}}$	s	Cycle time	Time for one complete motion cycle, from the start of the cycle until the start of the next cycle
	$t_L$	h	Required lifetime in hours	The lifetime of a cylinder in hours which is required to serve an application without damage during the expected life of the application.
	T	Nm	Torque	A measure of angular force applied to a linear axis to produce rotational motion
	$T_{\text{ambient}}$	°C	Ambient temperature	Temperature of the environment around the object
U				
	U	V	Nominal voltage	Is the supply voltage required by the electric motor
V				
	v	m/s	Linear speed	The linear speed is the change in position as a function of time.
	$v_{\text{max}}$	mm/s	Max. linear speed	Maximum linear speed, a linear unit or a cylinder can reach without damaging the mechanical system. Limiting factors can be the recirculating system of the balls or rollers, or the heat dissipation when using lead screws, or others. If the motor of the cylinder could turn faster, it needs to be limited
	$v_{\text{min}}$	mm/s	Min. linear speed	Minimum linear speed of a LEMC-A cylinder equipped with asynchronous motors that can be adjusted through the integrated frequency inverter







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